

LECTURE 12: ANGULAR MOMENTUM

TODAY: MOTIVATION

BACK GROUND

LADDER OP

NEXT TIME: DIFF EQ SOLN

SPHERICAL HARMONICS

LEGENDRE POLYNOMIALS

MOTIVATION: We want to solve hydrogen problem

1d \rightarrow 3d

Classical analogue: planetary motion

 \vec{L}^2 conserved

SHO $H = p^2 + x^2$

$H = p_x^2 + p_y^2 + p_z^2 + V(\vec{r})$

$a = x - ip$

$a^\dagger = x + ip$

$= \left[\frac{p^2}{2m} + V(\vec{r}) \right] + \frac{L^2}{2\hbar^2}$

$$\begin{array}{cc} \swarrow & \searrow \\ L^2 & L_z \end{array}$$

$L_\pm = L_x \pm iL_y$

CLASSICALLY

$$\vec{L} = \vec{r} \times \vec{p}$$

$$\vec{L} = \begin{pmatrix} \hat{L}_x & \hat{L}_y & \hat{L}_z \\ x & y & z \\ p_x & p_y & p_z \end{pmatrix} = L_x \hat{L}_x + L_y \hat{L}_y + L_z \hat{L}_z$$

$$= (y p_z - z p_y) \hat{L}_x - (x p_z - z p_x) \hat{L}_y + (x p_y - y p_x) \hat{L}_z$$

QM

$$L_{xop} = y_{op} p_{zop} - z_{op} p_{yop}$$

$$L_{yop} = - (x_{op} p_{zop} - z_{op} p_{xop})$$

$$L_{zop} = x_{op} p_{yop} - y_{op} p_{xop}$$

POSITION SPACE

$$x_{op} \rightarrow x$$

$$p_{xop} \rightarrow -i\hbar \frac{\partial}{\partial x}$$

$$y_{op} \rightarrow y$$

$$p_{yop} \rightarrow -i\hbar \frac{\partial}{\partial y}$$

$$z_{op} \rightarrow z$$

$$p_{zop} \rightarrow -i\hbar \frac{\partial}{\partial z}$$

MOMENTUM SPACE

$$x_{op} \rightarrow i\hbar \frac{\partial}{\partial p_x}$$

$$p_{xop} \rightarrow p_x$$

$$y_{op} \rightarrow i\hbar \frac{\partial}{\partial p_y}$$

$$p_{yop} \rightarrow p_y$$

$$z_{op} \rightarrow i\hbar \frac{\partial}{\partial p_z}$$

$$p_{zop} \rightarrow p_z$$

DEEP IDEA HERE

SYMMETRY



CONSERVATION LAW

TRANSLATIONAL
INVARIANCE



LINEAR MOMENTUM
CONSERVATION

ROTATIONAL
INVARIANCE



ANGULAR MOMENTUM
CONSERVATION

TIME TRANSLATION
INVARIANCE



ENERGY CONSERVATION

UNITARY OPERATORS

TRANSLATION BY $\vec{a} = (a_x, a_y, a_z)$

$$T(\vec{a}) = e^{-i\vec{p} \cdot \vec{a} / \hbar}$$

$$T(\vec{b}) T(\vec{a}) = T(\vec{a} + \vec{b})$$

$$[p_i, p_j] = \delta_{ij}$$

ROTATIONS

$$R(\vec{\theta}) = e^{-i\vec{L} \cdot \vec{\theta} / \hbar}$$

$$R(\theta_z) = e^{-iL_z \cdot \theta_z / \hbar}$$

in coordinates

$$L_z = x_{op} p_{yop} - y_{op} p_{xop}$$

$$= -i\hbar \left[x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right]$$

very messy to calculate...

