A note on reducing variance by estimating the nuisance

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Some people may have heard of a strange phenomenon in causal inference or missing data problem that an estimator based on estimated nuisance could have a smaller variance than an estimator based on oracle nuisance (knowing the true nuisance parameter such as the propensity score).

In this note, I will try to explain how this phenomenon occurs in the setting of estimating equations.

The main reference is

Lok, Judith J. "How estimating nuisance parameters can reduce the variance (with consistent variance estimation)." arXiv preprint arXiv:2109.02690 (2021).

1 Setup: estimating equations

We consider a general setup for the estimating equations with nuisance parameter.

Suppose our data consists of IID triplets

$$(X_1, Y_1, Z_1), \cdots, (X_n, Y_n, Z_n) \sim \mathbb{P}.$$

Let $\theta \in \mathbb{R}^d$ be the parameter of interest in our model. Let $\eta \in \mathbb{R}^q$ be the nuisance parameter that only involves *X*,*Z*.

Let \mathbb{P}_n be the empirical measure from the data and \mathbb{P} be the probability measure.

We consider the following two functions for identifying θ , η :

$$S_1(x,y,z;\theta,\eta) = S_1(\theta,\eta) \in \mathbb{R}^d$$

 $S_2(x,z;\eta) = S_2(\eta) \in \mathbb{R}^q.$

The estimators of θ and η are parameters that solves the estimating equations:

$$0 = \frac{1}{n} \sum_{i=1}^{n} S_1(X_i, Y_i, Z_i; \widehat{\theta}, \widehat{\eta}) = \mathbb{P}_n S_1(\widehat{\theta}, \widehat{\eta}) = S_{n,1}(\widehat{\theta}, \widehat{\eta})$$

$$0 = \frac{1}{n} \sum_{i=1}^{n} S_2(X_i, Z_i; \widehat{\eta}) = \mathbb{P}_n S_2(\widehat{\eta}) = S_{n,2}(\widehat{\eta}).$$

(1)

For abbreviation, we sometimes write

$$S_1(\cdot;\boldsymbol{\theta},\boldsymbol{\eta}) = S_1(X,Y,Z;\boldsymbol{\theta},\boldsymbol{\eta}), \qquad S_2(\cdot;\boldsymbol{\eta}) = S_2(X,Z;\boldsymbol{\eta}).$$

The population version of these quantities are

$$0 = \mathbb{E}[S_1(X_i, Y_i, Z_i; \boldsymbol{\theta}_0, \boldsymbol{\eta}_0)] = \mathbb{P}S_1(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0)$$

$$0 = \mathbb{E}[S_2(X_i, Z_i; \boldsymbol{\eta}_0)] = \mathbb{P}S_2(\boldsymbol{\eta}_0).$$
 (2)

Key assumption on the estimating equations: nuisance generative model. We consider the following additional requirement on the second estimating equation:

$$S_2(x,z;\eta) = \nabla_{\eta} \log p(z|x;\eta), \tag{3}$$

where $p(z|x;\eta)$ is the conditional PDF/PMF of Z given X. Namely, the nuisance parameter is identified from the log-likelihood model.

Equation (3) together with equation (2) implies that the joint distribution p(x, y, z) that generates our data can be factored as

$$p(x, y, z) = p(y|x, z; \boldsymbol{\theta}_0, \boldsymbol{\gamma}_0) p(z|x; \boldsymbol{\eta}_0) p(x),$$

where γ_0 is another set of nuisance parameters such that (θ_0, γ_0) together determines the conditional distribution $p(y|x, z; \theta_0, \gamma_0)$. This is because the parameter of interest θ may not uniquely determine a generative model. Thus, we allow another set of parameters γ in the conditional distribution. Note that p(x) itself is another nuisance function that is not specified in the estimating equations.

