

key

Once you have completed the exam, consider reflecting on your performance. The point value for each question is indicated inside a bracket at the start of each problem. The total exam is worth 45 points. You are to guess what your final score on this exam will be (either figuring it out question by question or with a holistic determination). The student(s) closest to their raw earned score will receive 1 bonus point. There is no penalty for guessing.

1. True/False: If the statement is *always* true, give a *brief* explanation of what it is (not a "formal proof"). If the statement is false, give a counterexample.

(a) [4] The set  $X = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mid x_1 + x_2 + x_3 \text{ is odd} \right\}$  is a subspace of  $\mathbb{R}^3$ .

False (+1)

nonempty b/c  $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \in X \checkmark$

closed under addition? No!  $\nabla$

note  $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 2 \end{bmatrix}$

but  $0+0+2$  is not odd so  $(0\ 0\ 2)^T \notin X$

- (b) [4] Given  $n \times n$  matrices  $A$  and  $B$ , if  $AB$  equals the zero matrix, then either  $A$  or  $B$  is the zero matrix.

False (+1)

consider  $A = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$

then  $AB = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

even though neither  $A$  or  $B$

- (c) [4] Let  $S = \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  be a spanning set for a vector space  $\mathbb{R}^3$  and  $\vec{v}_4 \in \mathbb{R}^3$ . Then  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$  is a spanning set for the vector space  $\mathbb{R}^3$  as well.

True (+1)

To show  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$  is a spanning set for  $\mathbb{R}^3$  we need to show for any  $\vec{z} \in \mathbb{R}^3$  that  $\exists c_1, c_2, c_3, c_4$

$\vec{z} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 + c_4 \vec{v}_4$

Since  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  spans  $\mathbb{R}^3 \exists b_1, b_2, b_3$   $\vec{z} = b_1 \vec{v}_1 + b_2 \vec{v}_2 + b_3 \vec{v}_3 + 0 \cdot \vec{v}_4$

$\vec{z} = b_1 \vec{v}_1 + b_2 \vec{v}_2 + b_3 \vec{v}_3 = b_1 \vec{v}_1 + b_2 \vec{v}_2 + b_3 \vec{v}_3 + 0 \cdot \vec{v}_4$

we thus have the scalars.  $\smile$

DHW 3.2 # 2

DHW 3.1 # 3

DHW 3.2 # 17

stat (+.5)  
logic (+1)  
sense/style (+.5)  
def of subspace (+1)

stat (+.5)  
logic (+1)  
sense/style (+.5)  
matrix mult/zeromatrix (+1)

stat (+.5)  
logic (+1)  
sense/style (+.5)  
span set def (+1)

2. [8] Assume that  $x$ ,  $y$ , and  $z$  are nonzero real numbers.

Let  $A = \begin{bmatrix} 1 & 3 \\ 0 & x \\ y & 2 \end{bmatrix}$ ,  $B = \begin{bmatrix} -1 & y \\ x & 2 \\ 5 & 1 \end{bmatrix}$ , and  $C = \begin{bmatrix} 2 & -3 & 0 & 1 \\ z & 0 & 0 & 2 \end{bmatrix}$ , and  $D = \begin{bmatrix} -1 \\ 0 \\ z \end{bmatrix}$ .

Perform each of the following computations or indicate that the operations is not defined:

DHW  
§.3 #12

substhan  
+1.5

(a)  $B^T$

$$\begin{bmatrix} -1 & x & 5 \\ y & 2 & 1 \end{bmatrix}$$

switch rows & columns

(+1.5)

got it (+1.5)

(b)  $A + B$

3x2 size + 3x2 size should work?

(+1.5)

$$\begin{bmatrix} 1 & 3 \\ 0 & x \\ y & 2 \end{bmatrix} + \begin{bmatrix} -1 & y \\ x & 2 \\ 5 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 3+y \\ x & 2+x \\ 5+y & 3 \end{bmatrix}$$

got it (+1.5)

(c)  $AC$

3x2 times 2x4 should give a 3 by 4

(+1.5)

$$\begin{bmatrix} 1 & 3 \\ 0 & x \\ y & 2 \end{bmatrix} \begin{bmatrix} 2 & -3 & 0 & 1 \\ z & 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 2+3z & -3 & 0 & 7 \\ xz & 0 & 0 & 2x \\ 2y+2z & -3y & 0 & y+4 \end{bmatrix}$$

got it (+1.5)

mult dg (+1)

(d)  $CA$

2x4 times 3x2 will not be defined?

