


# TCSS 422: OPERATING SYSTEMS

## Linux Thread API, Locks, Lock-based data structures



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October 28, 2021

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School of Engineering and Technology, University of Washington

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## OBJECTIVES – 10/28

- **Questions from 10/26**
- C Tutorial - Pointers, Strings, Exec in C - Due Fri Oct 29
- Assignment 1 - Due Fri Nov 12
- Quiz 1 (Due Tue Nov 2) – Quiz 2 (Due Thur Nov 4)
- Chapter 26: Concurrency: An Introduction
  - Race condition
  - Critical section
- Chapter 27: Linux Thread API
  - pthread\_create/\_join
  - pthread\_mutex\_lock/\_unlock/\_trylock/\_timelock
  - pthread\_cond\_wait/\_signal/\_broadcast
- Chapter 28: Locks
  - Introduction, Lock Granularity
  - Spin Locks, Test and Set, Compare and Swap
- Chapter 29: Lock Based Data Structures
  - Sloppy Counter
  - Concurrent Structures: Linked List, Queue, Hash Table

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## ONLINE DAILY FEEDBACK SURVEY

- Daily Feedback Quiz in Canvas – Available After Each Class
- Extra credit available for completing surveys **ON TIME**
- Tuesday surveys: due by ~ Wed @ 11:59p
- Thursday surveys: due ~ Mon @ 11:59p

☰ TCSS 422 A > Assignments

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Spring 2021

Home

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**TCSS 422 - Online Daily Feedback Survey - 4/1**  
Available until Apr 5 at 11:59pm | Due Apr 5 at 10pm | -/1 pts

Quiz 0 - C background survey

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### TCSS 422 - Online Daily Feedback Survey - 4/1

#### Quiz Instructions

**Question 1** 0.5 pts

On a scale of 1 to 10, please classify your perspective on material covered in today's class:

1	2	3	4	5	6	7	8	9	10
Mostly Review To Me				Equal New and Review					Mostly New to Me

**Question 2** 0.5 pts

Please rate the pace of today's class:


1	2	3	4	5	6	7	8	9	10
Slow				Just Right					Fast

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## MATERIAL / PACE

- Please classify your perspective on material covered in today's class (25 respondents):
- 1-mostly review, 5-equal new/review, 10-mostly new
- **Average - 6.66 (↑ - previous 6.23)**



- Please rate the pace of today's class:
- 1-slow, 5-just right, 10-fast
- **Average - 5.58 (↑ - previous 5.48)**

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## FEEDBACK

- ..

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## BONUS SESSION – EXAMPLE SCHEDULER PROBLEMS

- **Bonus session:**
  - Recorded on Wednesday October 27 starting at 6:30pm
    - Zoom link available on Canvas
    - Problems and solutions posted on “Schedule” tab of website
  
- **A series of example scheduling problems are solved:**
  - Focus on: FIFO, SJF, STCF, RR, MLFQ
  
- **Video recorded and now posted**

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## QUIZ 1

- Active reading on Chapter 9 – Proportional Share Schedulers
  
- Posted in Canvas
- Due Tuesday Nov 2<sup>nd</sup> at 11:59pm
- Grace period til Thursday Nov 4<sup>th</sup> at 11:59 \*\* AM \*\*
- Late submissions til Saturday Nov 6<sup>th</sup> at 11:59pm
  
- Link:
- [http://faculty.washington.edu/wlloyd/courses/tcss422/TCSS422\\_s2021\\_quiz\\_1.pdf](http://faculty.washington.edu/wlloyd/courses/tcss422/TCSS422_s2021_quiz_1.pdf)

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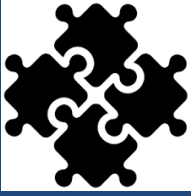
## QUIZ 2 - CPU SCHEDULING ALGORITHMS

- Quiz posted on Canvas
- Due Thursday Nov 4 @ 11:59p
- Provides CPU scheduling practice problems
  - FIFO, SJF, STCF, RR, MLFQ (Ch. 7 & 8)
- Unlimited attempts allowed
- Multiple choice and fill-in the blank
- Quiz automatically scored by Canvas
  - Please report any grading problems

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# CHAPTER 27 - LINUX THREAD API



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Text **WESLEYLLOYD641** to **22333** once to join

**W** Which **NON-BLOCKING** API call can be used to obtain a lock without **BLOCKING** the calling thread?

- `pthread_mutex_lock()`
- `pthread_mutex_unlock()`
- `pthread_join()`
- `pthread_mutex_trylock()`
- None of the above

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**W** Which API call **BLOCKS** temporarily for a specified amount of time while trying to obtain a lock before giving up?

