# Serverless Computing: Design, Implementation, and Performance

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Abstract—We present the design of a novel performanceoriented serverless computing platform implemented in .NET, deployed in Microsoft Azure, and utilizing Windows containers as function execution environments. Implementation challenges such as function scaling and container discovery, lifecycle, and reuse are discussed in detail. We propose metrics to evaluate the execution performance of serverless platforms and conduct tests on our prototype as well as AWS Lambda, Azure Functions, Google Cloud Functions, and IBM's deployment of Apache OpenWhisk. Our measurements show the prototype achieving greater throughput than other platforms at most concurrency levels, and we examine the scaling and instance expiration trends in the implementations. Additionally, we discuss the gaps and limitations in our current design, propose possible solutions, and highlight future research.

## I. INTRODUCTION

Following the lead of AWS Lambda [1], services such as Apache OpenWhisk [2], Azure Functions [3], Google Cloud Functions [4], Iron.io IronFunctions [5], and OpenLambda [6] have emerged and introduced serverless computing, a cloud offering where application logic is split into functions and executed in response to events. These events can be triggered from sources external to the cloud platform but also commonly occur internally between the cloud platform's service offerings, allowing developers to easily compose applications distributed across many services within a cloud.

Serverless computing is a partial realization of an eventdriven ideal, in which applications are defined by actions and the events that trigger them. This language is reminiscent of active database systems, and the event-driven literature has theorized for some time about general computing systems in which actions are processed reactively to event streams [7]. Serverless function platforms fully embrace these ideas, defining actions through simple function abstractions and building out event processing logic across their clouds. IBM strongly echoes these concepts in their OpenWhisk platform (now Apache OpenWhisk), in which functions are explicitly defined in terms of event, trigger, and action [8].

Beyond the event-driven foundation, design discussions shift toward container management and software development strategies used to leverage function centric infrastructure. Iron.io uses Docker to store function containers in private registries, pulling and running the containers when execution is required [9]. Peer work on the OpenLambda platform presents an analysis of the scaling advantages of serverless computing, as well as a performance analysis of various container transitions [10]. Other performance analyses have studied the effect of language runtime and VPC impact on AWS Lambda start times [11], and measured the potential of AWS Lambda for embarrassingly parallel high performance scientific computing [12].

Serverless computing has proved a good fit for IoT applications, intersecting with the edge/fog computing infrastructure conversation. There are ongoing efforts to integrate serverless computing into a "hierarchy of datacenters" to empower the foreseen proliferation of IoT devices [13]. AWS has recently joined this field with their Lambda@Edge [14] product, which allows application developers to place limited Lambda functions in edge nodes. AWS has been pursuing other expansions of serverless computing as well, including Greengrass [15], which provides a single programming model across IoT and Lambda functions. Serverless computing allows application developers to decompose large applications into small functions, allowing application components to scale individually, but this presents a new problem in the coherent management of a large array of functions. AWS recently introduced Step Functions [16], which allows for easier organization and visualization of function interaction.

The application of serverless computing is an active area of development. Our previous work on serverless computing studied serverless programming paradigms such as function cascades, and experimented with deploying monolithic applications on serverless platforms [17]. Other work has studied the architecture of scalable chatbots in serverless platforms [18]. There are multiple projects aimed at extending the functionality of existing serverless platforms. Lambdash [19] is a shim allowing the easy execution of shell commands in AWS Lambda containers, enabling developers to explore the Lambda runtime environment. Other efforts such as Apex [20] and Sparta [21] allow users to deploy functions to AWS Lambda in languages not supported natively, such as Go.

Serverless computing is often championed as a cost-saving tool, and there are multiple works which report cost saving op-

portunities in deploying microservices to serverless platforms rather than building out traditional applications [22] [23]. Others have tried to calculate the points at which serverless or virtual machine deployments become more cost effective [24].

