TCSS 422: OPERATING SYSTEMS

The Process API & Limited Direct Execution

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April 8, 2021 | TCSS422: Operating Systems [Spring 2021]
School of Engineering and Technology, University of Washington - Tacoma

OBJECTIVES – 4/8

- Questions from 4/6
- C Review Survey – Closes Friday Apr 9
- Assignment 0
- Chapter 5: Process API
  - fork(), wait(), exec()
- Chapter 6: Limited Direct Execution
  - Direct execution
  - Limited direct execution
  - CPU modes
  - System calls and traps
  - Cooperative multi-tasking
  - Context switching and preemptive multi-tasking

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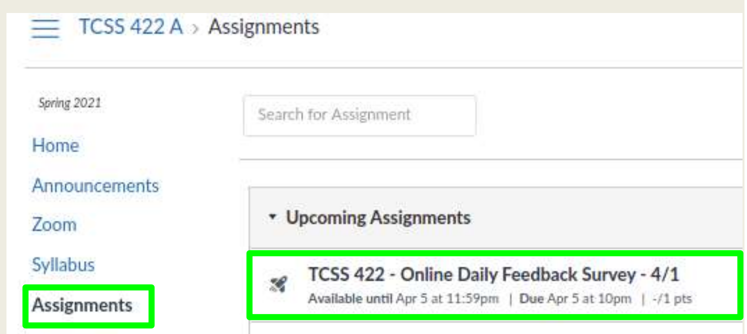
TEXT BOOK COUPON

- 15% off textbook code: **INSPIRE15** (*through Friday April 9*)
- https://www.lulu.com/shop/remzi-arpaci-dusseau-and-andrea-arpaci-dusseau/operating-systems-three-easy-pieces-softcover-version-100/paperback/product-23779877.html?page=1&pageSize=4

ONLINE DAILY FEEDBACK SURVEY

- Daily Feedback Quiz in Canvas – Available After Each Class
- Extra credit available for completing surveys ***ON TIME***
- Tuesday surveys: due by ~ Wed @ 11:59p
- Thursday surveys: due ~ Mon @ 11:59p



TCSS 422 - Online Daily Feedback Survey - 4/1

Quiz Instructions

Question 1 0.5 pts

On a scale of 1 to 10, please classify your perspective on material covered in today's class:

1	2	3	4	5	6	7	8	9	10
Mostly Review To Me				Equal New and Review					Mostly New to Me

Question 2 0.5 pts

Please rate the pace of today's class:

1	2	3	4	5	6	7	8	9	10
Slow				Just Right					Fast

MATERIAL / PACE

- Please classify your perspective on material covered in today's class (50 respondents):
- 1-mostly review, 5-equal new/review, 10-mostly new
- Average – 6.91 (↓ - previous 6.92)

- Please rate the pace of today's class:
- 1-slow, 5-just right, 10-fast
- Average – 5.67 (↑ - previous 5.57)

FEEDBACK

- ***Can we say the number of tasks is the number of processes?***
  - YES
  - Processes are identified as "tasks" in top
- ***How are memory leaks taken care of when we close a program?***
  - When a program is closed, all memory is freed
- ***Does the OS keep track of what parts of memory were being used by a program even if the program itself dereferences it?***
  - Unlike Java, C does not have automatic garbage collection
  - A programmer releases malloc'd memory using the free() function
  - The OS tracks the location of the heap. The data may still reside on the heap but it is no longer referenced. Allocating new variables on the heap may result in finding the old data. The values can be seen if the new variables are not initialized.

FEEDBACK - 2

- ***I'm confused about the differences between the READY and BLOCKED process states***
- **BLOCKED**: can not run, waiting on I/O to finish
- **READY**: is able to run, but not yet scheduled on the CPU

FEEDBACK - 3

- ***Can you fork a process multiple times?***
  - Yes
- ***Can a parent have more than one child?***
  - Yes
- ***Can a child have a child and become a parent?***
  - Yes
- ***I saw in a diagram on pg 8 of the lecture 3 slides that you can keep forking but if the child process's PID is 0 then how can you make a new child with a process PID 0 and then differentiate which is the parent?***
  - The child can call getPID() to discover its true PID
  - When the child calls fork, it will also receive back its PID

FEEDBACK - 4

- ***How is prioritization between the parent and child processes done after the call to fork() ?***
  - The operating system schedules which process goes next
  - If the computer has multiple cores, they may be scheduled to run at the same time
  - The programmer can enforce execution ordering by using the wait() API
- ***Is there a similar command to fork() that can create a child process without also copying memory, registers, and the program counter?***
  - Yes, these are threads, and the API is pthread_create()

FEEDBACK - 5

- ***What is overhead?***
  - *Question for the class…*
- ***(Assignment questions with example)***
  As I researched and understood, we have several command options to find the number of processes (question #1 ex: ""ps"" or ""top"").
- ***Is it okay to use any commands from these options, or do you expect specific commands which were mentioned from the lecture?***
  - Any command can be used

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CHAPTER 5: C PROCESS API

fork()

