

Overview of Topics

- ① Taylor Series and $\dot{x} = \lambda x$
- ② What is a Taylor Series (Matlab)
- ③ Second order systems

$$\ddot{x} + x = 0$$

- Harmonic oscillator, spring-mass

- Try Taylor Series

- Suspend variables (Next Lecture?)

Next
Lecture

$$\begin{aligned} \dot{x} &= v \\ \dot{v} &= -x \end{aligned} \Rightarrow \frac{d}{dt} \begin{bmatrix} x \\ v \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ v \end{bmatrix} \text{ (Linear!)}$$

$$\dot{X} = aX \quad \Rightarrow \quad X(t) = e^{at} X(0)$$

What is e^t ?

$$X = c_0 + c_1 t + c_2 t^2 + c_3 t^3 + c_4 t^4 + \dots$$

$$\dot{X} = c_1 + 2c_2 t + 3c_3 t^2 + 4c_4 t^3 + \dots$$

$$aX = ac_0 + ac_1 t + ac_2 t^2 + ac_3 t^3 + ac_4 t^4 + \dots$$

$\dot{X} = aX$ match each power of "t"

$$\underline{t^0=1} : c_1 = ac_0 = aX_0 \quad \text{since } X(0) = c_0 \\ = aX_0$$

$$\underline{t^1} : 2c_2 = ac_1 \Rightarrow c_2 = \frac{1}{2} a^2 X_0$$

$$\underline{t^2} : 3c_3 = ac_2 \Rightarrow c_3 = \frac{1}{3 \cdot 2} a^3 X_0$$

$$\underline{t^3} : 4c_4 = ac_3 \Rightarrow c_4 = \frac{1}{4 \cdot 3 \cdot 2} a^4 X_0$$

$$\vdots \\ c_k = \frac{1}{k!} a^k X_0$$

$$X(t) = X_0 + at X_0 + \frac{a^2 t^2}{2!} X_0 + \frac{a^3 t^3}{3!} X_0 + \dots + \frac{a^k t^k}{k!} X_0 + \dots$$

$$= e^{at} X_0$$

Taylor
Series Solution
to $\dot{X} = aX$

Taylor Series

A function $f(x + \Delta x)$ may be Taylor expanded about a base point x (assuming f is smooth at x)

$$f(x + \Delta x) = f(x) + \frac{df}{dx}(x) \cdot \Delta x + \frac{1}{2!} \frac{d^2 f}{dx^2}(x) \cdot \Delta x^2 + \frac{1}{3!} \frac{d^3 f}{dx^3}(x) \cdot \Delta x^3 + \text{h.o.t.}$$

$\mathcal{O}(\Delta x^4)$

h.o.t. = higher order terms

OR $f(x)$ expanded about a point "a":

$$f(x) = f(a) + \frac{df}{dx}(a)(x-a) + \frac{1}{2!} \frac{d^2 f}{dx^2}(a)(x-a)^2 + \dots \text{ h.o.t.}$$

Example: $f(x) = \sin(x)$

Taylor expand about $x=0$ (Maclaurin series)

$$f(x) = \sin(0) + x \cos(0) - \frac{x^2}{2!} \sin(0) - \frac{x^3}{3!} \cos(0) + \frac{x^4}{4!} \sin(0) + \frac{x^5}{5!} \cos(0) + \dots$$

$$= x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots \text{ forever.}$$

(MATLAB EXAMPLE)

Example: $f(x) = \cos(x)$

$$f(x) = \cos(0) - x \sin(0) - \frac{x^2}{2!} \cos(0) + \frac{x^3}{3!} \sin(0) + \dots$$

$$= 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$$

3/6

```
clear all; close all
x = -10:.01:10;
y = sin(x);
plot(x,y,'k','LineWidth',2)
axis([-10 10 -10 10])
grid on, hold on

%% First-order Taylor expansion
P = [1 0]; % x + 0;
yT1 = polyval(P,x);
plot(x,yT1,'b--','LineWidth',1.2)

%% Third-order Taylor expansion
P = [-1/factorial(3) 0 1 0]; % -(1/3!)x^3 + x + 0;
yT3 = polyval(P,x);
plot(x,yT3,'r--','LineWidth',1.2)

%% Fifth-order Taylor expansion
P = [1/factorial(5) 0 -1/factorial(3) 0 1 0]; % -(1/3!)x^3 + x + 0;
yT5 = polyval(P,x);
plot(x,yT5,'g--','LineWidth',1.2)

%% Seventh-order Taylor expansion
P = [-1/factorial(7) 0 1/factorial(5) 0 -1/factorial(3) 0 1 0]; % -(1/3!)x^3 + x + 0;
yT7 = polyval(P,x);
plot(x,yT7,'m--','LineWidth',1.2)

%% Ninth-order Taylor expansion
P = [1/factorial(9) 0 -1/factorial(7) 0 1/factorial(5) 0 -1/factorial(3) 0 1 0]; % -(1/3!)x^3 + x + 0;
yT9 = polyval(P,x);
plot(x,yT9,'c--','LineWidth',1.2)
```

Taylor Series Example: $f(x) = e^x$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots \text{ h.o.t.} = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

$$e^{ix} = 1 + ix + \frac{(ix)^2}{2!} + \frac{(ix)^3}{3!} + \frac{(ix)^4}{4!} + \frac{(ix)^5}{5!} + \dots$$

$$= 1 + ix - \frac{x^2}{2!} - \frac{ix^3}{3!} + \frac{x^4}{4!} + i \frac{x^5}{5!} + \dots$$

Even terms = $\cos(x)$

Odd terms = $i \sin(x)$

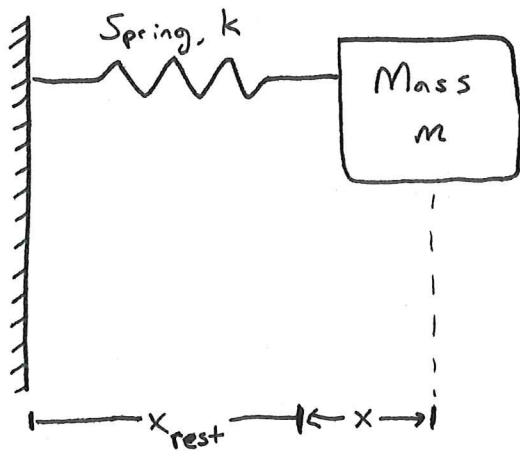
$$e^{ix} = \cos(x) + i \sin(x)$$

Euler's Formula!

FYI ... anything with Euler's name

is a big deal.

Second-order systems



Newton's 2nd Law:

$$F = ma$$

$$= m\ddot{x}$$

$$\Rightarrow \boxed{m\ddot{x} = -kx}$$

x is the displacement of the mass from a rest position x_{rest} , where spring exerts no net force.

First consider $k=m=1 \Rightarrow \boxed{\ddot{x} = -x}$ end L03

Method 1: Guess!

$$x(t) = \cos(t) x(0)$$

$$\dot{x}(t) = -\sin(t) x(0)$$

$$\ddot{x}(t) = -\cos(t) x(0) \quad \checkmark \quad \ddot{x} = -x$$

L04 start.

For general m, k :

$$x(t) = \cos\left(\sqrt{\frac{k}{m}} t\right) x(0)$$

so frequency of oscillation is $\omega = \sqrt{\frac{k}{m}}$