

COMMUNITY TREES IN NETWORKS

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UW Math



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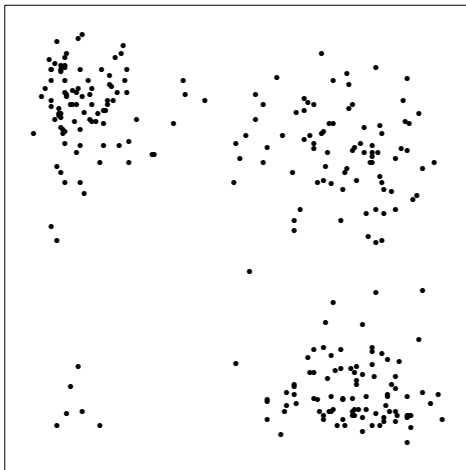


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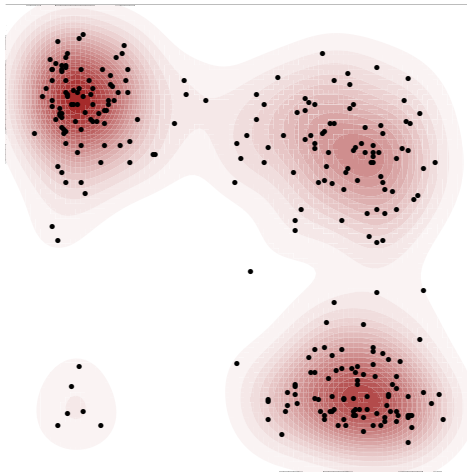
- Review: Density Tree
- Community Tree in Networks
- Future Work

DENSITY TREE

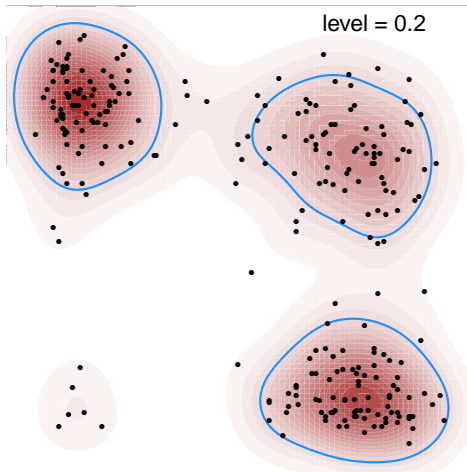
Clusters and Density Function: an Illustration



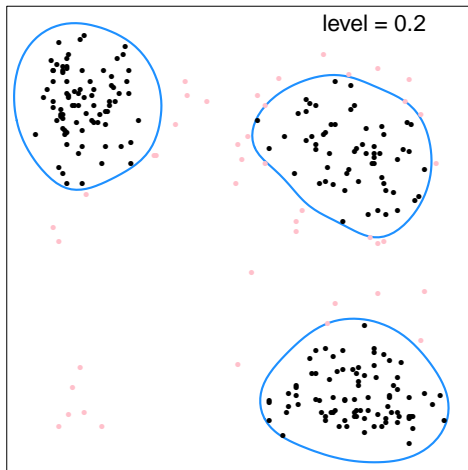
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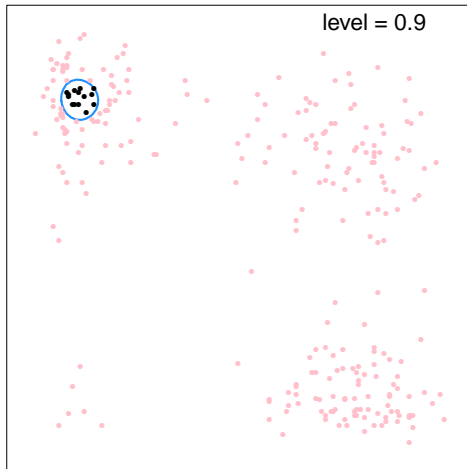
Clusters and Density Function - 1

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- Thus, the level λ has an effect on the clustering result.

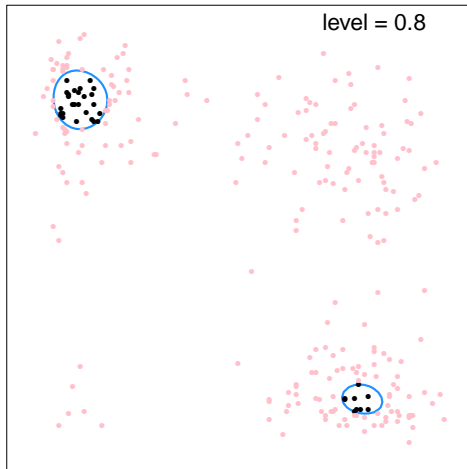
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- Thus, the level λ has an effect on the clustering result.
- Varying the level λ may lead to a creation of a new cluster or a merging of existing clusters.