- Creates a new process - think of "a fork in the road"
- "Parent" process is the original
- Creates "child" process of the program from the <u>**current execution point**</u>
- Book says "pretty odd"
- Creates a **duplicate** program instance (these are <u>**processes!**</u>)
- **Copy** of
  - Address space (memory)
  - Register
  - Program Counter (PC)
- Fork returns
  - child PID to parent
  - 0 to child

FORK EXAMPLE

- p1.c

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>

int main(int argc, char *argv[]){
    printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {          // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) { // child (new process)
        printf("hello, I am child (pid:%d)\n", (int) getpid());
    } else {              // parent goes down this path (main)
        printf("hello, I am parent of %d (pid:%d)\n",
        rc, (int) getpid());
    }
    return 0;
}
```


FORK EXAMPLE - 2

- Non deterministic ordering of execution

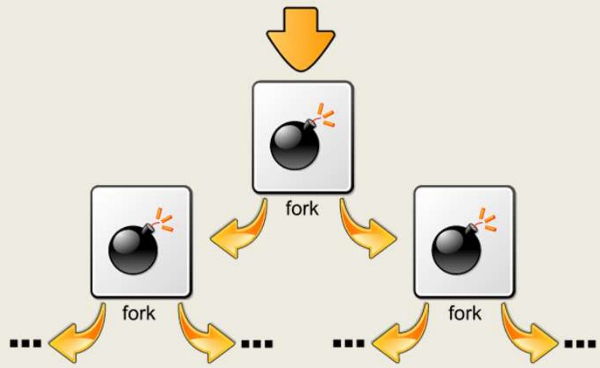
```
prompt> ./p1
hello world (pid:29146)
hello, I am parent of 29147 (pid:29146)
hello, I am child (pid:29147)
prompt>
```

or

```
prompt> ./p1
hello world (pid:29146)
hello, I am child (pid:29147)
hello, I am parent of 29147 (pid:29146)
prompt>
```

- CPU scheduler determines which to run first

:(){ :|: & };:



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wait()

- wait(), waitpid()
- Called by parent process
- Waits for a child process to finish executing
- Not a sleep() function
- Provides some ordering to multi-process execution

FORK WITH WAIT

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/wait.h>

int main(int argc, char *argv[]){
    printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {          // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) { // child (new process)
        printf("hello, I am child (pid:%d)\n", (int) getpid());
    } else {               // parent goes down this path (main)
        int wc = wait(NULL);
        printf("hello, I am parent of %d (wc:%d) (pid:%d)\n",
        rc, wc, (int) getpid());
    }
    return 0;
}
```

FORK WITH WAIT - 2

- Deterministic ordering of execution

```
prompt> ./p2
hello world (pid:29266)
hello, I am child (pid:29267)
hello, I am parent of 29267 (wc:29267) (pid:29266)
prompt>
```


FORK EXAMPLE

- Linux example

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exec()

- Supports running an external program by "transferring control"
- 6 types: execl(), execlp(), execle(), execv(), execvp(), execvpe()
- execl(), execlp(), execle(): const char *arg *(example: execl.c)*

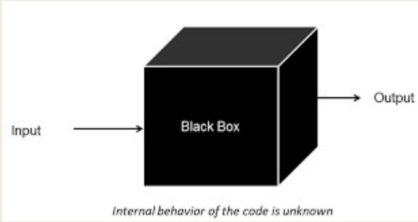
  Provide cmd and args as individual params to the function
  Each arg is a pointer to a null-terminated string
  ODD: pass a variable number of args: (arg0, arg1, .. argn)
- Execv(), execvp(), execvpe() *(example: exec.c)*
  Provide cmd and args as an Array of pointers to strings

  Strings are null-terminated
  First argument is name of command being executed
  Fixed number of args passed in

EXEC() - 2

- Common use case:
- Write a new program which wraps a legacy one
- Provide a new interface to an old system: Web services
- Legacy program thought of as a "black box"

- We don't want to know what is inside… ☺



EXEC EXAMPLE

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <string.h>
#include <sys/wait.h>

int main(int argc, char *argv[]){
    printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {                    // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) {            // child (new process)
        printf("hello, I am child (pid:%d)\n", (int) getpid());
        char *myargs[3];
        myargs[0] = strdup("wc");          // program: "wc" (word count)
        myargs[1] = strdup("p3.c");        // argument: file to count
        myargs[2] = NULL;                  // marks end of array
        …
```

EXEC EXAMPLE - 2

```
…
        execvp(myargs[0], myargs); // runs word count
        printf("this shouldn't print out");
    } else {                      // parent goes down this path (main)
        int wc = wait(NULL);
        printf("hello, I am parent of %d (wc:%d) (pid:%d)\n",
            rc, wc, (int) getpid());
    }
    return 0;
}
```

