

MATERIAL / PACE

- Please classify your perspective on material covered in today's class (51 respondents):
- 1-mostly review, 5-equal new/review, 10-mostly new
- Average 6.32 (\(\psi \text{previous 7.77}\)
- Please rate the pace of today's class:
- 1-slow, 5-just right, 10-fast
- Average $5.63 (\downarrow previous 5.81)$

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L14.5

L14.6

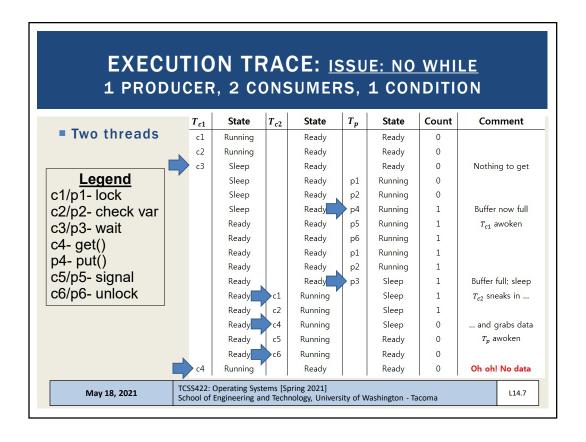
FEEDBACK

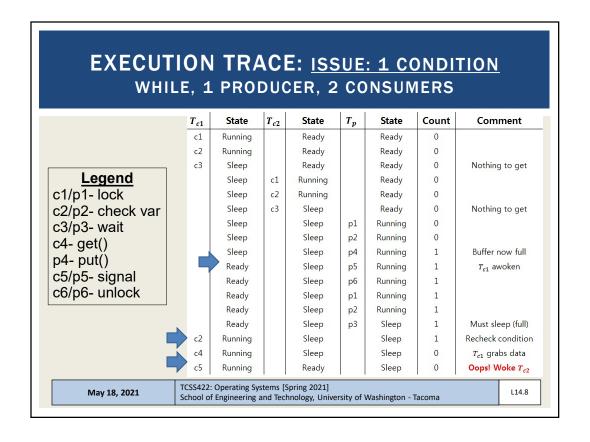
Could you review how execution trace table shows different results with while loop(condition)?

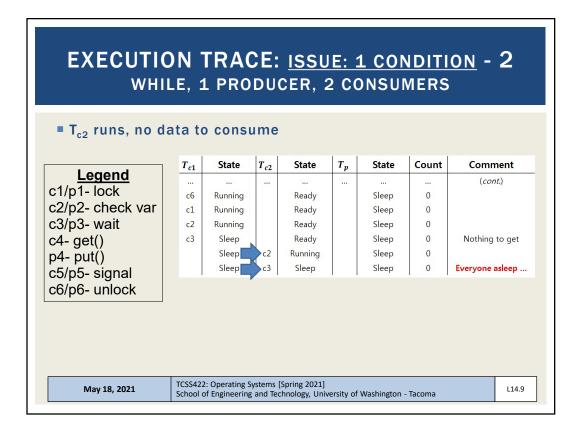
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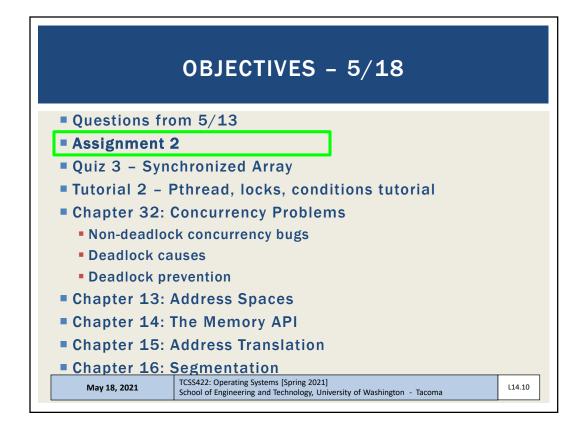
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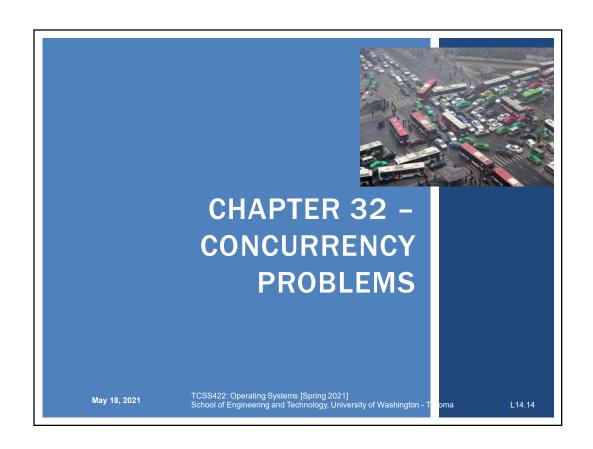
OBJECTIVES - 5/18 Questions from 5/13 Assignment 2 Quiz 3 - Synchronized Array Tutorial 2 - Pthread, locks, conditions tutorial Chapter 32: Concurrency Problems Non-deadlock concurrency bugs Deadlock causes Deadlock prevention Chapter 13: Address Spaces Chapter 14: The Memory API Chapter 15: Address Translation Chapter 16: Segmentation TCSS422: Operating Systems [Spring 2021] School of Engineering and Technology, University of Washington - Tacoma May 18, 2021 L14.11

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L14.13



■ Chapter 15: Address Translation

Chapter 16: Segmentation

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NON-DEADLOCK BUGS - 1

- ■97% of Non-Deadlock Bugs were
 - Atomicity
 - Order violations
- Consider what is involved in "spotting" these bugs in code
 - >> no use of locking constructs to search for
- Desire for automated tool support (IDE)

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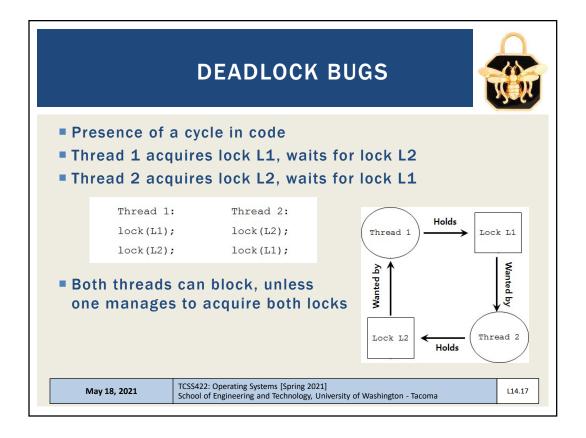
NON-DEADLOCK BUGS - 2

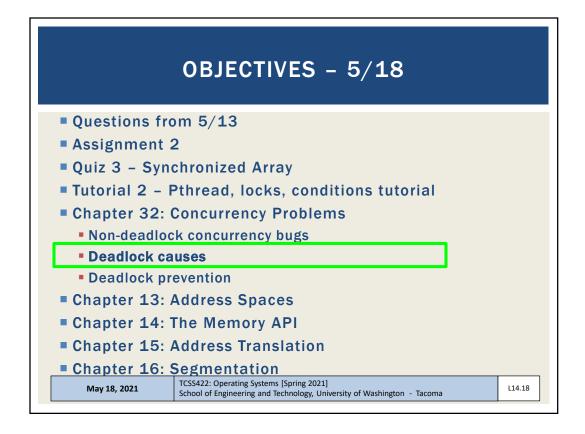
- Atomicity
 - How can we tell if a given variable is shared?
 - Can search the code for uses
 - How do we know if all instances of its use are shared?
 - Can some non-synchronized, non-atomic uses be legal?
 - Legal uses: before threads are created, after threads exit
 - Must verify the scope
- Order violation
 - Must consider all variable accesses
 - Must know desired order

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REASONS FOR DEADLOCKS

- Complex code
 - Must avoid circular dependencies can be hard to find...
- Encapsulation hides potential locking conflicts
 - Easy-to-use APIs embed locks inside
 - Programmer doesn't know they are there
 - Consider the Java Vector class:
 - 1 Vector v1, v2;
 - 2 v1.AddAll(v2);
 - Vector is thread safe (synchronized) by design
 - If there is a v2.AddAll(v1); call at nearly the same time deadlock could result

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CONDITIONS FOR DEADLOCK

■ Four conditions are required for dead lock to occur

Condition	Description
Mutual Exclusion	Threads claim exclusive control of resources that they require.
Hold-and-wait	Threads hold resources allocated to them while waiting for additional resources
No preemption	Resources cannot be forcibly removed from threads that are holding them.
Circular wait	There exists a circular chain of threads such that each thread holds one more resources that are being requested by the next thread in the chain