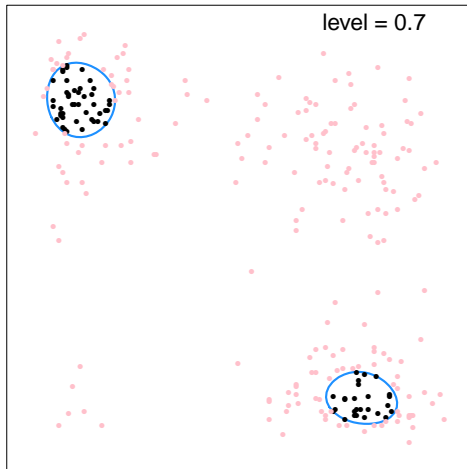
Clusters and Density Function: Different Levels



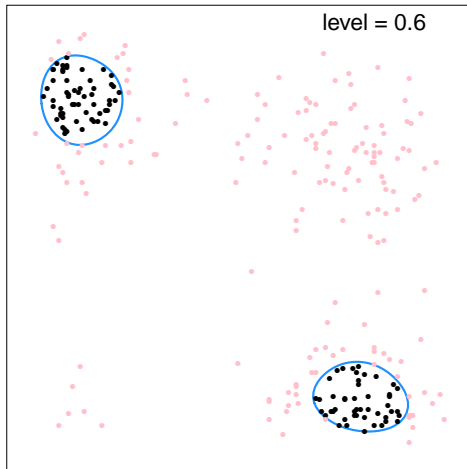
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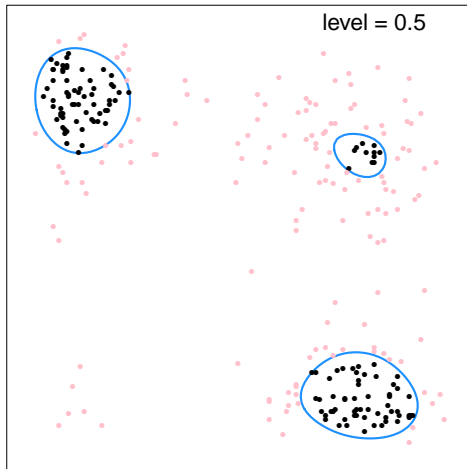
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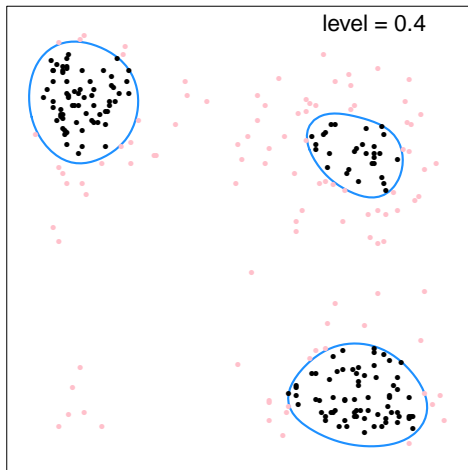
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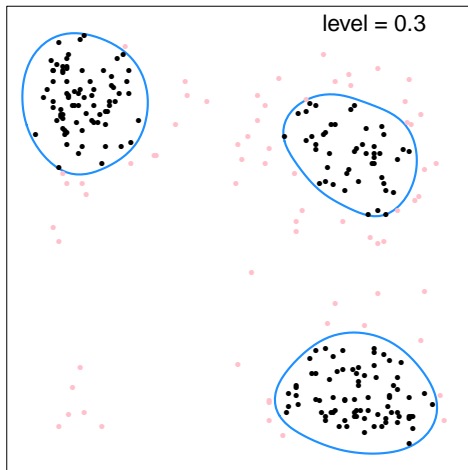
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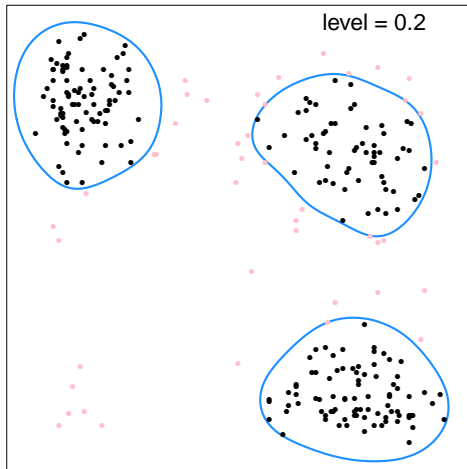
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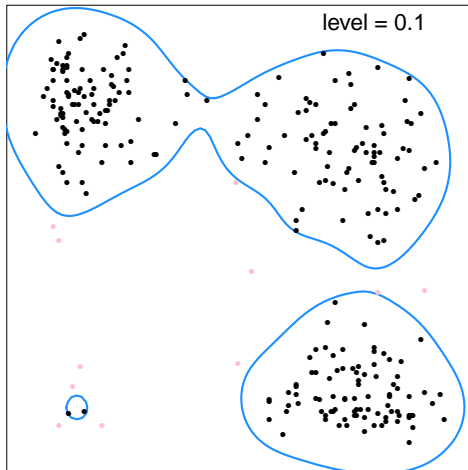
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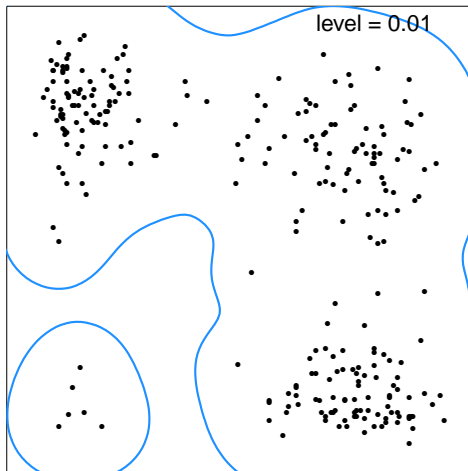
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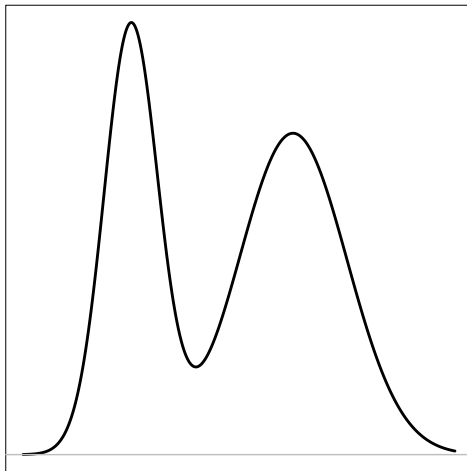
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Clusters and Density Function - 2