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## LOCKS - 3

- Error checking wrapper

```
// Use this to keep your code clean but check for failures  
// Only use if exiting program is OK upon failure  
void Pthread_mutex_lock(pthread_mutex_t *mutex) {  
    int rc = pthread_mutex_lock(mutex);  
    assert(rc == 0);  
}
```

- What if lock can't be obtained?

```
int pthread_mutex_trylock(pthread_mutex_t *mutex);  
int pthread_mutex_timelock(pthread_mutex_t *mutex,  
                           struct timespec *abs_timeout);
```

- trylock – returns immediately (fails) if lock is unavailable
- timelock – tries to obtain a lock for a specified duration

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## CONDITIONS AND SIGNALS

- Condition variables support “signaling” between threads

```
int pthread_cond_wait(pthread_cond_t *cond,  
                    pthread_mutex_t *mutex);  
int pthread_cond_signal(pthread_cond_t *cond);
```



- pthread\_cond\_t datatype
- pthread\_cond\_wait()
  - Puts thread to “sleep” (waits) (THREAD is BLOCKED)
  - Threads added to >FIFO queue<, lock is released
  - Waits (*llstems*) for a “signal” (NON-BUSY WAITING, no polling)
  - When signal occurs, interrupt fires, wakes up first thread, (THREAD is RUNNING), lock is provided to thread

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## CONDITIONS AND SIGNALS - 2

```
int pthread_cond_signal(pthread_cond_t * cond);  
int pthread_cond_broadcast(pthread_cond_t * cond);
```

- pthread\_cond\_signal()
  - Called to send a “signal” to wake-up first thread in FIFO “wait” queue
  - The goal is to unblock a thread to respond to the signal
- pthread\_cond\_broadcast()
  - Unblocks *all* threads in FIFO “wait” queue, currently blocked on the specified condition variable
  - Broadcast is used when all threads should wake-up for the signal
- Which thread is unblocked first?
  - Determined by OS scheduler (based on priority)
  - Thread(s) awoken based on placement order in FIFO wait queue
  - When awoken threads acquire lock as in pthread\_mutex\_lock()

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## CONDITIONS AND SIGNALS - 3

- **Wait example:**

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);
while (initialized == 0)
    pthread_cond_wait(&cond, &lock);
// Perform work that requires lock
a = a + b;
pthread_mutex_unlock(&lock);
```
- wait puts thread to sleep, releases lock
- when awoken, lock reacquired (but then **released by this code**)
- When initialized, another thread signals

```
pthread_mutex_lock(&lock);
initialized = 1;
pthread_cond_signal(&cond);
pthread_mutex_unlock(&lock);
```

State variable set, Enables other thread(s) to proceed above.

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## CONDITION AND SIGNALS - 4

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);
while (initialized == 0)
    pthread_cond_wait(&cond, &lock);
// Perform work that requires lock
a = a + b;
pthread_mutex_unlock(&lock);
```

- **Why do we wait inside a while loop?**
- **The while ensures upon awakening the condition is rechecked**
  - A signal is raised, but the pre-conditions required to proceed may have not been met. **\*\*MUST CHECK STATE VARIABLE\*\***
  - Without checking the state variable the thread may proceed to execute when it should not. (e.g. too early)

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## PTHREADS LIBRARY

- **Compilation:**  
gcc requires special option to require programs with pthreads:
  - gcc -pthread pthread.c -o pthread
  - Explicitly links library with compiler flag
  - **RECOMMEND:** using makefile to provide compiler arguments
  
- **List of pthread manpages**
  - man -k pthread

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## SAMPLE MAKEFILE

```
CC=gcc
CFLAGS=-pthread -I. -Wall

binaries=pthread pthread_int pthread_lock_cond pthread_struct

all: $(binaries)

pthread_mult: pthread.c pthread_int.c
    $(CC) $(CFLAGS) $^ -o $@

clean:
    $(RM) -f $(binaries) *.o
```

- **Example builds multiple single file programs**
  - All target
- **pthread\_mult**
  - Example if multiple source files should produce a single executable
- **clean target**

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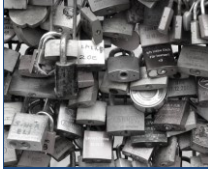
## W What key feature differentiates condition variables from mutex\_locks in C ?

