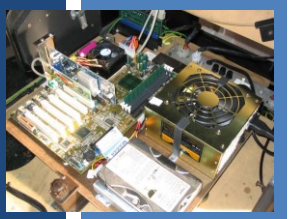
TCSS 422: OPERATING SYSTEMS



Memory Virtualization with Segments, Introduction to Paging

Wes J. Lloyd
School of Engineering and Technology
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MIDTERM REVIEW SESSION

- Make-up midterm exams are scheduled and will be completed by the end of Friday this week
- **Midterm Review Session:**
- Tuesday May 21, 6:00 pm (during office hour, from BHS106)
- Via Zoom / Live Stream / Recording
- Will discuss and review midterm exam problems and grading

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OBJECTIVES – 5/14

- **Questions from 5/9**
- Assignment 2 - May 31
- Quiz 3 – Class Activity-Synchronized Array - Thursday
- Tutorial 2 – Pthread/locks/conditions tutorial-Fri May 24
- Chapter 13: Address Spaces
- Chapter 14: The Memory API
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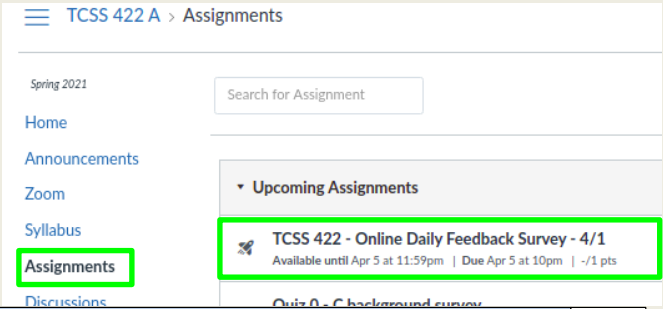
ONLINE DAILY FEEDBACK SURVEY

- Daily Feedback Quiz in Canvas – Available After Each Class
- Extra credit available for completing surveys ***ON TIME***
- Tuesday surveys: due by ~ Wed @ 11:59p
- Thursday surveys: due ~ Mon @ 11:59p



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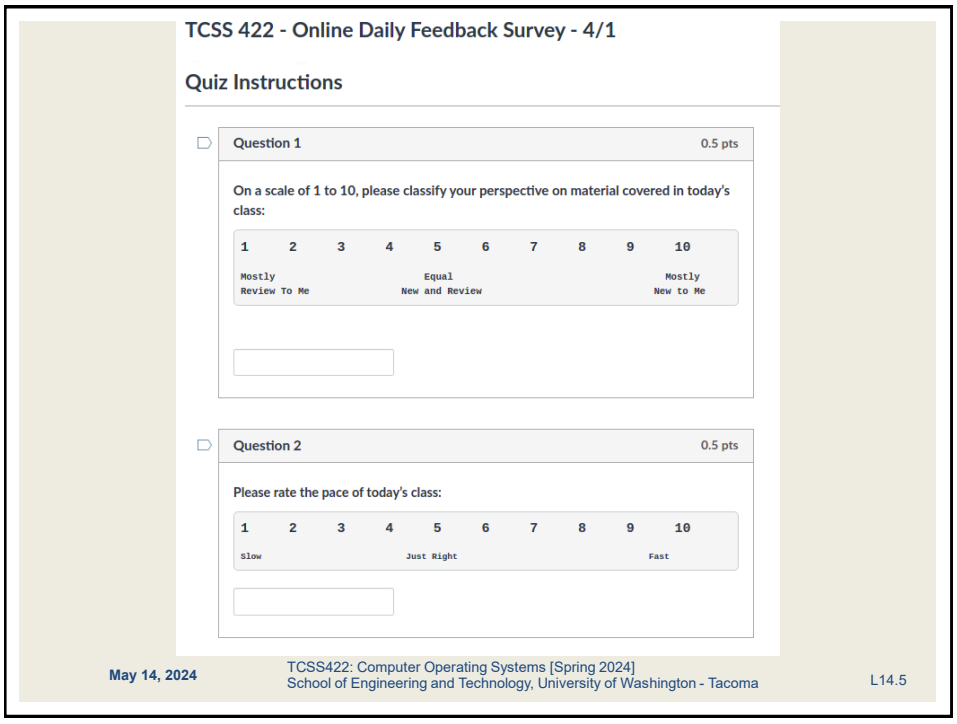
TCSS 422 - Online Daily Feedback Survey - 4/1
Quiz Instructions
Question 1
0.5 pts
On a scale of 1 to 10, please classify your perspective on material covered in today's class:
1 2 3 4 5 6 7 8 9 10
Mostly Review To Me
Equal New and Review
Mostly New to Me
Question 2
0.5 pts
Please rate the pace of today's class:
1 2 3 4 5 6 7 8 9 10
Slow
Just Right
Fast
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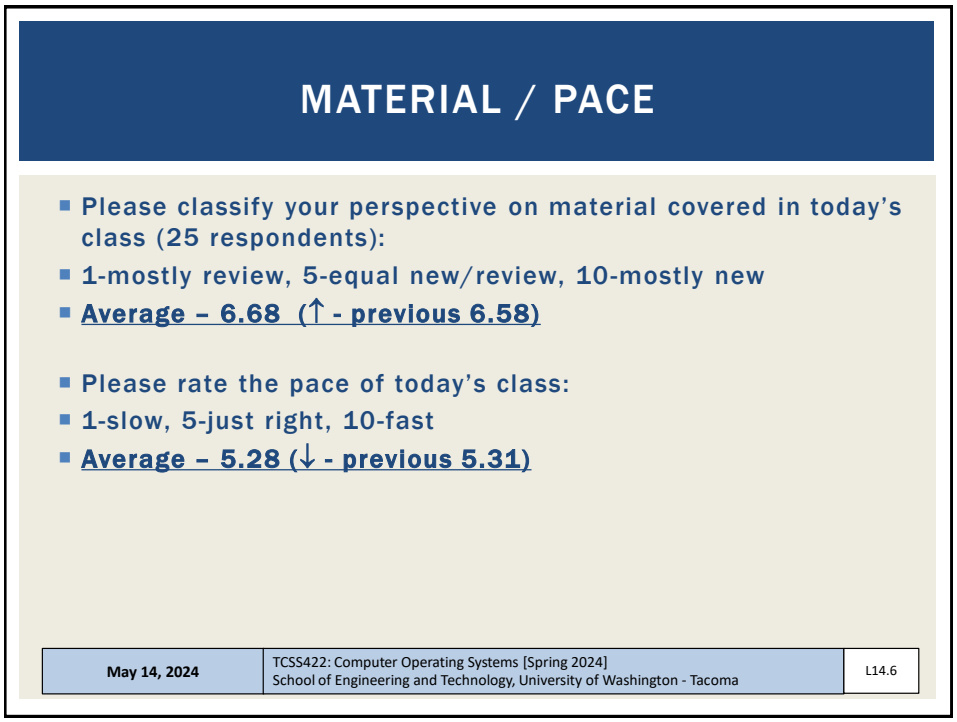
MATERIAL / PACE
Please classify your perspective on material covered in today's class (25 respondents):
1-mostly review, 5-equal new/review, 10-mostly new
Average – 6.68 (↑ - previous 6.58)
Please rate the pace of today's class:
1-slow, 5-just right, 10-fast
Average – 5.28 (↓ - previous 5.31)
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FEEDBACK FROM 5/9