Example: Inverse probability weighting in binary treatment problem. Consider a binary treatment effect problem where our *Y* is outcome of interest, *X* is confounders, $Z \in \{0, 1\}$ is the treatment indicator. A common estimator of the average treatment effect (ATE) θ is

$$\mathbf{\theta} = \mathbb{E}\left(rac{YZ}{\pi(X;\mathbf{\eta})} - rac{Y(1-Z)}{1-\pi(X;\mathbf{\eta})}
ight),$$

where $\pi(x;\eta) = P(Z = 1 | X = x; \eta)$. A common model of η is the logistic regression, i.e.,

$$\pi(x;\eta) = \frac{e^{\eta^T x}}{1+e^{\eta^T x}}.$$

A common estimator of θ is

$$\widehat{\boldsymbol{\theta}} = \frac{1}{n} \sum_{i=1}^{n} \frac{Y_i Z_i}{\pi(X_i; \widehat{\boldsymbol{\eta}})} - \frac{Y_i (1-Z_i)}{1-\pi(X_i; \widehat{\boldsymbol{\eta}})},$$

which can be written as $\hat{\theta}$ from solving

$$0 = \frac{1}{n} \sum_{i=1}^{n} \left(\widehat{\Theta} - \frac{Y_i Z_i}{\pi(X_i; \widehat{\eta})} - \frac{Y_i (1 - Z_i)}{1 - \pi(X_i; \widehat{\eta})} \right),$$

so this implies

$$S_1(X,Y,Z;\theta,\eta) = \theta - \frac{Y_i Z_i}{\pi(X_i;\eta)} - \frac{Y_i(1-Z_i)}{1-\pi(X_i;\eta)} = \theta - Y_i Z_i(1+e^{-\eta^T X_i}) - Y_i(1-Z_i)(1+e^{\eta^T X_i}).$$

The estimator $\hat{\eta}$ is often from the MLE, which in the case of logistic regression, is from the following score equation:

$$0 = \frac{1}{n} \sum_{i=1}^{n} Z_i X_i - \frac{X_i e^{\widehat{\eta}^T X_i}}{1 + e^{\widehat{\eta}^T X_i}}.$$

Thus,

$$S_2(X,Z;\eta) = ZX - \frac{Xe^{\eta^T X}}{1+e^{\eta^T X}}.$$

2 Asymptotic variance

To investigate the asymptotic variance of $\hat{\theta}, \hat{\eta}$, we use a standard procedure. First, let

$$S_n(\theta,\eta) = \begin{pmatrix} \mathbb{P}_n S_1(\theta,\eta) \\ \mathbb{P}_n S_2(\eta) \end{pmatrix} \in \mathbb{R}^{d+q}, \qquad \bar{S}(\theta,\eta) = \begin{pmatrix} \mathbb{P} S_1(\theta,\eta) \\ \mathbb{P} S_2(\eta) \end{pmatrix} \in \mathbb{R}^{d+q}.$$

Equations (1) and (2) imply that

$$0 = S_n(\widehat{\theta}, \widehat{\eta}) = \overline{S}(\theta_0, \eta_0).$$

Thus, Taylor expansion shows that

$$S_n(\theta_0, \eta_0) - \bar{S}(\theta_0, \eta_0) = S_n(\theta_0, \eta_0) - S_n(\widehat{\theta}, \widehat{\eta})$$

$$\approx -\nabla S_n(\theta_0, \eta_0) \begin{pmatrix} \widehat{\theta} - \theta_0 \\ \widehat{\eta} - \theta_0 \end{pmatrix},$$

which further implies that

$$\begin{pmatrix} \widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \\ \widehat{\boldsymbol{\eta}} - \boldsymbol{\theta}_0 \end{pmatrix} \approx -[\bar{H}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0)]^{-1} (S_n(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) - \bar{S}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0)), \tag{4}$$

where

$$\bar{H}(\theta,\eta) = \nabla \bar{S}(\theta,\eta)$$

is the asymptotic limit of $\nabla S_n(\theta_0, \eta_0)$.