- Condition variables provide only NON-BLOCKING API calls.
- Locks can not be used without condition variables.
- Condition variables introduce a FIFO queue enabling control of the order that threads will receive the lock which provides fairness.
- Condition variables must first be initialized to a non-NULL value before being used in the program.
- None of the above

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# CHAPTER 28 – LOCKS



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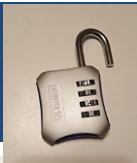
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## LOCKS



- Ensure critical section(s) are executed atomically-*as a unit*
  - Only one thread is allowed to execute a critical section at any given time
  - Ensures the code snippets are “mutually exclusive”
- Protect a global counter:

```
balance = balance + 1;
```
- A “critical section”:

```
1 lock_t mutex; // some globally-allocated lock 'mutex'
2 ...
3 lock (&mutex);
4 balance = balance + 1;
5 unlock (&mutex);
```

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## LOCKS - 2

- Lock variables are called “MUTEX”
  - Short for mutual exclusion (that’s what they guarantee)
- Lock variables store the state of the lock
- States
  - **Locked** (acquired or held)
  - **Unlocked** (available or free)
- Only 1 thread can hold a lock

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## LOCKS - 3

- `pthread_mutex_lock(&lock)`
  - Try to acquire lock
  - If lock is free, calling thread will acquire the lock
  - Thread with lock enters critical section
    - Thread “owns” the lock
- No other thread can acquire the lock before the owner releases it.

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## LOCKS - 4

- Program can have many mutex (lock) variables to “serialize” many critical sections
- Locks are also used to protect data structures
  - Prevent multiple threads from changing the same data simultaneously
  - Programmer can make sections of code “granular”
    - ***Fine grained*** – means just one grain of sand at a time through an hour glass
  - Similar to relational database transactions
    - DB transactions prevent multiple users from modifying a table, row, field

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## FINE GRAINED?

■ *Is this code a good example of “fine grained parallelism”?*

```
pthread_mutex_lock(&lock);  
a = b++;  
b = a * c;  
*d = a + b +c;  
FILE * fp = fopen ("file.txt", "r");  
fscanf(fp, "%s %s %s %d", str1, str2, str3, &e);  
ListNode *node = mylist->head;  
Int i=0  
while (node) {  
    node->title = str1;  
    node->subheading = str2;  
    node->desc = str3;  
    node->end = *e;  
    node = node->next;  
    i++  
}  
e = e - i;  
pthread_mutex_unlock(&lock);
```




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## FINE GRAINED PARALLELISM

```
pthread_mutex_lock(&lock_a);  
pthread_mutex_lock(&lock_b);  
a = b++;  
pthread_mutex_unlock(&lock_b);  
pthread_mutex_unlock(&lock_a);  
  
pthread_mutex_lock(&lock_b);  
b = a * c;  
pthread_mutex_unlock(&lock_b);  
  
pthread_mutex_lock(&lock_d);  
*d = a + b +c;  
pthread_mutex_unlock(&lock_d);  
  
FILE * fp = fopen ("file.txt", "r");  
pthread_mutex_lock(&lock_e);  
fscanf(fp, "%s %s %s %d", str1, str2, str3, &e);  
pthread_mutex_unlock(&lock_e);  
  
ListNode *node = mylist->head;  
int i=0 . . .
```



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## LOCK GRANULARITY TRADE-OFF SPACE

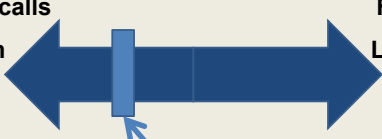
**FINE-GRAINED**

Many Lock (kernel) calls

More overhead from excessive locking

More parallelism

Higher code complexity & debugging



**COARSE-GRAINED**

Few Lock (kernel) calls

Low overhead from minimal locking

Less parallelism

Low code complexity & simpler debugging

Every program implementation lies someplace along the trade-off space...


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## EVALUATING LOCK IMPLEMENTATIONS

- **Correctness**
  - Does the lock work?
  - Are critical sections mutually exclusive? (atomic-as a unit?)
  
- **Fairness**
  - Do all threads that compete for a lock have a fair chance of acquiring it?
  
- **Overhead**

What makes a good lock?