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OBJECTIVES - 5/18

- Questions from 5/13
- Assignment 2
- Quiz 3 Synchronized Array
- Tutorial 2 Pthread, locks, conditions tutorial
- Chapter 32: Concurrency Problems
 - Non-deadlock concurrency bugs
 - Deadlock causes
 - Deadlock prevention
- Chapter 13: Address Spaces
- Chapter 14: The Memory API
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- Chapter 16: Segmentation

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PREVENTION - MUTUAL EXCLUSION

- Build wait-free data structures
 - Eliminate locks altogether
 - Build structures using CompareAndSwap atomic CPU (HW) instruction
- C pseudo code for CompareAndSwap
- Hardware executes this code atomically

```
int CompareAndSwap(int *address, int expected, int new) {
       if (*address == expected) {
                 *address = new;
3
                 return 1; // success
        return 0;
```

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PREVENTION - MUTUAL EXCLUSION - 2

Recall atomic increment

```
void AtomicIncrement(int *value, int amount) {
2
                 int old = *value;
3
4
         }while( CompareAndSwap(value, old, old+amount) == 0);
```

- Compare and Swap tries over and over until successful
- CompareAndSwap is guaranteed to be atomic
- When it runs it is ALWAYS atomic (at HW level)

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MUTUAL EXCLUSION: LIST INSERTION

Consider list insertion

```
void insert(int value) {
2
         node_t * n = malloc(sizeof(node_t));
          assert( n != NULL );
4
5
6
         n->value = value ;
n->next = head;
                    = n;
          head
```

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MUTUAL EXCLUSION - LIST INSERTION - 2

Lock based implementation

```
void insert(int value){
2
         node t * n = malloc(sizeof(node t));
3
         assert( n != NULL );
4
5
         n->value = value ;
         lock(listlock); // begin critical section
6
        n->next = head;
head = n;
        head
8
         unlock(listlock); //end critical section
```

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L14.26

MUTUAL EXCLUSION - LIST INSERTION - 3

Wait free (no lock) implementation

```
void insert(int value) {
         node_t *n = malloc(sizeof(node_t));
assert(n != NULL);
         n->value = value;
         do {
6
7
                   n->next = head;
         } while (CompareAndSwap(&head, n->next, n));
```

- Assign &head to n (new node ptr)
- Only when head = n->next

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Slides by Wes J. Lloyd

CONDITIONS FOR DEADLOCK

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	Mutual Exclusion	Threads claim exclusive control of resources that they require.
-	Hold-and-wait	Threads hold resources allocated to them while waiting for additional resources
	No preemption	Resources cannot be forcibly removed from threads that are holding them.
	Circular wait	There exists a circular chain of threads such that each thread holds one more resources that are being requested by the next thread in the chain

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PREVENTION LOCK - HOLD AND WAIT

- Problem: acquire all locks atomically
- Solution: use a "lock" "lock"... (like a guard lock)
 - lock (prevention);
 - lock(L1);
 - lock(L2);

 - unlock(prevention);
- Effective solution guarantees no race conditions while acquiring L1, L2, etc.
- Order doesn't matter for L1, L2
- Prevention (GLOBAL) lock decreases concurrency of code
 - Acts Lowers lock granularity
- Encapsulation: consider the Java Vector class...

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CONDITIONS FOR DEADLOCK

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PREVENTION - NO PREEMPTION

- When acquiring locks, don't BLOCK forever if unavailable...
- pthread_mutex_trylock() try once
- pthread_mutex_timedlock() try and wait awhile

```
1  top:
2   lock(L1);
3   if( tryLock(L2) == -1 ){
4         unlock(L1);
5         goto top;
6  }
```

NO STOPPING ANY TIME

Eliminates deadlocks

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NO PREEMPTION - LIVELOCKS PROBLEM

■ Can lead to livelock

```
3
       if(tryLock(L2) == -1){
               unlock(L1);
                goto top;
```

- Two threads execute code in parallel → always fail to obtain both locks
- Fix: add random delay
 - Allows one thread to win the livelock race!



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CONDITIONS FOR DEADLOCK

■ Four conditions are required for dead lock to occur

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PREVENTION - CIRCULAR WAIT

- Provide total ordering of lock acquisition throughout code
 - Always acquire locks in same order
 - L1, L2, L3, ...
 - Never mix: L2, L1, L3; L2, L3, L1; L3, L1, L2....
- Must carry out same ordering through entire program

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L14.33

L14.34

CONDITIONS FOR DEADLOCK

• If any of the following conditions DOES NOT **EXSIST, describe why deadlock can not occur?**

	Condition	Description
	Mutual Exclusion	Threads claim exclusive control of resources that they require.
-	Hold-and-wait	Threads hold resources allocated to them while waiting for additional resources
	No preemption	Resources cannot be forcibly removed from threads that are holding them.
-	Circular wait	There exists a circular chain of threads such that each thread holds one more resources that are being requested by the next thread in the chain

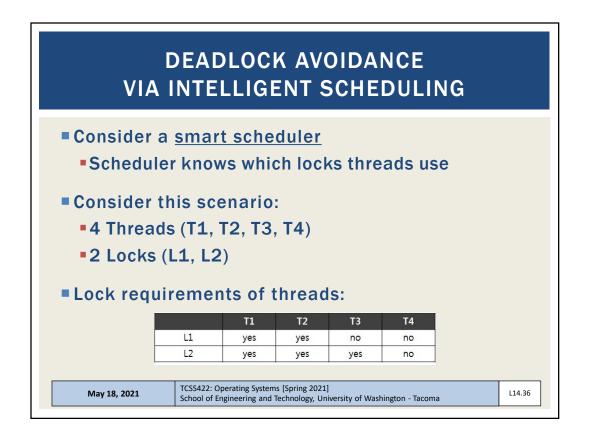
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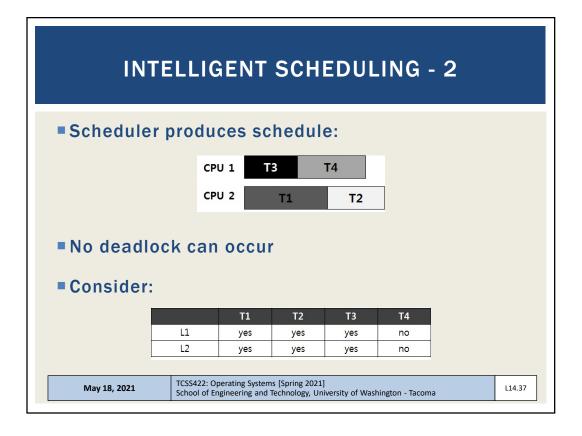
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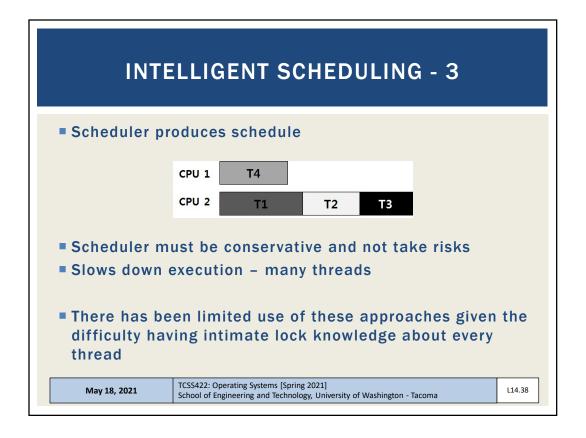
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The dining philosophers problem where 5
philosophers compete for 5 forks, and where a
philosopher must hold two forks to eat involves
which deadlock condition(s)?

Mutual Exclusion
Hold-and-wait
No preemption
Circular wait
All of the above







DETECT AND RECOVER

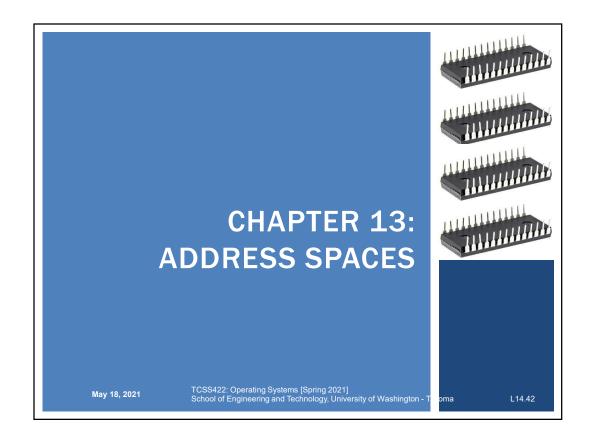
- Allow deadlock to occasionally occur and then take some action.
 - Example: When OS freezes, reboot...
- How often is this acceptable?
 - Once per year
 - Once per month
 - Once per day
 - Consider the effort tradeoff of finding every deadlock bug
- Many database systems employ deadlock detection and recovery techniques.