```
prompt> ./p3
hello world (pid:29383)
hello, I am child (pid:29384)
29 107 1030 p3.c
hello, I am parent of 29384 (wc:29384) (pid:29383)
prompt>
```


EXEC WITH FILE REDIRECTION (OUTPUT)

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <string.h>
#include <fcntl.h>
#include <sys/wait.h>

int
main(int argc, char *argv[]){
    int rc = fork();
    if (rc < 0) {          // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) { // child: redirect standard output to a file
        close(STDOUT_FILENO);
        open("./p4.output", O_CREAT|O_WRONLY|O_TRUNC, S_IRWXU);
        …
```

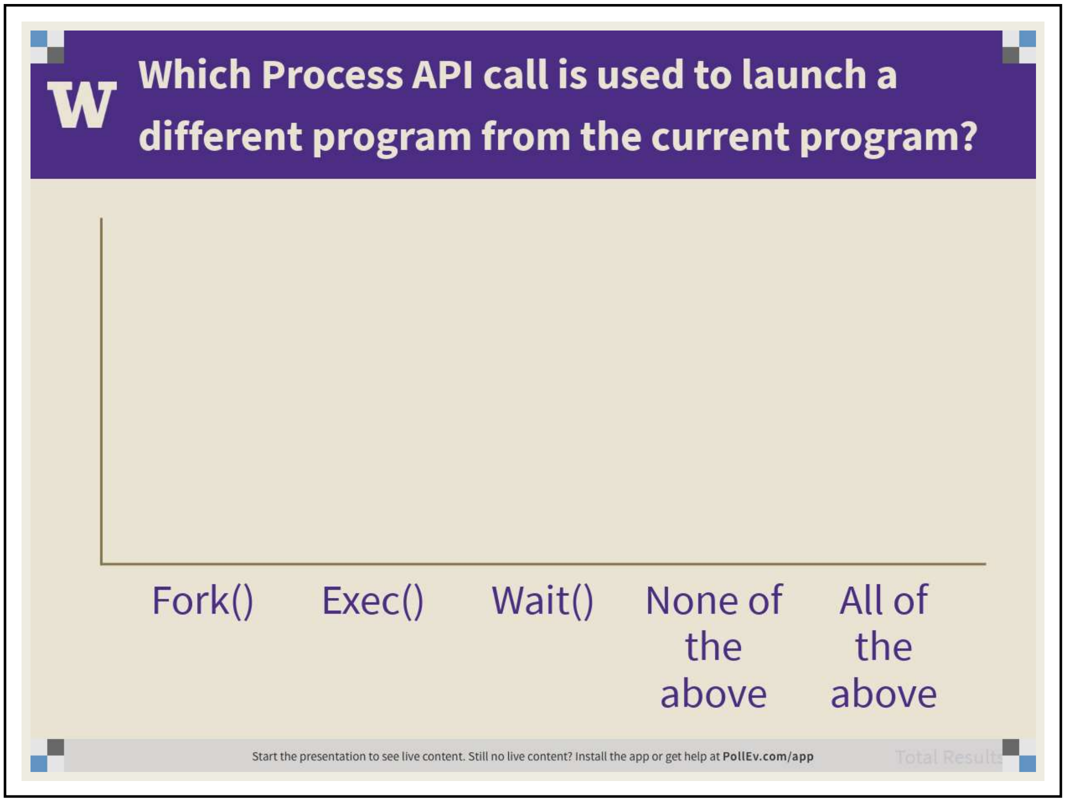
FILE MODE BITS

```
S_IRWXU
read, write, execute/search by owner
S_IRUSR
read permission, owner
S_IWUSR
write permission, owner
S_IXUSR
execute/search permission, owner
S_IRWXG
read, write, execute/search by group
S_IRGRP
read permission, group
S_IWGRP
write permission, group
S_IXGRP
execute/search permission, group
S_IRWXO
read, write, execute/search by others
S_IROTH
read permission, others
S_IWOTH
write permission, others
```


EXEC W/ FILE REDIRECTION (OUTPUT) - 2

```
        …
        // now exec "wc"...
        char *myargs[3];
        myargs[0] = strdup("wc");          // program: "wc" (word count)
        myargs[1] = strdup("p4.c");        // argument: file to count
        myargs[2] = NULL;                  // marks end of array
        execvp(myargs[0], myargs);         // runs word count
    } else {                        // parent goes down this path (main)
        int wc = wait(NULL);
    }
    return 0;
}
```

```
prompt> ./p4
prompt> cat p4.output
32 109 846 p4.c
prompt>
```



QUESTION: PROCESS API

- Which Process API call is used to launch a different program from the current program?