Serverless computing is becoming increasingly relevant, with Gartner reporting that "the value of [serverless computing] has been clearly demonstrated, maps naturally to microservice software architecture, and is on a trajectory of increased growth and adoption" [25]. Forrester argues that "today's PaaS investments lead to serverless computing," viewing serverless computing as the next-generation of cloud service abstractions [26]. Serverless computing is quickly proliferating across many cloud providers, and is powering an increasing number of mobile and IoT applications. As its scope and popularity expands, it is important to ensure the fundamental performance characteristics of serverless platforms are sound. In this work we hope to aid in this effort by detailing the implementation of a new performance-focused serverless platform, and comparing its performance to existing offerings.

## **II. PROTOTYPE DESIGN**

We have developed a performance-oriented serverless computing platform<sup>1</sup> to study serverless implementation considerations and provide a baseline for existing platform comparison. The platform is implemented in .NET, deployed to Microsoft Azure, and has a small feature-set and simple design. The prototype depends upon Azure Storage for data persistence and its messaging layer. Besides Azure Storage services, our implementation consists of two components: a web service which exposes the platform's public REST API, and a worker service which manages and executes function containers. The web service discovers available workers through a messaging layer consisting of various Azure Storage queues. Function metadata is stored in Azure Storage tables, and function code is stored in Azure Storage blobs.

Figure 1 shows an overview of the platform's components. Azure Storage was chosen because it provides highly scalable and low-latency storage primitives through a simple API, aligning well with the goals of this implementation [27]. For the sake of brevity these storage entities will be referred to as queues, tables, and blobs, with the understanding that in the context of this paper these terms apply to the respective Azure Storage services.

## A. Function Metadata

A function is associated with a number of entities across the platform, including its metadata, code, running containers, and "warm queue". Function metadata is the source of truth for function existence and is defined by four fields:

- Function Identifier Function identifiers are randomly generated GUIDs assigned during function creation and used to uniquely identify and locate function resources.
- 2) Language Runtime A function's language runtime specifies the language of the function's code. Only

Node.js functions are currently supported, which is our chosen language because of its availability on all major serverless computing platforms.

- 3) Memory Size A function's memory size determines the maximum memory a function's container can consume. The maximum function memory size is currently set at 1 GB. The CPU cores assigned to a function's container is set proportionally to its memory size.
- 4) Code Blob URI A zip archive containing a function's code is provided during function creation. This code is copied to a blob inside the platform's storage account, and the URI of that blob is placed in the function's metadata.

Function containers will be discussed in detail below, as will warm queues, which are queues indexed by function identifier which hold the available running containers of each function.

## B. Function Execution

Our implementation provides a very basic function programming model and only supports manual invocations. While the processing of event sources and quality of programming constructs are important considerations in serverless offerings, our work focuses on the execution processing of such systems, for which manual execution support is sufficient.

Functions are executed by calling an "/invoke" route off of function resources on the REST API. The invocation call request bodies are provided to the functions as inputs, and the response bodies contains the function outputs. Execution begins in the web service which receives the invocation calls and subsequently retrieves function metadata from table storage. An execution request object is created containing the function metadata and inputs, and then the web service attempts to locate an available container in the worker service to process the execution request.

Interaction between the web and worker services is controlled through a shared messaging layer. Specifically, there is a global "cold queue", as well as a "warm queue" for each function in the platform. These queues hold available container messages, which simply consist of a URI containing the address of the worker instance and the name of the available container. Messages in the cold queue indicate a worker has unallocated memory in which it could start a container, and visible messages in a function's warm queue indicate existing function containers not currently handling execution requests.

The web service first tries to dequeue a message from a function's warm queue. If no messages are found, the web service dequeues a message from the cold queue, which will assign a new container to the function when sent to the worker service. If all workers are fully allocated with running containers, the cold queue will be empty. Therefore, if the web service is unable to find an available container in both the warm queue and cold queue, it will return HTTP 503 Service Unavailable because there are no resources to fulfill the execution request. For this reason, the cold queue is an excellent target for auto-scaling, as it reflects the available space across the platform.

