

# TCSS 422: OPERATING SYSTEMS

## Three Easy Pieces, Processes, Process API



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## OBJECTIVES

- Feedback from 1/3
- Chapter 2: Operating Systems – Three Easy Pieces
  - ✓ Easy piece #1: CPU Virtualization
  - ✓ Easy piece #2: Memory Virtualization
  - Easy piece #3: I/O Virtualization
  - Operating system design goals
- Processes – Ch. 4
- C Linux Process API – Ch. 5
- Limited Direct Execution – Ch. 6 (wed)
  - Virtualizing the CPU

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# VIRTUAL MACHINE SURVEY

- Please complete the Virtual Machine Survey is wanting an Institute of Technology hosted Ubuntu 16.04 VM
- <https://goo.gl/forms/XAxxuZtut5o707lp1>

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# QUIZ 0 – C REVIEW

Descriptive Statistics

mean	6.34848484848485
standard deviation	1.45170906433046

6.348	79.36%	avg
2.000	25.00%	min
8.000	100.00%	max
7.000	87.50%	mode

Histogram of x

A histogram titled "Histogram of x" showing the frequency distribution of scores. The x-axis is labeled "x" and ranges from 2 to 8. The y-axis is labeled "Frequency" and ranges from 0 to 20. The bars are orange. The frequencies are: 2: 4, 3: 1, 4: 12, 5: 12, 6: 22, 7: 14, 8: 0.

x	Frequency
2	4
3	1
4	12
5	12
6	22
7	14
8	0

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## SELECTED FEEDBACK FROM 1/3

- What causes threads to interrupt each other?
  - The OS interrupts threads when:
    - Threads YIELD (e.g. give up) the CPU because they're waiting on I/O (disk or network)
    - They exceed their "time slice" of execution (e.g. 10ms)
- Is kernel-mode code written in a unified language, or does it vary from OS-to-OS?
  - In Linux, kernel code is written in C and Assembly Language

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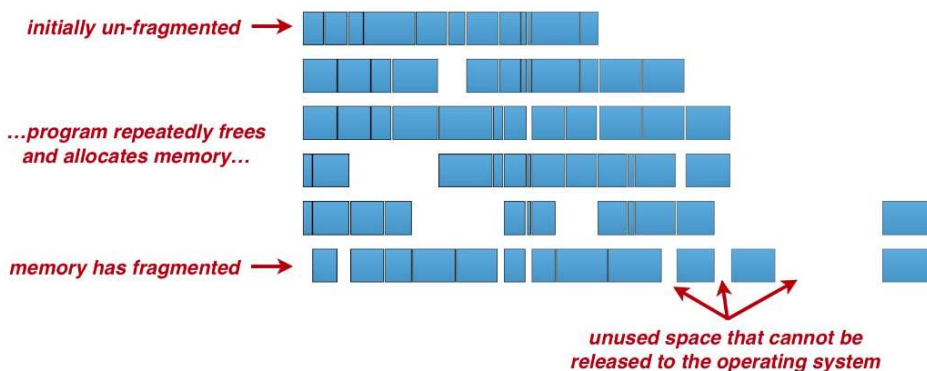
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## FEEDBACK - 2

- What is "memory" fragmentation?

### Malloc Memory Fragmentation Over Time



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## FEEDBACK - 3

- Are the resources given to a program static?
  - NO
- Can programs request more memory?
  - YES, In C, dynamic memory is allocated on the “HEAP” using the malloc() command
- What is a device driver?
  - A software program written in C and/or assembly language that facilitates transferring data to/from a device (e.g. Disk or Network Card) to the Computer
  - Block vs. char drivers, see:  
<http://www.linuxjournal.com/article/2890>

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## FEEDBACK - 4

- Are we allowed to publicly post source code for assignments later on in another term, or after graduation?
- Or should source code for programs be kept private indefinitely?
- During the term it could be grounds for an honor code violation if code pops up elsewhere
- FREE SPEECH – you’re always “allowed” to post code
- However, it is discouraged...

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## CH. 2: INTRODUCTION TO OPERATING SYSTEMS

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## VIRTUALIZATION

- Operating systems present **physical resources** as **virtual representations** to the programs sharing them
  - Physical resources: CPU, memory, disk ...
  - The virtual form is “**abstract**”
  - The OS presents an illusion that each user program runs in isolation on its own hardware
  - This virtual form is general, powerful, and easy-to-use

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## ABSTRACTIONS

- What form of abstraction does the OS provide?

- **CPU**

- Processes and threads

- **Memory**

- Address space
- → large array of bytes
- All programs see the same “size” of RAM

- **Disk**

- Files

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## WHY ABSTRACTION?

