

L22 : Feb. 25, 2015

ME565, Winter 2015

## Overview of Topics

① Laplace Transforms and ODEs

$$\text{ODE} \xrightarrow{\mathcal{L}} \text{Algebraic Eq}^n$$

Recall that  $\mathcal{L}\{f'(t)\} = s\bar{f}(s) - f(0)$

$$\mathcal{L}\{f''(t)\} = s\mathcal{L}\{f'(t)\} - f'(0)$$

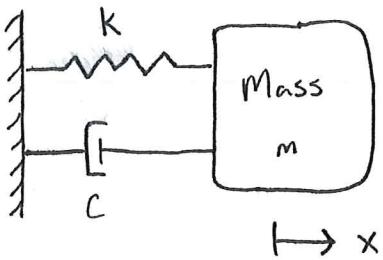
$$= s^2 \bar{f}(s) - sf(0) - f'(0)$$

Each '0' is technically  
 $\bar{0}$  ... the point just  
before  $t=0$ .

In general:  $\mathcal{L}\{f^{(n)}(t)\} = s^n \bar{f}(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - s f^{(n-2)}(0) - f^{(n-1)}(0)$ .

Extremely useful for solving ODEs

Example: Spring - Mass - Damper



$$m \ddot{x} + c \dot{x} + kx = 0$$

$$\omega_0 = \sqrt{k/m}$$

$$\zeta = c/(2\sqrt{km})$$

$$\ddot{x} + 2\zeta\omega_0 \dot{x} + \omega_0^2 x = 0$$

Lets solve for the following values:

$$\ddot{x} + 5\dot{x} + 4x = 0 \quad ; \quad x(0) = 2 \quad ; \quad \dot{x}(0) = -5$$

Laplace Transform:

$$\underbrace{s^2 \bar{x}(s)}_{\mathcal{L}\{\ddot{x}\}} - s x(0) - \dot{x}(0) + \underbrace{5(s \bar{x}(s) - x(0))}_{5\mathcal{L}\{\dot{x}\}} + \underbrace{4 \bar{x}(s)}_{4\mathcal{L}\{x\}} = 0$$

Collect  $\bar{x}(s)$  terms:

$$\underbrace{(s^2 + 5s + 4)}_{\text{Polynomial in } s} \bar{x}(s) = \underbrace{s(x(0)) + 5x(0) + \dot{x}(0)}_{\text{Polynomial in } s}$$

Initial conditions (just numbers...)

(characteristic polynomial)  
(dynamics)

Partial Fractions...

$$\bar{x}(s) = \frac{2s + 5}{s^2 + 5s + 4} = \frac{2s + 5}{(s+1)(s+4)} = \frac{1}{s+1} + \frac{1}{s+4}$$

Because linear superposition:  $x(t) = \mathcal{L}^{-1}\{\bar{x}(s)\} = \mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} + \mathcal{L}^{-1}\left\{\frac{1}{s+4}\right\}$

$$x(t) = e^{-t} + e^{-4t}$$

# Simple Example (Boyce & DiPrima)

$$\ddot{x} - \dot{x} - 2x = 0, \quad x(0) = 1, \quad \dot{x}(0) = 0$$

$$s^2 \bar{x}(s) - s x(0) - \dot{x}(0) - (s \bar{x}(s) - x(0)) - 2 \bar{x}(s) = 0$$

$$(s^2 - s - 2) \bar{x}(s) = s - 1$$

$$\begin{aligned} \bar{x}(s) &= \frac{s-1}{s^2 - s - 2} = \frac{s-1}{(s-2)(s+1)} = \frac{a}{s-2} + \frac{b}{s+1} \\ &= \frac{a(s+1) + b(s-2)}{(s-2)(s+1)} \end{aligned}$$

$$\text{so } a(s+1) + b(s-2) = s-1 \quad (\text{numerators must be equal...})$$

$$\left. \begin{array}{l} (a+b)s = s \\ a-2b = -1 \end{array} \right\} \quad \left. \begin{array}{l} a+b = 1 \\ a-2b = -1 \end{array} \right\} \quad \begin{aligned} 3b = 2 &\Rightarrow b = 2/3 \\ &\Rightarrow a = 1/3 \end{aligned}$$