- (a) Fork()
- (b) Exec()
- (c) Wait()
- (d) None of the above
- (e) All of the above

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CH. 6: LIMITED DIRECT EXECUTION

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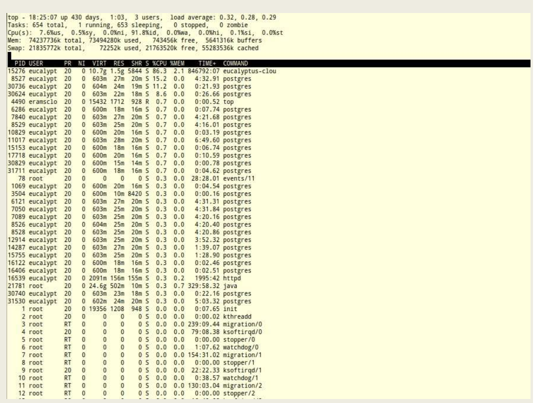
VIRTUALIZING THE CPU

- How does the CPU support running so many jobs simultaneously?
- **Time Sharing**
- Tradeoffs:
  - Performance
    - Excessive overhead
  - Control
    - Fairness
    - Security
- Both HW and OS support is used



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COMPUTER BOOT SEQUENCE: OS WITH DIRECT EXECUTION

- What if programs could directly control the CPU / system?

OS	Program
1. Create entry for process list 2. Allocate memory for program 3. Load program into memory 4. Set up stack with `argc` / `argv` 5. Clear registers 6. Execute call `main()`	
	7. Run `main()` 8. Execute `return` from `main()`
9. Free memory of process 10. Remove from process list	

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COMPUTER BOOT SEQUENCE: OS WITH DIRECT EXECUTION

- What if programs could directly control the CPU / system?

OS	Program
1. Create entry for process list 2. Allocate memory for … 5. Clear registers 6. Execute call `main()`	
	7. Run `main()` 8. Execute `return` from `main()`
9. Free memory of process 10. Remove from process list	

Without *limits* on running programs, the OS wouldn't be in control of anything and would "just be a library"

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DIRECT EXECUTION - 2

- **With direct execution:**

  How does the OS stop a program from running, and switch to another to support **time sharing**?

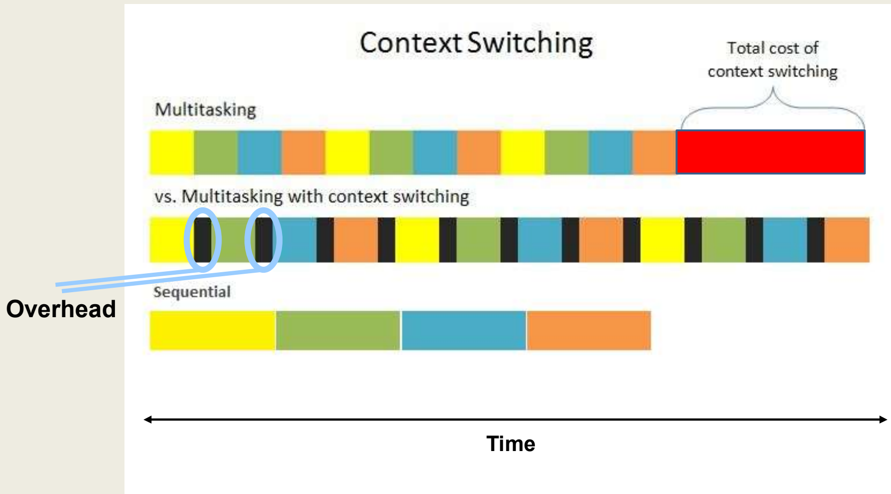
  How do programs share disks and perform I/O if they are given direct control? Do they know about each other?

  With direct execution, how can dynamic memory structures such as linked lists grow over time?

CONTROL TRADEOFF

- **Too little control:**
  - No security
  - No time sharing
- **Too much control:**
  - Too much OS overhead
  - Poor performance for compute & I/O
  - Complex APIs (system calls), difficult to use

CONTEXT SWITCHING OVERHEAD



WE WILL RETURN AT 5:10PM

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LIMITED DIRECT EXECUTION

- OS implements LDE to support time/resource sharing
- Limited direct execution means "only limited" processes can execute DIRECTLY on the CPU in ***trusted*** mode
- TRUSTED means the process is trusted, and it can do anything... (e.g. it is a system / kernel level process)
- Enabled by ***protected (safe) control transfer***
- CPU supported context switch
- Provides data isolation

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CPU MODES

- Utilize CPU Privilege Rings (Intel x86)
  - rings 0 (kernel), 1 (VM kernel), 2 (unused), 3 (user)

access ← no access

- **User mode**:
  Application is running, but w/o direct I/O access
- **Kernel mode**:
  OS kernel is running performing restricted operations

CPU MODES

- **User mode: ring 3 - untrusted**
  - Some instructions and registers are disabled by the CPU
  - Exception registers
  - HALT instruction
  - MMU instructions
  - OS memory access
  - I/O device access
- **Kernel mode: ring 0 – trusted**
  - All instructions and registers enabled

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SYSTEM CALLS

- Implement restricted "OS" operations
- Kernel exposes key functions through an API:
  - Device I/O (e.g. file I/O)
  - Task swapping: context switching between processes
  - Memory management/allocation: malloc()
  - Creating/destroying processes

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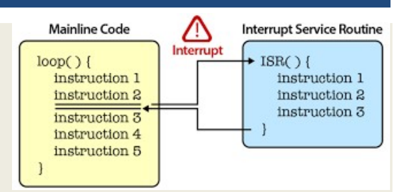
TRAPS: SYSTEM CALLS, EXCEPTIONS, INTERRUPTS



