

L07: Jan 21, 2015

ME565, Winter 2015

Overview of Topics

① PDEs

- types, construction, etc.

② Canonical PDEs

- Laplace's Equation

- Wave Equation

- Heat Equation

Partial Differential Equations (PDEs)

A partial differential equation is an equation relating multivariate functions and their partial derivatives.

Often the multivariate function "u" is a function of time and space

function $u(x, t)$
space time

Example PDE: $\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$ (Wave eq.ⁿ
more on this later...)

We typically solve the PDE for the unknown function "u", which generally has a physical interpretation

Note: We often denote partial derivatives with subscript: $u_t \triangleq \frac{\partial u}{\partial t}$

Canonical Partial Differential Equations:

Linear: No products or cross-terms between $u, u_x, u_{xx}, \dots$

Second Order: No more than 2 derivatives in any term

Homogeneous: No time dependent forcing or spatial forcing.

I. Wave Equation (hyperbolic)

$$u_{tt} = c^2 \nabla^2 u$$

$$u_{tt} = c^2 u_{xx}$$

II. Heat Equation (parabolic)

$$u_t = \alpha^2 \nabla^2 u$$

$$u_t = \alpha^2 u_{xx}$$

III. Laplace's Equation (elliptic)

$$0 = \nabla^2 u$$


General Vector
Form

$$u_{xx} + u_{yy} = 0$$


Specific Form for
2 Independent Variables.

Note: In each example, u is a scalar function of multiple variables.

Linear PDEs are built up using Linear Operators "L":

① multiplication by a constant: $L_1(u) = 5u$

② partial derivative: $L_2(u) = \partial u / \partial x$

$$\text{So } L_1(L_2(u)) = 0 \Rightarrow 5 \partial u / \partial x = 0.$$

Linearity means that A $L(u_1 + u_2) = L(u_1) + L(u_2)$ for all u_1, u_2
and B $L(au_1) = aL(u_1)$ for all u_1 and constant a .

Examples above: $L_1(u_1 + u_2) = 5(u_1 + u_2) = 5u_1 + 5u_2 = L_1(u_1) + L_1(u_2)$ ✓

$$L_1(au) = 5(au) = a5u = aL_1(u) \quad \checkmark$$

$$L_2(u_1 + u_2) = \frac{\partial}{\partial x}(u_1 + u_2) = \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial x} = L_2(u_1) + L_2(u_2) \quad \checkmark$$

$$L_2(au) = \frac{\partial}{\partial x}(au) = a \frac{\partial u}{\partial x} = aL_2(u) \quad \checkmark$$

What about ③ addition by constant: $L_3(u) = u + 7$?

$$L_3(u_1 + u_2) = u_1 + u_2 + 7 \neq L_3(u_1) + L_3(u_2) = u_1 + u_2 + 14.$$

So L_3 is NOT linear. L_3 is called an Affine Linear Operator.

We have tons of tools to solve (and understand)
linear PDEs.

In general, nonlinear PDEs are much more difficult,
although many important physical systems are nonlinear.

Examples of Nonlinearity:

Squaring, cubing, etc:

$$N(u) = u^2$$

$$N(u_1 + u_2) = (u_1 + u_2)^2 = \underbrace{u_1^2 + u_2^2}_{N(u_1) + N(u_2)} + 2u_1 u_2 \quad \times$$

extra terms!

Products:

$$N(u) = u \cdot u_x$$

$$N(u_1 + u_2) = (u_1 + u_2) \cdot \frac{\partial}{\partial x}(u_1 + u_2) = u_1 u_{1x} + \underbrace{u_1 u_{2x}}_{\text{extra terms}} + \underbrace{u_2 u_{1x}}_{\text{extra terms}} + u_2 u_{2x} \quad \times$$

$\neq u_1 u_{1x} + u_2 u_{2x}$

Absolute Value:

$$N(u) = |u|$$

$$N(5-7) = |-2| = 2$$

$$N(5) + N(-7) = 5 + 7 = 12 \quad \times$$

Important Example: Burger's Equation (canonical example w/ shock waves)

↙ nonlinear convection produces shocks

$$u_t + u u_x = \nu u_{xx} \quad \leftarrow \text{viscous diffusion spreads shocks}$$

$$\left(\vec{u}_t + \vec{u} \cdot \nabla \vec{u} = \nu \nabla^2 \vec{u} \right) \leftarrow \text{vector form} \dots$$