- ***Is list insertion the only deadlock prevention for mutual exclusion?***
- List insertion is not a deadlock prevention technique in Chapter 32
- In lecture 13, the "mutual exclusion" cause for deadlock is when critical sections of code are protected with locks, and for some reason, the lock is never available
- The solution is to remove the use of locks where possible by replacing locks with an atomic implementation of the CompareAndSwap CPU instruction (***assembly language***)
- Atomic CompareAndSwap (assembly) can be used to eliminate the use locks as shown Chapter 32 examples:
  - Increment a counter variable atomically
  - Insert an item into a list

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FEEDBACK - 2

- ***Is list insertion the only deadlock prevention for mutual exclusion?***
- KEY TAKEHOME MESSAGE from Chapter 32:
- Protecting critical code sections with locks is the "Mutual Exclusion" cause for deadlock in Chapter 32
- The solution is to eliminate locks to remove the requirement for mutual exclusion in high-level program code (C)
- Locks can be replaced with atomic CPU instructions (CompareAndSwap) or atomic data types can be used
  - E.g. lock-free data structures in Java

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CHAPTER 13: ADDRESS SPACES

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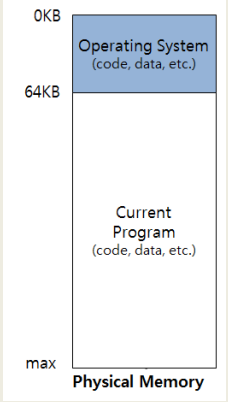
EARLY MEMORY MANAGEMENT

- Load one process at a time into memory
- Poor memory utilization
- Little abstraction



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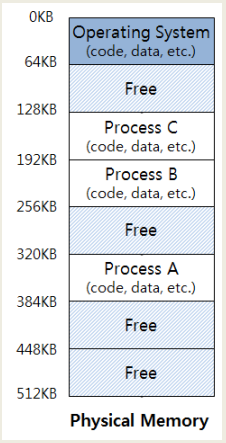
MULTIPROGRAMMING WITH SHARED MEMORY

- Later machines supported running multiple processes
- Swap out processes during I/O waits to increase system utilization and efficiency
- Swap entire memory of a process to disk for context switch
- Too slow, especially for large processes
- Solution→
  - Leave processes in memory
- Need to protect from errant memory accesses in a multiprocessing environment



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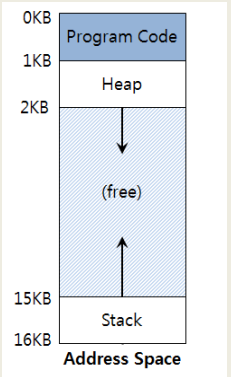
ADDRESS SPACE

- Easy-to-use abstraction of physical memory for a process
- Main elements:
  - Program code
  - Stack
  - Heap
- Example: 16KB address space



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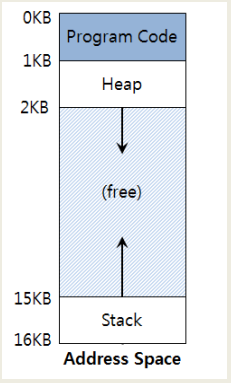
ADDRESS SPACE - 2

- Code
  - Program code
- Stack
  - Program counter (PC)
  - Local variables
  - Parameter variables
  - Return values (for functions)
- Heap
  - Dynamic storage
  - Malloc() new()



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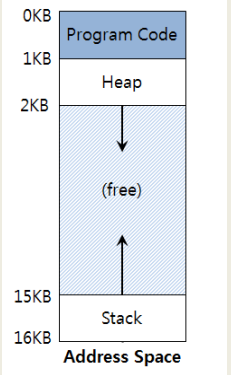
ADDRESS SPACE - 3

- Program code
  - Static size
- Heap and stack
  - Dynamic size
  - Grow and shrink during program execution
  - Placed at opposite ends
- Addresses are virtual
  - They must be physically mapped by the OS



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VIRTUAL ADDRESSING

- Every address is virtual
  - OS translates virtual to physical addresses

```
#include <stdio.h>
#include <stdlib.h>

int main(int argc, char *argv[]){

    printf("location of code  : %p\n", (void *) main);
    printf("location of heap  : %p\n", (void *) malloc(1));
    int x = 3;
    printf("location of stack : %p\n", (void *) &x);

    return x;
}
```

  - EXAMPLE: virtual.c

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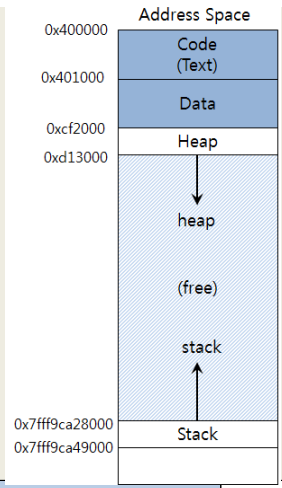
VIRTUAL ADDRESSING - 2

- Output from 64-bit Linux:

```
location of code: 0x400686
location of heap: 0x1129420
location of stack: 0x7ffe040d77e4
```



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GOALS OF OS MEMORY VIRTUALIZATION

- Transparency
  - Memory shouldn't appear virtualized to the program
  - OS multiplexes memory among different jobs behind the scenes
- Protection
  - Isolation among processes
  - OS itself must be isolated
  - One program should not be able to affect another (or the OS)

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GOALS - 2

- Efficiency
  - Time
    - Performance: virtualization must be fast
  - Space
    - Virtualization must not waste space
    - Consider data structures for organizing memory
    - Hardware support TLB: Translation Lookaside Buffer
- *Goals considered when evaluating memory virtualization schemes*

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OBJECTIVES – 5/14

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CHAPTER 14: THE MEMORY API

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OBJECTIVES – 5/18

- **Chapter 13: Introduction to memory virtualization**
  - The address space
  - Goals of OS memory virtualization
- **Chapter 14: Memory API**
  - Common memory errors

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MALLOC

```
#include <stdlib.h>

void* malloc(size_t size)
```

- Allocates memory on the heap
- size_t unsigned integer (must be +)
- size size of memory allocation in bytes

- Returns
- SUCCESS: A void * to a memory address
- FAIL: NULL

- sizeof() often used to ask the system how large a given datatype or struct is

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SIZEOF()

- Not safe to assume data type sizes using different compilers, systems
- Dynamic array of 10 ints
- Static array of 10 ints

```
int *x = malloc(10 * sizeof(int));
printf("%d\n", sizeof(x));
```

```
4
```

```
int x[10];
printf("%d\n", sizeof(x));
```

```
40
```


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FREE()

```
#include <stdlib.h>

void free(void* ptr)
```

- Free memory allocated with malloc()
- Provide: (void *) ptr to malloc'd memory
- Returns: nothing

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```
#include<stdio.h>

int * set_magic_number_a()
{
  int a =53247;
  return &a;
}

void set_magic_number_b()
{
  int b = 11111;
}

int main()
{
  int * x = NULL;
  x = set_magic_number_a();
  printf("The magic number is=%d\n“,*x);
  set_magic_number_b();
  printf(“The magic number is=%d\n“,*x);
  return 0;
}
```

What will this code do?

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```
#include<stdio.h>

int * set_magic_number_a()
{
  int a =53247;
  return &a;
}

void set_magic_number_b()
{
  int b = 11111;
}

int main()
{
  int * x = NULL;
  x = set_magic_number_a();
  printf("The magic number is=%d\n“,*x);
  set_magic_number_b();
  printf("The magic number is=%d\n“,*x);
  return 0;
}
```

What will this code do?