TIME TRANSLATION

$$U(t) = e^{-iHt/\hbar}$$

ROTATIONAL SYMMETRY \Rightarrow WORK IN SPHERICAL COORDINATES

$$(x, y, z) \rightarrow (r, \theta, \varphi)$$

$$L_z = -i\hbar \frac{\partial}{\partial \varphi}$$

$$L_x = i\hbar \left[\sin \varphi \frac{\partial}{\partial \theta} + \cos \varphi \cot \theta \frac{\partial}{\partial \varphi} \right]$$

$$L_y = i\hbar \left[-\cos \varphi \frac{\partial}{\partial \theta} + \sin \varphi \cot \theta \frac{\partial}{\partial \varphi} \right]$$

$$L^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right]$$

$$L^2 = -\hbar^2 \left[\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right]$$

LADDER OPERATORS $L_{\pm} = L_x \pm iL_y$

$$L_{\pm} = \pm \hbar e^{\pm i\varphi} \left[\frac{\partial}{\partial \theta} \pm i \cot \theta \frac{\partial}{\partial \varphi} \right]$$

EIGENVALUE PROBLEM

$$L^2 |l, m\rangle = l(l+1)\hbar^2 |l, m\rangle$$

$$L_z |l, m\rangle = m\hbar |l, m\rangle$$

IF H IS ROTATIONALLY INVARIANT

$$[H, L_i] = 0$$

$$[H, L^2] = 0$$

$$[H, L_z] = 0$$

(H eigenfns) = (radial eigenfns) (spherical harmonic)

LADDER OPERATOR SOLUTION

$$L^2 = \vec{L} \cdot \vec{L} = L_x^2 + L_y^2 + L_z^2$$

$$[L_i, L_j] = i\hbar \epsilon_{ijk} L_k$$

EINSTEIN
SUMMATION
OVER K .

ϵ_{ijk} CALLED TOTALLY ANTISYMMETRIC TENSOR

1 2 3

2 1 3

any two equal

2 3 1

1 3 2

3 1 2

3 2 1

$$\epsilon_{ijk} = +1$$

$$\epsilon_{ijk} = -1$$

$$\epsilon_{ijk} = 0$$

1 2 3

x y z

ANOTHER VIEW : $\epsilon_{123} = +1$

changes sign when interchange
two indices

$$[L_x, L_y] = i\hbar L_z$$

$$[L_y, L_z] = i\hbar L_x$$

$$[L_z, L_x] = i\hbar L_y$$

$$\vec{L} \times \vec{L} = i\hbar \vec{L} =$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ L_x & L_y & L_z \\ L_x & L_y & L_z \end{vmatrix}$$

CROSS PRODUCTS

$$\vec{c} = \vec{a} \times \vec{b}$$

$$c_i = \epsilon_{ijk} a_j b_k$$

EINSTEIN SUM OVER j, k .

SINCE L_x, L_y, L_z DO NOT COMMUTE...

CHOOSE L^2, L_z

RAISING AND LOWERING OPERATORS

$$L_+ = L_x + i L_y$$

$$L_- = L_x - i L_y$$

WORK OUT COMMUTATORS

$$[L^2, L_i] = 0$$

$$[L^2, L_{\pm}] = 0$$

$$[L_z, L_{\pm}] = \pm \hbar L_{\pm}$$

PROCEED AS BEFORE

$$L^2 |\alpha, \beta\rangle = \alpha |\alpha, \beta\rangle$$

$$L_z |\alpha, \beta\rangle = \beta |\alpha, \beta\rangle$$

$$[L_z, L_{\pm}] = \pm \hbar L_{\pm}$$

$$L_z L_{\pm} - L_{\pm} L_z = \hbar L_{\pm}$$

$$L_z [L_{\pm} |\alpha, \beta\rangle] = (\hbar L_{\pm} + L_{\pm} L_z) |\alpha, \beta\rangle$$

$$= (\beta + \hbar) [L_{\pm} |\alpha, \beta\rangle]$$

CONCLUDE

$L_{+} |\alpha, \beta\rangle$ is $e\vec{v}$ of L_z with $e\vec{v}$ $\beta + \hbar$

$L_{-} |\alpha, \beta\rangle$ $\beta - \hbar$

STEP SIZE = \hbar

HOW ABOUT L^2

$$[L^2, L_+] = 0$$

$$L^2 L_+ - L_+ L^2 = 0$$

$$\begin{aligned} L^2 [L_+ |\alpha, \beta\rangle] &= L_+ [L^2 |\alpha, \beta\rangle] \\ &= \alpha L_+ |\alpha, \beta\rangle \end{aligned}$$

$L_+ |\alpha, \beta\rangle$ is $e\hbar$ of L^2 with $e\hbar$ α

$L_- |\alpha, \beta\rangle$ α

NEW FEATURE!