The Hessian matrix $\bar{H}(\theta,\eta)$ has a block diagonal feature that

$$\begin{split} \bar{H}(\theta_0,\eta_0) &= \begin{pmatrix} \mathbb{E}[\nabla_{\theta}S_1(X,Y,Z;\theta_0,\eta_0)] & \mathbb{E}[\nabla_{\eta}S_1(X,Y,Z;\theta_0,\eta_0)] \\ \mathbb{E}[\nabla_{\theta}S_2(X,Z;\eta_0)] & \mathbb{E}[\nabla_{\eta}S_2(X,Z;\eta_0)] \end{pmatrix} \\ &= \begin{pmatrix} \mathbb{E}[\nabla_{\theta}S_1(X,Y,Z;\theta_0,\eta_0)] & \mathbb{E}[\nabla_{\eta}S_1(X,Y,Z;\theta_0,\eta_0)] \\ 0 & \mathbb{E}[\nabla_{\eta}S_2(X,Z;\eta_0)] \end{pmatrix}. \end{split}$$

This implies that the inverse matrix will have a similar block-diagonal structure:

$$\bar{H}(\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)^{-1} = \begin{pmatrix} \bar{\Omega}_{11}(\boldsymbol{\theta}_0,\boldsymbol{\eta}_0) & \bar{\Omega}_{12}(\boldsymbol{\theta}_0,\boldsymbol{\eta}_0) \\ 0 & \bar{\Omega}_2 2(\boldsymbol{\eta}_0) \end{pmatrix}.$$

Using the matrix algebra, one can show that the off-diagonal block is

$$\bar{\Omega}_{12}(\theta_0, \eta_0) = -\mathbb{E}[\nabla_{\theta} S_1(\cdot; \theta_0, \eta_0)]^{-1} \mathbb{E}[\nabla_{\eta} S_1(\cdot; \theta_0, \eta_0)] \mathbb{E}[\nabla_{\eta} S_2(\cdot; \eta_0)]^{-1}
= -H_{11}^{-1}(\theta_0, \eta_0) \mathbb{E}[\nabla_{\eta} S_1(\cdot; \theta_0, \eta_0)] H_{22}^{-1}(\eta_0).$$
(5)

An interesting note is that

$$H_{11}^{-1}(\theta_0, \eta_0) = \Omega_{11}(\theta_0, \eta_0), \qquad H_{22}^{-1}(\eta_0) = \Omega_{22}(\eta_0)$$

The quantity $\overline{\Omega}_{12}(\theta_0, \eta_0)$ will play a key role in the asymptotic variance of $\widehat{\theta}$. To see this, putting equation (5) into equation (4) leads to

$$\hat{\theta} - \theta_{0} = -\bar{\Omega}_{11}(\theta_{0}, \eta_{0})(S_{n,1}(\theta_{0}, \eta_{0}) - \underbrace{\bar{S}_{1}(\theta_{0}, \eta_{0})}_{=0}) - \bar{\Omega}_{12}(\theta_{0}, \eta_{0})(S_{n,2}(\eta_{0}) - \underbrace{\bar{S}_{2}(\eta_{0})}_{=0}) = 0$$

$$= -\bar{\Omega}_{11}(\theta_{0}, \eta_{0})[S_{n,1}(\theta_{0}, \eta_{0}) - \underbrace{\mathbb{E}[\nabla_{\eta}S_{1}(\cdot; \theta_{0}, \eta_{0})]\Omega_{22}(\eta_{0})S_{n,2}(\eta_{0})]}_{=(A)}].$$
(6)

The quantity (A) is how estimating the nuisance (from $S_{n,2}$) influences the variance of the estimator $\hat{\theta}$.

As a reference, if we are using the oracle estimator, i.e., knowing η_0 , the asymptotic expansion will be

$$\boldsymbol{\theta} - \boldsymbol{\theta}_0 \approx - \bar{\boldsymbol{\Omega}}_{11}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) S_{n,1}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0). \tag{7}$$

3 Invariance under linear transformation

To investigate how the asymptotic variance from equation (6) can be smaller than the oracle in equation (7), we use the following insight:

the estimating equations remain unchanged under some linear transformation.