Output:

```
$ ./pointer_error
The magic number is=53247
The magic number is=11111
```

We have not changed *x but the value has changed!!

Why?

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DANGLING POINTER (1/2)

- Dangling pointers arise when a variable referred (a) goes "out of scope", and it's memory is destroyed/overwritten (by b) without modifying the value of the pointer (*x).
- The pointer still points to the original memory location of the deallocated memory (a), which has now been reclaimed for (b).

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DANGLING POINTER (2/2)

- Fortunately in the case, a compiler warning is generated:

```
$ g++ -o pointer_error -std=c++0x pointer_error.cpp

pointer_error.cpp: In function 'int*
set_magic_number_a()':
pointer_error.cpp:6:7: warning: address of local
variable 'a' returned [enabled by default]
```

- This is a common mistake - - - accidentally referring to addresses that have gone "out of scope"

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CALLOC()

```
#include <stdlib.h>

void *calloc(size_t num, size_t size)
```

- Allocate "C"lear memory on the heap
- Calloc wipes memory in advance of use…
- `size_t num` : number of blocks to allocate
- `size_t size` : size of each block(in bytes)

- Calloc() prevents…

```
char *dest = malloc(20);
printf("dest string=%s\n", dest);

dest string=��F
```


REALLOC()

```
#include <stdlib.h>

void *realloc(void *ptr, size_t size)
```

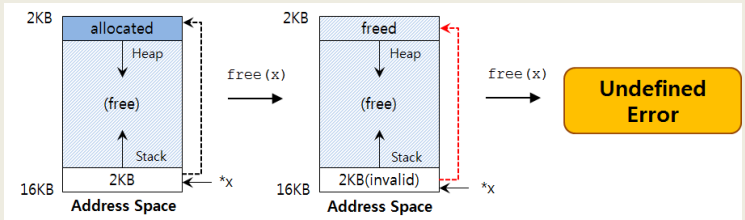
- Resize an existing memory allocation
- Returned pointer may be same address, or a new address
  - New if memory allocation must move
- `void *ptr`: Pointer to memory block allocated with malloc, calloc, or realloc
- `size_t size`: New size for the memory block(in bytes)

- EXAMPLE: realloc.c
- EXAMPLE: nom.c

DOUBLE FREE

```
int *x = (int *)malloc(sizeof(int)); // allocated
free(x); // free memory
free(x); // free repeatedly
```

- Can't deallocate twice
- Second call core dumps



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SYSTEM CALLS

- brk(), sbrk()
  - Used to change data segment size (the end of the heap)
  - Don't use these
- Mmap(), munmap()
  - Can be used to create an extra independent "heap" of memory for a user program
  - See man page

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WE WILL RETURN AT 5:07PM

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OBJECTIVES – 5/14

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CHAPTER 15: ADDRESS TRANSLATION

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OBJECTIVES – 5/18

- **Chapter 15: Address translation**
  - **Base and bounds**
  - **HW and OS Support**

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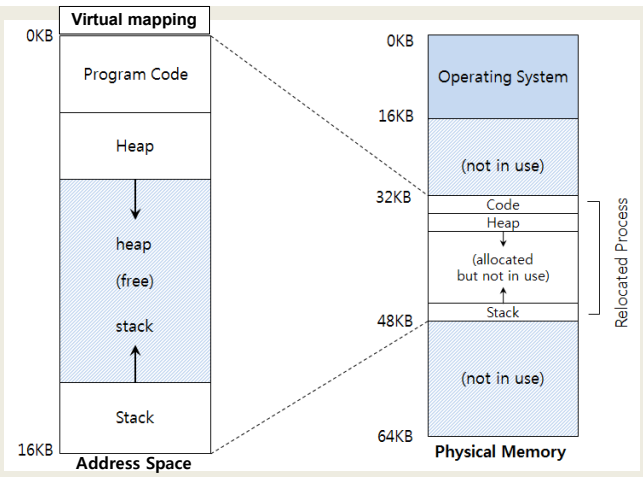
ADDRESS TRANSLATION

- 64KB Address space example
- Translation: mapping virtual to physical



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BASE AND BOUNDS

- Dynamic relocation
- Two registers base & bounds: **on the CPU**
- OS places program in memory
- Sets base register

$$physical\ address = virtual\ address + base$$

- Bounds register
  - Stores size of program address space (16KB)
- OS verifies that every address:

$$0 \leq virtual\ address < bounds$$

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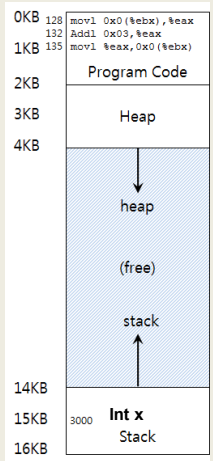
INSTRUCTION EXAMPLE

```
128 : movl 0x0(%ebx), %eax
```

- Base = 32768
- Bounds =16384
- Fetch instruction at 128 (virt addr) ↑
  - Phy addr = virt addr + base reg
  - 32896 = 128 + 32768 (base)
- Execute instruction
  - Load from address (var x is @ 15kb=15360)
  - 48128 = 15360 + 32768 (base) -- found x…
- Bounds register: terminate process if
  - ACCESS VIOLATION: Virtual address > bounds reg

physical address = virtual address + base



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MEMORY MANAGEMENT UNIT

- MMU
  - Portion of the CPU dedicated to address translation
  - Contains base & bounds registers
- Base & Bounds Example:
  - Consider address translation
  - 4 KB (4096 bytes) address space, loaded at 16 KB physical location

	Virtual Address	Physical Address
	0	16384
	1024	17408
	3000	19384
FAULT	4400	20784 (out of bounds)

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DYNAMIC RELOCATION OF PROGRAMS

- Hardware requirements:

Requirements	HW support
Privileged mode	CPU modes: kernel, user
Base / bounds registers	Registers to support address translation
Translate virtual addr; check if in bounds	Translation circuitry, check limits
Privileged instruction(s) to update base / bounds regs	Instructions for modifying base/bound registers
Privileged instruction(s) to register exception handlers	Set code pointers to OS code to handle faults
Ability to raise exceptions	For out-of-bounds memory access, or attempts to access privileged instr.

