

**Exercise 5–1:** Lets say that we are integrating the following stable ODE:

$$\dot{\mathbf{x}} = \begin{bmatrix} -2 & 0 \\ 0 & -4 \end{bmatrix} \mathbf{x}$$

- If we are using a forward Euler scheme, for what  $\Delta t > 0$  will the resulting simulation become unstable?
  - If we use the backward Euler scheme, for what  $\Delta t > 0$  will the simulation become unstable?
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**Exercise 5–2:** A (real valued) inner product space is a vector space that has an inner product  $\langle \mathbf{x}, \mathbf{y} \rangle$  that satisfies the following three axioms:

- $\langle \mathbf{x}, \mathbf{y} \rangle = \langle \mathbf{y}, \mathbf{x} \rangle$ ,
- $\langle a\mathbf{x}, \mathbf{y} \rangle = a\langle \mathbf{x}, \mathbf{y} \rangle$ , for all real numbers  $a \in \mathbb{R}$ ,
- $\langle \mathbf{x}, \mathbf{x} \rangle \geq 0$ , with equality only if  $\mathbf{x} = 0$ .

Consider the space of bounded functions on the interval  $[0, 1]$  with the following inner product

$$\langle f, g \rangle = \int_0^1 f(x)g(x)dx.$$

Bounded just means that the magnitude of both  $f$  and  $g$  never exceed some fixed large number on the interval  $[0, 1]$ . You can approximate this inner product in Matlab by defining the two vectors  $f$  and  $g$  on a discrete grid from 0 to 1.

- Verify that this space of functions and inner product satisfy the following three axioms above.
- Show that the functions  $\cos(\pi mx)$  and  $\cos(\pi nx)$  for non-negative integers  $m$  and  $n$  are orthogonal (using the inner product above) for all  $m \neq n$ . You may find the following identify useful:  $\cos(\alpha)\cos(\beta) = \frac{1}{2}[\cos(\alpha - \beta) + \cos(\alpha + \beta)]$ .
- Plot  $\cos(\pi mx)$  on the interval  $[0, 1]$  with  $dx = 0.01$  for  $m = 0, 1, 2, 3, 4$ , and 5. Verify numerically, using trapezoidal integration (i.e. `trapz`), that  $\cos(\pi mx)$  and  $\cos(\pi nx)$  are orthogonal for the following  $(m, n)$  pairs:  $(1, 4)$ ,  $(2, 6)$ , and  $(3, 15)$ .

Note that we have an *infinite* set of orthogonal functions, which each represent a unique and orthogonal *vector direction* in the inner product space of bounded functions on  $[0, 1]$ . We are starting to build an infinite dimensional vector space (called a Hilbert space) for representing functions. These functions will be the solutions of PDEs in ME565. (Note that we will eventually need to include sine functions as well.)

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