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## BUILDING LOCKS

- Locks require hardware support
  - To minimize overhead, ensure fairness and correctness
  - Special “atomic-as a *unit*” instructions to support lock implementation
  - Atomic-as a *unit* exchange instruction
    - XCHG
  - Compare and exchange instruction
    - CMPXCHG
    - CMPXCHG8B
    - CMPXCHG16B

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## HISTORICAL IMPLEMENTATION

- To implement mutual exclusion
  - Disable interrupts upon entering critical sections

```
1 void lock() {  
2     DisableInterrupts();  
3 }  
4 void unlock() {  
5     EnableInterrupts();  
6 }
```

- Any thread could disable system-wide interrupt
  - What if lock is never released?
- On a multiprocessor processor each CPU has its own interrupts
  - Do we disable interrupts for all cores simultaneously?
- While interrupts are disabled, they could be lost
  - If not queued...

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## SPIN LOCK IMPLEMENTATION

- Operate without atomic-as a *unit* assembly instructions
- “Do-it-yourself” Locks
- Is this lock implementation: **(1)Correct? (2)Fair? (3)Performant?**



```
1  typedef struct __lock_t { int flag; } lock_t;
2
3  void init(lock_t *mutex) {
4      // 0 → lock is available, 1 → held
5      mutex->flag = 0;
6  }
7
8  void lock(lock_t *mutex) {
9      while (mutex->flag == 1) // TEST the flag
10         ; // spin-wait (do nothing)
11     mutex->flag = 1; // now SET it !
12 }
13
14 void unlock(lock_t *mutex) {
15     mutex->flag = 0;
16 }
```

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## DIY: CORRECT?

- Correctness requires luck... (e.g. *DIY lock is incorrect*)

Thread1	Thread2
<pre>call lock() while (flag == 1) interrupt: switch to Thread 2</pre>	<pre>call lock() while (flag == 1) flag = 1; interrupt: switch to Thread 1</pre>
<pre>flag = 1; // set flag to 1 (too!)</pre>	

- Here both threads have “acquired” the lock simultaneously

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## DIY: PERFORMANT?

```

void lock(Lock_t *mutex)
{
  while (mutex->flag == 1); // while lock is unavailable, wait...
  mutex->flag = 1;
}

```

- What is wrong with while(<cond>); ?
- Spin-waiting wastes time actively waiting for another thread
- while (1); will “peg” a CPU core at 100%
  - Continuously loops, and evaluates mutex->flag value...
  - Generates heat...

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**WE WILL RETURN AT  
2:57PM**



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## TEST-AND-SET INSTRUCTION

- Hardware support required for working locks
- Book presents pseudo code of C implementation
  - TEST-and-SET adds a simple check to the basic spin lock
  - Assumption is this “C code” runs atomically on CPU:

```
1  int TestAndSet(int *ptr, int new) {  
2      int old = *ptr; // fetch old value at ptr  
3      *ptr = new;    // store 'new' into ptr  
4      return old;   // return the old value  
5  }
```

- lock() method checks that TestAndSet doesn't return 1
- Comparison is in the caller
  
- Can implement the C version (non-atomic) and have some success on a single-core VM

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## DIY: TEST-AND-SET - 2

- C version: requires preemptive scheduler on single core system
- Lock is never released without a context switch
- single-core VM: occasionally will deadlock, doesn't miscount

```
1  typedef struct __lock_t {  
2      int flag;  
3  } lock_t;  
4  
5  void init(lock_t *lock) {  
6      // 0 indicates that lock is available,  
7      // 1 that it is held  
8      lock->flag = 0;  
9  }  
10  
11 void lock(lock_t *lock) {  
12     while (TestAndSet(&lock->flag, 1) == 1)  
13         ; // spin-wait  
14 }  
15  
16 void unlock(lock_t *lock) {  
17     lock->flag = 0;  
18 }
```

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## SPIN LOCK EVALUATION

- **Correctness:**
  - Spin locks with atomic Test-and-Set:  
Critical sections won't be executed simultaneously by (2) threads
  
- **Fairness:**
  - No fairness guarantee. Once a thread has a lock, nothing forces it to relinquish it...
  
- **Performance:**
  - Spin locks perform “busy waiting”
  - Spin locks are best for short periods of waiting (< 1 time quantum)
  - Performance is slow when multiple threads share a CPU
    - Especially if “spinning” for long periods

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## COMPARE AND SWAP

- Checks that the lock variable has the expected value **FIRST**, before changing its value
  - If so, make assignment
  - Return value at location
- Adds a comparison to TestAndSet
  - Textbook presents C pseudo code
  - Assumption is that the compare-and-swap method runs atomically
- Useful for wait-free synchronization
  - Supports implementation of shared data structures which can be updated atomically (*as a unit*) using the HW support CompareAndSwap instruction
  - Shared data structure updates become “wait-free”
  - Upcoming in Chapter 32