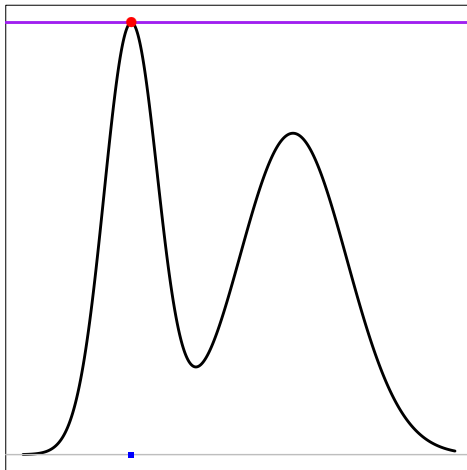
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- When applied to a density function, a cluster tree is also called a density tree ([Klemelä 2004](#)).

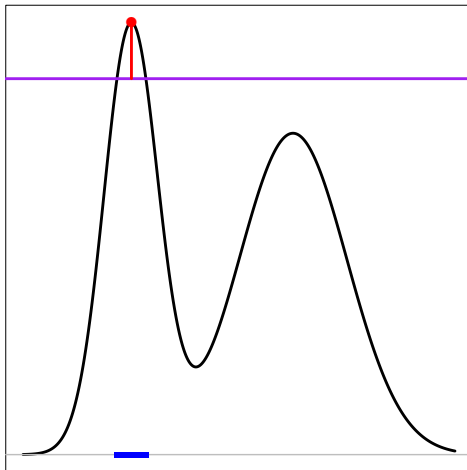
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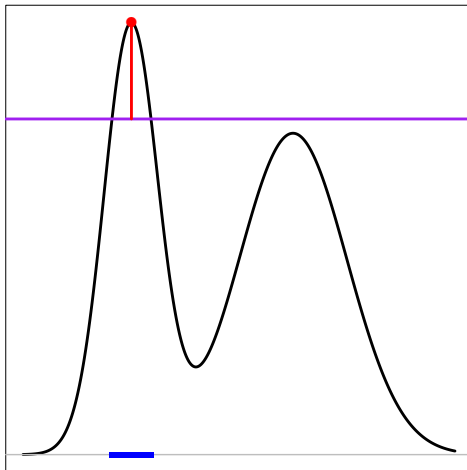
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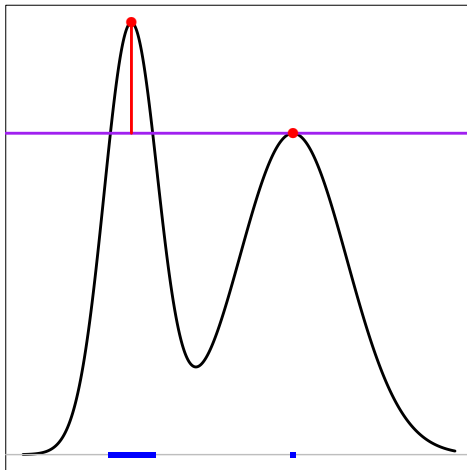
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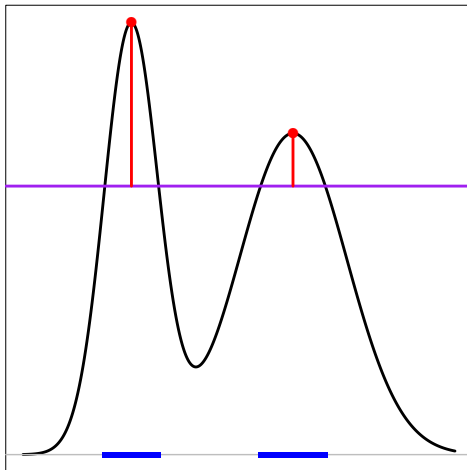
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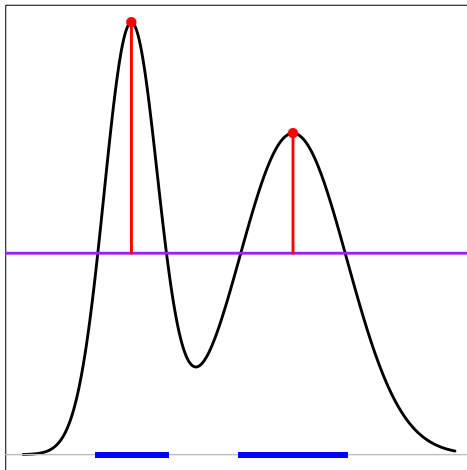
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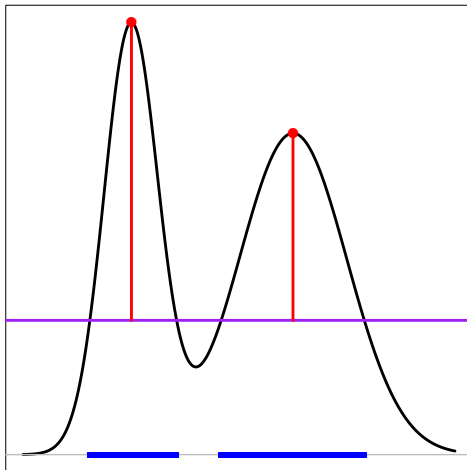
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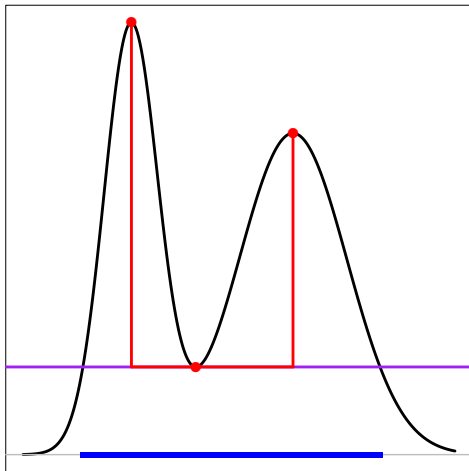