- Allow applications to reuse common facilities
- Make different devices look the same
  - Easier to write common code to use devices
    - Linux/Unix Block Devices
- Provide higher level abstractions
- More useful functionality

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ABSTRACTION CHALLENGES

- What is the right “level” of abstraction?
  - How much of the underlying hardware should be exposed?
    - What if **too much**?
    - What if **too little**?
- What are the correct abstractions?
  - Security concerns

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W

To perform parallel work, a single process may:

Launch multiple threads to execute code in parallel while sharing global data in memory

Launch multiple processes to execute code in parallel without sharing global data in memory

Both A and B

None of the above

Start the presentation to see live content. Still no live content? Install the app or get help at [PollEv.com/app](https://poll-ev.com/app)

Total Results

## PERSISTENCE

- **DRAM: Dynamic Random Access Memory: DIMMs/SIMMs**
  - Stores data while power is present
  - When power is lost, data is lost (*volatile*)
- **Operating System helps “persist” data more permanently**
  - I/O device(s): hard disk drive (HDD), solid state drive (SSD)
  - File system(s): “catalog” data for storage and retrieval

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## PERSISTENCE - 2

```
1  #include <stdio.h>
2  #include <unistd.h>
3  #include <assert.h>
4  #include <fcntl.h>
5  #include <sys/types.h>
6
7  int
8  main(int argc, char *argv[])
9  {
10     int fd = open("/tmp/file", O_WRONLY | O_CREAT
11                  | O_TRUNC, S_IRWXU);
12     assert(fd > -1);
13     int rc = write(fd, "hello world\n", 13);
14     assert(rc == 13);
15     close(fd);
16     return 0;
17 }
```

- **open(), write(), close(): OS system calls for device I/O**
- **Note: man page for open(), write() require page number: “man 2 open”, “man 2 write”, “man 2 close”**

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## PERSISTENCE - 3

- To write to disk, OS must:
  - Determine where on disk data should reside
  - Perform sys calls to perform I/O:
    - Read/write to file system (*inode record*)
    - Read/write data to file
- Provide fault tolerance for system crashes
  - Journaling: Record disk operations in a journal for replay
  - Copy-on-write: see *ZFS*
  - Carefully order writes on disk

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## SUMMARY: OPERATING SYSTEM DESIGN GOALS

- **ABSTRACTING THE HARDWARE**
  - Makes programming code easier to write
  - Automate sharing resources – save programmer burden
- **PROVIDE HIGH PERFORMANCE**
  - Minimize overhead from OS abstraction  
(Virtualization of CPU, RAM, I/O)
  - Share resources fairly
  - Attempt to tradeoff performance vs. fairness → consider priority
- **PROVIDE ISOLATION**
  - User programs can't interfere with each other's virtual machines, the underlying OS, or the sharing of resources

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SUMMARY:  
OPERATING SYSTEM DESIGN GOALS - 2

■ **RELIABILITY**

■ OS must not crash, 24/7 Up-time

■ Poor user programs must not bring down the system:

Blue Screen



■ Other Issues:

■ Energy-efficiency

■ Security (of data)

■ Cloud: Virtual Machines

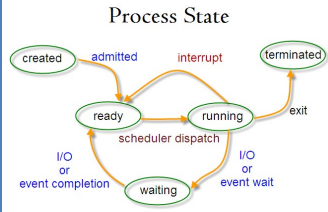
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CHAPTER 4:  
PROCESSES

Process State



 /proc

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## CPU VIRTUALIZING

- How should the CPU be shared?
- Time Sharing:  
Run one process, pause it, run another
- How do we SWAP processes in and out of the CPU efficiently?
  - Goal is to minimize **overhead** of the swap

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## PROCESS

A process is a running program.

- Process comprises of:
  - Memory
    - Instructions ("the code")
    - Data (heap)
  - Registers
    - PC: Program counter
    - Stack pointer

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## PROCESS API

- Modern OSes provide a Process API for process support
- Create
  - Create a new process
- Destroy
  - Terminate a process (ctrl-c)
- Wait
  - Wait for a process to complete/stop
- Miscellaneous Control
  - Suspend process (ctrl-z)
  - Resume process (fg, bg)
- Status
  - Obtain process statistics: (top)

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## PROCESS API: CREATE

1. Load program code (and static data) into memory
  - Program executable code (binary): loaded from disk
  - Static data: also loaded/created in address space
  - **Eager loading**: Load entire program before running
  - **Lazy loading**: Only load what is immediately needed
    - Modern OSes: Supports paging & swapping
2. Run-time stack creation
  - Stack: local variables, function params, return address(es)

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## PROCESS API: CREATE

### 3. Create program's heap memory

- For dynamically allocated data

### 4. Other initialization

- I/O Setup
  - Each process has three open file descriptors:  
Standard Input, Standard Output, Standard Error

