Name: Your name here
Due to Canvas by 11:00pm PDT on the due date.
To submit, see https://canvas.uw.edu/courses/1271892/assignments/4833214

- This final project is worth 65 points (same weight as the midterm).
- Some additional extra credit problems will be available soon.
- The description is long and has many parts, but much of the code you'll need is similar to things you have already written or that is provided in class notebooks.
- Please submit Python codes or notebooks for all the problems.
- Please write up your results nicely, preferably typeset and/or in Jupyter notebooks, but this is not required. Ideally you might turn in a single notebook that works through all the problems with appropriate discussion added in between. However you write it up, please organize things well and provide some discussion.

First consider the ODE

$$
\begin{equation*}
v^{\prime}(t)=\frac{1}{\epsilon} g(v) \tag{1}
\end{equation*}
$$

where

$$
\begin{equation*}
g(v)=v(\alpha-v)(v-1) \tag{2}
\end{equation*}
$$

with $0<\alpha<1$.
This equation has three possible steady state solutions: $v(t) \equiv 0, v(t) \equiv \alpha, v(t) \equiv 1$. The middle one is an unstable steady state. If $v(0)=\alpha+\delta$ with $\delta$ small but nonzero, then $v(t)$ moves away from $\alpha$, towards 0 if $\delta<0$ or towards 1 if $\delta>0$. These are the two stable steady states. The parameter $\epsilon>0$ controls the rate of decay towards these steady states. For small $\epsilon$ the solution moves rapidly towards 0 or 1 .

## Problem 1.

Set $\alpha=0.3$ and $\epsilon=1$. Use scipy.integrate.odeint (or scipy.integrate.solve_ivp if you prefer) in Python to plot solutions curves $v(t)$ for several different initial values $v(0)$ lying between 0 and 1 , in particular for $\mathrm{v} 0=\operatorname{linspace}(0,1,11)$. Plot all these curves $v(t)$ for $0 \leq t \leq 10$ on a single plot.
Produce similar plots for $\epsilon=0.1$ and $\epsilon=0.05$.

## Problem 2.

(a) Implement the Forward Euler method to solve this problem. Since it is a scalar nonlinear problem, the Jacobian is simply the derivative of the right-hand side in (1). Based on this function and assuming $v$ stays between 0 and 1 , estimate the stability limit for Forward Euler as a function of $\epsilon$ for $\alpha=0.3$. Experiment with different values of $\epsilon$ and different time steps to see if this gives reasonable guidance and provide some plots and discussion. Is it reasonable to assume $v$ stays within these bounds?
(b) Do the same for the 2-stage explicit Runge-Kutta method given by (5.30) in the book. Explain any curious behavior, in particular with $\epsilon=0.01, \eta=0.6$, and 22 time steps (up to $t=1$ ) you should obtain something like this figure:


Why does it seem to tend to a non-physical steady state with this method? Can you determine the value it tends to from the ODE and method?
(c) Implement the Backward Euler method for this problem and confirm that it remains stable and behaves well for much larger time steps that what would be allowed by the explicit methods.

The Allen-Cahn Equation. We can turn (1) into a PDE in one space dimension and time by letting $v(x, t)$ vary in space and adding spatial diffusion, obtaining

$$
\begin{equation*}
v_{t}(x, t)=\kappa v_{x x}(x, t)+\frac{1}{\epsilon} g(v) \tag{3}
\end{equation*}
$$

This is a scalar reaction-diffusion equation, a variant of the Allen-Cahn equation that is used as a simple model of phase transition.

The lower stable steady state at $v=0$ corresponds to a material in one phase (e.g. solid) while the upper stable steady state at $v=1$ corresponds to a different phase (e.g. liquid).
Consider initial data

$$
v(x, 0)= \begin{cases}1 & \text { if } x<0  \tag{4}\\ 0 & \text { if } x \geq 0\end{cases}
$$

and the Cauchy problem on $-\infty<x<\infty$ so we don't have to worry about boundary conditions for the moment.

