











WAITING FOR THREADS TO FINISH

```
int pthread join(pthread t thread, void **value ptr);
```

thread: which thread?

- Returned values *must* be on the heap
- Thread stacks destroyed upon thread termination (join)
- Pointers to thread stack memory addresses are invalid
 - May appear as gibberish or lead to crash (seg fault)
- Not all threads join What would be Examples ??

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```
struct myarg {
                    What will this code do?
  int a;
  int b;
void *worker(void *arg)
  struct myarg *input = (struct myarg *) arg;
printf("a=%d b=%d\n",input->a, input->b);
  struct myarg output;
                                  Data on thread stack
  output.a = 1;
  output.b = 2;
  return (void *) &output;
                                               $ ./pthread_struct
                                               a=10 b=20
                                               Segmentation fault (core dumped)
int main (int argc, char * argv[])
  pthread_t p1;
  struct myarg args;
  struct myarg *ret_args;
  args.a = 10;
  args.b = 20;
  pthread_0
  pthread_
printf("
               How can this code be fixed?
  return 0
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                                                                                   L7a.8
```

```
struct myarg {
                      How about this code?
  int a:
  int b;
};
void *worker(void *arg)
  struct myarg *input = (struct myarg *) arg;
printf("a=%d b=%d\n",input->a, input->b);
  input->a = 1;
  input->b = 2;
  return (void *) &input;
                                                              $ ./pthread struct
                                                              a=10 b=20
int main (int argc, char * argv[])
                                                              returned 1 2
  pthread_t p1;
  struct myarg args;
  struct myarg *ret_args;
  args.a = 10;
  args.b = 20;
  pthread_create(&p1, NULL, worker, &args);
  pthread_join(p1, (void *)&ret_args);
printf("returned %d %d\n", ret_args->a, ret_args->b);
  return 0;
}
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```

ADDING CASTS

- Casting
- Suppresses compiler warnings when passing "typed" data where (void) or (void *) is called for
- Example: uncasted capture in pthread_join
 pthread_int.c: In function 'main':
 pthread_int.c:34:20: warning: passing argument 2 of 'pthread_join'
 from incompatible pointer type [-Wincompatible-pointer-types]
 pthread_join(p1, &p1val);
- Example: uncasted return

```
In file included from pthread_int.c:3:0:
/usr/include/pthread.h:250:12: note: expected 'void **' but argument
is of type 'int **'
  extern int pthread_join (pthread_t __th, void **__thread_return);
```

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ADDING CASTS - 2 • pthread_join int * p1val; int * p2val; pthread_join(p1, (void *)&p1val); pthread_join(p2, (void *)&p2val); • return from thread function int * counterval = malloc(sizeof(int)); *counterval = counter; return (void *) counterval;

LOCKS pthread_mutex_t data type /usr/include/bits/pthread_types.h // Global Address Space static volatile int counter = 0; pthread_mutex_t lock; void *worker(void *arg) int i; for (i=0;i<10000000;i++) { int rc = pthread_mutex_lock(&lock); assert(rc==0); counter = counter + 1; pthread_mutex_unlock(&lock); return NULL; TCSS422: Operating Systems [Spring 2018] April 18, 2018 L7a.12 Institute of Technology, University of Washington - Tacoma

LOCKS - 2

- Ensure critical sections are executed atomically-as a unit
 - Provides implementation of "Mutual Exclusion"
- API

```
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

Example w/o initialization & error checking

```
pthread_mutex_t lock;
pthread_mutex_lock(&lock);
x = x + 1; // or whatever your critical section is
pthread_mutex_unlock(&lock);
```

- Blocks forever until lock can be obtained
- Enters critical section once lock is obtained
- Releases lock

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LOCK INITIALIZATION

Assigning the constant

```
pthread mutex t lock = PTHREAD MUTEX INITIALIZER;
```

API call:

```
int rc = pthread_mutex_init(&lock, NULL);
assert(rc == 0); // always check success!
```

- Initializes mutex with attributes specified by 2nd argument
- If NULL, then default attributes are used
- Upon initialization, the mutex is initialized and unlocked

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LOCKS - 3

Error checking wrapper

```
// Use this to keep your code clean but check for failure
// Only use if exiting program is OK upon failure
void Pthread_mutex_lock(pthread_mutex_t *mutex) {
   int rc = pthread_mutex_lock(mutex);
   assert(rc == 0);
}
```

■ What if lock can't be obtained?

- trylock returns immediately (fails) if lock is unavailable
- timelock tries to obtain a lock for a specified duration

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CONDITIONS AND SIGNALS

Condition variables support "signaling" between threads



- pthread_cond_t datatype
- pthread_cond_wait()
 - Puts thread to "sleep" (waits) (THREAD is BLOCKED)
 - Threads added to FIFO queue, lock is released
 - Waits (<u>listens</u>) for a "signal" (NON-BUSY WAITING, no polling)
 - When signal occurs, interrupt fires, wakes up first thread, (THREAD is RUNNING), lock is provided to thread

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CONDITIONS AND SIGNALS - 2

int pthread_cond_signal(pthread_cond_t * cond);
int pthread_cond_broadcast(pthread_cond_t * cond);

- pthread_cond_signal()
 - Called to send a "signal" to wake-up first thread in FIFO "wait" queue
 - The goal is to unblock a thread to respond to the signal
- pthread_cond_broadcast()
 - Unblocks <u>all</u> threads in FIFO "wait" queue, currently blocked on the specified condition variable
 - Broadcast is used when all threads should wake-up for the signal
- Which thread is unblocked first?
 - Determined by OS scheduler (based on priority)
 - Thread(s) awoken based on placement order in FIFO wait queue
 - When awoken threads acquire lock as in pthread_mutex_lock()

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CONDITIONS AND SIGNALS - 3

```
Wait example:
```

```
pthread mutex t lock = PTHREAD MUTEX_INITIALIZER;
pthread_cond t cond = PTHREAD_COND_INITIALIZER;

pthread mutex lock(&lock);
while (initialized == 0)
    pthread_cond_wait(&cond, &lock);

// Perform work that requires lock
a = a + b;
pthread_mutex_unlock(&lock);
```

- wait puts thread to sleep, releases lock
- when awoken, lock reacquired (but then released by this code)
- When initialized, another thread signals

State variable set, Enables other thread(s) to proceed above.

pthread_mutex_lock(&lock);
initialized = 1;
pthread_cond_signal(&init);
pthread mutex_unlock(&lock);

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CONDITION AND SIGNALS - 4

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;

pthread mutex lock(&lock);
while (initialized == 0)
    pthread cond wait(&cond, &lock);

// Perform work that requires lock
a = a + b;
pthread_mutex_unlock(&lock);
```

- Why do we wait inside a while loop?
- The while ensures upon awakening the condition is rechecked
 - A signal is raised, but the pre-conditions required to proceed may have not been met. **MUST CHECK STATE VARIABLE**
 - Without checking the state variable the thread may proceed to execute when it should not. (e.g. too early)

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PTHREADS LIBRARY

- Compilation
 - gcc -pthread pthread.c -o pthread
 - Requires explicitly linking the library with compiler flag
 - Use makefile to provide compiler arguments
- List of pthread manpages
 - man -k pthread

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