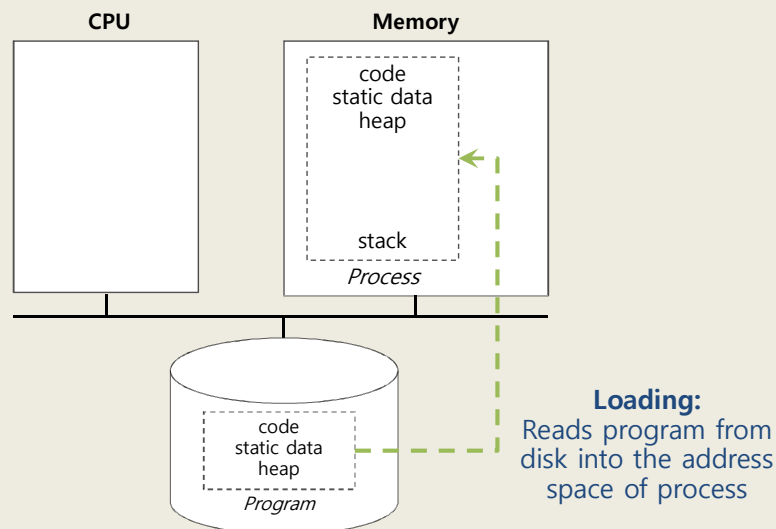
### 5. Start program running at the entry point: `main()`

- OS transfers CPU control to the new process

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## PROCESS STATES

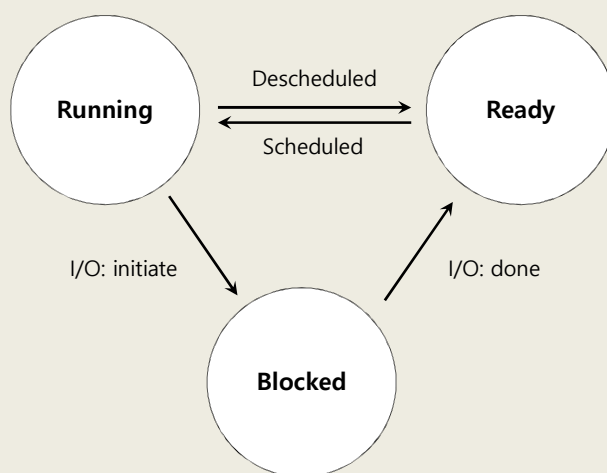
- **RUNNING**
  - Currently executing instructions
- **READY**
  - Process is ready to run, but has been preempted
  - CPU is presently allocated for other tasks
- **BLOCKED**
  - Process is **not** ready to run. It is waiting for another event to complete:
    - Process has already been initialized and run for awhile
    - Is now waiting on I/O from disk(s) or other devices

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## PROCESS STATE TRANSITIONS



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## PROCESS DATA STRUCTURES

- OS provides data structures to track process information
  - Process list
    - Process Data
    - State of process: Ready, Blocked, Running
  - Register context
- PCB (Process Control Block)
  - A C-structure that contains information about each process

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## XV6 KERNEL DATA STRUCTURES

- xv6: pedagogical implementation of Linux
- Simplified structures

```
// the registers xv6 will save and restore
// to stop and subsequently restart a process
struct context {
    int eip;    // Index pointer register
    int esp;    // Stack pointer register
    int ebx;    // Called the base register
    int ecx;    // Called the counter register
    int edx;    // Called the data register
    int esi;    // Source index register
    int edi;    // Destination index register
    int ebp;    // Stack base pointer register
};

// the different states a process can be in
enum proc_state { UNUSED, EMBRYO, SLEEPING,
                  RUNNABLE, RUNNING, ZOMBIE };
```

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## XV6 KERNEL DATA STRUCTURES - 2

```
// the information xv6 tracks about each process
// including its register context and state
struct proc {
    char *mem;                // Start of process memory
    uint sz;                  // Size of process memory
    char *kstack;             // Bottom of kernel stack
                                // for this process
    enum proc_state state;    // Process state
    int pid;                  // Process ID
    struct proc *parent;      // Parent process
    void *chan;               // If non-zero, sleeping on chan
    int killed;               // If non-zero, have been killed
    struct file *ofile[NOFILE]; // Open files
    struct inode *cwd;        // Current directory
    struct context context;    // Switch here to run process
    struct trapframe *tf;     // Trap frame for the
                                // current interrupt
};
```

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## LINUX: STRUCTURES

- **struct task\_struct**, equivalent to struct proc
  - Provides process description
  - Large: 10,000+ bytes
  - /usr/src/linux-headers-{kernel version}/include/linux/sched.h
    - 1227 - 1587
- **struct thread\_info**, provides “context”
  - thread\_info.h is at:
    - /usr/src/linux-headers-{kernel version}/arch/x86/include/asm/