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## COMPARE AND SWAP

- Compare and Swap
 

```

1  int CompareAndSwap(int *ptr, int expected, int new) {
2      int actual = *ptr;
3      if (actual == expected)
4          *ptr = new;
5      return actual;
6  }
```
- Spin lock
 

**C implementation 1-core VM:  
Count is correct, no deadlock**

```

1
2
3          ; // spin
4      }
```
- X86 provides “`cmpxchg1`” compare-and-exchange instruction
  - `cmpxchg8b`
  - `cmpxchg16b`

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**When implementing locks in a high-level language (e.g. C), what is missing that prevents implementation of CORRECT locks?**

- Shared state variable
- Condition variables
- ATOMIC instructions
- Fairness
- None of the above

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## TWO MORE “LOCK BUILDING” CPU INSTRUCTIONS

- Cooperative instructions used together to support synchronization on RISC systems
- No support on x86 processors
  - Supported by RISC: Alpha, PowerPC, ARM
- Load-linked (LL)
  - Loads value into register
  - Same as typical load
  - Used as a mechanism to track competition
- Store-conditional (SC)
  - Performs “mutually exclusive” store
  - Allows only one thread to store value

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## LL/SC LOCK

```
1 int LoadLinked(int *ptr) {
2     return *ptr;
3 }
4
5 int StoreConditional(int *ptr, int value) {
6     if (no one has updated *ptr since the LoadLinked to this address) {
7         *ptr = value;
8         return 1; // success!
9     } else {
10        return 0; // failed to update
11    }
12 }
```

- LL instruction loads pointer value (ptr)
- SC only stores if the load link pointer has not changed
- Requires HW support
  - C code is psuedo code

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## LL/SC LOCK - 2

```
1 void lock(lock_t *lock) {
2     while (1) {
3         while (LoadLinked(&lock->flag) == 1)
4             ; // spin until it's zero
5         if (StoreConditional(&lock->flag, 1) == 1)
6             return; // if set-it-to-1 was a success: all done
7                 // otherwise: try it all over again
8     }
9 }
10
11 void unlock(lock_t *lock) {
12     lock->flag = 0;
13 }
```

- Two instruction lock

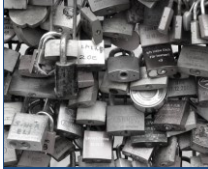
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# CHAPTER 29 – LOCK BASED DATA STRUCTURES



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## LOCK-BASED CONCURRENT DATA STRUCTURES

- Adding locks to data structures make them **thread safe**.
- Considerations:
  - Correctness
  - Performance
  - Lock granularity

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## COUNTER STRUCTURE W/O LOCK

- Synchronization weary --- not thread safe

```
1     typedef struct __counter_t {
2         int value;
3     } counter_t;
4
5     void init(counter_t *c) {
6         c->value = 0;
7     }
8
9     void increment(counter_t *c) {
10        c->value++;
11    }
12
13    void decrement(counter_t *c) {
14        c->value--;
15    }
16
17    int get(counter_t *c) {
18        return c->value;
19    }
```

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## CONCURRENT COUNTER

```
1  typedef struct __counter_t {
2      int value;
3      pthread_lock_t lock;
4  } counter_t;
5
6  void init(counter_t *c) {
7      c->value = 0;
8      Pthread_mutex_init(&c->lock, NULL);
9  }
10
11 void increment(counter_t *c) {
12     Pthread_mutex_lock(&c->lock);
13     c->value++;
14     Pthread_mutex_unlock(&c->lock);
15 }
16
```

- Add lock to the counter
- Require lock to change data

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## CONCURRENT COUNTER - 2

- Decrease counter
- Get value

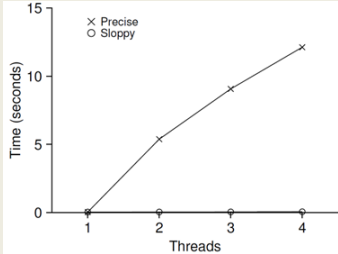
```
(Cont.)
17 void decrement(counter_t *c) {
18     Pthread_mutex_lock(&c->lock);
19     c->value--;
20     Pthread_mutex_unlock(&c->lock);
21 }
22
23 int get(counter_t *c) {
24     Pthread_mutex_lock(&c->lock);
25     int rc = c->value;
26     Pthread_mutex_unlock(&c->lock);
27     return rc;
28 }
```

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## CONCURRENT COUNTERS - PERFORMANCE

- iMac: four core Intel 2.7 GHz i5 CPU
- Each thread increments counter 1,000,000 times