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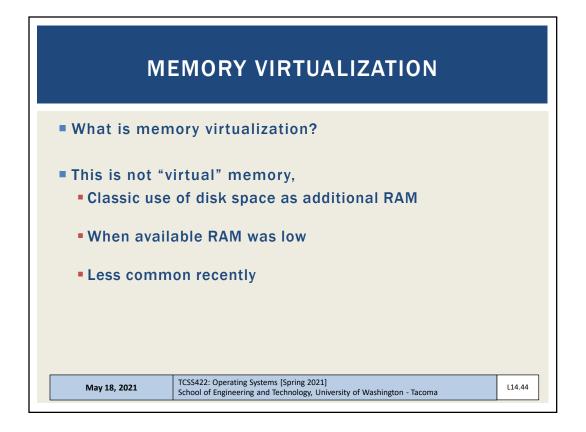
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Chapter 13: Introduction to memory virtualization The address space Goals of OS memory virtualization Chapter 14: Memory API Common memory errors TCSS42: Operating Systems (Spring 2021) School of Engineering and Technology, University of Washington - Tacoma



MEMORY VIRTUALIZATION - 2

- Presentation of system memory to each process
- Appears as if each process can access the entire machine's address space
- Each process's view of memory is isolated from others
- Everyone has their own sandbox

Process A



Process B



Process C



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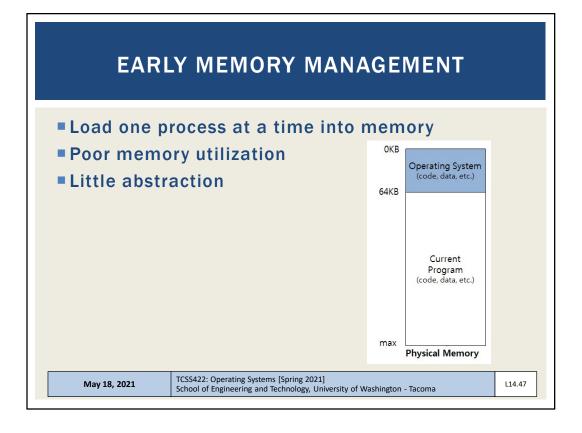
MOTIVATION FOR MEMORY VIRTUALIZATION

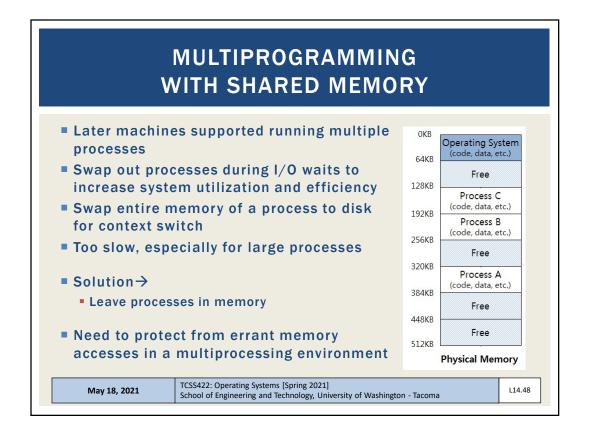
- Easier to program
 - Programs don't need to understand special memory models
- Abstraction enables sophisticated approaches to manage and share memory among processes
- Isolation
 - From other processes: easier to code
- Protection
 - From other processes
 - From programmer error (segmentation fault)

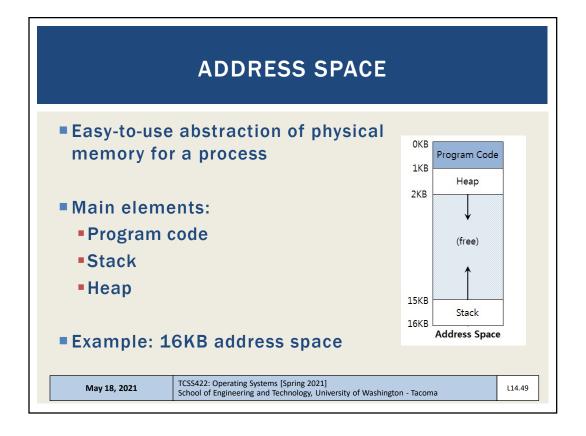
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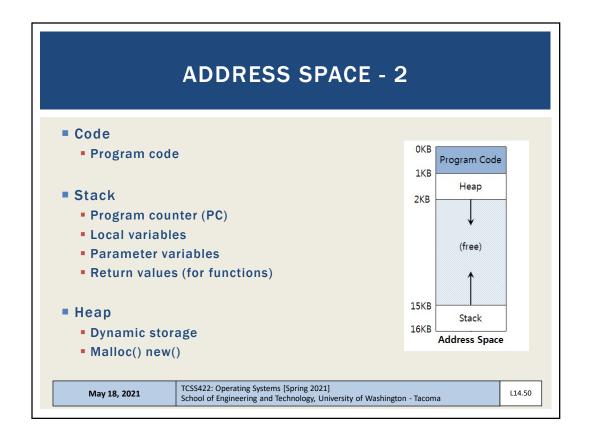
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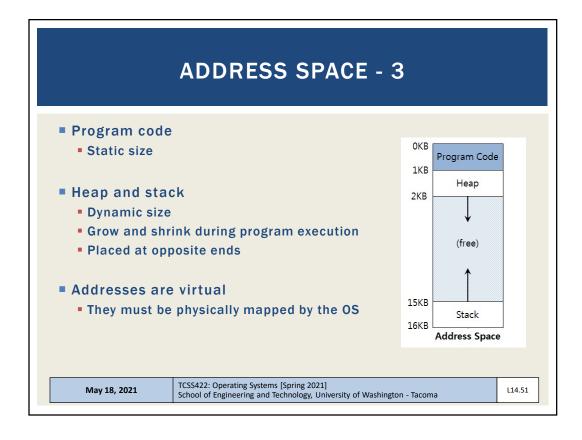
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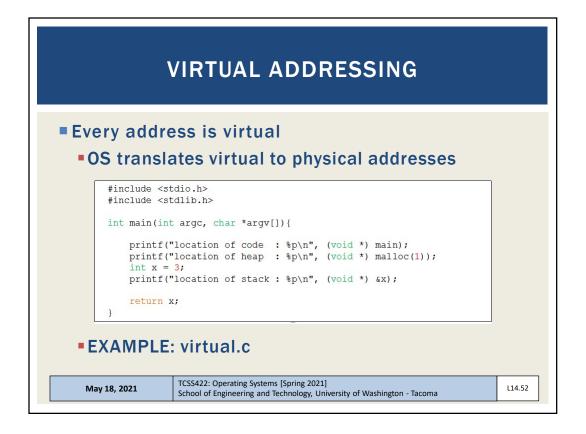


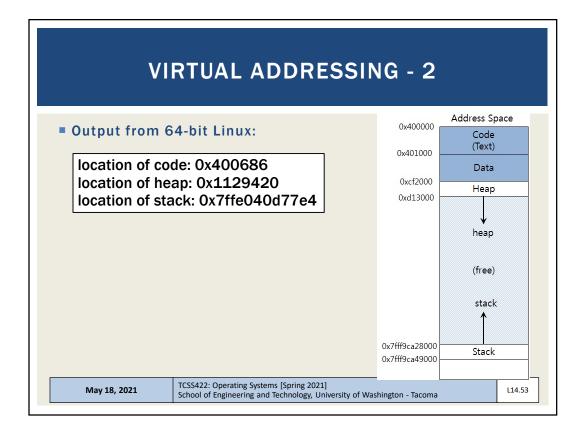


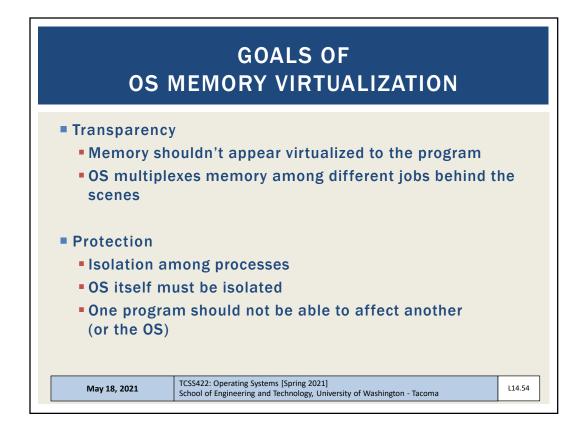












GOALS - 2

- Efficiency
 - Time
 - Performance: virtualization must be fast
 - Space
 - Virtualization must not waste space
 - Consider data structures for organizing memory
 - Hardware support TLB: Translation Lookaside Buffer
- Goals considered when evaluating memory virtualization schemes