<sup>&</sup>lt;sup>1</sup>Available: https://github.com/mgarrettm/serverless-prototype

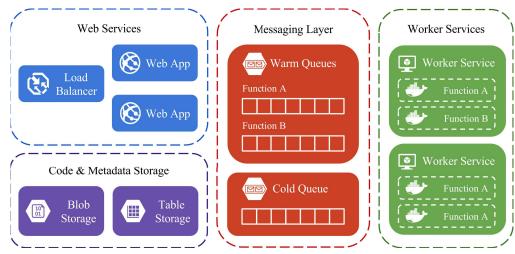


Fig. 1. Overview of prototype components, showing the organization of the web and worker services, as well as code, metadata, and messaging entities in Azure Storage.

Once a container allocation message is found in a queue, the web service sends an HTTP request to a worker service using the URI contained in the message. The worker then executes the function and returns the function outputs to the web service, which in turn responds to the invocation call.

## C. Container Allocation

Each worker manages a pool of unallocated memory which it can assign to function containers. When memory is reserved, a container name is generated, which uniquely identifies a container and its memory reservation, and is embedded in the URI sent in container allocation messages. Therefore, each message in the queues is uniquely identifiable and can be associated with a specific memory reservation within a worker service instance. Memory is allocated conservatively, and worker services assume all functions will consume their allocated memory size.

When container allocations are sent to the cold queue, they have not yet been assigned to a function. To ensure workers do not over-provision their memory pool, it is assumed the assigned function will have the maximum function memory size. Then, when a worker service receives an execution request for an unassigned allocation, it reclaims memory if the assigned function requires less than the maximum size. After the container is created and its function executed for the first time, the container allocation message is placed in that function's warm queue.

## D. Container Removal

There are two ways a container can be removed. Firstly, when a function is deleted, the web service deletes the function's warm queue, which is periodically monitored for existence by the worker service instances holding containers of that function. If a worker service detects that a deleted function queue, it removes that function's running containers and reclaims their memory reservations. Secondly, in our implementation a container can be removed if it is idle for an arbitrarily set period of 15 minutes, after which it is removed and its memory reclaimed. Whenever memory is reclaimed, worker services send new container allocations to the cold queue if their unused memory exceeds the maximum function memory size.

Container expiration has implications for the web service because it is possible to dequeue an expired container from a function's warm queue. In this case, when the web service sends the execution request, the worker service will return HTTP 404 Not Found. The web service will then delete the expired message from the queue and retry.

#### E. Container Image

The platform uses Docker to run Windows Nano Server containers and communicates with the Docker service through the Docker Engine API. The container image is built to include the function runtime (currently only Node.js v6.9.5) and an execution handler. Notably absent from the image is any function code. Custom containers are not built for each function in the platform, instead we attach a read-only volume containing function code when starting the container. A singleimage design was chosen for multiple reasons: it is simpler to only manage a single image, attaching volumes is a fast operation, and Windows Nano Server container images are significantly larger than lightweight Linux images such as Alpine Linux, affecting both storage costs and start-up times. In addition to the read-only volume, the memory size and CPU percentage of the container are proportionally set based upon the function's memory size.

The container's execution handler is a simple Node.js server which receives function inputs from the worker service. The worker service sends function inputs to the handler in the request body of an HTTP request, the handler calls the function with the specified inputs, and responds to the worker service with the function outputs. The container is addressable on the worker service's LAN because containers are added to the default "nat" network, which is the Windows equivalent of the Linux container "bridge" network.

## **III. PERFORMANCE RESULTS**

We designed two tests to measure the execution performance of our implementation, AWS Lambda, Azure Functions, Google Cloud Functions, and Apache OpenWhisk. We developed a performance tool<sup>2</sup> to conduct these experiments, which deploys a Node.js test function to the different services using the Serverless Framework [28]. We also built a Serverless Plugin<sup>3</sup> to enable Serverless Framework support for our platform.

This tool is deigned to measure the overhead introduced by the platforms using a simple test function which immediately completes execution and returns. This function is invoked synchronously with HTTP events/triggers as supported by the various platforms, and through the function's invocation route on our platform. Manual invocation calls were not used on the other services as they are typically viewed as development and testing routes, and we believed a popular production event/trigger such as an HTTP endpoint would better reflect existing platform performance. A 512MB function memory size was used in all platforms except Microsoft Azure, which dynamically discovers the memory requirements of functions.