Threads	Precise (seconds)	Sloppy (seconds)
1	0.5	0.1
2	5.5	0.1
3	9.5	0.1
4	13.5	0.1

Traditional vs. sloppy counter  
Sloppy Threshold (S) = 1024

**Synchronized counter scales poorly.**

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## PERFECT SCALING

- Achieve (N) performance gain with (N) additional resources
- Throughput:
  - Transactions per second (tps)
  - 1 core
  - N = 100 tps
  - 10 cores (x10)
  - N = 1000 tps (x10)

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## SLOPPY COUNTER

- Provides single logical shared counter
  - Implemented using local counters for each ~CPU core
    - 4 CPU cores = 4 local counters & 1 global counter
    - Local counters are synchronized via local locks
  - Global counter is updated periodically
    - Global counter has lock to protect global counter value
    - Sloppiness threshold (S):
      - Update threshold of global counter with local values
    - Small (S): more updates, more overhead
    - Large (S): fewer updates, more performant, less synchronized
- Why this implementation?  
Why do we want counters local to each CPU Core?

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## SLOPPY COUNTER – MAIN POINTS

- Idea of Sloppy Counter is to **RELAX** the synchronization requirement for counting
  - Instead of synchronizing global count variable each time:  
**counter=counter+1**
  - Synchronization occurs only every so often:  
e.g. *every 1000 counts*
- Relaxing the synchronization requirement **drastically** reduces locking API overhead by trading-off split-second accuracy of the counter
- Sloppy counter: trade-off accuracy for speed
  - It's sloppy because it's not so accurate (until the end)

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## SLOPPY COUNTER - 2

- Update threshold (S) = 5
- Synchronized across four CPU cores
- Threads update local CPU counters

Time	L <sub>1</sub>	L <sub>2</sub>	L <sub>3</sub>	L <sub>4</sub>	G
0	0	0	0	0	0
1	0	0	1	1	0
2	1	0	2	1	0
3	2	0	3	1	0
4	3	0	3	2	0
5	4	1	3	3	0
6	5 → 0	1	3	4	5 (from L <sub>1</sub> )
7	0	2	4	5 → 0	10 (from L <sub>4</sub> )

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## THRESHOLD VALUE S

- Consider 4 threads increment a counter 1000000 times each
- Low S → What is the consequence?
- High S → What is the consequence?

Sloppiness	Time (seconds)
1	11.5
2	5.5
4	3.0
8	1.8
16	1.1
32	0.7
64	0.45
128	0.3
256	0.2
512	0.15
1024	0.1

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## SLOPPY COUNTER - EXAMPLE

- Example implementation
- Also with CPU affinity

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## CONCURRENT LINKED LIST - 1

- Simplification - only basic list operations shown
- Structs and initialization:

```
1 // basic node structure
2 typedef struct __node_t {
3     int key;
4     struct __node_t *next;
5 } node_t;
6
7 // basic list structure (one used per list)
8 typedef struct __list_t {
9     node_t *head;
10    pthread_mutex_t lock;
11 } list_t;
12
13 void List_Init(list_t *L) {
14     L->head = NULL;
15     pthread_mutex_init(&L->lock, NULL);
16 }
17
18 (Cont.)
```

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## CONCURRENT LINKED LIST - 2

- Insert – adds item to list
- Everything is critical!
  - There are two unlocks

```
(Cont.)
18  int List_Insert(list_t *L, int key) {
19      pthread_mutex_lock(&L->lock);
20      node_t *new = malloc(sizeof(node_t));
21      if (new == NULL) {
22          perror("malloc");
23          pthread_mutex_unlock(&L->lock);
24      }
25      return -1; // fail
26      new->key = key;
27      new->next = L->head;
28      L->head = new;
29      pthread_mutex_unlock(&L->lock);
30      return 0; // success
31  }
(Cont.)
```

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## CONCURRENT LINKED LIST - 3

- Lookup – checks list for existence of item with key
- Once again everything is critical
  - Note - there are also two unlocks

```
(Cont.)
32
33  int List_Lookup(list_t *L, int key) {
34      pthread_mutex_lock(&L->lock);
35      node_t *curr = L->head;
36      while (curr) {
37          if (curr->key == key) {
38              pthread_mutex_unlock(&L->lock);
39              return 0; // success
40          }
41          curr = curr->next;
42      }
43      pthread_mutex_unlock(&L->lock);
44      return -1; // failure
45  }
```