If $\kappa=0$ (no diffusion) then $v(x, t)=v(x, 0)$ for all time since both $v=1$ and $v=0$ are steady states and so $v_{t} \equiv 0$. With diffusion, however, this step discontinuity immediately smooths out and $v(x, t)$ for $t>0$ will be a continuous function taking all values between 0 and 1 . For these values of $v$ the reaction term drives $v$ back towards 0 (where $v<\alpha$ ) or towards 1 (where $v>\alpha$ ), tending to sharpen the smeared profile back towards a step discontinuity. There is a competition between the smearing effect of diffusion and the sharpening effect of the reaction, leading to a steady profile that is smeared to a finite degree that depends on the relation between the parameters $\epsilon$ and $\kappa$.
The smearing effect of diffusion is symmetric about $v=1 / 2$ : for $\epsilon \rightarrow \infty$ the solution to the pure diffusion equation with data (4) has $v>1 / 2$ for $x<0$ and $v<1 / 2$ for $x>0$ and appears symmetric about this point. The sharpening from the reaction term is also symmetric about $v=1 / 2$ if $\alpha=1 / 2$. In this case $v(x, t)$ approaches a steady state profile $v(x, t) \rightarrow \bar{v}(x / \delta)$ as $t \rightarrow \infty$. A new parameter $\delta$ has been introduced that will be related to $\kappa$ and $\epsilon$ below. The idea is that the profile $\bar{v}(\xi)$ should be independent of the parameters $\kappa$ and $\epsilon$ but is rescaled based on these parameters since the width of the transition from $v=1$ to $v=0$ will depend on these parameters.
We can determine $\delta$ and $\bar{v}$ by inserting $v(x, t)=\bar{v}(x / \delta)$ into the $\operatorname{PDE}(3)$, obtaining a boundary value
problem

$$
\begin{equation*}
0=\frac{\kappa}{\delta^{2}} \bar{v}^{\prime \prime}(x / \delta)+\frac{1}{\epsilon} g(\bar{v}(x / \delta)) . \tag{5}
\end{equation*}
$$

Multiplying by $\delta^{2} / \kappa$ and rearranging gives

$$
\begin{equation*}
\bar{v}^{\prime \prime}(x / \delta)=-\frac{\delta^{2}}{\kappa \epsilon} g(\bar{v}(x / \delta)) \tag{6}
\end{equation*}
$$

This suggests that we should choose $\delta^{2}$ to be proportional to $\kappa \epsilon$ in order to obtain an ODE for $\bar{v}$ that is independent of the parameters. In order to easily solve the resulting BVP it is convenient to choose

$$
\begin{equation*}
\delta=\sqrt{2 \kappa \epsilon} \tag{7}
\end{equation*}
$$

Setting $\xi=x / \delta$ then gives the ODE for $\bar{v}(\xi)$,

$$
\begin{equation*}
\bar{v}^{\prime \prime}(\xi)=-2 \bar{v}(\xi)(1 / 2-\bar{v}(\xi))(\bar{v}(\xi)-1) \tag{8}
\end{equation*}
$$

with asymptotic boundary conditions $\bar{v}(x) \rightarrow 1$ as $x \rightarrow-\infty$ and $\bar{v}(x) \rightarrow 0$ as $x \rightarrow \infty$. We also want $\bar{v}(\xi)$ to be centered about $\xi=0$, so we would like $v(0)=1 / 2$.

Note that even without solving the ODE (8) we can deduce that the width of the transition zone in the traveling wave is proportional to $\delta$ and hence to $\sqrt{\kappa \epsilon}$. This information might be useful if we wanted to use a nonuniform grid to solve the problem numerically, or to choose an appropriate value of $h$ for a uniform grid.

## Problem 3.

Show that the function

$$
\begin{equation*}
\bar{v}(\xi)=\frac{1}{1+\exp (\xi)} \tag{9}
\end{equation*}
$$

satisfies both of the equations

$$
\begin{equation*}
\bar{v}^{\prime}(\xi)=-\bar{v}(\xi)(1-\bar{v}(\xi)) \tag{10}
\end{equation*}
$$

and

$$
\begin{equation*}
\bar{v}^{\prime \prime}(\xi)=2 \bar{v}(\xi)(1-\bar{v}(\xi))(1 / 2-\bar{v}(\xi)) \tag{11}
\end{equation*}
$$

and also satisfies

$$
\begin{align*}
& \bar{v}(\xi) \rightarrow 1 \quad \text { as } \quad \xi \rightarrow-\infty, \\
& \bar{v}(\xi) \rightarrow 0 \quad \text { as } \quad \xi \rightarrow+\infty,  \tag{12}\\
& \bar{v}(0)=1 / 2
\end{align*}
$$

Hence this is a steady state solution for the case $\alpha=1 / 2$.