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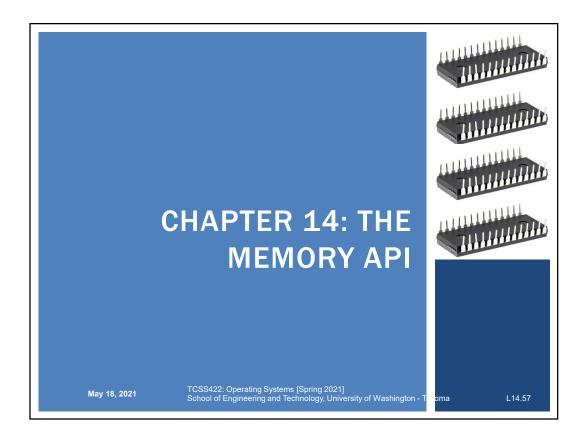
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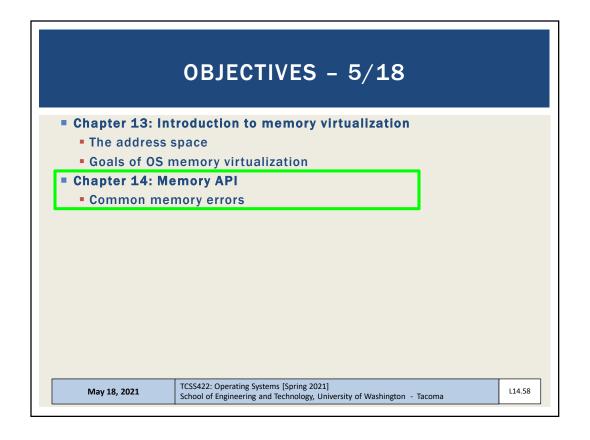
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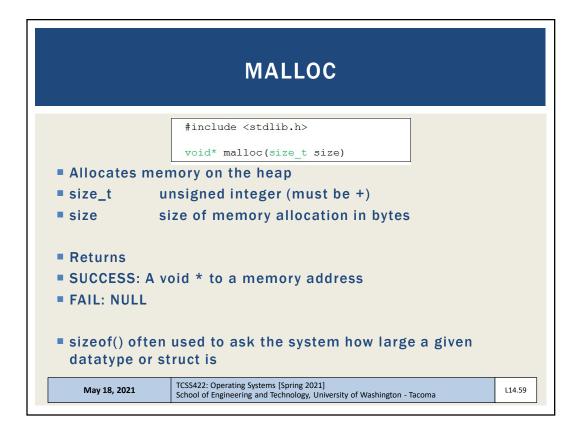
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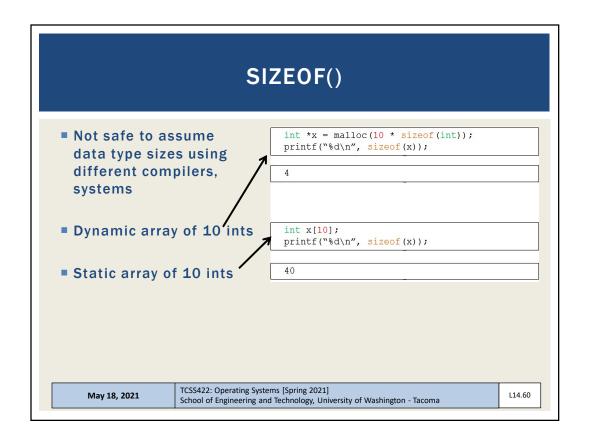
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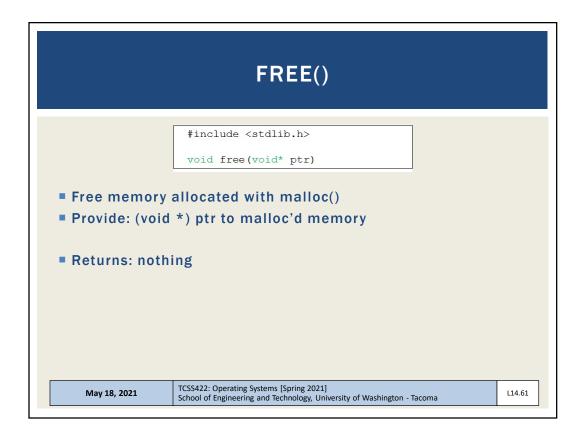
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```
#include<stdio.h>
                               What will this code do?
int * set_magic_number_a()
  int a = 53247;
  return &a;
}
void set_magic_number_b()
  int b = 11111;
}
int main()
 int * x = NULL;
 x = set_magic_number_a();
 printf("The magic number is=%d\n",*x);
  set_magic_number_b();
  printf("The magic number is=%d\n",*x);
  return 0;
                                                      62
```

```
#include<stdio.h>
                               What will this code do?
int * set_magic_number_a()
  int a = 53247;
                                      Output:
  return &a;
}
                            $ ./pointer error
                            The magic number is=53247
void set_magic_number_b()
                            The magic number is=11111
  int b = 111111;
                            We have not changed *x but
int main()
                              the value has changed!!
  int * x = NULL;
                                       Why?
 x = set_magic_number_a();
  printf("The magic number is=%d\n",*x);
  set_magic_number_b();
  printf("The magic number is=%d\n",*x);
  return 0;
```

DANGLING POINTER (1/2)

- Dangling pointers arise when a variable referred (a) goes "out of scope", and it's memory is destroyed/overwritten (by b) without modifying the value of the pointer (*x).
- The pointer still points to the original memory location of the deallocated memory (a), which has now been reclaimed for (b).

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DANGLING POINTER (2/2)

Fortunately in the case, a compiler warning is generated:

```
$ g++ -o pointer_error -std=c++0x pointer_error.cpp
pointer_error.cpp: In function 'int*
set_magic_number_a()':
pointer_error.cpp:6:7: warning: address of local
variable 'a' returned [enabled by default]
```

This is a common mistake - - accidentally referring to addresses that have gone "out of scope"

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CALLOC()

