

SHALLOW WATER WAVES

#.4

$$\left. \begin{array}{l} \text{x mom} \quad u_t = -g\eta_x \\ \text{mass} \quad \eta_t + H u_x = 0 \end{array} \right\} \eta_{tt} - gH \eta_{xx} = 0$$

Note:

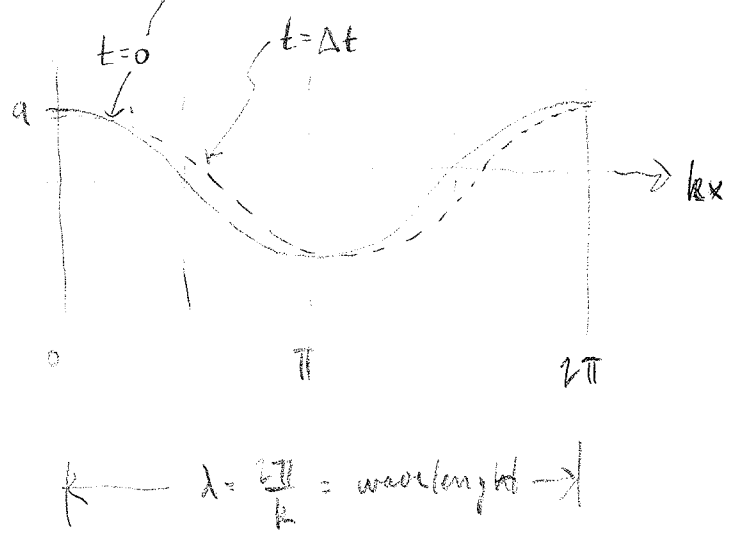
$$\left. \begin{array}{l} \frac{d}{dt} \text{x mom} \Rightarrow u_{tt} + g \eta_{xt} = 0 \\ \frac{d}{dx} \text{mass} \Rightarrow \eta_{xt} = -H u_{xx} \end{array} \right\} \Rightarrow u_{tt} - gH u_{xx} = 0$$

We showed any pattern of  $\eta$  moves w/ speed  $\pm c = \pm \sqrt{gH}$   
 same is true of pattern of  $u$ .

Note: including  $y$  mom  $\Rightarrow \eta_{tt} - gH(\eta_{xx} + \eta_{yy}) = 0$

Useful solutions given by the functional form

$$\eta = a \cos(kx - \omega t) + b \sin(kx - \omega t)$$



$\hat{\eta}$  complex

$$\eta = \text{Re} \{ \hat{\eta} \exp[i(kx - \omega t)] \}$$

pattern moves to right with speed

$$c = \frac{\omega}{k} = \text{"phase speed"}$$

where  $\varphi = kx - \omega t = \text{"phase"}$

$$c = \frac{dx}{dt} \Big|_{\varphi = \text{const}}$$

$\omega = \frac{2\pi}{\text{oscillation period}} = \text{frequency} \quad [\text{rad s}^{-1}]$  convention is to assume positive (2)

$k = \frac{2\pi}{\text{wavelength}} = \text{wavenumber} \quad [\text{rad m}^{-1}]$

convention (sometimes) is to allow either sign, then negative  $k$  denotes waves moving to the left ( $c = -\sqrt{gh}$  for the 1-D solution)

Initial / boundary Conditions (IC + BC)

You need 2 for a 2nd order equation

Example:

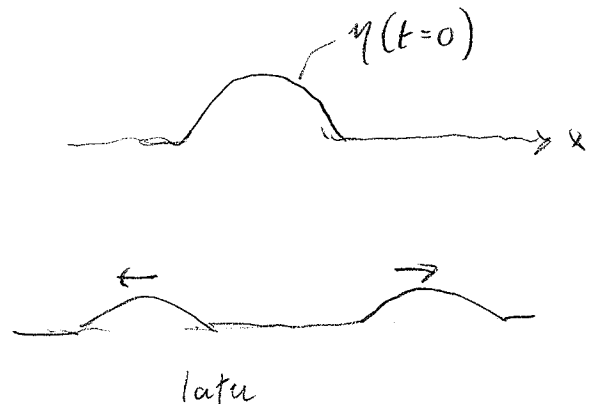
IC ①  $\eta(x, t=0) = \eta_0(x)$

and  $u(x, t=0) = 0$

$\Rightarrow u_x(t=0) = 0$

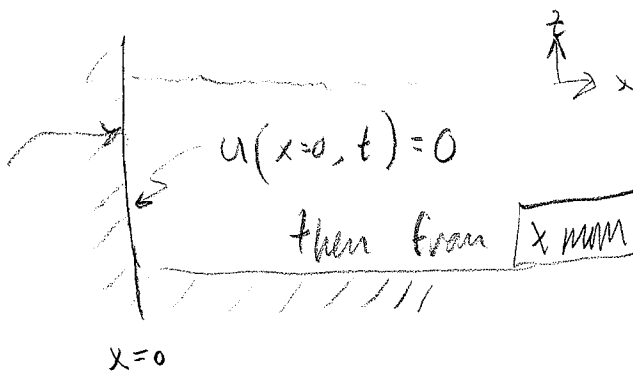
②  $\Rightarrow \eta_t(t=0) = 0$

from mass  $\eta_t + H u_x = 0$



BC:

e.g. a wall



$u(x=0, t) = 0$

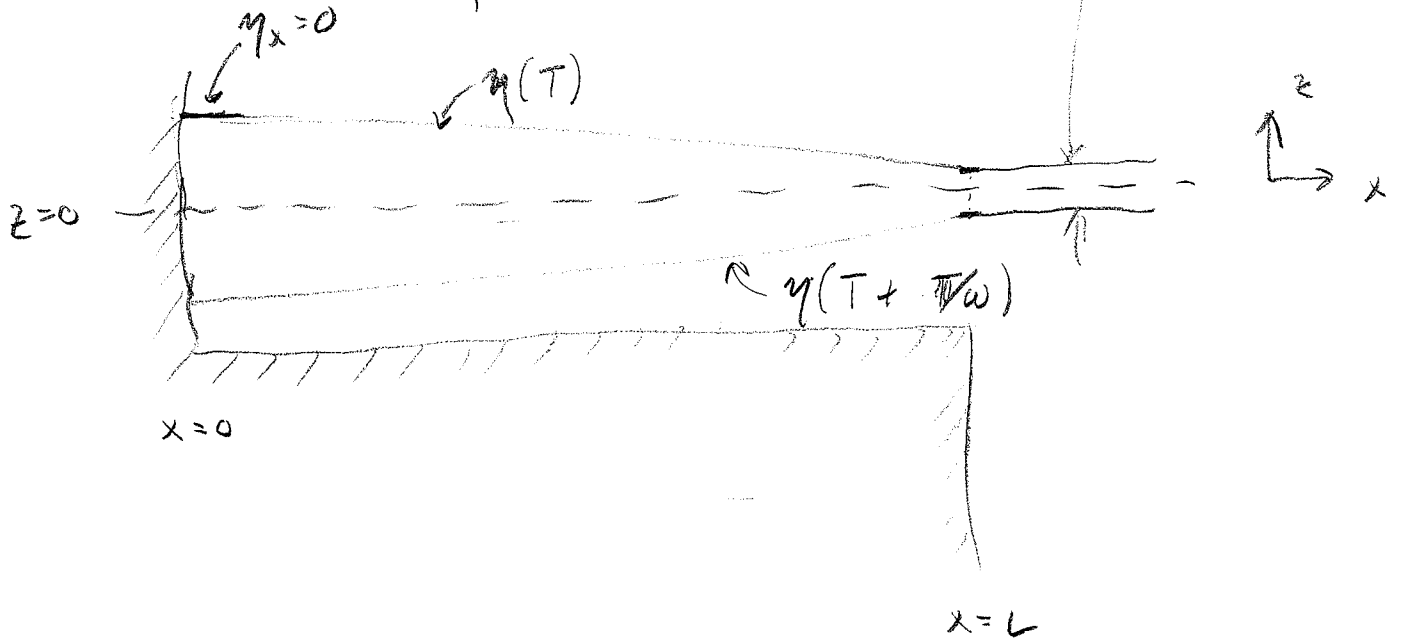
then from x mm

$u_t = -g \eta_x$

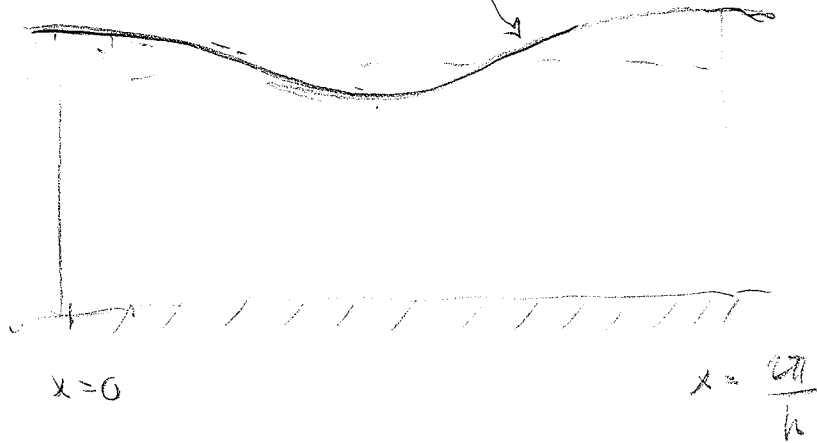
$\Rightarrow \eta_x(x=0, t) = 0$  (BC)

(3)

For the lab experiment the second BC would be  $\eta(x=L, t) = \eta_0 \cos \omega t$



Note: Progressive wave:  $\eta = \eta_0 \cos(kx - \omega t)$



pattern moves to right

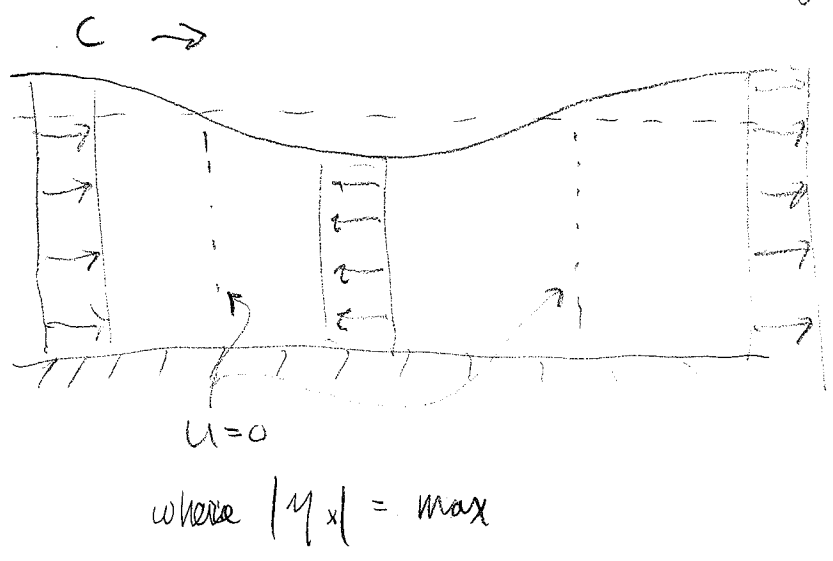
$$c = \frac{\omega}{k} = \sqrt{gH}$$

$$\boxed{x \text{ max}} \quad u_t = -g\eta_x = -g\eta_0 k(-1) \sin(kx - \omega t)$$

$$\Rightarrow u = \int u_t dt = \frac{g\eta_0 k(-1)}{(-\omega)} \cos(kx - \omega t) = g\eta_0 \frac{k}{\omega} \cos(kx - \omega t)$$

$$\text{so } u = \eta_0 g \frac{1}{\sqrt{gH}} \frac{1}{\sqrt{gH}} = \frac{\eta_0}{H} \sqrt{gH} \cos(kx - \omega t)$$