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OS SUPPORT FOR MEMORY VIRTUALIZATION

- For base and bounds OS support required
  - When process starts running
    - Allocate address space in physical memory
  - When a process is terminated
    - Reclaiming memory for use
  - When context switch occurs
    - Saving and storing the base-bounds pair
  - Exception handlers
    - Function pointers set at OS boot time

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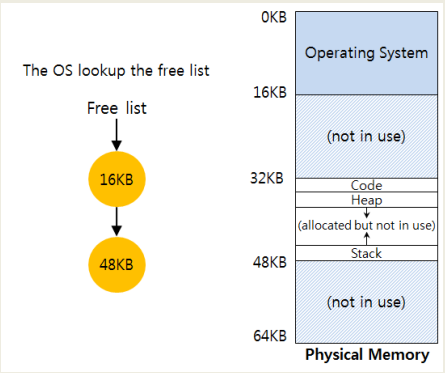
OS: WHEN PROCESS STARTS RUNNING

- OS searches for free space for new process
  - Free list: data structure that tracks available memory slots



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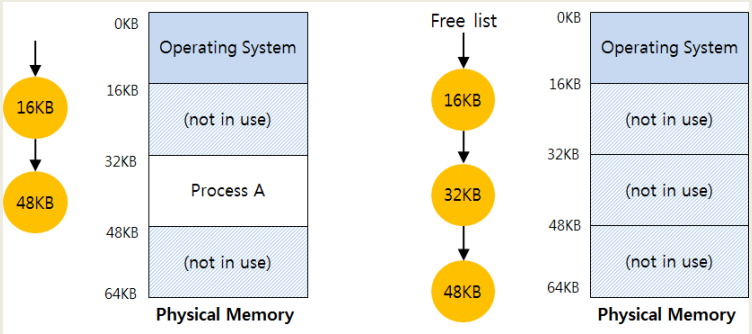
OS: WHEN PROCESS IS TERMINATED

- OS places memory back on the free list



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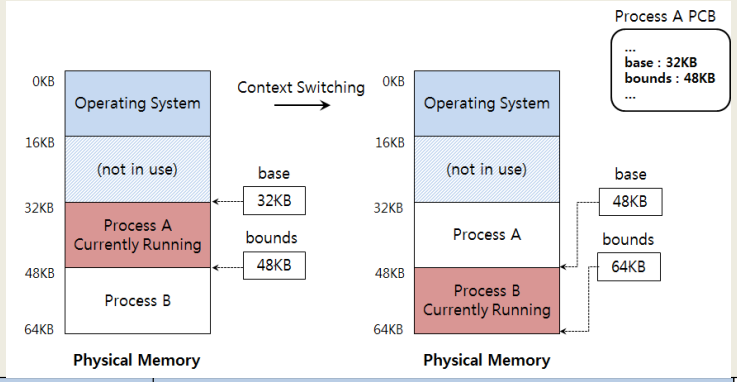
OS: WHEN CONTEXT SWITCH OCCURS

- OS must save base and bounds registers
  - Saved to the Process Control Block PCB (task_struct in Linux)



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DYNAMIC RELOCATION

- OS can move process data when not running

1. OS un-schedules process from scheduler
2. OS copies address space from current to new location
3. OS updates PCB (base and bounds registers)
4. OS reschedules process

- When process runs new base register is restored to CPU
- **Process doesn't know it was even moved!**

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Consider a 64KB computer the loads a program. The BASE register is set to 32768, and the BOUNDS register is set to 4096. What is the physical memory address translation for a virtual address of 6000 ?

- 34768
- 38768
- 32769
- 36864
- Out of bounds

Start the presentation to see live content. For screen share software, share the entire screen. Get help at **pollev.com/app**

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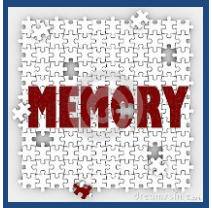
CHAPTER 16: SEGMENTATION



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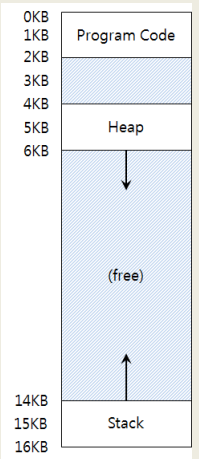
BASE AND BOUNDS INEFFICIENCIES

- Address space
  - Contains significant unused memory
  - Is relatively large
  - Preallocates space to handle stack/heap growth
- Large address spaces
  - Hard to fit in memory
- How can these issues be addressed?



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MULTIPLE SEGMENTS

- Memory segmentation
- Manage the address space as (3) separate segments
  - Each is a contiguous address space
  - Provides logically separate segments for: code, stack, heap
- Each segment can placed separately
- Track base and bounds for each segment (registers)

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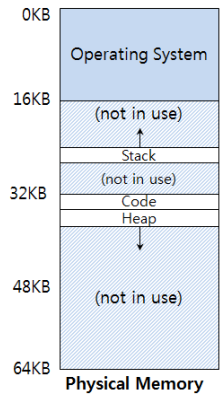
SEGMENTS IN MEMORY

- Consider 3 segments:



Much smaller

Segment	Base	Size
Code	32K	2K
Heap	34K	2K
Stack	28K	2K

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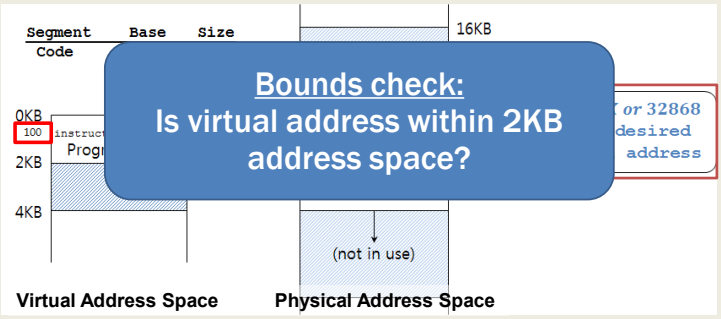
ADDRESS TRANSLATION: CODE SEGMENT

$$physical\ address = offset + base$$

- Code segment - physically starts at 32KB (base)
- Starts at "0" in virtual address space



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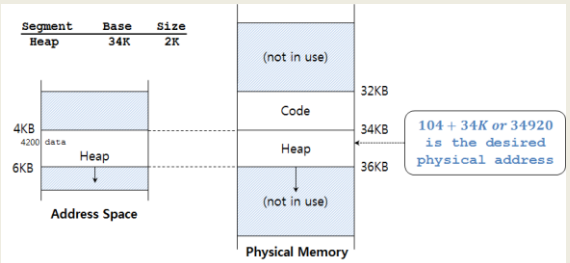
ADDRESS TRANSLATION: HEAP

Virtual address + base is not the correct physical address.

- Heap starts at virtual address 4096
- The data is at 4200
- Offset= 4200 – 4096 = 104 (virt addr – virt heap start)
- Physical address = 104 + 34816 (offset + heap base)



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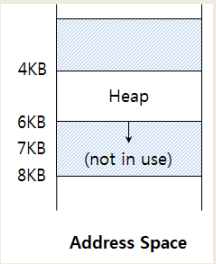
SEGMENTATION FAULT

- Access beyond the address space
- Heap starts at virtual address: 4096
- Data pointer is to 7KB (7168)
- Is data pointer valid?