- Trap: any transfer to kernel mode
- Three kinds of traps
  - **System call:** (planned) user → kernel
    - SYSCALL for I/O, etc.
  - **Exception:** (error) user → kernel
    - Div by zero, page fault, page protection error
  - **Interrupt:** (event) user → kernel
    - Non-maskable vs. maskable
    - Keyboard event, network packet arrival, timer ticks
    - Memory parity error (ECC), hard drive failure

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EXCEPTION TYPES

Exception type	Synchronous vs. asynchronous	User request vs. coerced	User maskable vs. nonmaskable	Within vs. between instructions	Resume vs. terminate
I/O device request	Asynchronous	Coerced	Nonmaskable	Between	Resume
Invoke operating system	Synchronous	User request	Nonmaskable	Between	Resume
Tracing instruction execution	Synchronous	User request	User maskable	Between	Resume
Breakpoint	Synchronous	User request	User maskable	Between	Resume
Integer arithmetic overflow	Synchronous	Coerced	User maskable	Within	Resume
Floating-point arithmetic overflow or underflow	Synchronous	Coerced	User maskable	Within	Resume
Page fault	Synchronous	Coerced	Nonmaskable	Within	Resume
Misaligned memory accesses	Synchronous	Coerced	User maskable	Within	Resume
Memory protection violation	Synchronous	Coerced	Nonmaskable	Within	Resume
Using undefined instruction	Synchronous	Coerced	Nonmaskable	Within	Terminate
Hardware malfunction	Asynchronous	Coerced	Nonmaskable	Within	Terminate
Power failure	Asynchronous	Coerced	Nonmaskable	Within	Terminate

OS @ boot (kernel mode) | **Hardware**

initialize trap table

remember address of …
syscall handler

OS @ run (kernel mode) | **Hardware** | **Program (user mode)**

Create entry for process list
Allocate memory for program
Load program into memory
Setup user stack with argv
Fill kernel stack with reg/PC
return-from -trap

restore regs from kernel stack
move to user mode
jump to main

Run main()
…
Call system
trap into OS

save regs to kernel stack
move to kernel mode
jump to trap handler

Handle trap
Do work of syscall
return-from-trap

restore regs from kernel stack
move to user mode
jump to PC after trap

…
return from main
trap (via `exit()`)

Free memory of process
Remove from process list

OS @ boot (kernel mode)	Hardware	
initialize trap table		
	remember address of … syscall handler	

OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list Allocate memory for program Load program into memory Setup user stack with argv Fill kernel stack with reg/PC		
	move to kernel mode jump to trap handler	
Handle trap Do work of syscall **return-from-trap**		
	restore regs from kernel stack move to user mode jump to PC after trap	
		… return from main trap (via `exit()`)
Free memory of process Remove from process list		

Computer BOOT Sequence: OS with Limited Direct Execution

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MULTITASKING

- How/when should the OS regain control of the CPU to switch between processes?

- Cooperative multitasking (mostly pre 32-bit)
  - < Windows 95, Mac OSX
  - Opportunistic: running programs must give up control
    - User programs must call a special **yield** system call
    - When performing I/O
    - Illegal operations
  - (POLLEV)
    What problems could you for see with this approach?

MULTITASKING

- How/when should the OS regain control of the CPU to switch between processes?

- Cooperative multitasking (mostly pre 32-bit)
  - < W
  - Op   l
    - When performing I/O
    - Illegal operations
  - (POLLEV)
    What problems could you for see with this approach?

A process gets stuck in an infinite loop.
→ Reboot the machine

What problems exist for regaining the control of the CPU with cooperative multitasking OSes?

Start the presentation to see live content. Still no live content? Install the app or get help at **PollEv.com/app**

Total Results

QUESTION: MULTITASKING

- What problems exist for regaining the control of the CPU with cooperative multitasking OSes?

MULTITASKING - 2

- Preemptive multitasking (32 & 64 bit OSes)
- >= Mac OSX, Windows 95+

- Timer interrupt
  - Raised at some regular interval (in ms)
  - Interrupt handling
    1. Current program is halted
    2. Program states are saved
    3. OS Interrupt handler is run (kernel mode)

- (PollEV) What is a good interval for the timer interrupt?

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MULTITASKING - 2

- Preemptive multitasking (32 & 64 bit OSes)
- >= Mac OSX, Windows 95+

- Timer
  - Rais
  - Inte
    1. Current program is halted
    2. Program states are saved
    3. OS Interrupt handler is run (kernel mode)

A **timer interrupt** gives OS the ability to run again on a CPU.

- (PollEV) What is a good interval for the timer interrupt?

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W

For an OS that uses a system timer to force arbitrary context switches to share the CPU, what is a good value (in seconds) for the timer interrupt?

QUESTION: TIME SLICE

- For an OS that uses a system timer to force arbitrary context switches to share the CPU, what is a good value (in seconds) for the timer interrupt?