so  $u = \eta_0 \frac{g}{\sqrt{gH}} \frac{\sqrt{H}}{\sqrt{H}} \cos(kx - \omega t) = \frac{\eta_0}{H} \sqrt{gH} \cos(kx - \omega t) = u$



for  $\frac{\eta_0}{H} \ll 1$   
 $\Rightarrow |u| \ll c$

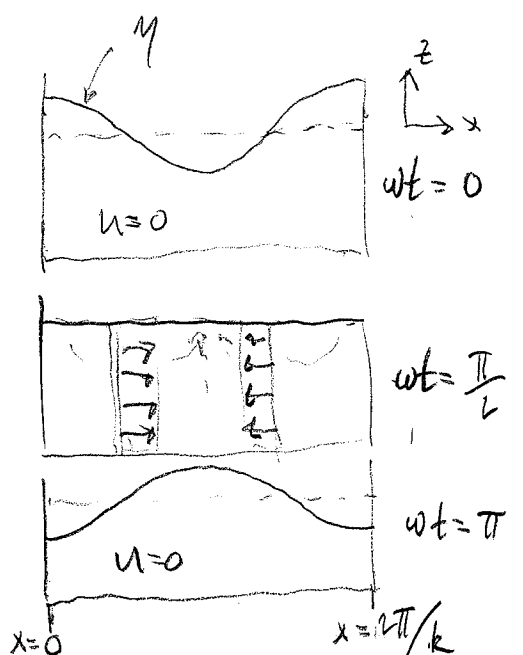
Note: "Standing wave" = sum of two equal waves going opposite directions

$$\eta = a \cos(kx - \omega t) + a \cos(kx + \omega t)$$

$$= a \cos kx \cos \omega t + a \cancel{\sin kx} \cancel{\sin \omega t}$$

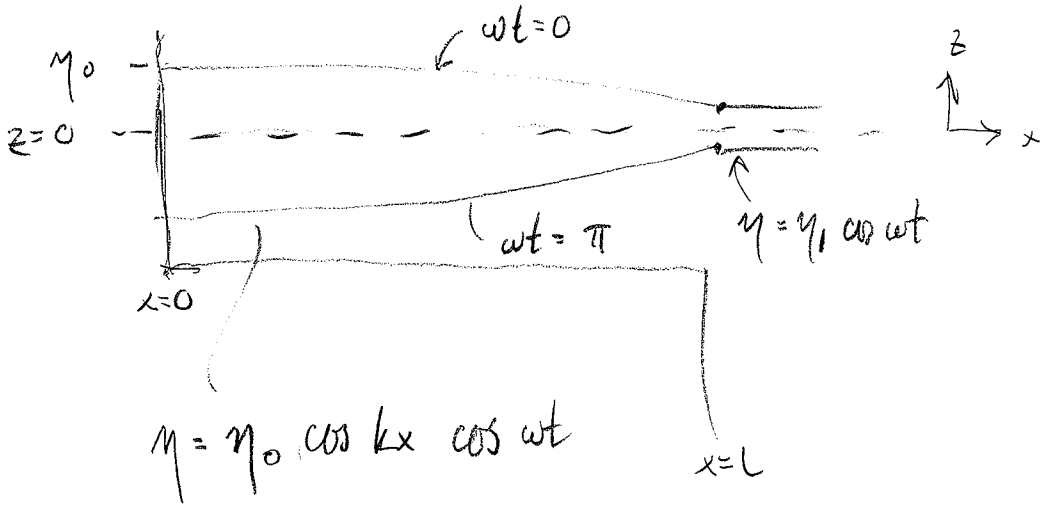
$$+ a \cos kx \cos \omega t - a \cancel{\sin kx} \cancel{\sin \omega t}$$

$$= 2a \cos kx \cos \omega t$$



eq. for the lab experiment

(5)



satisfies BC1 :  $\eta_x(x=0) = 0$

to satisfy BC2  $\Rightarrow$

$$\eta_0 \cos kL \cos \omega t = \eta_1 \cos \omega t$$

*1/4 wave oscillator*

$$\Rightarrow \eta_0 = \frac{\eta_1}{\cos(kL)}$$