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## CONCURRENT LINKED LIST

- **First Implementation:**
  - Lock **everything** inside Insert() and Lookup()
  - If malloc() fails lock must be released
    - Research has shown “**exception-based control flow**” to be error prone
    - 40% of Linux OS bugs occur in rarely taken code paths
    - Unlocking in an exception handler is considered a poor coding practice
    - There is nothing specifically wrong with this example however
  
- **Second Implementation ...**

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## CCL – SECOND IMPLEMENTATION

- **Init and Insert**

```
1 void List_Init(list_t *L) {
2     L->head = NULL;
3     pthread_mutex_init(&L->lock, NULL);
4 }
5
6 void List_Insert(list_t *L, int key) {
7     // synchronization not needed
8     node_t *new = malloc(sizeof(node_t));
9     if (new == NULL) {
10        perror("malloc");
11        return;
12    }
13    new->key = key;
14
15    // just lock critical section
16    pthread_mutex_lock(&L->lock);
17    new->next = L->head;
18    L->head = new;
19    pthread_mutex_unlock(&L->lock);
20 }
21
```

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## CCL – SECOND IMPLEMENTATION - 2

### ▪ Lookup

```
(Cont.)  
22  int List_Lookup(list_t *L, int key) {  
23      int rv = -1;  
24      pthread_mutex_lock(&L->lock);  
25      node_t *curr = L->head;  
26      while (curr) {  
27          if (curr->key == key) {  
28              rv = 0;  
29              break;  
30          }  
31          curr = curr->next;  
32      }  
33      pthread_mutex_unlock(&L->lock);  
34      return rv; // now both success and failure  
35  }
```

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## CONCURRENT LINKED LIST PERFORMANCE

- Using a single lock for entire list is not very performant
- Users must “wait” in line for a single lock to access/modify any item
- Hand-over-hand-locking (lock coupling)
  - Introduce a lock for each node of a list
  - Traversal involves handing over previous node’s lock, acquiring the next node’s lock...
  - Improves lock granularity
  - Degrades traversal performance
- Consider hybrid approach
  - Fewer locks, but more than 1
  - Best lock-to-node distribution?



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## MICHAEL AND SCOTT CONCURRENT QUEUES

- Improvement beyond a single master lock for a queue (FIFO)
- Two locks:
  - One for the **head** of the queue
  - One for the **tail**
- Synchronize enqueue and dequeue operations
  
- Add a dummy node
  - Allocated in the queue initialization routine
  - Supports separation of head and tail operations
  
- Items can be added and removed by separate threads at the same time

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# CONCURRENT QUEUE

- Remove from queue

```
1     typedef struct __node_t {
2         int value;
3         struct __node_t *next;
4     } node_t;
5
6     typedef struct __queue_t {
7         node_t *head;
8         node_t *tail;
9         pthread_mutex_t headLock;
10        pthread_mutex_t tailLock;
11    } queue_t;
12
13    void Queue_Init(queue_t *q) {
14        node_t *tmp = malloc(sizeof(node_t));
15        tmp->next = NULL;
16        q->head = q->tail = tmp;
17        pthread_mutex_init(&q->headLock, NULL);
18        pthread_mutex_init(&q->tailLock, NULL);
19    }
20
(Cont.)
```

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# CONCURRENT QUEUE - 2

- Add to queue

```
(Cont.)
21    void Queue_Enqueue(queue_t *q, int value) {
22        node_t *tmp = malloc(sizeof(node_t));
23        assert(tmp != NULL);
24
25        tmp->value = value;
26        tmp->next = NULL;
27
28        pthread_mutex_lock(&q->tailLock);
29        q->tail->next = tmp;
30        q->tail = tmp;
31        pthread_mutex_unlock(&q->tailLock);
32    }
(Cont.)
```

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## OBJECTIVES – 10/28

- Questions from 10/26
- C Tutorial - Pointers, Strings, Exec in C - Due Fri Oct 29
- Assignment 1 - Due Fri Nov 12
- Quiz 1 (Due Tue Nov 2) – Quiz 2 (Due Thur Nov 4)
- Chapter 26: Concurrency: An Introduction
  - Race condition
  - Critical section
- Chapter 27: Linux Thread API
  - pthread\_create/\_join
  - pthread\_mutex\_lock/\_unlock/\_trylock/\_timelock
  - pthread\_cond\_wait/\_signal/\_broadcast
- Chapter 28: Locks
  - Introduction, Lock Granularity
  - Spin Locks, Test and Set, Compare and Swap
- Chapter 29: Lock Based Data Structures
  - Sloppy Counter
  - Concurrent Structures: Linked List, Queue, **Hash Table**