OBJECTIVES – 4/8

- Questions from 4/6
- C Review Survey – Closes Friday Apr 9
- Assignment 0
- Chapter 5: Process API
  - fork(), wait(), exec()
- Chapter 6: Limited Direct Execution
  - Direct execution
  - Limited direct execution
  - CPU modes
  - System calls and traps
  - Cooperative multi-tasking
  - Context switching and preemptive multi-tasking

CONTEXT SWITCH

- Preemptive multitasking initiates "trap" into the OS code to determine:
  - Whether to continue running the **current process**, or switch to a **different one.**
  - If the decision is made to switch, the OS performs a context switch swapping out the current process for a new one.

CONTEXT SWITCH - 2

1. Save register values of the current process to its kernel stack
   - General purpose registers
   - PC: program counter (instruction pointer)
   - kernel stack pointer

2. Restore soon-to-be-executing process from its kernel stack
3. Switch to the kernel stack for the soon-to-be-executing process

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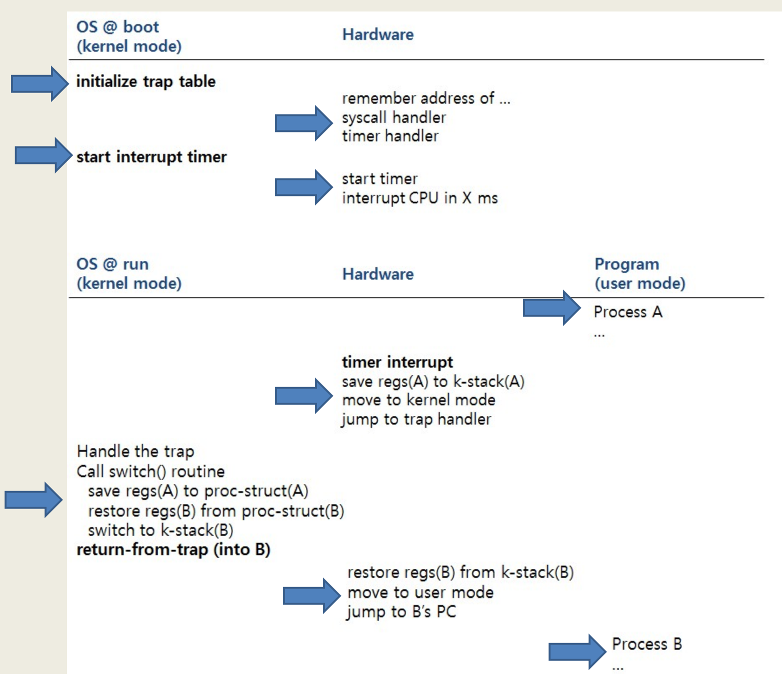

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OS @ boot (kernel mode)	Hardware
initialize trap table	
	remember address of … syscall handler timer handler
start interrupt timer	
	start timer interrupt CPU in X ms

OS @ run (kernel mode)	Hardware	Program (user mode)

Context Switch

Call switch() routine save regs(A) to proc-struct(A) restore regs(B) from proc-struct(B) switch to k-stack(B)		
return-from-trap (into B)		
	restore regs(B) from k-stack(B) move to user mode jump to B's PC	
		Process B …

INTERRUPTED INTERRUPTS

- What happens if during an interrupt (trap to kernel mode), another interrupt occurs?
- Linux
  - < 2.6 kernel: non-preemptive kernel
  - >= 2.6 kernel: preemptive kernel

PREEMPTIVE KERNEL

- Use "locks" as markers of regions of non-preemptibility (non-maskable interrupt)
- Preemption counter (`preempt_count`)
  - begins at zero
  - increments for each lock acquired (not safe to preempt)
  - decrements when locks are released
- Interrupt can be interrupted when `preempt_count=0`
  - It is safe to preempt (maskable interrupt)
  - the interrupt is more important

CHAPTER 7- SCHEDULING: INTRODUCTION

OBJECTIVES – 4/8

- Chapter 7: Scheduling Introduction
  - Scheduling metrics
    - Turnaround time, Jain's Fairness Index, Response time
  - FIFO, SJF, STCF, RR schedulers

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SCHEDULING METRICS

- **Metrics**: A standard measure to quantify to what degree a system possesses some property. Metrics provide *repeatable* techniques to quantify and compare systems.
- **Measurements** are the numbers derived from the application of metrics

- Scheduling Metric #1: Turnaround time
- The time at which the job completes minus the time at which the job arrived in the system

$$T_{turnaround} = T_{completion} - T_{arrival}$$

- How is turnaround time different than execution time?