This ladder has a top and a bottom

$$L^2 = L_x^2 + L_y^2 + L_z^2$$

$$L^2 - L_z^2 = L_x^2 + L_y^2$$

$$\begin{aligned} \langle \alpha, \beta | L^2 - L_z^2 | \alpha, \beta \rangle &= \langle \alpha, \beta | L_x^2 + L_y^2 | \alpha, \beta \rangle \\ &= \alpha - \beta^2 \end{aligned}$$

$$(\alpha - \beta^2) \langle \alpha, \beta | \alpha, \beta \rangle = \langle \alpha, \beta | L_x^2 + L_y^2 | \alpha, \beta \rangle \geq 0$$

$$\beta^2 \leq \alpha$$

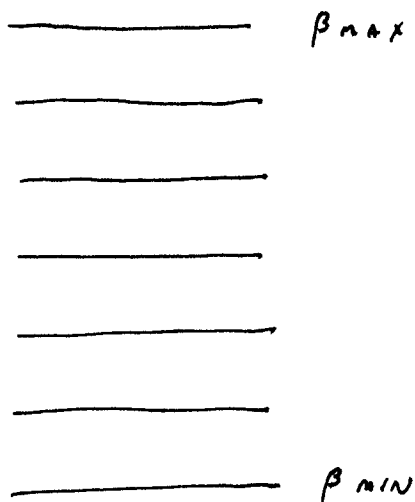
Physically, given a total angular momentum,
there is a maximum z projection

TOP AND BOTTOM TO LADDER

$$L_+ | \alpha, \beta_{\max} \rangle = 0$$

$$L_- | \alpha, \beta_{\min} \rangle = 0$$

next show $\beta_{\max} = -\beta_{\min}$



$$\beta_{\max} = \hbar j$$

$$\alpha = j(j+1) \hbar^2$$

OH, MY KOSH! WE ACCIDENTALLY SOLVED A
MORE GENERAL PROBLEM!

ORBITAL ANGULAR MOMENTUM L^2, L_z CAN
ONLY HAVE INTEGRAL L !

TOTAL ANGULAR MOMENTUM J^2, J_z CAN
HAVE INTEGER OR HALF INTEGER J ...

SPIN ANGULAR MOMENTUM S^2, S_z CAN
HAVE INTEGER OR HALF INTEGER S

$$\vec{J} = \vec{L} + \vec{S}$$

NEXT QUARTER \vec{J} , and \vec{S} :
adding angular
momentum

CLEBSCH-GORDON

COEFF'S

GRIFFITH'S QUOTE...

LET'S CONSIDER SOME EXAMPLES

If you think this is starting to sound like mystical numerology, I don't blame you. We will not be using the Clebsch-Gordon tables much in the rest of this book, but I wanted you to know where they fit into the scheme of things, in case you encounter them later on. In a mathematical sense this is all applied group theory---what we are talking about is the decomposition of the direct product of two irreducible representations of the rotation group into a direct sum of irreducible representations (you can quote that, to impress your friends).

ORBITAL ANGULAR MOMENTUM

$$l = 0, 1, 2, 3, \dots$$

$$m = -l, \dots, 0, \dots, l$$

$$L^2 |l, m\rangle = l(l+1) \hbar^2 |l, m\rangle$$

$$L_z |l, m\rangle = m \hbar |l, m\rangle$$

$$L_{\pm} |l, m\rangle = \sqrt{l(l+1) - m(m \pm 1)} \hbar |l, m \pm 1\rangle$$

SPECIAL CASES:

$$l = 0 \Rightarrow m = 0$$

$$\text{————— } |0, 0\rangle$$

$$L^2 |0, 0\rangle = 0 \hbar^2 |0, 0\rangle$$

$$L_z |0, 0\rangle = 0 \hbar |0, 0\rangle$$

$$l = 1 \quad m = -1, 0, +1$$

$$\text{-----} \quad |1, 1\rangle$$

$$\text{-----} \quad |1, 0\rangle$$

$$\text{-----} \quad |1, -1\rangle$$

$$L^2 |1, m\rangle = 1(1+1) \hbar^2 |1, m\rangle = 2 \hbar^2 |1, m\rangle$$

$$L_z |1, m\rangle = m \hbar |1, m\rangle$$

$$l = 2 \quad m = -2, -1, 0, +1, +2$$

$$\text{-----} \quad |2, 2\rangle$$

$$\text{-----} \quad |2, 1\rangle$$

$$\text{-----} \quad |2, 0\rangle$$

$$\text{-----} \quad |2, -1\rangle$$

$$\text{-----} \quad |2, -2\rangle$$

$$L^2 |2, m\rangle = 6 \hbar^2 |2, m\rangle$$

$$L_z |2, m\rangle = m \hbar |2, m\rangle$$

SEMICLASSICAL VECTOR MODEL

length of ang momentum vector $\sqrt{l(l+1)\hbar^2}$

z projection of \vec{L} $m\hbar$

$$l=1 \quad \sqrt{l(l+1)\hbar^2} = \sqrt{2}\hbar$$

$$m\hbar = -\hbar, 0, +\hbar$$

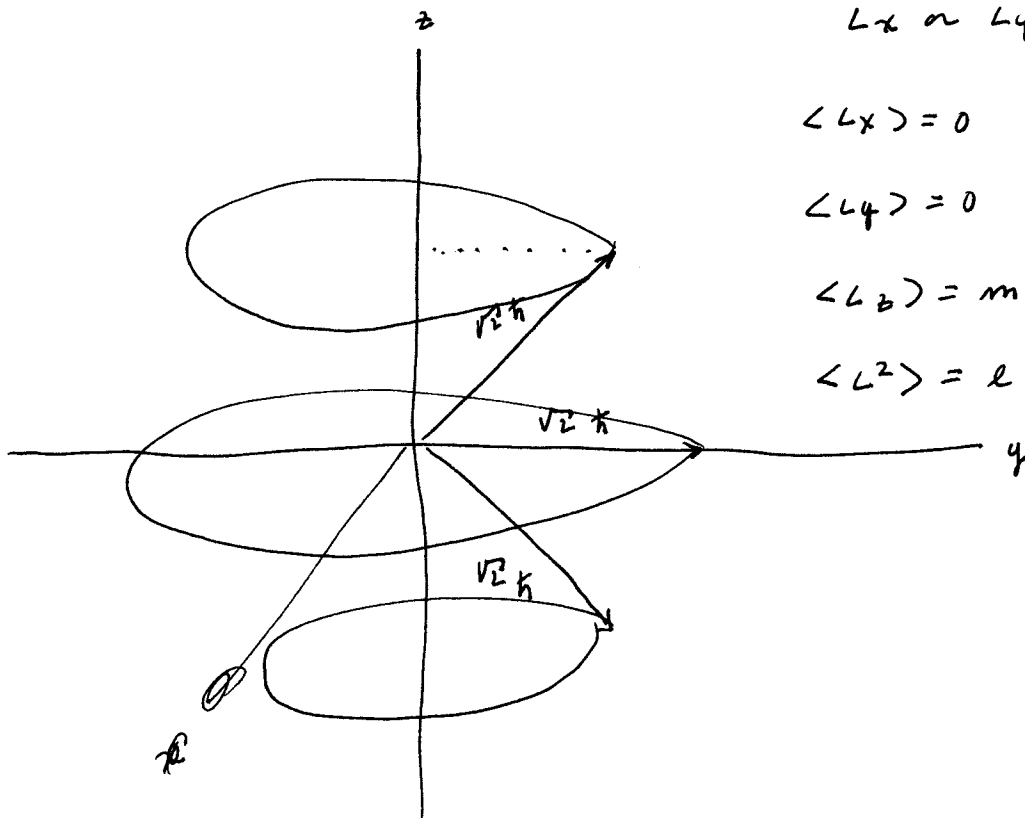
L_z does not commute with L_x or $L_y \Rightarrow$

