


TCSS 422: OPERATING SYSTEMS

Three Easy Pieces:
Ch. 26: Concurrency Introduction

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OBJECTIVES

- Concurrency: Introduction – Ch. 26

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CHAPTER 26 -
CONCURRENCY:
AN INTRODUCTION

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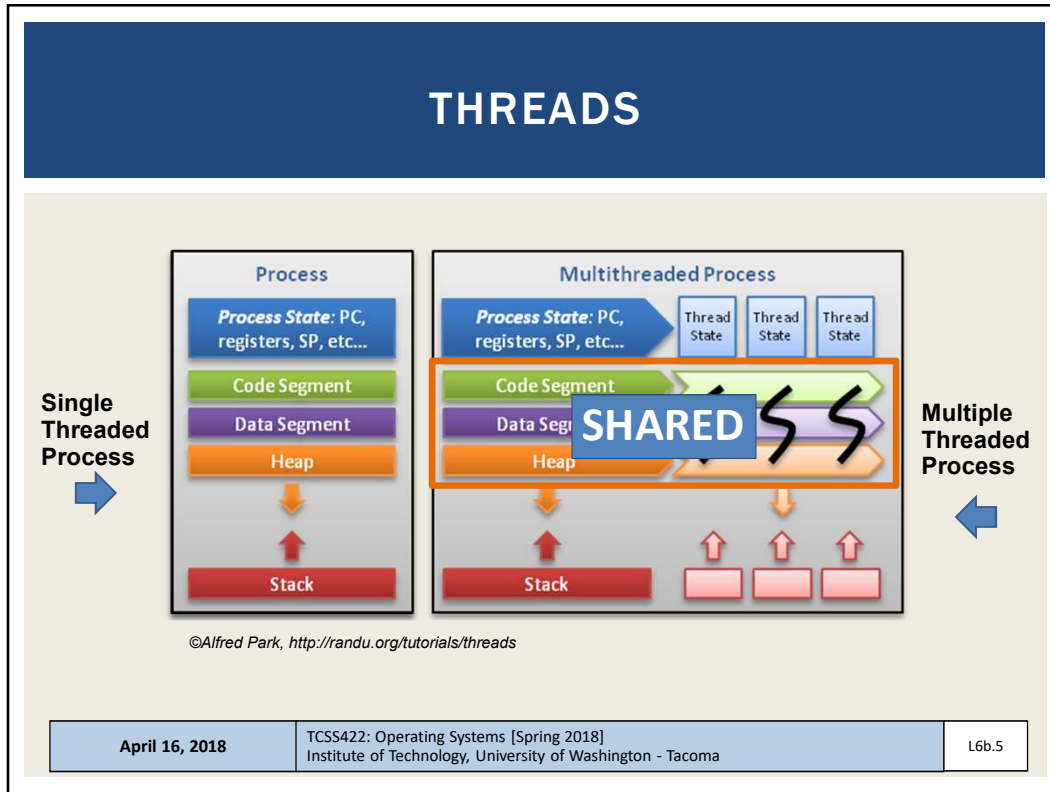
OBJECTIVES

- Introduction to threads
- Race condition
- Critical section
- Thread API

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THREADS - 2

- Enables a single process (program) to have multiple “workers”
- Supports independent path(s) of execution within a program *with shared memory ...*
- Each thread has its own Thread Control Block (TCB)
 - PC, registers, SP, and stack
- Code segment, memory, and heap are shared

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PROCESS AND THREAD METADATA

■ Thread Control Block vs. Process Control Block

Thread identification
Thread state
CPU information:
 Program counter
 Register contents
Thread priority
Pointer to process that created this thread
Pointers to all other threads created by this thread

Process identification
Process status
Process state:
 Process status word
 Register contents
 Main memory
 Resources
 Process priority
Accounting

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SHARED ADDRESS SPACE

■ Every thread has it's own stack / PC

0KB
1KB
2KB
15KB
16KB

Program Code

Heap

(free)

Stack (1)

The code segment:
where instructions live

The heap segment:
contains malloc'd data
dynamic data structures
(it grows downward)

(it grows upward)
The stack segment:
contains local variables
arguments to routines,
return values, etc.