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## LINUX: THREAD\_INFO

```
struct thread_info {
    struct task_struct    *task;           /* main task structure */
    struct exec_domain    *exec_domain;    /* execution domain */
    __u32                 flags;           /* low level flags */
    __u32                 status;          /* thread synchronous flags */
    __u32                 cpu;             /* current CPU */
    int                    preempt_count;  /* 0 => preemptable,
                                           <0 => BUG */

    mm_segment_t          addr_limit;
    struct restart_block  restart_block;
    void __user            *sysenter_return;

#ifdef CONFIG_X86_32
    unsigned long         previous_esp;    /* ESP of the previous stack in
                                           case of nested (IRQ) stacks
                                           */
    __u8                  supervisor_stack[0];

#endif
    int                    uaccess_err;
};
```

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## LINUX STRUCTURES - 2

- List of Linux data structures:  
<http://www.tldp.org/LDP/tlk/ds/ds.html>
- Description of process data structures:  
<http://www.makelinux.net/books/lkd2/ch03lev1sec1>  
2<sup>nd</sup> edition is online (dated from 2005):  
Linux Kernel Development, 2<sup>nd</sup> edition  
Robert Love  
Sams Publishing

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The image shows a presentation slide with a blue background and a dark blue sidebar on the right. The title "CHAPTER 5: C PROCESS API" is centered in large white text. On the sidebar, there is a white square containing a dark blue gear icon with the letters "API" in white. At the bottom left, the date "January 8, 2018" and the course information "TCSS422: Operating Systems [Winter 2018] Institute of Technology, University of Washington - Tacoma" are displayed in white. At the bottom right of the sidebar, the text "L2.36" is shown in white.

## fork()

- Creates a new process - think of “a fork in the road”
- “Parent” process is the original
- Creates “child” process of the program from the current execution point
- Book says “pretty odd”
- Creates a **duplicate** program instance (these are processes!)
- **Copy of**
  - Address space (memory)
  - Register
  - Program Counter (PC)
- **Fork returns**
  - child PID to parent
  - 0 to child



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## FORK EXAMPLE

### ■ p1.c

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>

int main(int argc, char *argv[]){
    printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {                // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) { // child (new process)
        printf("hello, I am child (pid:%d)\n", (int) getpid());
    } else {                // parent goes down this path (main)
        printf("hello, I am parent of %d (pid:%d)\n",
            rc, (int) getpid());
    }
    return 0;
}
```

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FORK EXAMPLE - 2

■ Non deterministic ordering of execution

```
prompt> ./p1
hello world (pid:29146)
hello, I am parent of 29147 (pid:29146)
hello, I am child (pid:29147)
prompt>
```

or

```
prompt> ./p1
hello world (pid:29146)
hello, I am child (pid:29147)
hello, I am parent of 29147 (pid:29146)
prompt>
```

■ CPU scheduler determines which to run first

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:(){:|: & }::

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## wait()

- wait(), waitpid()
- Called by parent process
- Waits for a child process to finish executing
- Not a sleep() function
- Provides some ordering to multi-process execution



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## FORK WITH WAIT

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <sys/wait.h>

int main(int argc, char *argv[]){
    printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {                // fork failed; exit
        fprintf(stderr, "fork failed\n");
        exit(1);
    } else if (rc == 0) { // child (new process)
        printf("hello, I am child (pid:%d)\n", (int) getpid());
    } else { // parent goes down this path (main)
        int wc = wait(NULL);
        printf("hello, I am parent of %d (wc:%d) (pid:%d)\n",
            rc, wc, (int) getpid());
    }
    return 0;
}
```

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FORK WITH WAIT - 2

■ Deterministic ordering of execution

```
prompt> ./p2
hello world (pid:29266)
hello, I am child (pid:29267)
hello, I am parent of 29267 (wc:29267) (pid:29266)
prompt>
```

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FORK EXAMPLE

■ Linux example

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## exec()

- Supports running an external program
- 6 types: `execl()`, `execlp()`, `execle()`, `execv()`, `execvp()`, `execvpe()`
- `execl()`, `execlp()`, `execle()`: `const char *arg`  
List of pointers (terminated by null pointer)  
to strings provided as arguments... (`arg0`, `arg1`, .. `argn`)
- `Execv()`, `execvp()`, `execvpe()`  
Array of pointers to strings as arguments  
Strings are null-terminated  
First argument is name of file being executed

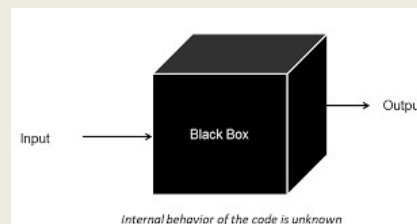
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## EXEC() - 2

- Common use case:
- Write a new program which wraps a legacy one
- Provide a new interface to an old system: Web services
- Legacy program thought of as a “black box”
- We don’t want to know what is inside... 😊



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