Let $A \in \mathbb{R}^{d \times p}$ be a none-random matrix. The estimators from equation (1) will be the same if we replace $S_1(X, Y, Z; \theta, \eta)$ by

$$S_{1,A}(X,Y,Z;\theta,\eta) = S_1(X,Y,Z;\theta,\eta) + AS_2(X,Z;\eta).$$

After this change, we can redo all the derivation, which leads to another asymptotic linear representation of $\hat{\theta}$:

$$\widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \approx -\bar{\boldsymbol{\Omega}}_{11,A}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) [S_{n,1,A}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) - \mathbb{E}[\nabla_{\boldsymbol{\eta}} S_{1,A}(\cdot; \boldsymbol{\theta}_0, \boldsymbol{\eta}_0)] \boldsymbol{\Omega}_{22,A}(\boldsymbol{\eta}_0) S_{n,2}(\boldsymbol{\eta}_0)],$$

where $\bar{\Omega}_{11,A}$ and $\bar{\Omega}_{22,A}$ are the corresponding quantities of $\bar{\Omega}_{11}$ and $\bar{\Omega}_{11}$ under the linear transformation. An important note is that $\bar{\Omega}_{11,A} = \bar{\Omega}_{11}$ and $\bar{\Omega}_{22,A} = \bar{\Omega}_{22}!$

Thus, we conclude that

$$\widehat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \approx -\bar{\boldsymbol{\Omega}}_{11}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) [\underbrace{S_{n,1,A}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0)}_{=(B)} - \underbrace{\mathbb{E}[\nabla_{\boldsymbol{\eta}} S_{1,A}(\cdot; \boldsymbol{\theta}_0, \boldsymbol{\eta}_0)] \boldsymbol{\Omega}_{22}(\boldsymbol{\eta}_0) S_{n,2}(\boldsymbol{\eta}_0)}_{=(C)}], \tag{8}$$

where

$$S_{n,1,A}(\theta_0,\eta_0) = \mathbb{P}_n[S_1(\theta_0,\eta_0) + A \cdot S_2(\eta_0)]$$

$$S_{1,A}(\cdot;\theta_0,\eta_0) = S_1(\cdot;\theta_0,\eta_0) + A \cdot S_2(\cdot;\eta_0).$$

This holds for any non-random A. So the question is: how can we choose A to minimize this variance.

We will consider the following choice:

$$A^* = \mathbb{E}[S_1(X, Y, Z; \theta_0, \eta_0) S_2(X, Z; \eta_0)^T] \mathbb{E}[S_2(X, Z; \eta_0) S_2(X, Z; \eta_0)^T]^{-1}$$

Note that equation (3) implies the following two powerful results:

$$\mathbb{E}(\nabla_{\eta}S_2(X,Z;\eta)) = \mathbb{E}(S_2(X,Z;\eta)S_2(X,Z;\eta)^T),$$

$$\mathbb{E}(\nabla_{\eta}S_1(X,Y,Z;\theta_0,\eta_0)) = -\mathbb{E}[S_1(X,Y,Z;\theta_0,\eta_0)S_2(X,Z;\eta_0)^T].$$
(9)

This will imply a powerful fact about $\mathbb{E}[\nabla_{\eta}S_{1,A}(\cdot;\theta_0,\eta_0)]$ that is a key quantity in term (C). A simple derivation shows that

$$\begin{split} \mathbb{E}[\nabla_{\eta}S_{1,A^*}(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)] &= \mathbb{E}[\nabla_{\eta}S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0) + A^* \cdot \nabla_{\eta}S_2(\cdot;\boldsymbol{\eta}_0)] \\ &= \mathbb{E}[\nabla_{\eta}S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)] + \mathbb{E}[S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)S_2(\cdot;\boldsymbol{\eta}_0)^T] \underbrace{\mathbb{E}[S_2(\cdot;\boldsymbol{\eta}_0)S_2(\cdot;\boldsymbol{\eta}_0)^T]^{-1}\mathbb{E}[\nabla_{\eta}S_2(\cdot;\boldsymbol{\eta}_0)]}_{=I_d} \\ &= \mathbb{E}[\nabla_{\eta}S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)] + \mathbb{E}[S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)S_2(\cdot;\boldsymbol{\eta}_0)^T] \\ &= 0. \end{split}$$

Therefore, under $A = A^*$, (C) = 0.