A Single-Threaded
Address Space

0KB
1KB
2KB
15KB
16KB

Program Code

Heap

(free)

Stack (2)

(free)

Stack (1)

Two threaded
Address Space

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THREAD CREATION EXAMPLE

```
#include <stdio.h>
#include <assert.h>
#include <pthread.h>

void *mythread(void *arg) {
    printf("%s\n", (char *) arg);
    return NULL;
}

int
main(int argc, char *argv[]) {
    pthread_t p1, p2;
    int rc;
    printf("main: begin\n");
    rc = pthread_create(&p1, NULL, mythread, "A"); assert(rc == 0);
    rc = pthread_create(&p2, NULL, mythread, "B"); assert(rc == 0);
    // join waits for the threads to finish
    rc = pthread_join(p1, NULL); assert(rc == 0);
    rc = pthread_join(p2, NULL); assert(rc == 0);
    printf("main: end\n");
    return 0;
}
```

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POSSIBLE ORDERINGS OF EVENTS

Int main()	Thread 1	Thread 2
Starts running		
Prints 'main: begin'		
Creates Thread 1		
Creates Thread 2		
Waits for T1		
	Runs	
	Prints 'A'	
	Returns	
Waits for T2		
		Runs
		Prints 'B'
		Returns
Prints 'main: end'		

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POSSIBLE ORDERINGS OF EVENTS - 2

int main()	Thread 1	Thread 2
Starts running		
Prints 'main: begin'		
Creates Thread 1		
	Runs	
	Prints 'A'	
	Returns	
Creates Thread 2		
		Runs
		Prints 'B'
		Returns
Waits for T1	Returns immediately	
Waits for T2		Returns immediately
Prints 'main: end'		

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POSSIBLE ORDERINGS OF EVENTS - 3

int main()	Thread 1	Thread 2
Starts running		
Prints 'main: begin'		
Creates Thread 1		
Creates Thread 2		
Waits for T1		
	Runs	
	Prints 'A'	
	Returns	
Waits for T2		Immediately returns
Prints 'main: end'		

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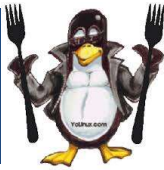
COUNTER EXAMPLE

- Counter example
 - A + B : ordering
 - Counter: incrementing global variable by two threads

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PROCESSES VS. THREADS

- What's the difference between forks and threads?
 - Forks: duplicate a process
 - Think of **CLONING** - There will be two identical processes at the end
 - Threads: no duplicate of code/heap, lightweight execution threads

Process

Process State: PC, registers, SP, etc...

Code Segment

Data Segment

Heap

Stack

Process

Process State: PC, registers, SP, etc...

Code Segment

Data Segment

Heap

Stack

code

data

files

registers

stack

thread →

single-threaded process

code

data

files

registers

registers

registers

stack

stack

stack

← thread

multithreaded process

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RACE CONDITION

- What is happening with our counter?
 - When counter=50, consider code: counter = counter + 1
 - If synchronized, counter will = 52

OS	Thread1	Thread2	(after instruction)		
			PC	%eax	counter
{	before critical section		100	0	50
	mov 0x8049a1c, %eax		105	50	50
	add \$0x1, %eax		108	51	50
	interrupt				
{	save T1's state				
	restore T2's state		100	0	50
		mov 0x8049a1c, %eax	105	50	50
		add \$0x1, %eax	108	51	50
		mov %eax, 0x8049a1c	113	51	51
	interrupt				
{	save T2's state				
	restore T1's state		108	51	50
	mov %eax, 0x8049a1c		113	51	51


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CRITICAL SECTION

- Code that accesses a shared variable must not be concurrently executed by more than one thread
- Multiple active threads inside a critical section produce a race condition.
- Atomic execution (all code executed as a unit) must be ensured in critical sections
 - These sections must be mutually exclusive



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LOCKS

- To demonstrate how critical section(s) can be executed “atomically-as a *unit*” Chapter 27 & beyond introduce locks

```
1  lock_t mutex;  
2  . . .  
3  lock(&mutex);  
4  balance = balance + 1;  
5  unlock(&mutex);
```

Critical section

- Counter example revisited

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QUESTIONS

