

A short note on the information bounds of generalization errors

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February 14, 2022

References:

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1 Problem setup

In this note, I will summarize a simple information bound on the generalization error. Consider a classical prediction problem where our training data is

$$(X_1, Y_1), \dots, (X_n, Y_n) \in \mathcal{X} \times \mathcal{Y}$$

that are IID from some unknown distribution P_{XY} . For simplicity, we may denote $Z_i = (X_i, Y_i)$ so that the training data can be viewed as IID from P_Z . We denote $P_Z^{\otimes n} = P_Z \times P_Z \times \dots \times P_Z$ as the joint PDF of (Z_1, \dots, Z_n) .

In a typical supervised learning, we try to construct a predictor $c : \mathcal{X} \rightarrow \mathcal{Y}$. To simplify the problem, we assume that this predictor is indexed by a parameter θ , so we can write $c(x) = c_\theta(x)$.

Let $\ell_0 : \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}$ be the loss function. For a new observation $(X', Y') = Z'$ and a given predictor c_θ , the loss incurred is

$$\ell_0(c_\theta(X'), Y') = \ell(\theta, Z').$$

Namely, *we can rewrite the loss in terms of θ and Z* . This expression will be a key in our future analysis.

With the above notations, we define both the training and test error for a given classifier c_θ :

- Training error (empirical risk):

$$\widehat{R}_n(\theta) = \frac{1}{n} \sum_{i=1}^n \ell_0(c_\theta(X_i), Y_i) = \frac{1}{n} \sum_{i=1}^n \ell(\theta, Z_i).$$

If the predictor is trained from the training data, we plug-in $\widehat{\theta} = \widehat{\theta}(Z_1, \dots, Z_n)$ into the above expression and obtain

$$\widehat{R}_n(\widehat{\theta}) = \frac{1}{n} \sum_{i=1}^n \ell(\widehat{\theta}, Z_i).$$

- Test error (test risk):

$$R(\theta) = \mathbb{E}[\ell_0(c_\theta(X'), Y')] = \mathbb{E}[\ell(\theta, Z')].$$

When the predictor is $\hat{\theta}$, its test risk is

$$R(\hat{\theta}) = \mathbb{E}[\ell(\hat{\theta}, Z') | \hat{\theta}].$$

The expectation only applies to Z' , not $\hat{\theta}$.

- Generalization error (generalization risk): In this case, the generalization error is the expected difference between the training error and test error of the estimator $\hat{\theta}$, which is

$$\text{Gen} = \mathbb{E}[\hat{R}_n(\hat{\theta}) - R(\hat{\theta})] = \mathbb{E}[\hat{R}_n(\hat{\theta})] - \mathbb{E}[R(\hat{\theta})]. \quad (1)$$

The expectation is applied to the training data Z_1, \dots, Z_n , which includes $\hat{\theta}$.

In the end, we will show that

$$\text{Gen} = \mathbb{E}[\hat{R}_n(\hat{\theta}) - R(\hat{\theta})] \leq O\left(\sqrt{I(\hat{\theta}, Z_1, \dots, Z_n)}\right),$$

where $I(\hat{\theta}, Z_1, \dots, Z_n)$ is the mutual information between $\hat{\theta}$ and the training data (Z_1, \dots, Z_n) .

2 Generalization error and independence

A key insight is that the generalization error in equation (1) is related to the difference between independent and dependent distributions. Recall that $P_{Z,n}$ is the joint distribution of Z_1, \dots, Z_n . We denote $P_{\theta, Z_1, \dots, Z_n}$ to be the joint distribution of $\hat{\theta}, Z_1, \dots, Z_n$ and $P_{\theta|Z,n}$ to be the conditional distribution of $\hat{\theta} | Z_1, \dots, Z_n$. Note that here we assume that $\hat{\theta}$ is a randomized estimator so that even if the data is held fixed, $\hat{\theta}$ may still be random.

We can rewrite $\mathbb{E}[\hat{R}_n(\hat{\theta})]$ as

$$\begin{aligned} \mathbb{E}[\hat{R}_n(\hat{\theta})] &= \mathbb{E}\left[\frac{1}{n} \sum_{i=1}^n \ell(\hat{\theta}, Z_i)\right] \\ &= \int \frac{1}{n} \sum_{i=1}^n \ell(\theta, z_i) P_{\theta, Z_1, \dots, Z_n}(d\theta, dz_1, \dots, dz_n) \\ &= \int \frac{1}{n} \sum_{i=1}^n \ell(\theta, z_i) P_{\theta|Z,n}(d\theta) \prod_{j=1}^n P_Z(dz_j) \end{aligned} \quad (2)$$

Thus, in the expectation of the empirical risk, we are integrating over the *joint distribution*

$$P_{\theta, Z_1, \dots, Z_n} = P_{\theta|Z,n} \cdot P_Z^{\otimes n}, \quad (3)$$

where $P_Z^{\otimes n} = P_Z \times P_Z \times \dots \times P_Z$ is the joint distribution of Z_1, \dots, Z_n .