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SCHEDULING METRICS - 2

- Scheduling Metric #2: **Fairness**
  - Jain's fairness index
  - Quantifies if jobs receive a fair share of system resources

$$\mathcal{J}(x_1, x_2, \ldots, x_n) = \frac{(\sum_{i=1}^{n} x_i)^2}{n \cdot \sum_{i=1}^{n} {x_i}^2}$$

- n processes
- x_i is time share of each process
- worst case = 1/n
- best case = 1

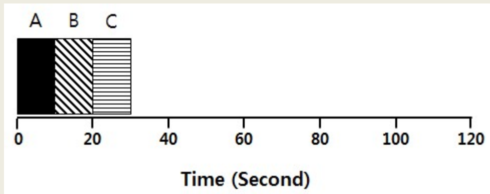
- Consider n=3, worst case = .333, best case=1
- With n=3 and x_1=.2, x_2=.7, x_3=.1, fairness=.62
- With n=3 and x_1=.33, x_2=.33, x_3=.33, fairness=1

OBJECTIVES – 4/8

- Chapter 7: Scheduling Introduction
  - Scheduling metrics
    - Turnaround time, Jain's Fairness Index, Response time
  - FIFO SJF, STCF, RR schedulers

SCHEDULERS

- FIFO: first in, first out
  - Very simple, easy to implement
- Consider
  - 3 x 10sec jobs, arrival: A B C, duration 10 sec each



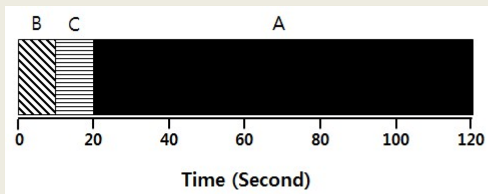
$$\textit{Average turnaround time} = \frac{10 + 20 + 30}{3} = 20\ sec$$

OBJECTIVES – 4/8

- Chapter 7: Scheduling Introduction
  - Scheduling metrics
    - Turnaround time, Jain's Fairness Index, Response time
  - FIFO, SJF, STCF, RR schedulers

SJF: SHORTEST JOB FIRST

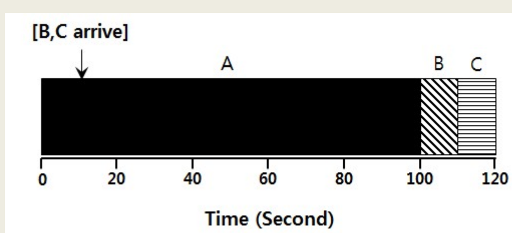
- Given that we know execution times in advance:
  - Run in order of duration, shortest to longest
  - Non preemptive scheduler
  - This is not realistic
  - Arrival: A B C, duration a=100 sec, b/c=10sec



$$Average\ turnaround\ time = \frac{10 + 20 + 120}{3} = 50\ sec$$

SJF: WITH RANDOM ARRIVAL

- If jobs arrive at any time: duration a=100s, b/c=10s
- A @ t=0sec, B @ t=10sec, C @ t=10sec



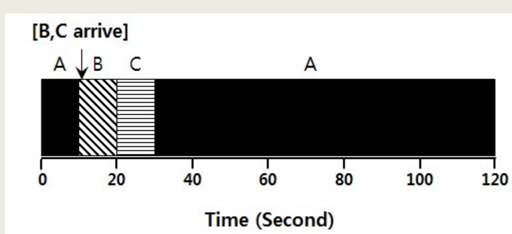
$$Average\ turnaround\ time = \frac{100 + (110 - 10) + (120 - 10)}{3} = 103.33\ sec$$

OBJECTIVES – 4/8

- Chapter 7: Scheduling Introduction
  - Scheduling metrics
    - Turnaround time, Jain's Fairness Index, Response time
  - FIFO, SJF, STCF, RR schedulers

STCF - 2

- Consider: duration a=100sec, b/c=10sec
  - $A_{len}=100$ $A_{arrival}=0$
  - $B_{len}=10$, $B_{arrival}=10$, $C_{len}=10$, $C_{arrival}=10$



$$Average\ turnaround\ time = \frac{(120-0)+(20-10)+(30-10)}{3} = 50\ sec$$

SCHEDULING METRICS - 3

- Scheduling Metric #3: Response Time
- Time from when job arrives until it starts execution

$$T_{response} = T_{firstrun} - T_{arrival}$$

- STCF, SJF, FIFO
  - can perform poorly with respect to response time

What scheduling algorithm(s) can help minimize response time?

OBJECTIVES – 4/8

- Chapter 7: Scheduling Introduction
  - Scheduling metrics
    - Turnaround time, Jain's Fairness Index, Response time
  - FIFO, SJF, STCF, RR schedulers

RR: ROUND ROBIN

- Run each job awhile, then switch to another distributing the CPU evenly (fairly)
- Scheduling Quantum is called a time slice
- Time ... a mu... time ... period.