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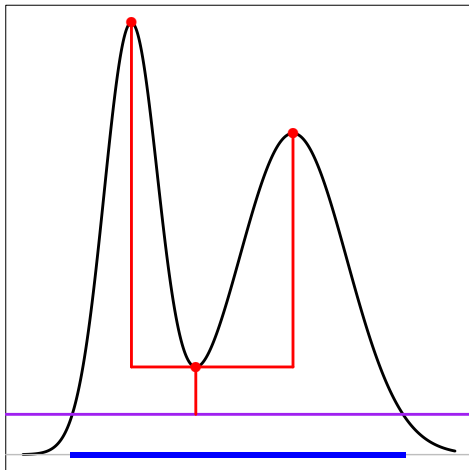
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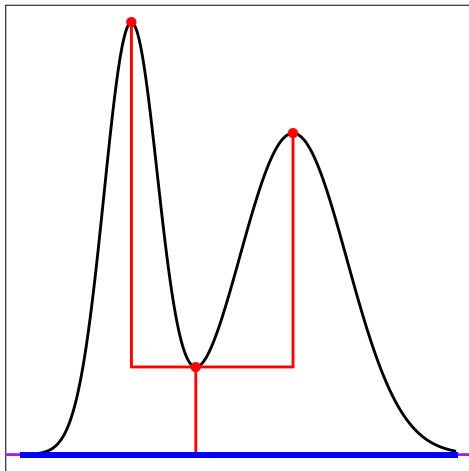
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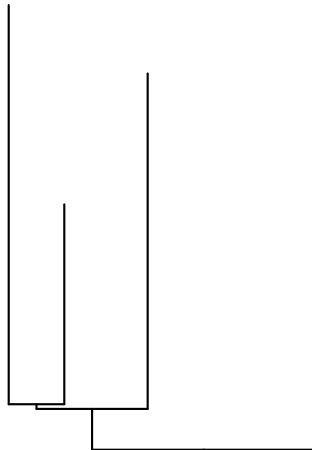
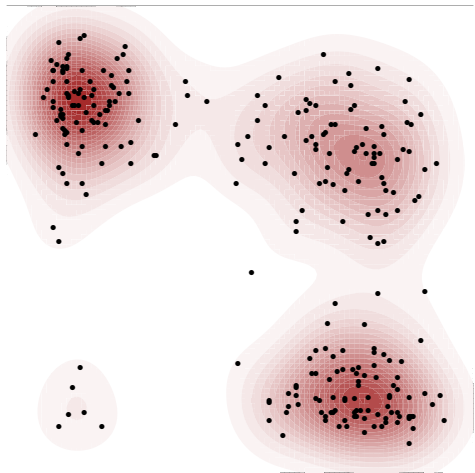
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An Example of 2D Density Tree



Features of Density Trees

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- When using density level sets to define clusters, the density tree contains the information about the evolution and stability of clusters.
- Moreover, density trees can always be displayed in 2D plane. So they are good tools for visualizing multivariate functions.