```
#include <stdlib.h>
void *calloc(size t num, size t size)
```

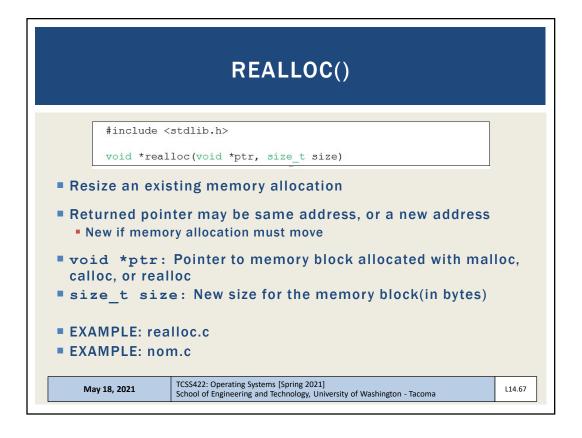
- Allocate "C"lear memory on the heap
- Calloc wipes memory in advance of use...
- size t num : number of blocks to allocate
- size t size: size of each block(in bytes)
- Calloc() prevents...

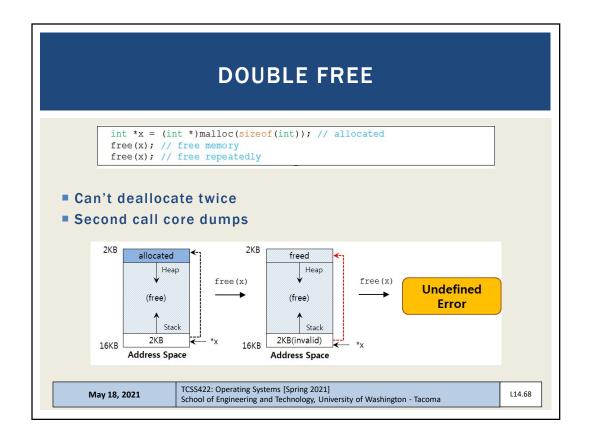
```
char *dest = malloc(20);
printf("dest string=%s\n", dest);
dest string=��F
```

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SYSTEM CALLS

- brk(), sbrk()
- Used to change data segment size (the end of the heap)
- Don't use these
- Mmap(), munmap()
- Can be used to create an extra independent "heap" of memory for a user program
- See man page

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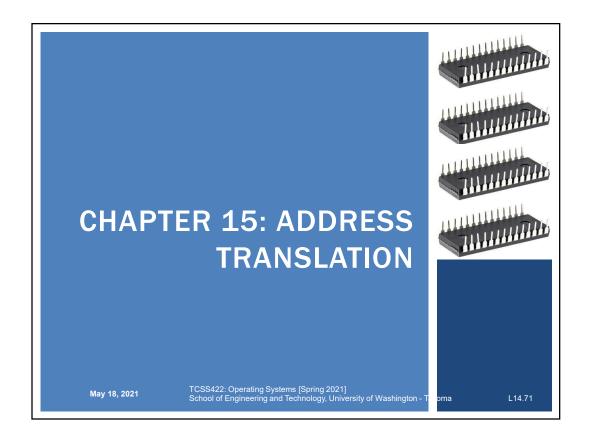
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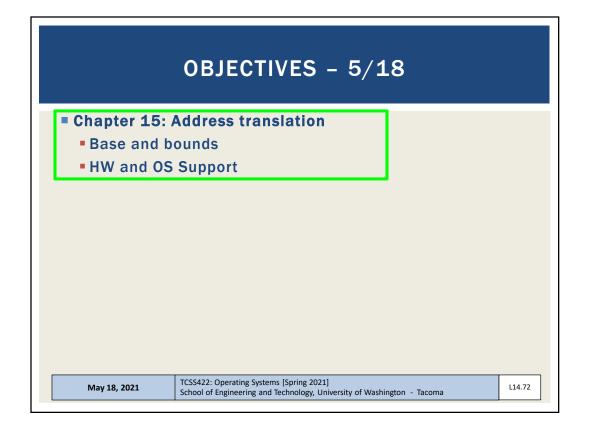
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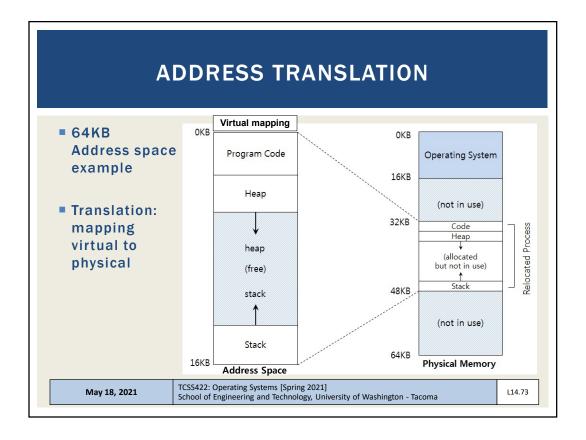
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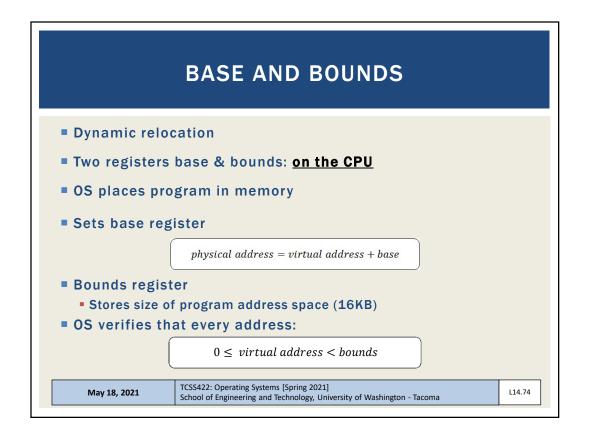
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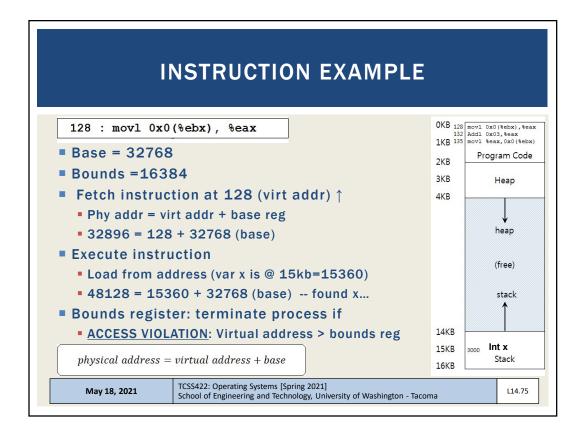
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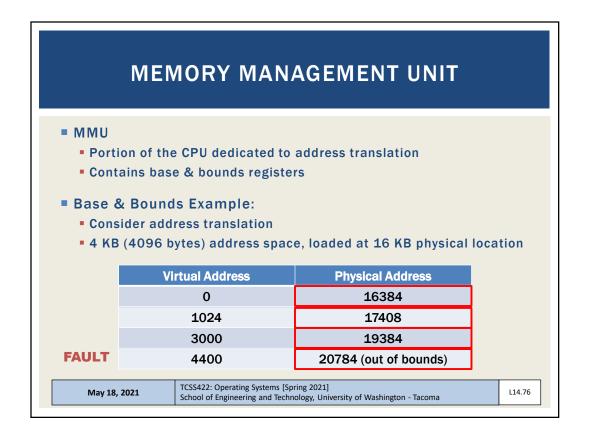






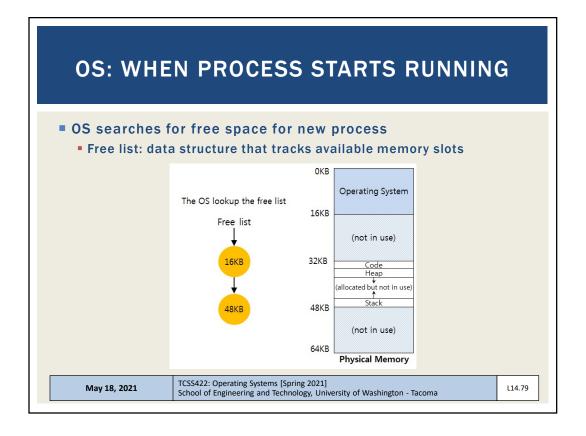


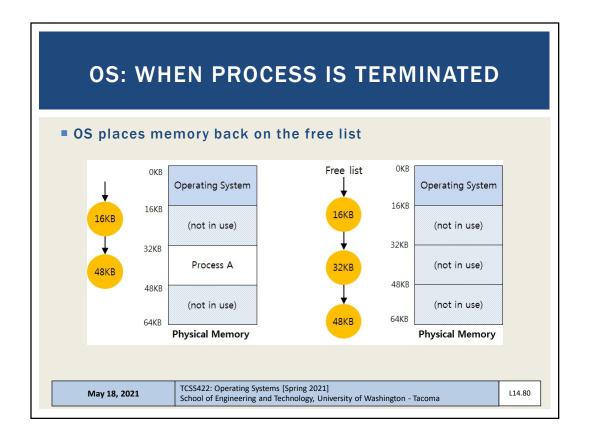


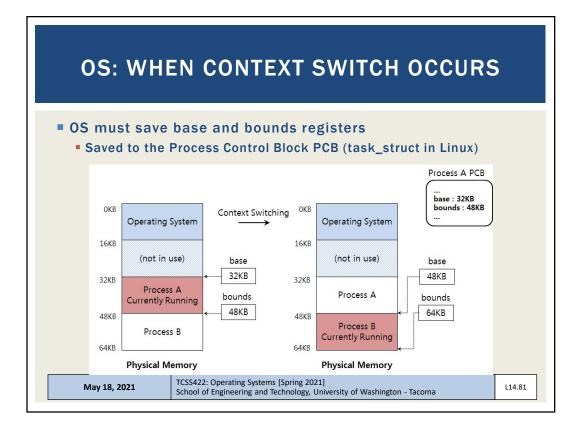


DYNAMIC RELOCATION OF PROGRAMS Hardware requirements: Requirements **HW** support Privileged mode CPU modes: kernel, user Base / bounds registers Registers to support address translation Translate virtual addr; check if in Translation circuitry, check limits bounds Privileged instruction(s) to Instructions for modifying base/bound update base / bounds regs registers Privileged instruction(s) Set code pointers to OS code to handle faults to register exception handlers Ability to raise exceptions For out-of-bounds memory access, or attempts to access privileged instr. TCSS422: Operating Systems [Spring 2021] School of Engineering and Technology, University of Washington - Tacoma May 18, 2021 L14.77