$$\langle L_x \rangle = 0$$

$$\langle L_y \rangle = 0$$

$$\langle L_z \rangle = m\hbar$$

$$\langle L^2 \rangle = l(l+1)\hbar^2$$



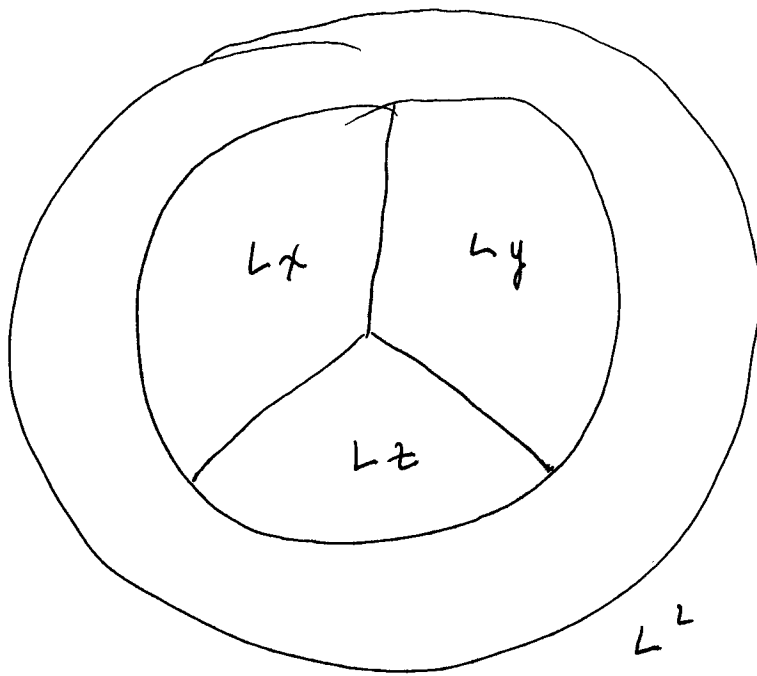
GENERALIZED UNCERTAINTY RELATION

$$\frac{(\Delta A)^2}{\sigma_A^2} \frac{(\Delta B)^2}{\sigma_B^2} \geq \left(\frac{1}{2i} \langle [A, B] \rangle \right)^2$$

$$\frac{(\Delta L_x)^2}{\sigma_{L_x}^2} \frac{(\Delta L_y)^2}{\sigma_{L_y}^2} \geq \left(\frac{1}{2i} \langle i \hbar L_z \rangle \right)^2$$

$$\geq \frac{\hbar^2}{4} \langle L_z \rangle^2$$

$$\frac{\Delta L_x}{\sigma_{L_x}} \frac{\Delta L_y}{\sigma_{L_y}} \geq \frac{\hbar}{2} | \langle L_z \rangle |$$



NEXT STEP ... go into real space

$$|l, m\rangle$$

$$\langle \theta, \varphi | l, m \rangle = Y_{lm}(\theta, \varphi)$$

$$\langle l, m | \theta, \varphi \rangle = Y_{lm}^*(\theta, \varphi)$$

$$\langle l', m' | l, m \rangle = \delta_{ll'} \delta_{mm'}$$

$$\int Y_{l'm'}^*(\theta, \varphi) Y_{lm}(\theta, \varphi) d(\cos\theta) d\varphi = \delta_{ll'} \delta_{mm'}$$

Q: HOW TO FIND ALL THE Y_{lm} 'S?

A: Solve the differential equation ... OR

JUST LIKE SHO, WE HAVE TWO CHOICES

$$L^2 |l, m\rangle = l(l+1)\hbar^2 |l, m\rangle$$

$$L_z |l, m\rangle = m\hbar |l, m\rangle$$

$$-\hbar^2 \left[\frac{\partial^2}{\partial \theta^2} + \frac{1}{\tan \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right] Y_{lm}(\theta, \varphi) =$$

$$l(l+1)\hbar^2 Y_{lm}(\theta, \varphi)$$

$$-i\hbar \frac{\partial}{\partial \varphi} Y_{lm}(\theta, \varphi) = m\hbar Y_{lm}(\theta, \varphi)$$