(recall the # of col in the left matrix must equal # of rows in the right matrix to multiply)

(+1)

substhan  
+1.5

(e)  $\det(C)$

(+1)

$C$  is a 2 by 4 matrix but determinants are only defined for square matrices

3. Consider the augmented matrix  $X = \left[ \begin{array}{cccccc|c} 1 & -1 & 2 & 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 & -1 & 0 & b-c \\ 0 & 0 & 0 & 0 & 0 & 0 & c+a-b \end{array} \right]$

(a) [3] What minimal restriction are required on scalars  $a, b,$  and  $c$  to make  $X$  consistent.

start (+.5)  
sense (+1)  
need  $c+a-b=0$  (+1)  
or  $a=b-c$   
the above system would become  
on topic (+.5)

$$\left[ \begin{array}{cccccc|c} 1 & -1 & 2 & 0 & 0 & 1 & a \\ 0 & 0 & 0 & 1 & -1 & 0 & b-c \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

(b) [5] Assume that  $a = b = c = 0$ , write the solution set for the associated system of equations defined by  $X$ .

use 0 (+.5)  
set up free variables (+1)  
interpret as system (+1)  
write  $x_1, x_4$   
notation (+1)  
sense (+.5)  
so considering  $x_1, x_2, x_3, x_4, x_5, x_6$   
Call these  $s, t, u, v$  respectively  
Then  $x_1 - s + 2t + v = 0$  and  $x_4 - u = 0$   
 $\Rightarrow x_1 = s - 2t - v$  and  $x_4 = u$   
answer is a set (+.5)  
get it (+.5)

$$\left[ \begin{array}{cccccc|c} 1 & -1 & 2 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\Rightarrow \begin{cases} s-2t-v \\ s \\ t \\ u \\ v \end{cases} \mid s, t, u, v \in \mathbb{R}$$

4. Let  $A = \begin{bmatrix} 3 & 6 & 12 \\ 1 & 1 & 1 \\ 2 & 4 & 8 \end{bmatrix}, B = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$ .

(a) [3] Determine the elementary row operations to reduce the matrix  $A$  to  $B$ .

$$\begin{bmatrix} 3 & 6 & 12 \\ 1 & 1 & 1 \\ 2 & 4 & 8 \end{bmatrix} \xrightarrow[\frac{1}{2}R_3]{\frac{1}{3}R_1} \begin{bmatrix} 1 & 2 & 4 \\ 1 & 1 & 1 \\ 1 & 2 & 4 \end{bmatrix} \xrightarrow{R_3 - R_1} \begin{bmatrix} 1 & 2 & 4 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$$

(b) [3] Then find the matrix  $E$ , a product of elementary matrices, so that  $EA = B$ . You may leave  $E$  in factored form.

DHW 4 #1.5  
correspond to (+.5)  
order (+.5)

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{1}{3} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(c) [2] Find the determinant of  $E$ .

DHW 6 #2.2 #3  
then just multiply (+1)  
since  $\det(AB) = \det(A)\det(B)$   
we can find the determinant of the factor matrices above and  
 $(1)(-1)(1)(\frac{1}{2})(\frac{1}{3}) = -\frac{1}{6}$  get it (+.5)

justification for each is stated (+.5)

Midterm Review on Day 11  
stuff +.5  
sense +.5

5. [5] Grade the following proof on clarity (scale between 0 and 3) and accuracy/correctness (scale between 0 and 4). Justify your scores by indicating what was done well or what can be improved upon (it's likely that there will be a mix of such comments!).

good/accurate connection made here

Let  $A$  and  $B$  be  $n \times n$  invertible matrices, we will show that  $AB$  is nonsingular.

good intro/outline

Recall that a matrix  $AB$  is nonsingular if the inverse,  $(AB)^{-1}$  exists. To complete the proof thus suffices to show that  $(AB)^{-1}$  exists.

needs to say  $A^{-1}$  exists  
Does not follow? what is

Since we are assuming that  $A$  and  $B$  are invertible matrices, we know  $AA^{-1} = A^{-1}A = I$  and that  $BB^{-1} = B^{-1}B = I$ , thus  $A$  and  $B$  commute.

could make this much easier to read.

Consider the element  $A^{-1}B^{-1}$ . We will show  $A^{-1}B^{-1}$  is the inverse to  $AB$ . We compute:

$$(AB)(A^{-1}B^{-1}) = ABA^{-1}B^{-1} \text{ (since matrix multiplication is associative)}$$

$$ABA^{-1}B^{-1} = BAA^{-1}B^{-1} \text{ (since we know } A \text{ and } B \text{ commute)}$$

$$B(AA^{-1})B^{-1} = BIB^{-1} \text{ (since } AA^{-1} = I)$$

$$BIB^{-1} = BB^{-1} \text{ (since } I \text{ is the multiplicative identity)}$$

$$BB^{-1} = I \text{ (by definition of } B^{-1})$$

like the words linked to the algebraic steps

good conclusion

Thus we have shown that  $A^{-1}B^{-1}$  is the inverse to  $AB$  meaning that  $AB$  is nonsingular, which is what we wanted to show.

Accuracy/correctness 3

Definition of inverse is correct  
Matrix multiplication is not generally commutative - you showed that  $A$  and  $A^{-1}$  commute and that  $B$  and  $B^{-1}$  commute. Nothing was shown about  $A$  and  $B$ .

specific ex

Clarity 2 or 3

lots of narration? "remember to introduce terms before you use them (like  $A^{-1}$ )"  
consider lining up "=" signs & only writing the right side

logic error  
1.5

6. [4] Take one (mathematical, technical, or social!) problem you have worked on this quarter that you struggled to understand and solve, and explain how the struggle itself was valuable.

Midterm Review start Day 11  
describe problem +1  
struggle usefulness +1  
sense +1