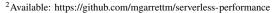
The prototype was deployed in Microsoft Azure, where the web service was an API App in Azure App Service, and the worker service was two DS2\_v2 virtual machines running Windows Server 2016. All platform tables, queues, and blobs resided in a single Azure storage account.

Network latencies were not accounted for in our tests, but to reduce their effects we performed our experiments from virtual machines inside the same region as our target function, except in the case of OpenWhisk, which we measured from Azure's South Central US region, and from which we observed singledigit millisecond network latencies to our function endpoint in IBM's US South region.

#### A. Concurrency Test

Figure 2 shows the results of the concurrency test, which is designed to measure the ability of serverless platforms to performantly invoke a function at scale. Our tool maintains invocation calls to the test function by reissuing each request immediately after receiving the response from the previous call. The test begins by maintaining a single invocation call in this way, and every 10 seconds adds an additional concurrent call, up to a maximum of 15 concurrent requests to the test function. The tool measures the number of responses received per second, which should increase with the level of concurrency. This test was repeated 10 times on each of the platforms.

The prototype demonstrates near-linear scaling between concurrency levels 1 and 14, but sees a significant performance drop at 15 concurrent requests. This drop is due to increased latencies observed from the warm queue, indicating that the



<sup>&</sup>lt;sup>3</sup>Available: https://github.com/mgarrettm/serverless-prototype-plugin

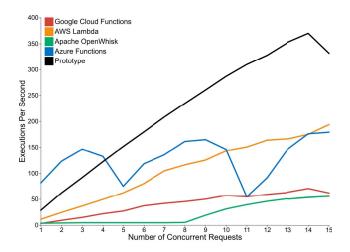


Fig. 2. Concurrency test results, plotting the average number of executions completed per second versus the number of concurrent execution requests to the function.

load is approaching the scalability targets of a single Azure Storage queue [29]. AWS Lambda appears to scale linearly and exhibits the highest throughput of the commercial platforms at 15 concurrent requests. Google Cloud Functions exhibits sub-linear scaling and appears to taper off as the number of concurrent requests approaches 15. The performance of Azure Functions is extremely variable, although the throughput reported is quite high in places, outperforming the other platforms at lower concurrency levels. This variability is intriguing, especially because it persists across test iterations. OpenWhisk's performance is curious, and shows low throughput until eight concurrent requests, at which point the function begins to sub-linearly scale. This behavior may be caused by OpenWhisk's container pool starting multiple containers before beginning reuse, but this behavior is dependent on the configuration of IBM's deployment.

## B. Backoff Test

Figure 3 shows the results of the backoff test, which is designed to study the cold start times and expiration behaviors of function instances in the various platforms. The backoff test sends single execution requests to the test function at increasing intervals, ranging from one to thirty minutes.

As described in the prototype design, function containers expire after 15 minutes of unuse. Figure 3 shows this behavior, and the execution latencies after 15 minutes show the cold start performance of our prototype. It appears Azure Functions also expires function resources after a few minutes, and exhibits similar cold start times as our prototype. It is important to note that although both our prototype and Azure Functions are Windows implementations, their function execution environments are very different, as our prototype uses Windows containers and Azure Functions runs in Azure App Service. OpenWhisk also appears to deallocate containers after about 10 minutes and has much lower cold start times than Azure Functions or our prototype. Most notably, AWS Lambda and Google

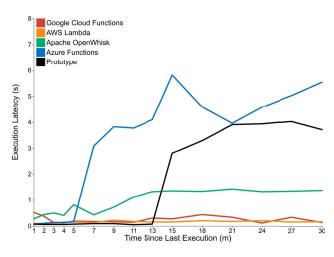


Fig. 3. Backoff test results, plotting the average execution latency of the function versus the time since the function's previous execution.

Cloud Functions appear largely unaffected by function idling. Possible explanations for this behavior could be extremely fast container start times or preallocation of containers as considered below in the discussion of Windows containers.