OR

$$L_+ Y_{ll}(\theta, \varphi) = 0 \Rightarrow Y_{ll} \begin{array}{l} \downarrow L_- \\ Y_{l, l-1} \end{array} \begin{array}{l} \downarrow L_- \\ \end{array}$$

$$L_- Y_{l-l}(\theta, \varphi) = 0 \Rightarrow Y_{l-l} \begin{array}{l} \uparrow L_+ \\ \end{array}$$

IMPORTANT TECHNIQUE # 137

SEPARATION OF VARIABLES

$$Y_{lm}(\theta, \varphi) = f_{lm}(\theta) g_{lm}(\varphi)$$

$$L_z |l, m\rangle = m\hbar |l, m\rangle$$

$$-i\hbar \frac{\partial}{\partial \varphi} (f_{lm}(\theta) g_{lm}(\varphi)) = m\hbar (f_{lm}(\theta) g_{lm}(\varphi))$$

$$-i\hbar \cancel{f_{lm}(\theta)} \frac{\partial g_{lm}(\varphi)}{\partial \varphi} = m\hbar \cancel{f_{lm}(\theta)} g_{lm}(\varphi)$$

$$\frac{\partial g}{\partial \varphi} = im g \quad \Rightarrow \quad g = e^{im\varphi}$$

So it separates ~~and~~

and it does not depend on θ

next step find $F_{\ell\ell}(\theta)$'s

$$L_+ Y_{\ell\ell}(\theta, \varphi) = 0$$

$$\cancel{e^{i\varphi}} \left[\frac{\partial}{\partial \theta} + i \cot \theta \frac{d}{d\varphi} \right] [F_{\ell\ell}(\theta) \cancel{e^{i\ell\varphi}}] = 0$$

$$\frac{dF_{\ell\ell}}{d\theta} \cancel{e^{i\ell\varphi}} + i \cot \theta F_{\ell\ell} \cancel{i\ell e^{i\ell\varphi}} = 0$$

$$\left[\frac{d}{d\theta} - \ell \cot \theta \right] F_{\ell\ell}(\theta) = 0$$

TRY $F_{\ell\ell} = A (\sin \theta)^\ell$

$$\frac{d}{d\theta} A (\sin \theta)^\ell = A (\sin \theta)^{\ell-1} \cos \theta$$

$$A (\sin \theta)^{\ell-1} \cos \theta - \ell \frac{\cos \theta}{\sin \theta} A (\sin \theta)^\ell \stackrel{?}{=} 0$$

yep!

$$\Rightarrow Y_{\ell\ell}(\theta, \varphi) = A_\ell (\sin \theta)^\ell e^{i\ell\varphi}$$

TO GET THE REST

$$L_- Y_{\ell\ell} = a Y_{\ell\ell-1}$$

then normalize using

$$\int Y_{\ell m}^* Y_{\ell m} d\Omega = 1$$

$$L_- = \hbar e^{-i\varphi} \left(\frac{d}{d\theta} + i \cot\theta \frac{d}{d\varphi} \right)$$

SPHERICAL HARMONICS

$$\ell = 0$$

$$Y_{00}(\theta, \varphi) = \langle \theta, \varphi | 0, 0 \rangle = \frac{1}{\sqrt{4\pi}}$$

$$\int \left(\frac{1}{\sqrt{4\pi}} \right)^* \frac{1}{\sqrt{4\pi}} d\Omega = 1 \quad \checkmark$$

$$l=1$$

$$Y_{1,1}(\theta, \varphi) = \sqrt{\frac{3}{8\pi}} \sin \theta e^{i\varphi}$$

$$Y_{1,0}(\theta, \varphi) = \sqrt{\frac{3}{4\pi}} \cos \theta$$

$$Y_{1,-1}(\theta, \varphi) = \sqrt{\frac{3}{8\pi}} \sin \theta e^{-i\varphi}$$

note symmetry

$$l=2$$

$$Y_{2,\pm 2}(\theta, \varphi) = \sqrt{\frac{15}{32\pi}} (\sin \theta)^2 e^{\pm 2i\varphi}$$

$$Y_{2,\pm 1}(\theta, \varphi) = \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{\pm i\varphi}$$

$$Y_{2,0}(\theta, \varphi) = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$$