Discrete Optimization Graphs

Ngày 1 tháng 8 năm 2011

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A finite graph is a pair (V, E) where V is a finite set called vertices, E is a family of pairs $(x, y) | x, y \in V$ called edges.

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We shall usually denote graphs by G(V, E) or H(V, E) etc.

Remark

We used the word family rather than set to account for the possibility that a pair (x,y) will appear more than once. Also we used (x,y) rather than $\{x,y\}$ to account for a pair (x,x).

Graphs are dynamic data structures. They can grow (adding vertice and edges) or shrink (deleting edges or vertices). When a vertex is delted, all edges incident with it are also deleted.



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• $V = GF^*(q)$ $E = \{(x, y) | x - y \in QR(q)\}.$

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- *B-5:* A graph *G* is **labeled** if the vertices are assigned unique names.

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- G-7: A closed walk in which $v_i \neq v_j$, for $i \neq j$, $0 \le i, j < k$ is a cycle.

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In a digraph D, $\sum_{i=1}^{n} in_D(v_i) = \sum_{i=1}^{n} out_D(v_i)$.

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Theorem

Every tournament has a hamiltonian path.

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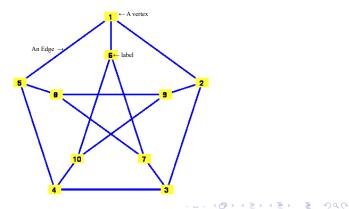
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The Petersen Graph

Petersen's graph.

Petersen's graph has 10 vertices and 15 edges. This rendition of the graph is labeled. Every vertex has 3 adjacent vertices (neighbors).

The degree of every vertex is 3. This graph is regular of degree 3 (3-regular, or cubic).



Using graphs to model problems



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- 4. Can a tourist visit all airpots in Vietnam by flying in and out of airports? Is there a closed walk through all vertices?

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- *G-8:* A graph G = G(V, E) is **connected** if between any pair of vertices there is a path.
- G-9: A path containing all vertices is a **Hamiltonian path**. If G has such a path we say that G is **traceable**.

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- *G-12:* The **distance** between two vertices in a graph is the length of the shortest path between them.
- G-13: The diameter of a connected graph is the length of the longest distance among all pairs of vertices.

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A graph G is **r-connected** if $G = K_r$ or G cannot be disconnected by removing less than r vertices.

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Cycles, Notation

Definition (Notation)

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- The 5-prism has a perfect matching and girth 4.

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- 4. Fault tolerance.

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Discrete OptimizationGraphs

 To build a mathematical model for tackling this problem we define a graph G(V, E) where V(G) is the set of all computers (or processors) and E(G) is the pairs of computers we will connect by hard wire.

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- For the third goal we would like to have many edge-disjoint Hamiltonian cycles in the graph.

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Let us study the case of connecting 10 computers where each computer can be connected to three other computers.

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So which design is better?

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Discrete OptimizationGraphs

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- Start from scratch, designing a graph with 20 vertices regular of degree 4.

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- Suppose you want to merge two networks with 10 computers each by adding just one connection for each computer. How would you do it?
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- Preserve the previous design and connect each computer to its "clone" (the prism).

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Answer

To be answered by you in the assignment.

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