OS SUPPORT FOR MEMORY VIRTUALIZATION For base and bounds OS support required When process starts running Allocate address space in physical memory When a process is terminated Reclaiming memory for use When context switch occurs Saving and storing the base-bounds pair Exception handlers Function pointers set at OS boot time May 18, 2021 TCSS422: Operating Systems (Spring 2021) School of Engineering and Technology, University of Washington - Tacoma







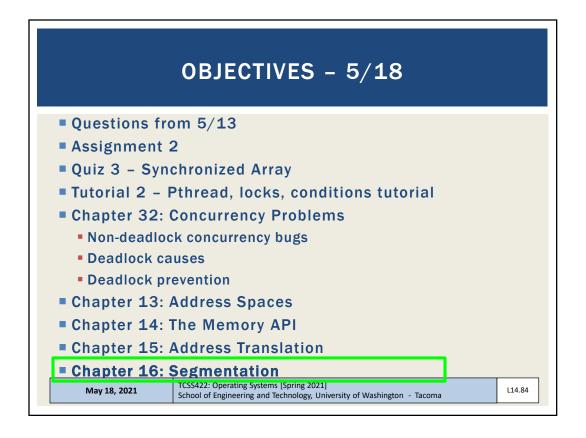
DYNAMIC RELOCATION

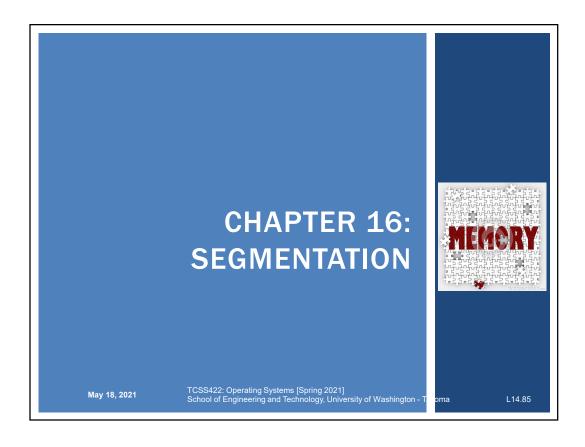
- OS can move process data when not running
- 1. OS deschedules process from scheduler
- 2. OS copies address space from current to new location
- 3. OS updates PCB (base and bounds registers)
- 4. OS reschedules process
- When process runs new base register is restored to CPU
- Process doesn't know it was even moved!

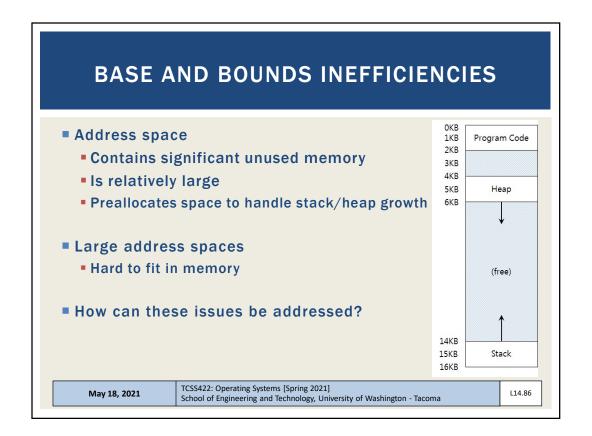
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Consider a 64KB computer the loads a program. The BASE register is set to 32768, and the BOUNDS register is set to 4096. What is the physical memory address translation for a virtual address of 6000?

34768
38768
32769
36864
Out of bounds





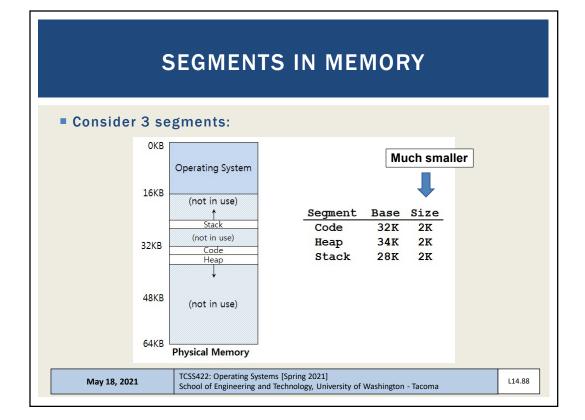


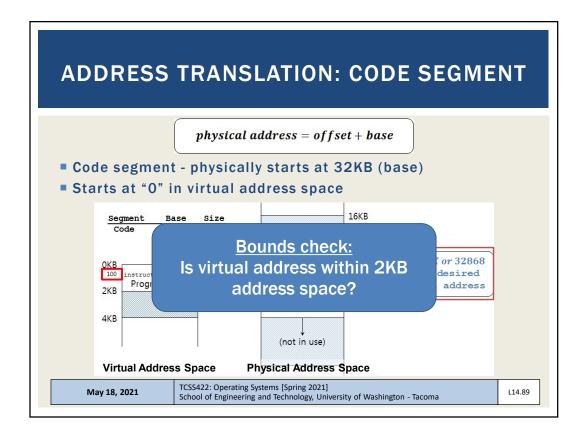
MULTIPLE SEGMENTS

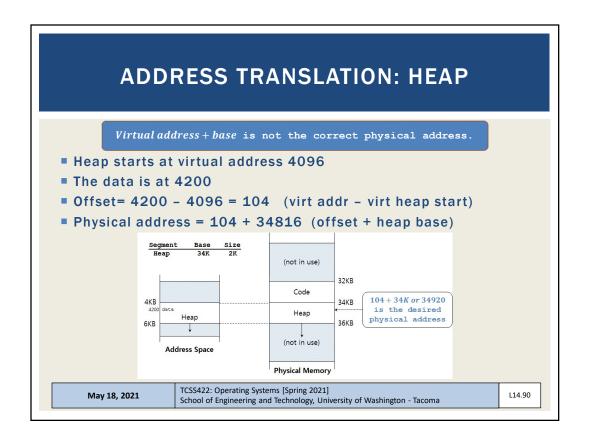
- Memory segmentation
- Manage the address space as (3) separate segments
 - Each is a contiguous address space
 - Provides logically separate segments for: code, stack, heap
- Each segment can placed separately
- Track base and bounds for each segment (registers)

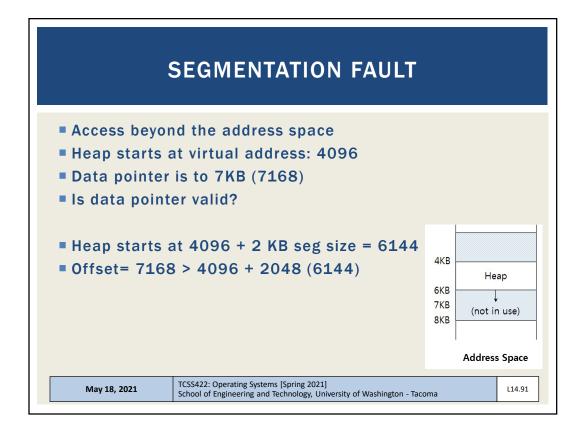
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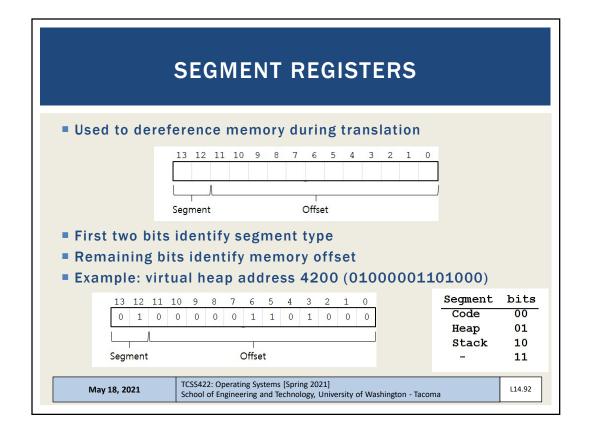
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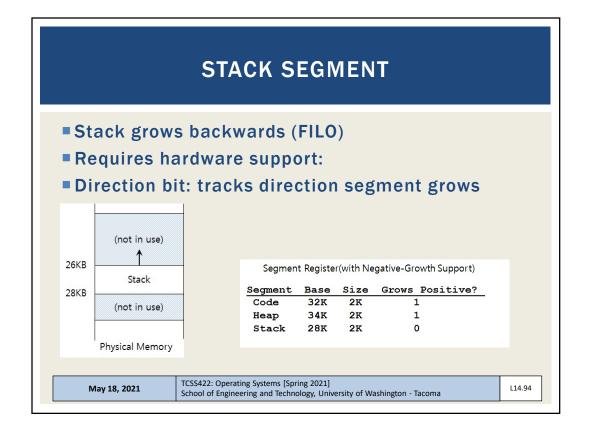


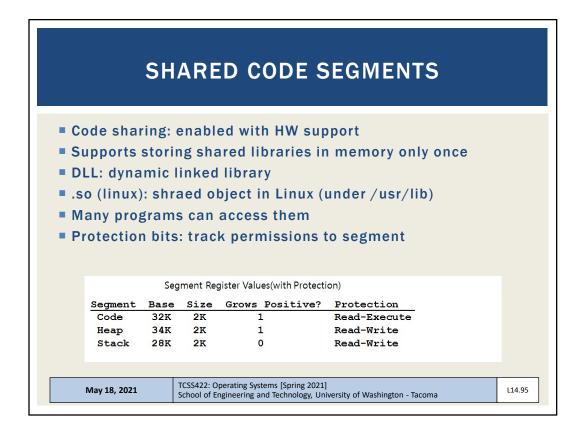


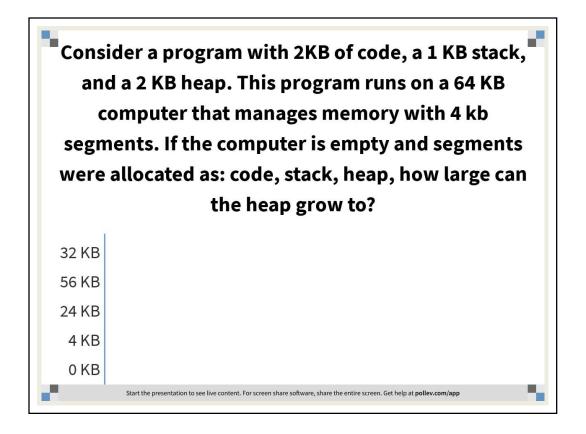