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## CONCURRENT HASH TABLE

- Consider a simple hash table
  - Fixed (static) size
  - Hash maps to a bucket
    - Bucket is implemented using a concurrent linked list
    - One lock per hash (bucket)
    - Hash bucket is a linked lists

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## INSERT PERFORMANCE – CONCURRENT HASH TABLE

- Four threads – 10,000 to 50,000 inserts
  - iMac with four-core Intel 2.7 GHz CPU

Inserts (Thousands)	Simple Concurrent List (seconds)	Concurrent Hash Table (seconds)
10	~1.0	~0.1
20	~2.5	~0.1
30	~4.5	~0.1
40	~7.5	~0.1
50	~11.5	~0.1

**The simple concurrent hash table scales magnificently.**

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## CONCURRENT HASH TABLE

```
1      #define BUCKETS (101)
2
3      typedef struct __hash_t {
4          list_t lists[BUCKETS];
5      } hash_t;
6
7      void Hash_Init(hash_t *H) {
8          int i;
9          for (i = 0; i < BUCKETS; i++) {
10             List_Init(&H->lists[i]);
11         }
12     }
13
14     int Hash_Insert(hash_t *H, int key) {
15         int bucket = key % BUCKETS;
16         return List_Insert(&H->lists[bucket], key);
17     }
18
19     int Hash_Lookup(hash_t *H, int key) {
20         int bucket = key % BUCKETS;
21         return List_Lookup(&H->lists[bucket], key);
22     }
```

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## Which is a major advantage of using concurrent data structures in your programs?

- Locks are encapsulated within data structure code ensuring thread safety.
- Lock granularity tradeoff already optimized inside data structurew
- Multiple threads can more easily share data
- All of the above
- None of the above

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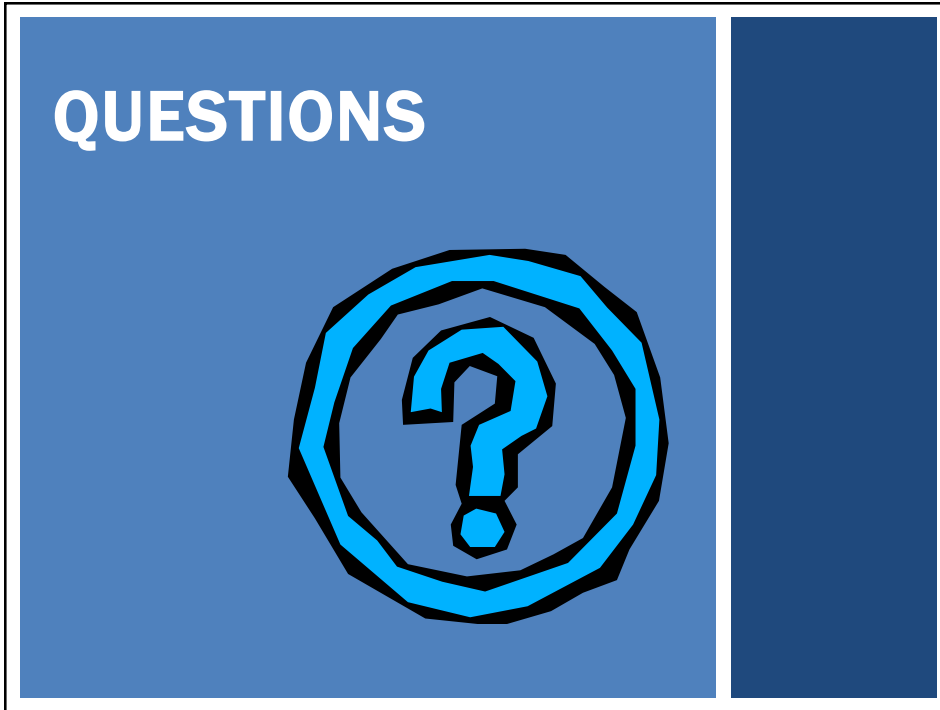
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## LOCK-FREE DATA STRUCTURES

- Lock-free data structures in Java
- `java.util.concurrent.atomic` package
- Classes:
  - `AtomicBoolean`
  - `AtomicInteger`
  - `AtomicIntegerArray`
  - `AtomicIntegerFieldUpdater`
  - `AtomicLong`
  - `AtomicLongArray`
  - `AtomicLongFieldUpdater`
  - `AtomicReference`
- See: <https://docs.oracle.com/en/java/javase/11/docs/api/java.base/java/util/concurrent/atomic/package-summary.html>

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