COMMUNITY TREES

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- CPM is a popular and powerful method in community detection.
- CPM uses cliques and their overlapping to define communities.
- Communities from CPM can be overlapping – this allows a broader way to interpret communities.

Finding level sets \leftrightarrow CPM

Density level $\lambda \leftrightarrow$ Clique order k

Clusters \leftrightarrow Communities

Density/cluster trees \leftrightarrow Community trees

Cliques and Communities

- Cliques: a subgraph such that all vertices are connected.
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Cliques and Communities

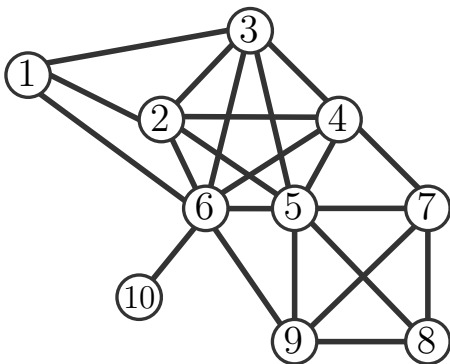
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- The number k of a clique community is called the order.

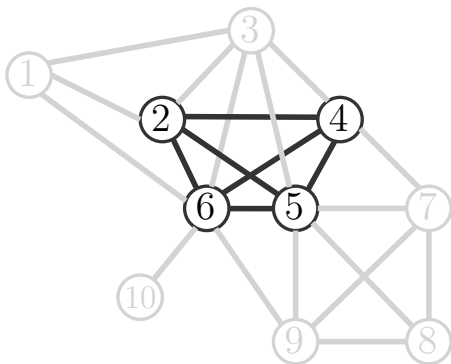
An Example: 4-communities

What are the 4-communities in the following network?