SEGMENTATION DEREFERENCE // get top 2 bits of 14-bit VA Segment = (VirtualAddress & SEG_MASK) >> SEG_SHIFT // now get offset Offset = VirtualAddress & OFFSET_MASK if (Offset >= Bounds[Segment]) RaiseException(PROTECTION FAULT) 8 PhysAddr = Base[Segment] + Offset Register = AccessMemory(PhysAddr) VIRTUAL ADDRESS = 01000001101000 (on heap) \blacksquare SEG_MASK = 0x3000 (110000000000) ■ SEG_SHIFT = 01 → heap (mask gives us segment code) OFFSET_MASK = 0xFFF (00111111111111) • OFFSET = 000001101000 = 104 (isolates segment offset) OFFSET < BOUNDS : 104 < 2048</p> TCSS422: Operating Systems [Spring 2021] School of Engineering and Technology, University of Washington - Tacoma May 18, 2021 L14.93







SEGMENTATION GRANULARITY

- Coarse-grained
- Manage memory as large purpose based segments:
 - Code segment
 - Heap segment
 - Stack segment



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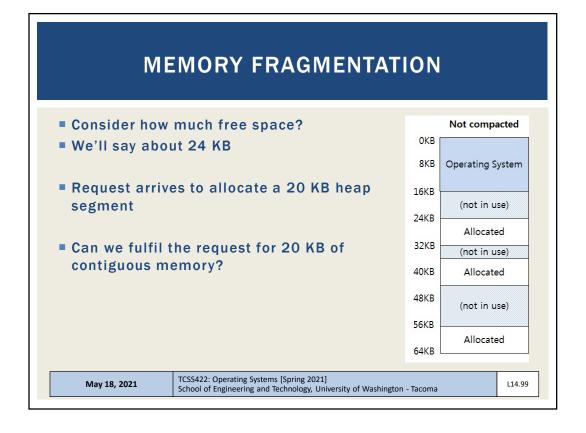
SEGMENTATION GRANULARITY - 2

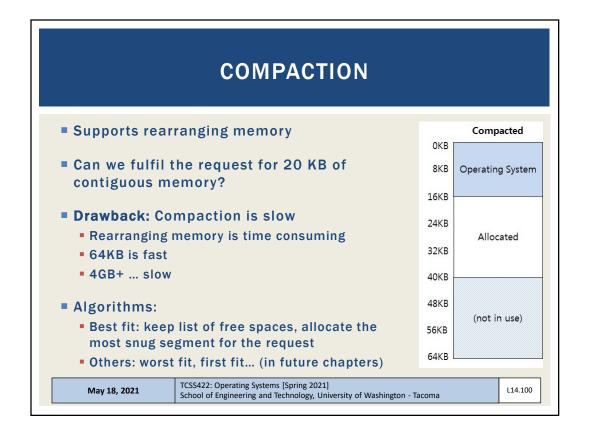
- Fine-grained
- Manage memory as list of segments
- Code, heap, stack segments composed of multiple smaller segments
- Segment table
 - On early systems
 - Stored in memory
 - Tracked large number of segments

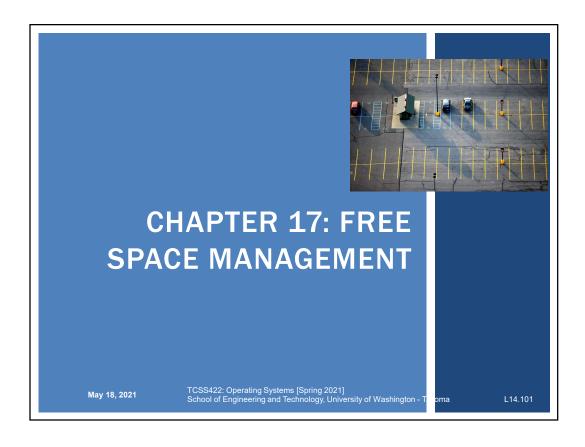


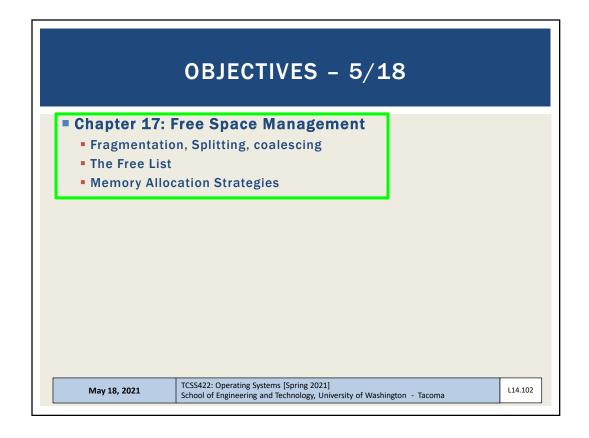
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FREE SPACE MANAGEMENT

- How should free space be managed, when satisfying variable-sized requests?
- What strategies can be used to minimize fragmentation?
- What are the time and space overheads of alternate approaches?

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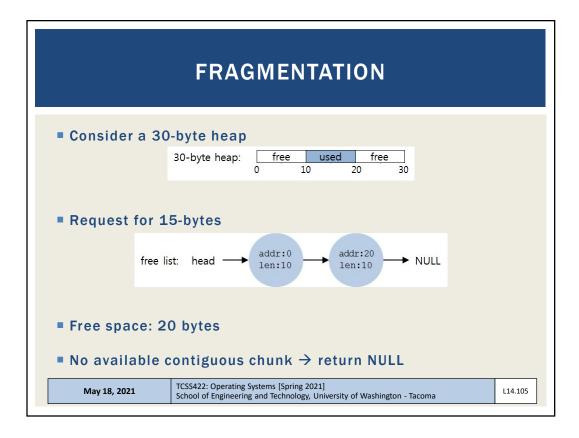
FREE SPACE MANAGEMENT

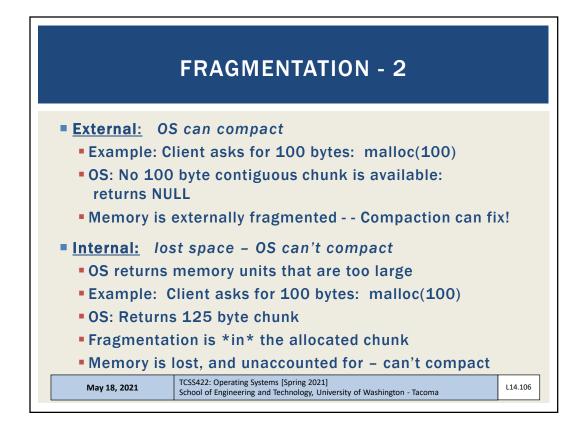
- Management of memory using
- Only fixed-sized units
 - Easy: keep a list
 - Memory request → return first free entry
 - Simple search
- With variable sized units
 - More challenging
 - Results from variable sized malloc requests
 - Leads to fragmentation

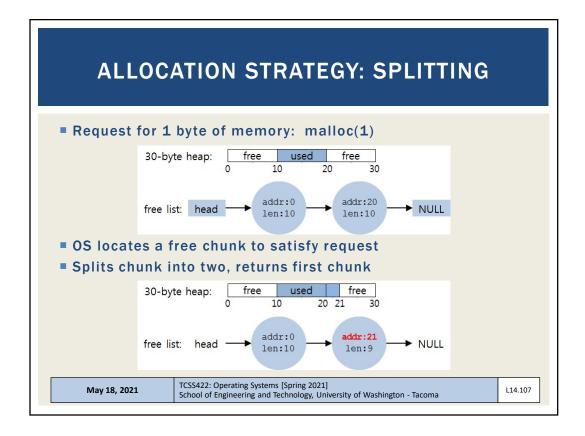
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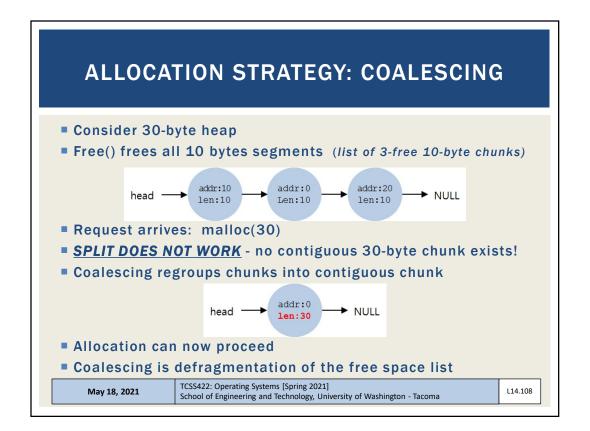
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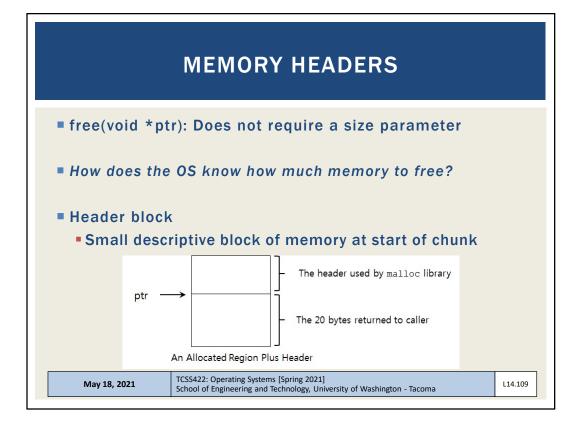
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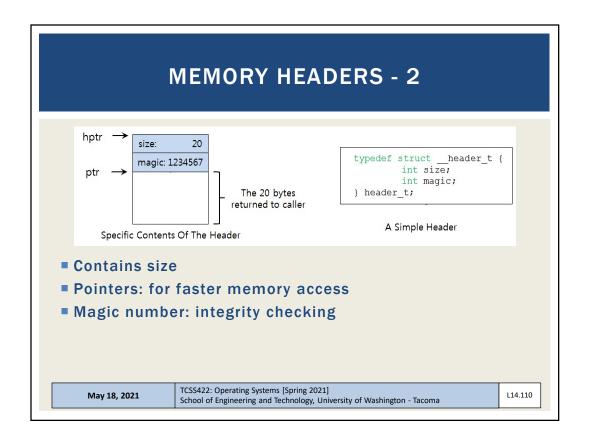












MEMORY HEADERS - 3

- Size of memory chunk is:
- Header size + user malloc size
- N bytes + sizeof(header)
- Easy to determine address of header