Now we turn to our analysis on the test risk. Let P_θ be the marginal distribution of $\widehat{\theta}$ from $P_{\theta, Z_1, \dots, Z_n}$. We can rewrite the test risk as

$$\begin{aligned} \mathbb{E}[R(\widehat{\theta})] &= \mathbb{E} \left[\ell(\widehat{\theta}, Z') \right] \\ &= \int \ell(\theta, z') P_\theta(d\theta) \cdot P_Z(dz') \\ &= \int \frac{1}{n} \sum_{i=1}^n \ell(\theta, z'_i) P_\theta(d\theta) \cdot P_Z(dz'_i) \\ &= \int \frac{1}{n} \sum_{i=1}^n \ell(\theta, z'_i) P_\theta(d\theta) \cdot \prod_{j=1}^n P_Z(dz'_j). \end{aligned} \quad (4)$$

So in the test risk, we are integrating over the joint distribution

$$P_{\theta, Z'_1, \dots, Z'_n} = P_\theta \cdot P_Z^{\otimes n}, \quad (5)$$

which is the case of *assuming θ and Z'_1, \dots, Z'_n are independent!*

As a result, the generalization error is the difference between expectation of dependent θ, Z_1, \dots, Z_n and the independent θ and Z_1, \dots, Z_n . From this perspective, you can see why the information bounds on dependence will be useful in controlling the generalization errors.

3 A useful mutual information bound

From the above analysis, we have seen that we may bound the generalization errors using measures of dependency. Here is a simple bound based on mutual information.

Lemma 1 *Let (U, V) be two continuous random vectors that are dependent with each other. Let (\bar{U}, \bar{V}) be random vectors such that $\bar{U} \stackrel{d}{=} U$ and $\bar{V} \stackrel{d}{=} V$ with $\bar{U} \perp \bar{V}$. Namely, \bar{U} has the same distribution as U but it is independent of \bar{V} . Consider a function $f(u, v)$. If $f(\bar{U}, \bar{V})$ is σ -sub-Gaussian, then*

$$|\mathbb{E}[f(U, V)] - \mathbb{E}(f(\bar{U}, \bar{V}))| \leq \sqrt{2\sigma^2 I(U, V)},$$

where $I(U, V)$ is the mutual information between U and V .

Proof. Recall that the mutual information $I(U, V) = KL(p_{U, V} || p_U \cdot p_V)$, where KL is the Kullback-Leiber divergence and $p_{U, V}$ is the joint PDF of U, V .

A key of the proof is the following variational form of the KL-divergence. For any two PDF q, π ,

$$KL(q || \pi) = \sup_{\eta} \left\{ \int \eta(x) dq(x) - \log \int e^{\eta(x)} d\pi(x) \right\};$$

see, e.g. Corollary 4.15 of

S. Boucheron, G. Lugosi, and P. Massart, Concentration Inequalities: A Nonasymptotic Theory of Independence. Oxford Univ. Press, 2013.

We choose q to be the PDF of (U, V) and π to be the PDF of (\bar{U}, \bar{V}) and $\eta = \lambda \cdot f$, where λ is a free parameter.

Then the above variational form implies

$$\begin{aligned}
I(U, V) &= KL(p_{U,V} || p_U \cdot p_V) \\
&\geq \int \lambda f(u, v) dp_{U,V}(u, v) - \log \int e^{\lambda f(u, v)} dp_U(u) dp_V(v) \\
&= \mathbb{E}(\lambda f(U, V)) - \log \mathbb{E} \left(e^{\lambda f(\bar{U}, \bar{V})} \right) \\
&= \mathbb{E}(\lambda f(U, V)) - \log \mathbb{E} \left(e^{\lambda [f(\bar{U}, \bar{V}) - \mathbb{E}(f(\bar{U}, \bar{V}))]} \right) - \mathbb{E}(\lambda f(\bar{U}, \bar{V})).
\end{aligned}$$

By σ -sub-Gaussian property of $f(\bar{U}, \bar{V})$, we have

$$\log \mathbb{E} \left(e^{\lambda [f(\bar{U}, \bar{V}) - \mathbb{E}(f(\bar{U}, \bar{V}))]} \right) \leq \frac{1}{2} \lambda^2 \sigma^2.$$

So the above inequality becomes

$$\begin{aligned}
I(U, V) &\geq \mathbb{E}(\lambda f(U, V)) - \log \mathbb{E} \left(e^{\lambda [f(\bar{U}, \bar{V}) - \mathbb{E}(f(\bar{U}, \bar{V}))]} \right) - \mathbb{E}(\lambda f(\bar{U}, \bar{V})) \\
&\geq \lambda \mathbb{E}(f(U, V)) - f(\bar{U}, \bar{V}) - \frac{1}{2} \lambda^2 \sigma^2 \\
&\geq \frac{\mathbb{E}^2(f(U, V)) - f(\bar{U}, \bar{V})}{2\sigma^2},
\end{aligned}$$

where the last inequality follows from optimizing λ , which occurs at $\lambda^* = \frac{\mathbb{E}(f(U, V)) - f(\bar{U}, \bar{V})}{\sigma^2}$.

Thus, this implies

$$|\mathbb{E}[f(U, V)] - f(\bar{U}, \bar{V})| \leq \sqrt{2\sigma^2 I(U, V)},$$

which completes the proof.

□

4 Conclusion

By applying Lemma 1 with $\hat{\theta} = U$ and $(Z_1, \dots, Z_n) = V$, we conclude that

$$\text{Gen} = \mathbb{E}[\hat{R}_n(\hat{\theta}) - R(\hat{\theta})] \leq \sqrt{2\sigma^2 I(\hat{\theta}, Z_1, \dots, Z_n)}$$

assuming the σ -sub-Gaussianity.