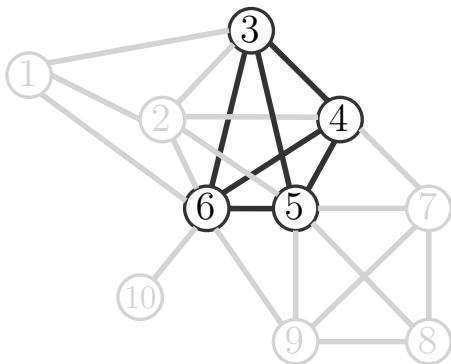
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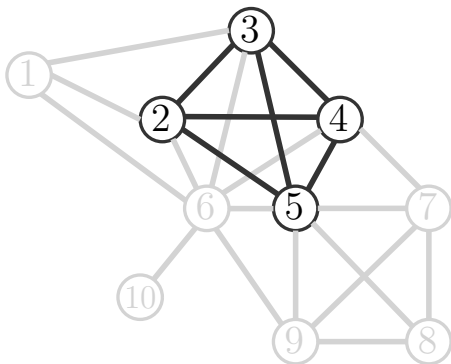
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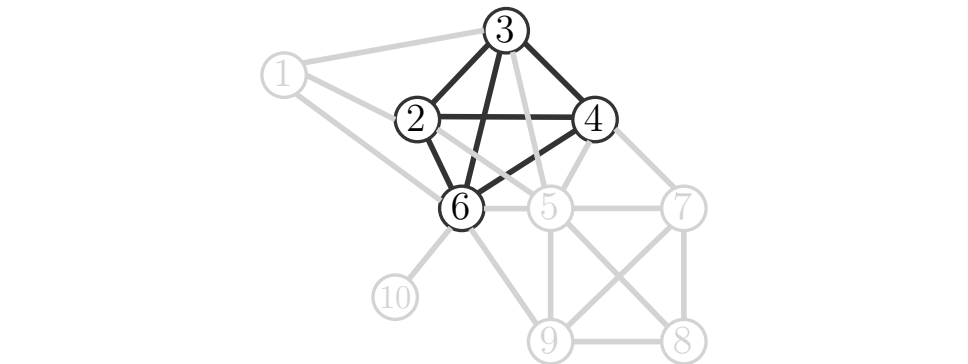
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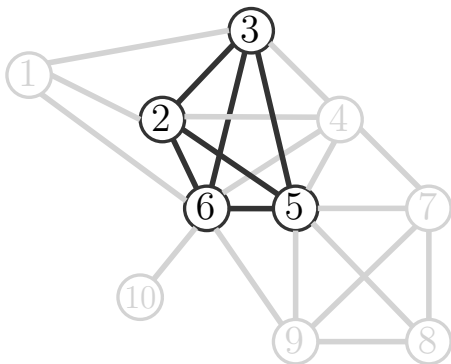
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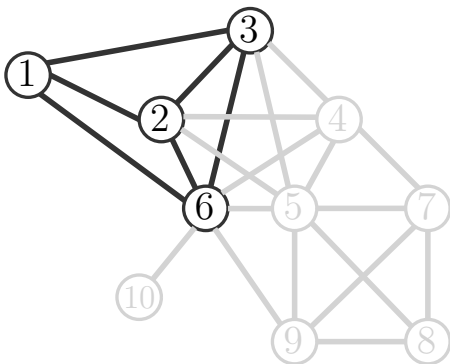
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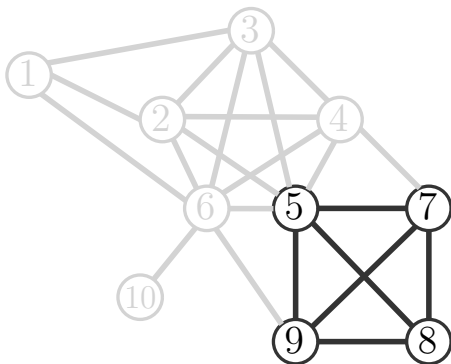
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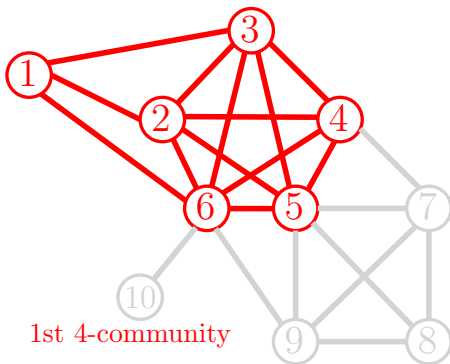
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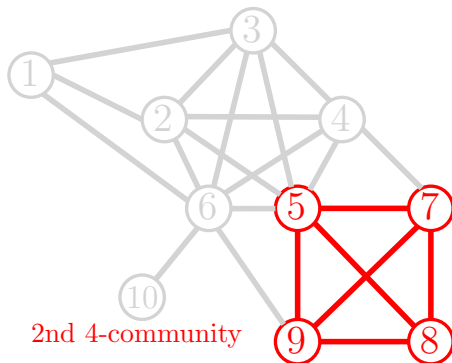
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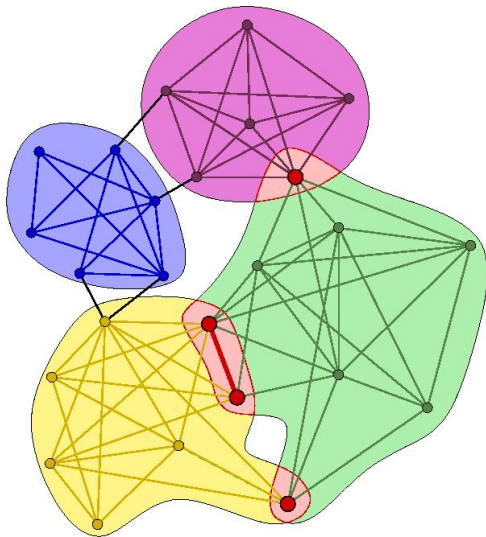


An Example: 4-communities

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A more Complex Network



Another example of 4-communities (source: wikipedia).

Communities of Different Orders

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- Then for a k -community \mathcal{C}_k , there exists a sequence of subgraphs

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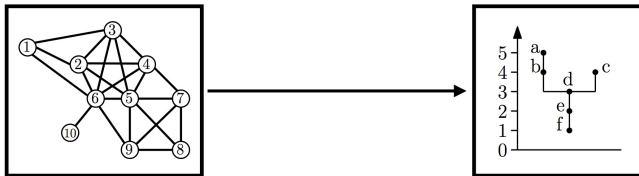
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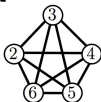
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- This property, which we refer to as the nested property, defines a tree structure of all (clique) communities within a graph.
- The resulting tree is called the **community tree**.

Community Tree: an Example

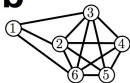


a



5-community

b

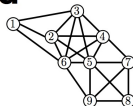


c



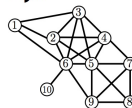
4-community

d



3-community

e,f



**2-community
1-community**

A Key Insight (revisited)

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Density/cluster trees \leftrightarrow Community trees

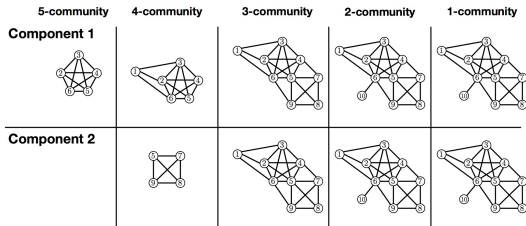
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- In a sense, the community tree can be viewed as a generalization of the cluster tree to networks.