```
void free(void *ptr) {
        header t *hptr = (void *)ptr - sizeof(header t);
```

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THE FREE LIST

■ Simple free list struct

```
typedef struct __node_t {
         int size;
         struct __node_t *next;
} nodet t;
```

- Use mmap to create free list
- 4kb heap, 4 byte header, one contiguous free chunk

```
// mmap() returns a pointer to a chunk of free space
node_t *head = mmap(NULL, 4096, PROT_READ|PROT_WRITE,
                             MAP_ANON|MAP_PRIVATE, -1, 0);
head->size = 4096 - sizeof(node_t);
head->next = NULL;
```

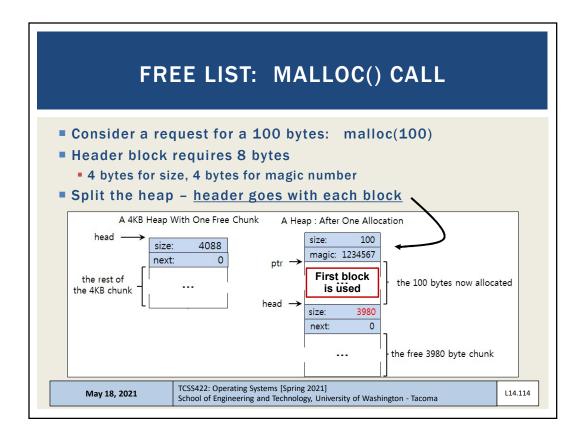
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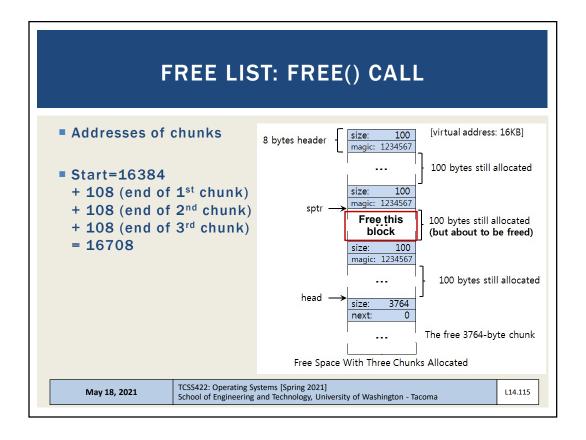
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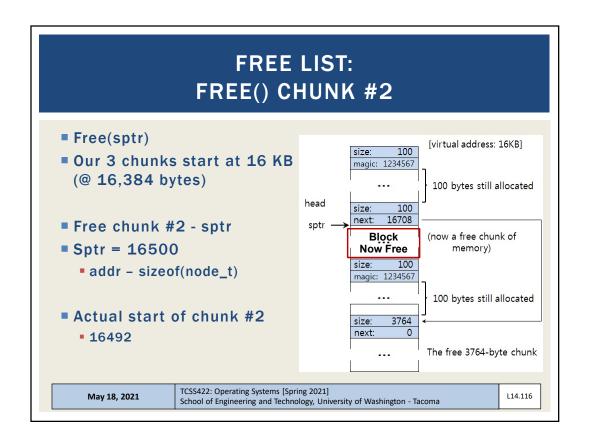
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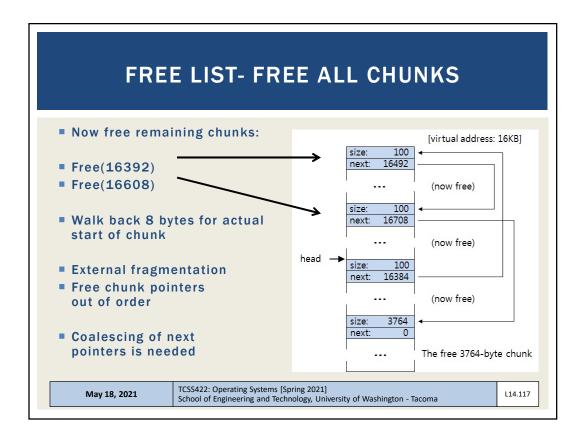
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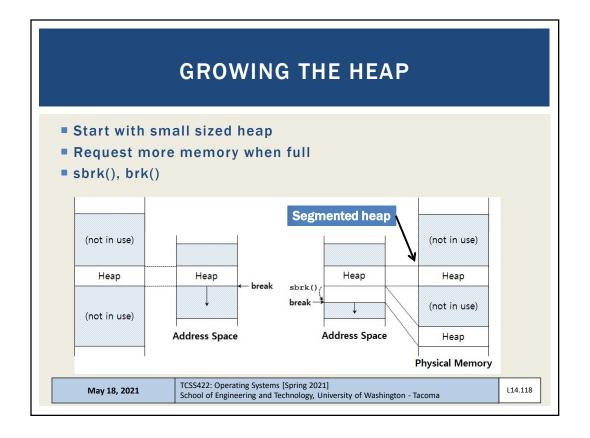










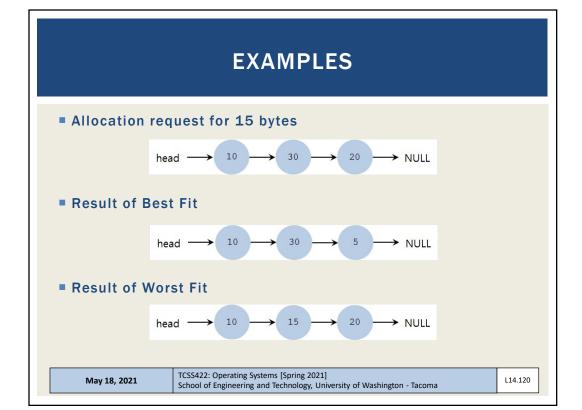


MEMORY ALLOCATION STRATEGIES

- Best fit
 - Traverse free list
 - Identify all candidate free chunks
 - Note which is smallest (has best fit)
 - When splitting, "leftover" pieces are small (and potentially less useful -- fragmented)
- Worst fit
 - Traverse free list
 - Identify largest free chunk
 - Split largest free chunk, leaving a still large free chunk

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MEMORY ALLOCATION STRATEGIES - 2

First fit

- Start search at beginning of free list
- Find first chunk large enough for request
- Split chunk, returning a "fit" chunk, saving the remainder
- Avoids full free list traversal of best and worst fit

Next fit

- Similar to first fit, but start search at last search location
- Maintain a pointer that "cycles" through the list
- Helps balance chunk distribution vs. first fit
- Find first chunk, that is large enough for the request, and split
- Avoids full free list traversal

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SEGREGATED LISTS

- For popular sized requests
 e.g. for kernel objects such as locks, inodes, etc.
- Manage as segregated free lists
- Provide object caches: stores pre-initialized objects
- How much memory should be dedicated for specialized requests (object caches)?
- If a given cache is low in memory, can request "slabs" of memory from the general allocator for caches.
- General allocator will reclaim slabs when not used

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