

A short note on the proximal causal inference

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References:

[TYCSM2020] Tchetgen, E. J. T., Ying, A., Cui, Y., Shi, X., & Miao, W. (2020). An introduction to proximal causal learning. arXiv preprint arXiv:2009.10982.

[SWT2021] Shpitser, I., Wood-Doughty, Z., & Tchetgen, E. J. T. (2021). The proximal id algorithm. arXiv preprint arXiv:2108.06818.

1 Problem setup

In this note, I will briefly review the idea of proximal causal inference approach. This will be a short summary/introduction to the above two recent papers.

We consider a standard causal inference problem under observational data that $A \in \{0, 1\}$ is the binary treatment variable and $Y \in \mathbb{R}$ is the outcome/response of interest. Let X be observed covariates that may include part of the confounders. Under the potential outcome model, the outcome Y admits two potential outcomes $Y(0), Y(1)$. The parameter of interest is the average treatment effect (ATE) $\tau = \mathbb{E}(Y(1) - Y(0))$.

Suppose X contains all confounders, we have

$$(Y(0), Y(1)) \perp A | X$$

and it is well-known that the ATE is identifiable.

However, if X does not contain all confounders, i.e., there is another unobserved random vector U , the ATE is in general non-identifiable. Note that in this case, we still have

$$(U) \quad (Y(0), Y(1)) \perp A | X, U. \tag{1}$$

To identify the ATE, we need additional information. The idea of proximal causal inference is based on the introduction of two proxy variables (Z, W):

- *The treatment proxy Z .* Z is a variable that is caused by the treatment A so it admits two potential outcomes $Z(0), Z(1)$ and it may be dependent with the confounders (X, U). However, the proxy control Z is not associated with Y or W conditioned on the confounders.
- *The outcome proxy (negative control outcome) W .* W is a variable that is known to be unaffected by the treatment A but it may be dependent with confounders (X, U) and Y .

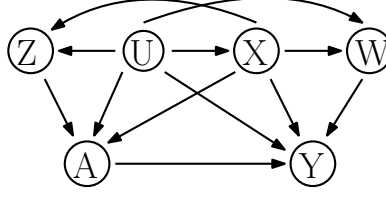


Figure 1: A causal DAG for the proximal inference.

Figure 1 provides a graphical representation under the proximal inference. Formally, the two proxies (Z, W) has to satisfy the following proximal assumptions:

$$(P1) \quad Z(a) \perp Y(a) | X, U \quad (2)$$

$$(P2) \quad W \perp (A, Z(a)) | X, U. \quad (3)$$

Note that the above assumptions imply that

$$Y \perp Z | U, X, A, \quad W \perp Z | U, X, A. \quad (4)$$

2 Bridge function

Based on the above notations, our observed data consists of variables (Y, A, X, Z, W) . And there is a bridge function $b^*(y, w, a, x, z)$ such that

$$p(y|a, x, z) = \int b^*(y, w, a, x, z) p(w|a, x, z) dw.$$

Namely,

$$p(y|a, x, z) = \mathbb{E}[b^*(y, W, A, X, Z) | A = a, X = x, Z = z].$$

To identify the ATE, we need two additional assumptions related to the bridge function

$$(A1) \quad b^*(y, w, a, x, z) = b^*(y, w, a, x) \quad (5)$$

$$(A2) \quad \mathbb{E}(f(U) | A, X, Z) = 0 \quad \forall A, X, Z \Leftrightarrow f(u) = 0. \quad (6)$$

Assumption (A1) is the main assumption on the bridge function. Under assumption (A1), [TYCSM2020] has provided an approach to construct b^* from the data. So in what follows, we assume that the bridge function $b^*(y, w, a, x)$ is known.

Assumption (A2) is called the *completeness assumption*. It requires that most information/randomness of unmeasured confounders U is contained in the variables (A, X, Z) .

3 Identification of potential outcome

Now we will show that under (U), (P1-2), and (A1-2), the distribution of potential outcome $Y(a)$ is identifiable.

Theorem 1 Assume (U), (P1-2), and (A1-2). Then the distribution of potential outcome $Y(a)$, $p(y(a))$, is identified from the following formula:

$$p(y(a)) = \int b^*(y, w, a, x) p(w, x) dw dx.$$

The above formula is also known as *proximal g-formula*.

Proof.

First, note that

$$\begin{aligned} p(y|a, x, z) &= \int p(y, u|a, x, z) \\ &= \int p(y|u, a, x, z) p(u|a, x, z) du \\ &\stackrel{(4)}{=} \int p(y|a, u, x) p(u|a, x, z) du. \end{aligned}$$

Similarly,

$$\begin{aligned} p(w|a, x, z) &= \int p(w, u|a, x, z) \\ &= \int p(w|u, a, x, z) p(u|a, x, z) du \\ &\stackrel{(4)}{=} \int p(w|u, a, x) p(u|a, x, z). \end{aligned}$$

Recall from assumption (A1), we have

$$p(y|a, x, z) = \int b^*(y, w, a, x) p(w|a, x, z) dw.$$

So the above two new representations of $p(y|a, x, z)$ and $p(w|a, x, z)$ will imply:

$$\int p(y|a, u, x) p(u|a, x, z) du = \int \int b^*(y, w, a, x) p(w|u, a, x) p(u|a, x, z) dw du,$$

which is equivalent to

$$\begin{aligned} 0 &= \int \left[p(y|a, u, x) - \int b^*(y, w, a, x) p(w|u, a, x) dw \right] p(u|a, x, z) du \\ &= \mathbb{E}[p(y|A, U, X) - \int b^*(y, w, A, X) p(w|U, A, X) dw | A = a, X = x, Z = z] \end{aligned}$$

for all a, x, z . By assumption (A2), this implies that

$$p(y|a, u, x) = \int b^*(y, w, a, x) p(w|a, u, x) dw. \quad (7)$$

By assumption (U),

$$p(y|a, u, x) = p(y(a)|a, u, x) \stackrel{(U)}{=} p(y(a)|u, x).$$

Thus,

$$\begin{aligned} p(y(a)) &= \int p(y(a)|u, x) p(u, x) du dx \\ &= \int p(y|a, u, x) p(u, x) du dx \\ &\stackrel{(7)}{=} \int \int b^*(y, w, a, x) \underbrace{p(w|a, u, x)}_{=p(w|u, x) \text{ by (3)}} p(u, x) dw du dx \\ &= \int b^*(y, w, a, x) \int p(w, u, x) du dw dx \\ &= \int b^*(y, w, a, x) dw dx, \end{aligned}$$

which completes the proof.

□