- Heap starts at 4096 + 2 KB seg size = 6144
- Offset= 7168 > 4096 + 2048 (6144)



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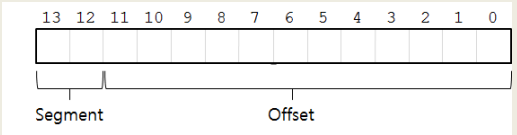
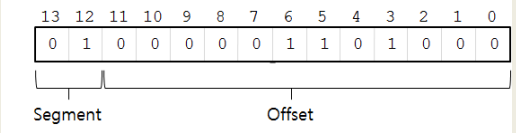
SEGMENT REGISTERS

- Used to dereference memory during translation



- First two bits identify segment type
- Remaining bits identify memory offset
- Example: virtual heap address 4200 (01000001101000)



Segment	bits
Code	00
Heap	01
Stack	10
-	11

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SEGMENTATION DEREFERENCE

```
1   // get top 2 bits of 14-bit VA
2   Segment = (VirtualAddress & SEG_MASK) >> SEG_SHIFT
3   // now get offset
4   Offset = VirtualAddress & OFFSET_MASK
5   if (Offset >= Bounds[Segment])
6        RaiseException(PROTECTION_FAULT)
7   else
8        PhysAddr = Base[Segment] + Offset
9        Register = AccessMemory(PhysAddr)
```

- VIRTUAL ADDRESS = 01000001101000 (on heap)
- SEG_MASK = 0x3000 (11000000000000)
- SEG_SHIFT = 01 → ***heap*** (mask gives us segment code)
- OFFSET_MASK = 0xFFF (00111111111111)
- OFFSET = 000001101000 = 104 (isolates segment offset)
- OFFSET < BOUNDS : 104 < 2048

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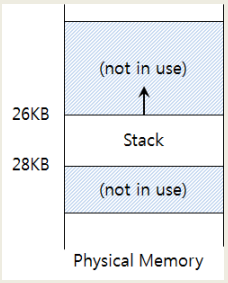
STACK SEGMENT

- Stack grows backwards (FILO)
- Requires hardware support:
- Direction bit: tracks direction segment grows



Segment Register(with Negative-Growth Support)

Segment	Base	Size	Grows Positive?
Code	32K	2K	1
Heap	34K	2K	1
Stack	28K	2K	0

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SHARED CODE SEGMENTS

- Code sharing: enabled with HW support
- Supports storing shared libraries in memory only once
- DLL: dynamic linked library
- .so (linux): shared object in Linux (under /usr/lib)
- Many programs can access them
- Protection bits: track permissions to segment

Segment Register Values(with Protection)

Segment	Base	Size	Grows Positive?	Protection
Code	32K	2K	1	Read-Execute
Heap	34K	2K	1	Read-Write
Stack	28K	2K	0	Read-Write

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Consider a program with 2KB of code, a 1 KB stack, and a 2 KB heap. This program runs on a 64 KB computer that manages memory with 4 kb segments. If the computer is empty and segments were allocated as: code, stack, heap, how large can the heap grow to?

32 KB
56 KB
24 KB
4 KB
0 KB

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SEGMENTATION GRANULARITY

- Coarse-grained
- Manage memory as large purpose based segments:
  - Code segment
  - Heap segment
  - Stack segment

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SEGMENTATION GRANULARITY - 2

- Fine-grained
- Manage memory as list of segments
- Code, heap, stack segments composed of multiple smaller segments
- Segment table
  - On early systems
  - Stored in memory
  - Tracked large number of segments

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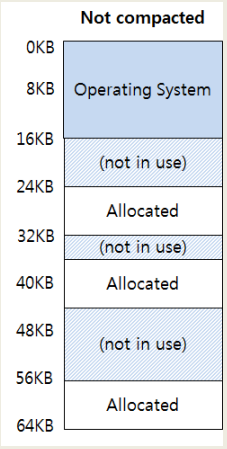
MEMORY FRAGMENTATION

- Consider how much free space?
- We'll say about 24 KB
- Request arrives to allocate a 20 KB heap segment
- Can we fulfil the request for 20 KB of contiguous memory?



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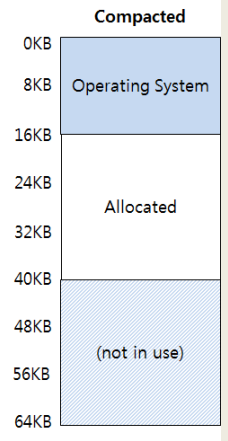
COMPACTION

- Supports rearranging memory
- Can we fulfil the request for 20 KB of contiguous memory?
- **Drawback:** Compaction is slow
  - Rearranging memory is time consuming
  - 64KB is fast
  - 4GB+ … slow
- Algorithms:
  - Best fit: keep list of free spaces, allocate the most snug segment for the request
  - Others: worst fit, first fit… (in future chapters)



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OBJECTIVES – 5/14

- Questions from 5/9
- Assignment 2 - May 31
- Quiz 3 – Activity-Synchronized Array - Thursday
- Tutorial 2 – Pthread/locks/conditions tutorial-Fri May 24
- Chapter 13: Address Spaces
- Chapter 14: The Memory API
- Chapter 15: Address Translation
- Chapter 16: Segmentation
- **Chapter 17: Free Space Management**
- Chapter 18: Introduction to Paging

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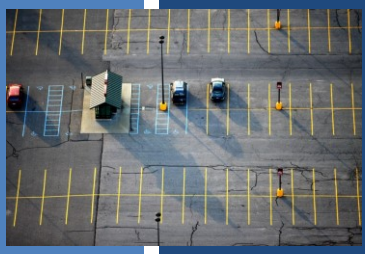

CHAPTER 17: FREE SPACE MANAGEMENT

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OBJECTIVES – 5/18

- **Chapter 17: Free Space Management**
  - Fragmentation, Splitting, coalescing
  - The Free List
  - Memory Allocation Strategies

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FREE SPACE MANAGEMENT

- How should free space be managed, when satisfying variable-sized requests?
- What strategies can be used to minimize fragmentation?
- What are the time and space overheads of alternate approaches?

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FREE SPACE MANAGEMENT

- Management of memory using
- Only fixed-sized units
  - Easy: keep a list
  - Memory request → return first free entry
    - Simple search
- With variable sized units
  - More challenging
  - Results from variable sized malloc requests
  - Leads to fragmentation

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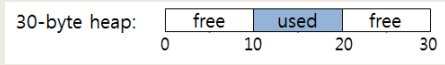
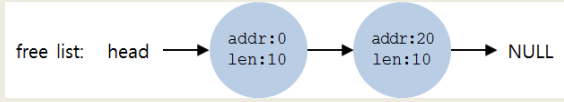
FRAGMENTATION

- Consider a 30-byte heap



- Request for 15-bytes



- Free space: 20 bytes
- No available contiguous chunk → return NULL

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FRAGMENTATION - 2

- **External:** *OS can compact*
  - Example: Client asks for 100 bytes: malloc(100)
  - OS: No 100 byte contiguous chunk is available: returns NULL
  - Memory is externally fragmented - - Compaction can fix!
- **Internal:** *lost space – OS can't compact*
  - OS returns memory units that are too large
  - Example: Client asks for 100 bytes: malloc(100)
  - OS: Returns 125 byte chunk
  - Fragmentation is *in* the allocated chunk
  - Memory is lost, and unaccounted for – can't compact

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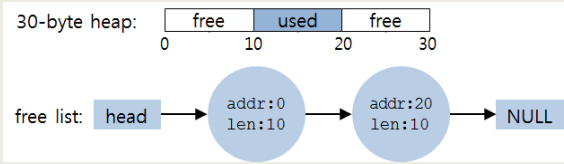
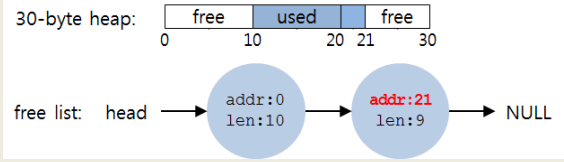
ALLOCATION STRATEGY: SPLITTING

- Request for 1 byte of memory: malloc(1)



- OS locates a free chunk to satisfy request
- Splits chunk into two, returns first chunk