If $\alpha \neq 1 / 2$ then the effect of the reaction term is not symmetric. If $0<\alpha<1 / 2$ then some values of $v$ less than $1 / 2$ are driven towards $v=1$ by the reaction term. When coupled with the symmetric diffusion this leads to a traveling wave propagating with some velocity $c$ that is positive if $\alpha<1 / 2$ or negative if $\alpha>1 / 2$. The traveling wave profile is given by the same function $\bar{v}(x)$ that satisfies the boundary value problem (8), and that the traveling wave has the form

$$
\begin{equation*}
v(x, t)=\bar{v}((x-c t) / \delta) \tag{13}
\end{equation*}
$$

where the speed $c$ is given by

$$
\begin{equation*}
c=\sqrt{\frac{2 \kappa}{\epsilon}}\left(\frac{1}{2}-\alpha\right) . \tag{14}
\end{equation*}
$$

## Problem 4.

(a) For any $0<\alpha<1$, show that $v(x, t)=\bar{v}((x-c t) / \delta)$ is a traveling wave solution to (3) provided that $c$ satisfies (14).
(b) Suppose we define the width of the transition zone (wave front) in a traveling wave to be the distance in $x$ over which $v$ falls from 0.99 to 0.01 . Show that the width of wave front is roughly $9 \delta$. This can be used to choose a suitable value of $h$. For example, choosing $h \approx \delta$ would give roughly 9 grid points in the wave front, which is probably about the minimum needed to resolve it well numerically.

## Problem 5.

(a) Implement a fractional step method to approximate solutions to the Allen-Cahn equation on the interval $-1 \leq x \leq 3$ with initial data $v(x, 0)=V(x / \delta)$, where $\delta$ is determined from specified values of $\kappa=0.3$ and $\epsilon$.

Each time step, first take a time step of the diffusion equation, and then a time step of the nonlinear ODEs (at each grid point).
Your code should use:

- The Crank-Nicolson method for the diffusion equation. You might want to use code from the notebook notebooks/HeatEquation.ipynb for the diffusion part. Adapt this to work on the interval $-1 \leq x \leq 3$.
- To solve the ODE in each timestep, use either the Forward Euler method, the two-stage explicit Runge-Kutta method (5.30), or the Backward Euler method. Introduce a parameter odemethod in the input data of your function to select one of these. Note that for Backward Euler, an implicit nonlinear equation must be solved at each grid point (in every time step). You can use scipy.optimize.fsolve for these.
- Similar to notebooks/HeatEquation.ipynb, set initial condition and boundary conditions in each time step using a function utrue that implements the true solution for a traveling wave.
(b) Test your method using $\alpha=0.3$ and $\epsilon=0.01$ with initial data given by the exact traveling wave solution at $t=0$, going up to time $t=1$, and plotting both the exact and computed solution for comparison. Produce some plots of the solution to show that the code works with both ODE solvers.

You should see results like this for the case when Forward Euler is used and $m=49$ with 100 time steps up to time 1:


(c) What order of accuracy do you observe for each choice of ODE solver? Test by refining in space and time with $k / h$ fixed (for $\alpha=0.3$ and $\epsilon=0.01$ ) and produce a log-log plot of the errors in each case.
(d) Test your code also with $\alpha=0.5$ and $\alpha=0.7$ and verify that it gives the expected solutions in these cases. (You don't need to repeat the convergence test for these values.)

## Problem 6.

Now try using $\epsilon=0.003$ with $\alpha=0.3$ and a grid with $m=49$ and 45 time steps over up to a final time of 0.5 (a shorter time interval since with smaller $\epsilon$ the wave propagates faster).
When using Backward Euler for the ODE term, you should see results like shown in this figure:


The wave appears stable, but moves at the wrong speed. This could be quite misleading if we didn't know the true solution!

For these values of $\epsilon$ and $\alpha$, experiment with different resolutions in space and in time to explore how the numerical solution behaves, both when the Forward Euler method and when the Backward Euler method are used. Given that the implicit ODE method requires a lot more work than the explicit method (solving a nonlinear equation at every grid point, every time step), try to reach some conclusions on whether it is worthwhile to use the implicit ODE solver for this Allen-Cahn problem. (Recall that Problems 2(a) and 4(b) give some ideas on what sort of resolution might be needed in time and space).
This problem is a bit open-ended. Feel free to experiment with other values of $\epsilon$ too if useful (or other variations). A variety of different wrong numerical solutions can be generated depending on parameter choices.