$$\bar{x}(s) = \frac{1}{3} \cdot \frac{1}{s-2} + \frac{2}{3} \cdot \frac{1}{s+1}$$

$$x(t) = \frac{1}{3} \mathcal{L}^{-1} \left\{ \frac{1}{s-2} \right\} + \frac{2}{3} \mathcal{L}^{-1} \left\{ \frac{1}{s+1} \right\}$$

$$x(t) = \frac{1}{3} e^{2t} + \frac{2}{3} e^{-t}$$

# General Procedure:

I.

Well-posed  
ODE with  
Initial  
Conditions

$$\begin{aligned} x^{(n)} + a_{n-1}x^{(n-1)} + \dots + a_2\ddot{x} + a_1\dot{x} + a_0x &= 0 \\ x(0) &= b_0 \\ \dot{x}(0) &= b_1 \\ \vdots &\vdots \\ x^{(n-1)}(0) &= b_{n-1} \end{aligned}$$

II.

Laplace + form  
all terms

$$\underbrace{\left[ s^n \bar{x}(s) - \dots - b_{n-1} \right]}_{\mathcal{L}\{x^{(n)}\}} + a_{n-1} \underbrace{\left[ s^{n-1} \bar{x}(s) - \dots - b_{n-2} \right]}_{\mathcal{L}\{x^{(n-1)}\}} + \dots + a_1 \underbrace{\left[ s \bar{x}(s) - b_0 \right]}_{\mathcal{L}\{\dot{x}\}} + a_0 \bar{x}(s) = 0$$

III.

Collect all terms  
with  $\bar{x}(s)$  and  
separate from  
I.C. terms

$$\underbrace{\left( s^n + a_{n-1}s^{n-1} + \dots + a_2s^2 + a_1s + a_0 \right) \bar{x}(s)}_{\text{Characteristic polynomial}} = \text{polynomial in 's' with coefficients given by a's and b's...}$$

Captures all dynamics

This polynomial accounts for all initial conditions.

$$\triangleq P(s; a, b)$$

IV.

Isolate solution  
 $\bar{x}$

$$\bar{x}(s) = \frac{P(s; a, b)}{s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0}$$

find roots of denominator (i.e. eigenvalues)

solve for  $c_1, c_2, \dots, c_n$  using  
method of partial fractions

V.  
Partial Fractions.

$$\bar{x}(s) = \frac{c_1}{(s+\lambda_1)} + \frac{c_2}{(s+\lambda_2)} + \dots + \frac{c_n}{(s+\lambda_n)}$$

VI.  
Solution

$$x(t) = c_1 e^{-\lambda_1 t} + c_2 e^{-\lambda_2 t} + \dots + c_n e^{-\lambda_n t}$$

Solution.

What if our ODE is forced?

$$\ddot{x} + 5\dot{x} + 4x = u(t)$$

$$x(0) = 2$$

$$\dot{x}(0) = -5$$

↑  
forcing term ... inhomogeneous ... basis for all of control theory!

$$\mathcal{L}\{\cdot\} \Rightarrow (s^2 + 5s + 4)\bar{x}(s) = \underbrace{2s+5}_{\text{Initial Conditions}} + \underbrace{\bar{u}(s)}_{\text{Forcing!}}$$

$$\bar{x}(s) = \frac{2s+5}{s^2 + 5s + 4} + \frac{\bar{u}(s)}{s^2 + 5s + 4}$$

$$G(s) = \frac{1}{s^2 + 5s + 4}$$

is called the "transfer function"

$$\bar{x}(s) = \frac{1}{s+1} + \frac{1}{s+4} + G(s) \bar{u}(s)$$

$$x(t) = \underbrace{e^{-t} - e^{-4t}}_{\text{Homogeneous soln}} + \underbrace{\mathcal{L}^{-1}\{G(s)\} * u(t)}_{\text{Particular soln...}}$$