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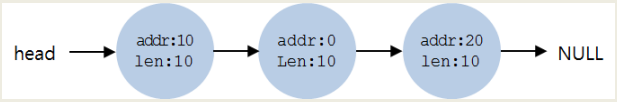
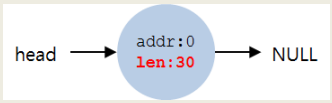
ALLOCATION STRATEGY: COALESCING

- Consider 30-byte heap
- Free() frees all 10 bytes segments *(list of 3-free 10-byte chunks)*



- Request arrives: malloc(30)
- ***SPLIT DOES NOT WORK*** - no contiguous 30-byte chunk exists!
- Coalescing regroups chunks into contiguous chunk



- Allocation can now proceed
- Coalescing is defragmentation of the free space list

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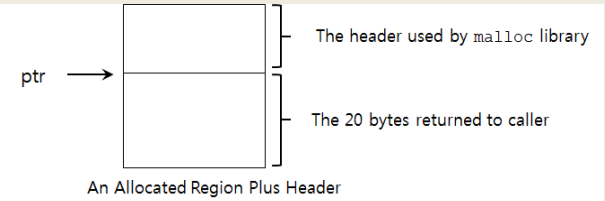
MEMORY HEADERS

- free(void *ptr): Does not require a size parameter
- *How does the OS know how much memory to free?*
- Header block
  - Small descriptive block of memory at start of chunk



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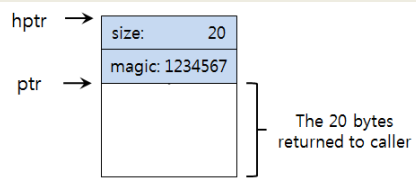
MEMORY HEADERS - 2




```
typedef struct __header_t {
        int size;
        int magic;
} header_t;
```

A Simple Header

- Contains size
- Pointers: for faster memory access
- Magic number: integrity checking

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MEMORY HEADERS - 3

- Size of memory chunk is:
- Header size + user malloc size
- N bytes + sizeof(header)

- Easy to determine address of header

```
void free(void *ptr) {
        header_t *hptr = (void *)ptr - sizeof(header_t);
}
```


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THE FREE LIST

- Simple free list struct

```
typedef struct __node_t {
        int size;
        struct __node_t *next;
} nodet_t;
```

- Use mmap to create free list
- 4kb heap, 4 byte header, one contiguous free chunk

```
// mmap() returns a pointer to a chunk of free space
node_t *head = mmap(NULL, 4096, PROT_READ|PROT_WRITE,
                    MAP_ANON|MAP_PRIVATE, -1, 0);
head->size = 4096 - sizeof(node_t);
head->next = NULL;
```


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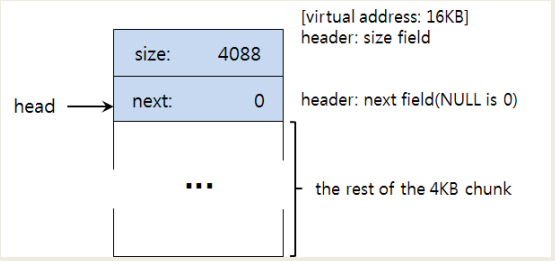
FREE LIST - 2

- Create and initialize free-list "heap"

```
// mmap() returns a pointer to a chunk of free space
node_t *head = mmap(NULL, 4096, PROT_READ|PROT_WRITE,
                    MAP_ANON|MAP_PRIVATE, -1, 0);
head->size = 4096 - sizeof(node_t);
head->next = NULL;
```

- Heap layout:



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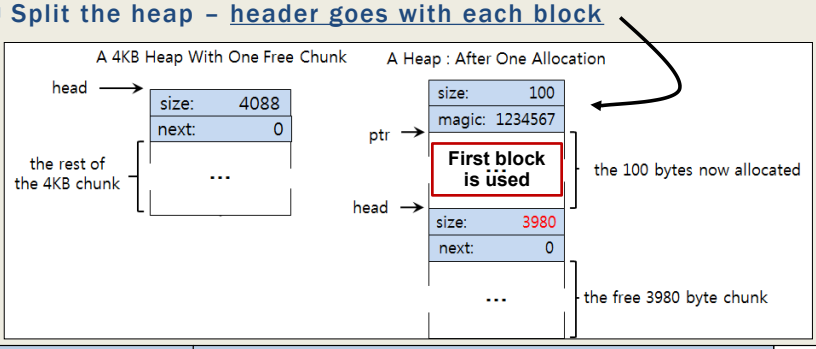
FREE LIST: MALLOC() CALL

- Consider a request for a 100 bytes: malloc(100)
- Header block requires 8 bytes
  - 4 bytes for size, 4 bytes for magic number
- Split the heap – header goes with each block



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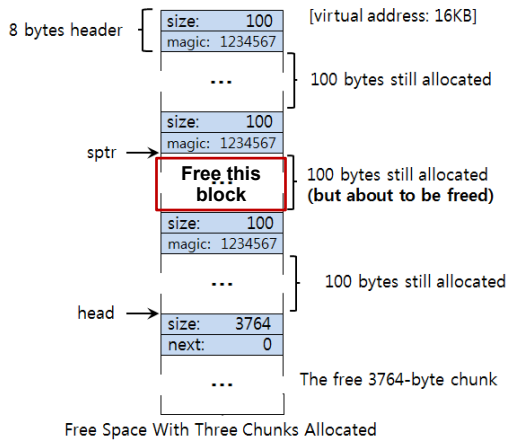
FREE LIST: FREE() CALL

- Addresses of chunks
- Start=16384
  + 108 (end of 1st chunk)
  + 108 (end of 2nd chunk)
  + 108 (end of 3rd chunk)
  = 16708



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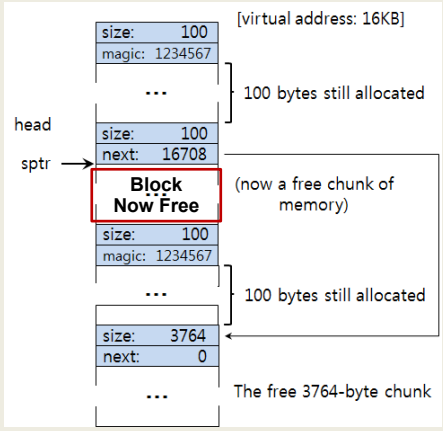
FREE LIST: FREE() CHUNK #2

- Free(sptr)
- Our 3 chunks start at 16 KB (@ 16,384 bytes)
- Free chunk #2 - sptr
- Sptr = 16500
  - addr – sizeof(node_t)
- Actual start of chunk #2
  - 16492



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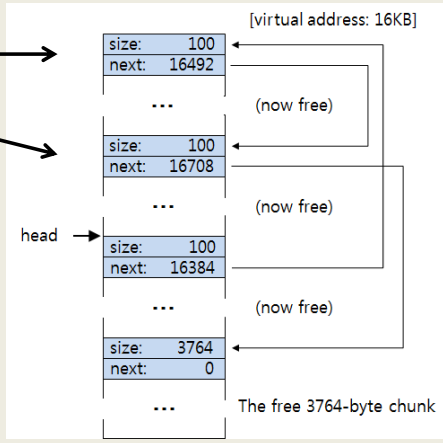
FREE LIST- FREE ALL CHUNKS