Therefore, the only quantity left is term (B). So we can rewrite equation (8) as

$$\hat{\boldsymbol{\theta}} - \boldsymbol{\theta}_0 \approx -\bar{\boldsymbol{\Omega}}_{11}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0) S_{n,1,A^*}(\boldsymbol{\theta}_0, \boldsymbol{\eta}_0),$$

where

$$S_{n,1,A^*}(\theta_0,\eta_0) = \mathbb{P}_n S_{1,A^*}(\theta_0,\eta_0)$$

$$S_{1,A^*}(\cdot;\theta_0,\eta_0) = S_1(\cdot;\theta_0,\eta_0) - \mathbb{E}(S_1(\cdot;\theta_0,\eta_0)S_2(\cdot;\eta_0)^T) \mathbb{E}(S_2(\cdot;\eta_0)S_2(\cdot;\eta_0)^T)^{-1}S_2(\cdot;\eta_0).$$

The quantity $S_{1,A^*}(\theta_0, \eta_0)$ is the orthogonal component of $S_1(\theta_0, \theta_0)$ of $S_2(\eta_0)$. Thus, the covariance matrix of $S_{1,A^*}(\theta_0, \eta_0)$ will be smaller than the covariance matrix of $S_1(\theta_0, \eta_0)$! Namely, one can show that

$$\mathbb{E}[S_{1,A^*}(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)S_{1,A^*}(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)^T] - \mathbb{E}[S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)S_1(\cdot;\boldsymbol{\theta}_0,\boldsymbol{\eta}_0)^T]$$

is negative definite. This implies that the estimator $\hat{\theta}$ has a smaller asymptotic variance than the oracle estimator $\tilde{\theta}!$

4 **Derivation of equation** (9)

This derivation is similar to the derivation in the maximum likelihood estimator theory. For the completeness, we provide a derivation on the second equation. The first equation can be obtained in a similar manner. Equation (3) requires

$$S_2(x,z;\eta) = \nabla_{\eta} \log p(z|x;\eta).$$

Using the population estimating equations,

$$0 = \mathbb{E}(S_1(X, Y, Z; \boldsymbol{\theta}_0, \boldsymbol{\eta}_0)) = \int S_1(x, y, z; \boldsymbol{\theta}_0, \boldsymbol{\eta}_0) p(y|x, z; \boldsymbol{\theta}_0, \boldsymbol{\gamma}_0) p(z|x; \boldsymbol{\eta}_0) p(x) dy dz dx$$

assuming that the data is from $p(x, y, z; \theta_0, \gamma_0, \eta_0)$, where γ_0 is another set of nuisance parameter such that (θ_0, γ_0) together determines the distribution $p(y|x, z; \theta_0, \gamma_0)$. See the discussion after Equation (3).

The above result implies that if the data is from $p(x, y, z; \theta, \gamma, \eta)$, we have the integral relation

$$0 = \int S_1(x, y, z; \theta, \eta) p(y|x, z; \theta, \gamma) p(z|x; \eta) p(x) dy dz dx.$$

for any $\eta, \theta.$ Taking derivative with respect to η leads to

$$\begin{split} 0 &= \nabla_{\eta} 0 \\ &= \nabla_{\eta} \int S_{1}(x, y, z; \theta, \eta) p(y|x, z; \theta, \gamma) p(z|x; \eta) p(x) dy dz dx \\ &= \int [\nabla_{\eta} S_{1}(x, y, z; \theta, \eta)] p(y|x, z; \theta, \gamma) p(z|x; \eta) p(x) dy dz dx \\ &+ \int S_{1}(x, y, z; \theta, \eta) p(y|x, z; \theta, \gamma) [\nabla_{\eta} \log p(z|x; \eta)] \log p(z|x; \eta) p(x) dy dz dx \\ &= \mathbb{E} [\nabla_{\eta} (S_{1}(X, Y, Z; \theta, \eta))] + \mathbb{E} [S_{1}(X, Y, Z; \theta, \eta) S_{2}(X, Z; \eta)^{T}], \end{split}$$

which is the desired result.