## IV. LIMITATIONS AND FUTURE WORK

## A. Warm Queues

The warm queue is a FIFO queue, which is problematic for container expiration. Imagine a function under heavy load has 10 containers allocated for execution, and then load drops such that a single container could handle all of the function's executions. Ideally, the extra 9 containers would expire after a short time, but because of the FIFO queue, so long as there are 10 executions of the function per container expiration period, all containers will remain allocated to the function. Of course, the solution is to use "warm stacks" instead of "warm queues", but Azure Storage does not currently support LIFO queues. This is perhaps the largest issue with our current implementation; however, other warm stack storage options such as a Redis cache [30] or a consistent hashing [31] implementation are promising, and may offer improved performance as well.

#### B. Asynchronous Executions

Currently the prototype only supports synchronous invocations. In other words, a request to execute a function will return the result of that function execution, it will not simply start the function and return. Asynchronous executions by themselves are simple to support, the web service can simply respond to the invocation call and then process the execution request normally. The difficulty in asynchronous execution is in guaranteeing at-least-once execution rather than best effort execution. It is important to understand that synchronous or asynchronous execution is only guaranteed once an invocation request returns with a successful status code. Therefore, no further work is needed for synchronous execution requests (as in our implementation), because a successful status code is only returned once execution has completed. However, asynchronous executions respond to clients before function execution, so it is necessary to have additional logic to ensure these executions complete successfully.

We believe the prototype can support this requirement by storing active executions in a set of queues and introducing a third service responsible for monitoring the status of these queue messages. Worker services would continually update message visibility delays during function execution, and the monitoring service would detect failures by looking for visible messages. Failed messages could then be re-executed. Note that this is about handling platform execution failures and not exceptions thrown by the function during execution, for which retry may also be desired.

## C. Worker Utilization

A large area for improvement in our implementation is worker utilization. Realistic designs would require an overallocation of worker resources, with the observation that not all functions on a worker are constantly executing, or using all of their memory reservation. Utilization in a serverless context presents competing tradeoffs between execution performance and operating costs; however, the evaluation of utilization strategies is difficult without representative datasets of execution loads on serverless platforms. Future research would benefit from increased transparency from existing platforms, and from methods of synthesizing serverless computing loads.

## D. Windows Containers

Windows containers have some limitations compared to Linux containers, largely because Linux containers were designed around Linux cgroups which support useful operations not available on Windows. Most notably in the context of serverless computing is the support of container resource updating and container pausing. A common pattern in serverless platform implementations is pausing containers when idle to prevent resource consumption, and then unpausing them before execution resumes [10], [32].

Another potentially useful operation is container resource updating. Because we reserve resources for containers before executions begin, it would be beneficial for cold start performance if we were able to start containers before they are assigned to a function, and then resize the container once an execution request is received. Future work can study how to support these semantics in Windows containers, perhaps by limiting or updating the resources to the function process itself rather than the container as a whole. Alternatively, the prototype could experiment with Linux containers to compare startup performances and test the viability of container resizing during cold starts.

## E. Security

Security of serverless systems is also an open research question. Hosting arbitrary user code in containers on multitenant systems is a dangerous proposition, and care must be taken when constructing and running function containers to prevent vulnerabilities. This intersection of remote procedure calls (RPC) and container security represents a significant realworld test of general container security. Therefore, although serverless platforms are able to carefully craft the function containers and restrict function permissions arbitrarily, increasing the chances of secure execution, further study is needed to assess the attack surface within function execution environments.

#### F. Performance Measures

There are significant opportunities to expand understanding of serverless platform performance by defining performance measures and tests thereof. This work focused on the overhead introduced by the platforms during single-function execution, but the quality of these measurements can be improved by better handling of network latencies and clocking considerations. Other aspects of platform performance such as latency variations between language runtimes and function code size, system-wide performance of serverless platforms, performance differences between event types, and CPU allocation scaling also warrant study.

## V. CONCLUSION

Serverless computing offers powerful, event-driven integrations with numerous cloud services, simple programming and deployment models, and fine-grained scaling and cost management. Driven by these benefits, the growing adoption of serverless applications warrants the evaluation of serverless platform quality, and the development of new techniques to maximize the technology's potential. The performance results of our platform are encouraging and our analysis of the current implementation presents many opportunities for continued development and study. We hope to see increased interest in serverless computing by academia and increased openness by the industry leaders for the wider benefit of serverless technologies.

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