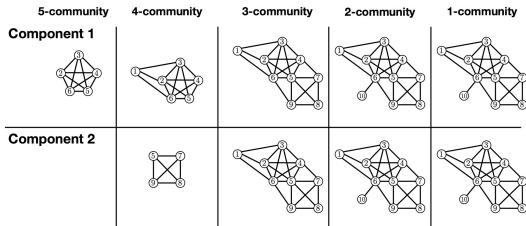
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- Moreover, the community tree leads to a persistent diagram.

Components in a Community Tree



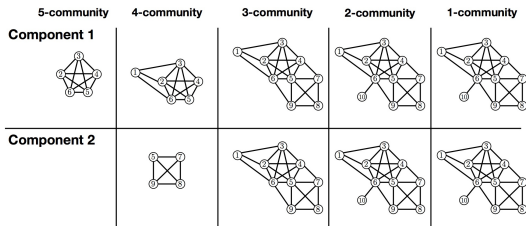
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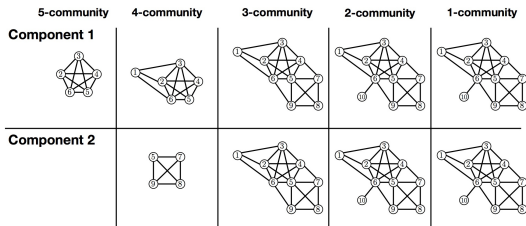
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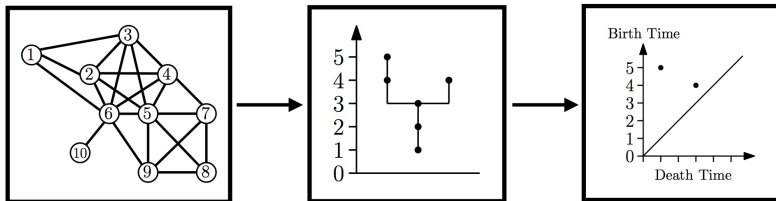


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- The birth time of a component is the highest order of its nodes.
- Two components merge at an order if they share the same node. When two components merge, the one that has a lower birth time merged into the other component.
- The death time of a component is the highest order that it merge into another component.

Persistent Diagram of a Community Tree

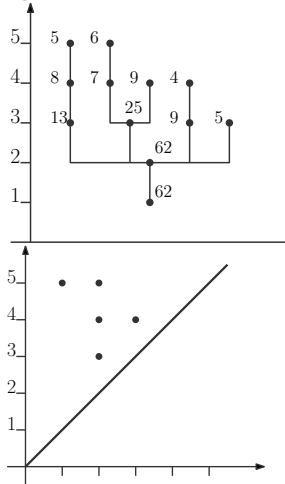
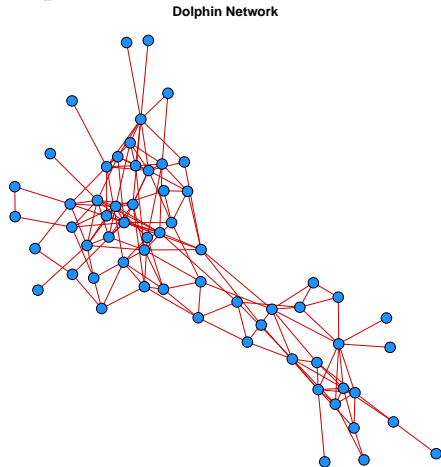
- Using the birth and death time of components, we obtain the persistent diagram of a community tree.
- Let $(b_1, d_1), \dots, (b_K, d_K)$ be the birth time and death time of components of a community tree. The persistent diagram is

$$\text{PD} = \{(d_i, b_i) : i = 1, \dots, K\} \cup \{(d, b) : d = b\}.$$



Example: Dolphin Network

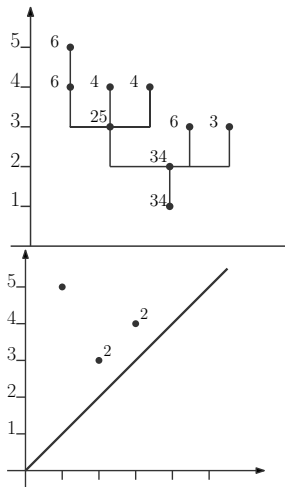
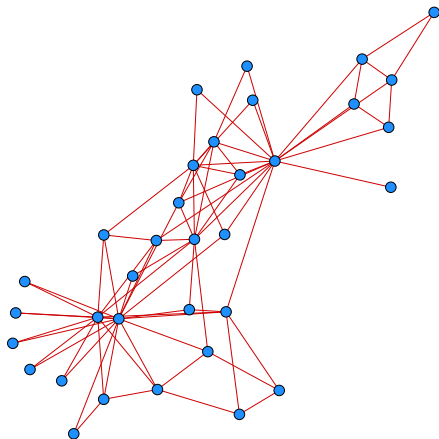
62 Dolphins' social network data with 159 edges.