- Now free remaining chunks:
- Free(16392)
- Free(16608)
- Walk back 8 bytes for actual start of chunk
- External fragmentation
- Free chunk pointers out of order
- Coalescing of next pointers is needed



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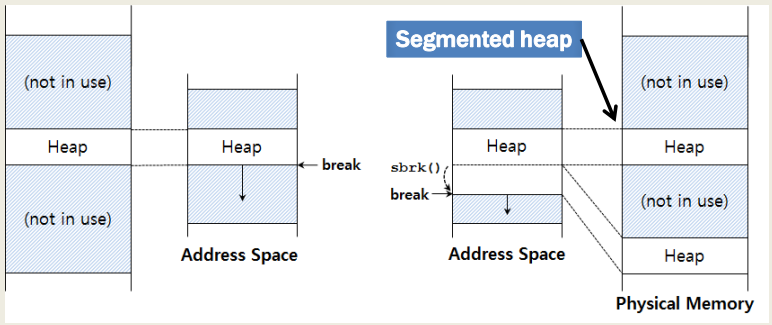
GROWING THE HEAP

- Start with small sized heap
- Request more memory when full
- sbrk(), brk()



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MEMORY ALLOCATION STRATEGIES

- **Best fit**
  - Traverse free list
  - Identify all candidate free chunks
  - Note which is smallest (has best fit)
  - When splitting, "leftover" pieces are small (and potentially less useful -- fragmented)
- **Worst fit**
  - Traverse free list
  - Identify largest free chunk
  - Split largest free chunk, leaving a still large free chunk

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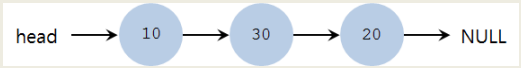
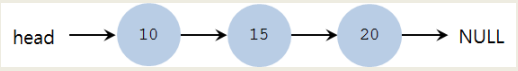
EXAMPLES

- Allocation request for 15 bytes



- Result of Best Fit

- Result of Worst Fit



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MEMORY ALLOCATION STRATEGIES - 2

- **First fit**
  - Start search at beginning of free list
  - Find first chunk large enough for request
  - Split chunk, returning a "fit" chunk, saving the remainder
  - Avoids full free list traversal of best and worst fit
- **Next fit**
  - Similar to first fit, but start search at last search location
  - Maintain a pointer that "cycles" through the list
  - Helps balance chunk distribution vs. first fit
  - Find first chunk, that is large enough for the request, and split
  - Avoids full free list traversal

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Which memory allocation strategy is more likely to distribute free chunks closer together which could help when coalescing the free space list?

- Best Fit
- Worst Fit
- First Fit
- None of the above
- All of the above

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SEGREGATED LISTS

- For popular sized requests
  e.g. for kernel objects such as locks, inodes, etc.
- Manage as segregated free lists
- Provide object caches: stores pre-initialized objects
- How much memory should be dedicated for specialized requests (object caches)?
- If a given cache is low in memory, can request "*slabs*" of memory from the general allocator for caches.
- General allocator will reclaim slabs when not used

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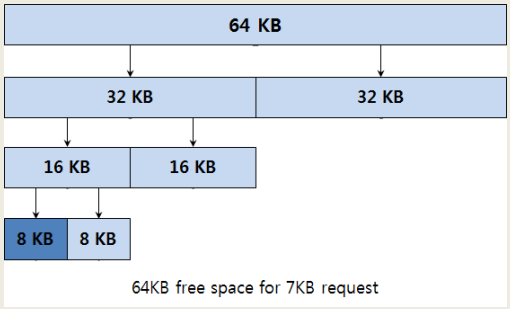
BUDDY ALLOCATION

- Binary buddy allocation
  - Divides free space by two to find a block that is big enough to accommodate the request; the next split is too small…
- Consider a 7KB request



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BUDDY ALLOCATION - 2

- Buddy allocation: suffers from internal fragmentation
- Allocated fragments, typically too large
- Coalescing is simple
  - Two adjacent blocks are promoted up

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A computer system manages program memory using three separate segments for code, stack, and the heap. The codesize of a program is 1KB but the minimal segment available is 16KB. This is an example of:

- External fragmentation
- Binary buddy allocation
- Internal fragmentation
- Coalescing
- Splitting

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A request is made to store 1 byte. For this scenario, which memory allocation strategy will always locate memory the fastest?

- Best fit
- Worst fit
- Next fit
- None of the above
- All of the above

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OBJECTIVES – 5/14

- Questions from 5/9
- Assignment 2 - May 31
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- Chapter 15: Address Translation
- Chapter 16: Segmentation
- Chapter 17: Free Space Management
- **Chapter 18: Introduction to Paging**

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CHAPTER 18: INTRODUCTION TO PAGING

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PAGING

- Split up address space of process into *fixed sized pieces* called **pages**
- Alternative to *variable sized pieces* (Segmentation) which suffers from significant fragmentation
- Physical memory is split up into an array of fixed-size slots called **page frames**.
- Each process has a **page table** which translates virtual addresses to physical addresses

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ADVANTAGES OF PAGING

- Flexibility
  - Abstracts the process address space into pages
  - No need to track direction of HEAP / STACK growth
    - *Just add more pages…*
  - No need to store unused space
    - *As with segments…*
- Simplicity
  - Pages and page frames are the same size
  - Easy to allocate and keep a free list of pages

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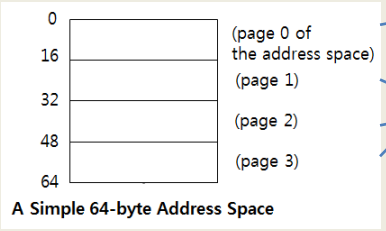
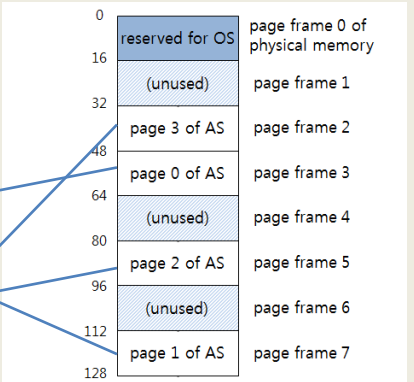
PAGING: EXAMPLE

Page Table:
VP0 → PF3
VP1 → PF7
VP2 → PF5
VP3 → PF2

- Consider a 128 byte (2^7) address space with 16-byte (2^4) pages
- Consider a 64-byte (2^6) program address space



A Simple 64-byte Address Space



64-Byte Address Space Placed In Physical Memory

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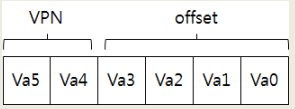
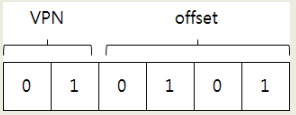
PAGING: ADDRESS TRANSLATION

- PAGE: Has two address components
  - VPN: Virtual Page Number *(serves as the page ID)*
  - Offset: Offset within a Page *(indexes any byte in the page)*



- Example:
  Page Size: 16-bytes (2^4),
  Program Address Space: 64-bytes (2^6)



Here program can have just four pages…

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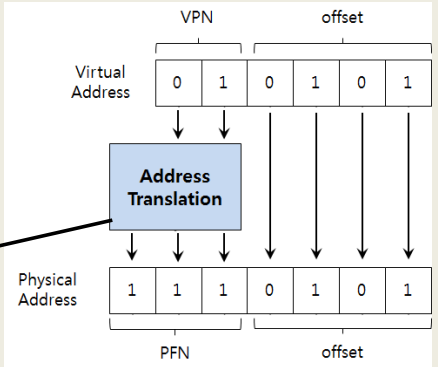
EXAMPLE: PAGING ADDRESS TRANSLATION

- Consider a 64-byte (2^6) program address space (4 pages→2^2)
- Stored in 128-byte (2^7) physical memory (8 frames→2^3)
- Offset is preserved
  - 4 bits indexes any byte
  - Page size is 16 bytes (2^4)
- **Page table** translates a Virtual Page Number (VPN) to a Physical Frame Number (PFN)

Page Table:
VP0 → PF3
VP1 → PF7
VP2 → PF5
VP3 → PF2



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PAGING DESIGN QUESTIONS

- (1) Where are page tables stored?
- (2) What are the typical contents of the page table?
- (3) How big are page tables?
- (4) Does paging make the system too slow?