Process	Burst Time
P1	12

RR is fair, but performs poorly on metrics such as turnaround time

Round Robin scheduling algorithm Gantt chart

Scheduling Quantum = 5 seconds

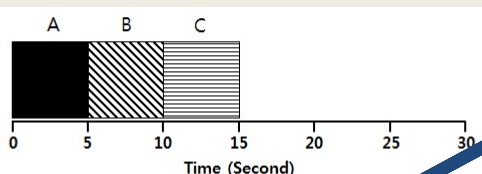
P1	P2	P3	P4	P5	P1	P2	P4	P1

0 5 10 14 19 24 29 32 37 39

RR EXAMPLE

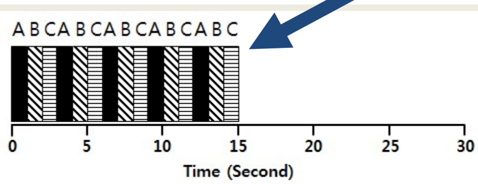
- ABC arrive at time=0, each run for 5 seconds

OVERHEAD not considered



SJF (Bad for Response Time)

$$T_{average\ response} = \frac{0+5+10}{3} = 5sec$$



RR with a time-slice of 1sec (Good for Response Time)

$$T_{average\ response} = \frac{0+1+2}{3} = 1sec$$

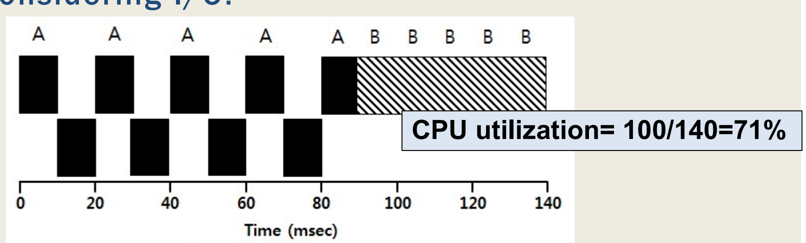
ROUND ROBIN: TRADEOFFS

Short Time Slice	**Long Time Slice**
Fast Response Time	**Slow Response Time**
High overhead from context switching	**Low overhead from context switching**

- Time slice impact:
  - Turnaround time (for earlier example): ts(1,2,3,4,5)=14,14,13,14,10
  - Fairness: round robin is always fair, J=1

SCHEDULING WITH I/O

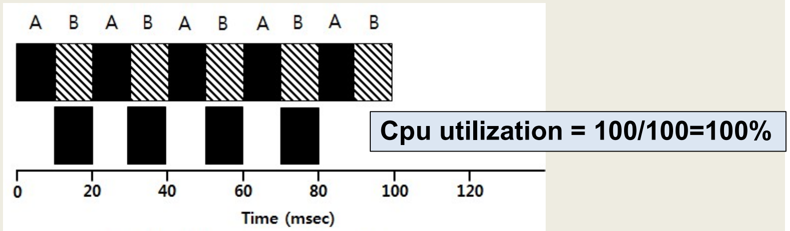
- STCF scheduler
  - A: CPU=50ms, I/O=40ms, 10ms intervals
  - B: CPU=50ms, I/O=0ms
  - Consider A as 10ms subjobs (CPU, then I/O)
- Without considering I/O:



Poor Use of Resources

SCHEDULING WITH I/O - 2

- When a job initiates an I/O request
  - A is blocked, waits for I/O to compute, frees CPU
  - STCF scheduler assigns B to CPU
- When I/O completes → raise interrupt
  - Unblock A, STCF goes back to executing A: (10ms sub-job)



Overlap Allows Better Use of Resources

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Which scheduler, thus far, best address fairness and average response time of jobs?

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First In - First Out (FIFO) **1**

Shortest Job First (SJF) **2**

Shortest Time to Completion First (STCF) **3**

Round Robin **4**

None of the Above **5**

All of the Above **6**

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Total Results

QUESTION: SCHEDULING FAIRNESS

- Which scheduler, this far, best addresses fairness and average response time of jobs?
- First In – First Out (FIFO)
- Shortest Job First (SJF)
- Shortest Time to Completion First (STCF)
- Round Robin (RR)
- None of the Above
- All of the Above

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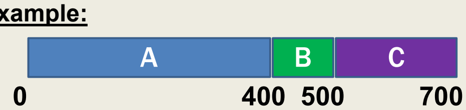
SCHEDULING METRICS

- Consider Three jobs (A, B, C) that require: $time_A$=400ms, $time_B$=100ms, and $time_C$=200ms
- All jobs arrive at time=0 in the sequence of A B C.
- Draw a scheduling graph to help compute the average response time (ART) and average turnaround time (ATT) scheduling metrics for the FIFO scheduler.

Example:



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What is the Average Response Time of the FIFO scheduler?

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What is the Average Turnaround Time of the FIFO scheduler?

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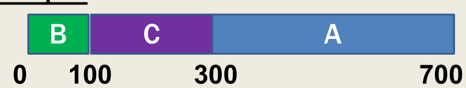
SCHEDULING METRICS

- Consider Three jobs (A, B, C) that require: $time_A$=400ms, $time_B$=100ms, and $time_C$=200ms
- All jobs arrive at time=0 in the sequence of A B C.
- Draw a scheduling graph to help compute the <u>average response time (ART)</u> and <u>average turnaround time (ATT)</u> scheduling metrics for the SJF scheduler.

Example:



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What is the Average Response Time of the Shortest Job First Scheduler?

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What is the Average Turnaround Time of the Shortest Job First Scheduler?

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QUESTIONS