Example: Zachary Karate Club Network

A social network data about Zachary karate club; 34 vertices and 78 edges.

Zachary Karate Club Network



Stability of a Community Tree - 1

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- For a network G_0 , if we only perturb it a little bit, how will its community tree change?
- Namely, we want to understand the stability of a community tree.
- However, quantifying the tree difference is not easy.
- Here we measure their difference using the bottleneck distance between the corresponding persistent diagrams.

- Given two persistent diagrams PD_1, PD_2 , their bottleneck distance is

$$d_\infty(\text{PD}_1, \text{PD}_2) = \inf_{\gamma} \sup_{A \in \text{PD}_1} \|A - \gamma(A)\|_\infty,$$

where the infimum is taking over all bijective mappings between PD_1 and PD_2 .

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where the infimum is taking over all bijective mappings between PD_1 and PD_2 .

- Let $\text{PB}(T)$ be the persistent diagram of a community tree T . Then we define a distance d_B for community trees T_1 and T_2 as

$$d_B(T_1, T_2) = d_\infty(\text{PB}(T_1), \text{PB}(T_2)).$$

- Given two networks G_1 and G_2 , let $T(G_1)$ and $T(G_2)$ be their corresponding community trees.
- It turns out that the difference between their community trees are bounded by a quantity called the total star number $\text{TSN}(G_1, G_2)$:

Theorem (Chen et al. 2017)

Let G_1 and G_2 be two networks. Then

$$d_B(T(G_1), T(G_2)) \leq \text{TSN}(G_1, G_2).$$

Total Star Number

- The total star number

$$\text{TSN}(G_1, G_2) = \text{RSN}(G_1, G_2) + \text{RSN}(G_2, G_1).$$

- $\text{RSN}(G_1, G_2)$ is the removal star number which is defined as

$$\text{RSN}(G_1, G_2) = \min\{|V_0| : v(e) \cap V_0 \neq \emptyset \ \forall e \in E(G_1) \setminus E(G_2)\},$$

where V_0 is a collection of vertices and $|V_0|$ is the number of elements in the set V_0 and $E(G)$ is the edge of a network G and $v(e)$ is the vertices attached to the edge e .

- The total star number

$$\text{TSN}(G_1, G_2) = \text{RSN}(G_1, G_2) + \text{RSN}(G_2, G_1).$$

- $\text{RSN}(G_1, G_2)$ is the removal star number which is defined as

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- $\text{RSN}(G_1, G_2)$ can be interpreted as the minimal number of vertices we need to remove so that G_1 is a subgraph of G_2 .
- Informally, the total star number can be interpreted as the minimal number of vertices that the network difference can be attributed to.

Theorem (Chen et al. 2017)

Let G_1 and G_2 be two networks. Then

$$d_B(T(G_1), T(G_2)) \leq \text{TSN}(G_1, G_2).$$

- The TSN can be small while many edges are removed.

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Theorem (Chen et al. 2017)

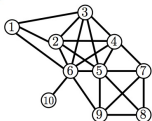
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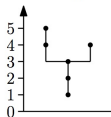
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- For instance, if G_1 is the same as G_2 except removing all edges connecting to a particular vertex of G_1 , then $\text{TSN}(G_1, G_2) = 1$.
- Computing the total star number *does not* require building a community tree.

Community Tree: an Example

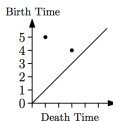
Original Network



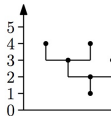
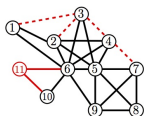
Community Tree



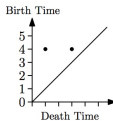
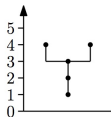
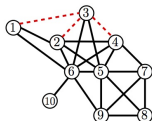
Persistence Diagram



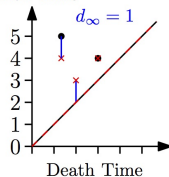
New Network - 1



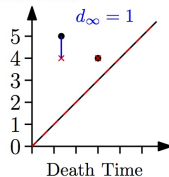
New Network - 2



Birth Time



Birth Time



Computing the Total Star Number

- Although the total star number provides a useful bound for community trees, it cannot be computed easily.

Theorem (Chen et al. 2017)

Computing the total star number is an NP-complete problem.

- Note that the proof relies only on one simple observation: computing the total star number is the same as finding the minimum vertex cover.

FUTURE WORK

- Practical algorithm for bounding the total star number.
- Visualization tool using community trees.
- Effects from stochastic updates on community trees.
- Connections to overlapping communities.

Thank You!

More details can be found in [Chen et al. \(2017\)](#):
"A Note on Community Trees in Networks"
(<https://arxiv.org/abs/1710.03924>)

1. Chen, Ruqian, et al. "A Note on Community Trees in Networks." arXiv preprint arXiv:1710.03924 (2017).
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