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(1) WHERE ARE PAGE TABLES STORED?

- Example:
  - Consider a 32-bit process address space (4GB=2^{32} bytes)
  - With 4 KB pages (4KB=2^{12} bytes)
  - 20 bits for VPN (2^{20} pages)
  - 12 bits for the page offset (2^{12} unique bytes in a page)
- Page tables for each process are stored in RAM
  - Support potential storage of 2^{20} translations = 1,048,576 pages per process
  - Each page has a page table entry size of 4 bytes

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PAGE TABLE EXAMPLE

- With 2^{20} slots in our page table for a single process
- Each slot (i.e. entry) dereferences a VPN
- Each entry provides a physical frame number
- Each entry requires 4 bytes (32 bits)
  - 20 for the PFN on a 4GB system with 4KB pages
  - 12 for the offset which is preserved
  - (note we have no status bits, so this is unrealistically small)

VPN_0
VPN_1
VPN_2
...
...
$VPN_{1048576}$

- How much memory is required to store the page table for 1 process?
  - Hint: # of entries x space per entry
  - 4,194,304 bytes (or 4MB) to index one process

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NOW FOR AN ENTIRE OS

- If 4 MB is required to store one process
- Consider how much memory is required for an entire OS?
  - With for example 100 processes…
- Page table memory requirement is now 4MB x 100 = 400MB
- If computer has 4GB memory (maximum for 32-bits), the page table consumes 10% of memory

  400 MB / 4000 GB
- **Is this efficient?**

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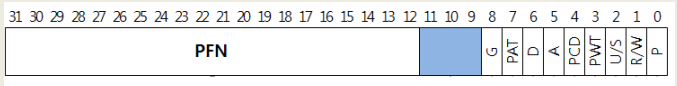
(2) WHAT'S ACTUALLY IN THE PAGE TABLE

- Page table is data structure used to map virtual page numbers (VPN) to the physical address (Physical Frame Number PFN)
  - Linear page table → simple array
- Page-table entry
  - 32 bits for capturing state



An x86 Page Table Entry(PTE)

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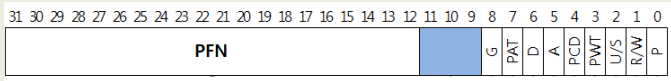
PAGE TABLE ENTRY

- P: present
- R/W: read/write bit
- U/S: supervisor
- A: accessed bit
- D: dirty bit
- PFN: the page frame number



An x86 Page Table Entry(PTE)

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PAGE TABLE ENTRY - 2

- Common flags:
- **Valid Bit:** Indicating whether the particular translation is valid.
- **Protection Bit:** Indicating whether the page could be read from, written to, or executed from
- **Present Bit:** Indicating whether this page is in physical memory or on disk(swapped out)
- **Dirty Bit:** Indicating whether the page has been modified since it was brought into memory
- **Reference Bit(Accessed Bit):** Indicating that a page has been accessed

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(3) HOW BIG ARE PAGE TABLES?

- Page tables are too big to store on the CPU
- Page tables are stored using physical memory
- Paging supports efficiently storing a sparsely populated address space
  - Reduced memory requirement
    Compared to base and bounds, and segments

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(4) DOES PAGING MAKE THE SYSTEM TOO SLOW?

- Translation
- **Issue #1:** Starting location of the page table is needed
  - HW Support: Page-table base register
    - stores active process
    - Facilitates translation

Stored in RAM →

Page Table:
VP0 → PF3
VP1 → PF7
VP2 → PF5
VP3 → PF2

- **Issue #2:** Each memory address translation for paging requires an extra memory reference
  - HW Support: TLBs (Chapter 19)

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PAGING MEMORY ACCESS

```
1.      // Extract the VPN from the virtual address
2.      VPN = (VirtualAddress & VPN_MASK) >> SHIFT
3.
4.      // Form the address of the page-table entry (PTE)
5.      PTEAddr = PTBR + (VPN * sizeof(PTE))
6.
7.      // Fetch the PTE
8.      PTE = AccessMemory(PTEAddr)
9.
10.     // Check if process can access the page
11.     if (PTE.Valid == False)
12.             RaiseException(SEGMENTATION_FAULT)
13.     else if (CanAccess(PTE.ProtectBits) == False)
14.             RaiseException(PROTECTION_FAULT)
15.     else
16.             // Access is OK: form physical address and fetch it
17.             offset = VirtualAddress & OFFSET_MASK
18.             PhysAddr = (PTE.PFN << PFN_SHIFT) | offset
19.             Register = AccessMemory(PhysAddr)
```


COUNTING MEMORY ACCESSES

- Example: Use this Array initialization Code

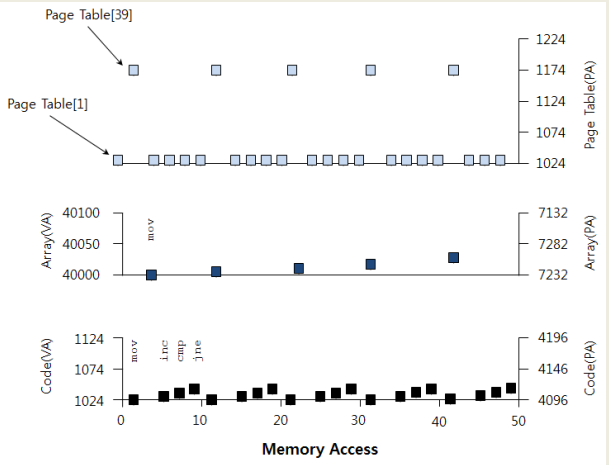
```
int array[1000];
...
for (i = 0; i < 1000; i++)
        array[i] = 0;
```

- Assembly equivalent:

```
0x1024 movl $0x0,(%edi,%eax,4)
0x1028 incl %eax
0x102c cmpl $0x03e8,%eax
0x1030 jne 0x1024
```

VISUALIZING MEMORY ACCESSES:
FOR THE FIRST 5 LOOP ITERATIONS

- Locations:
  - Page table
  - Array
  - Code
- 50 accesses for 5 loop iterations



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Consider a 4GB Computer with 4KB (4096 byte) pages. How many pages would fit into physical memory?

- 2^32 / 2^20 = 2^12 pages
- 2^32 / 2^12 = 2^20 pages
- 2^32 / 2^16 = 2^16 pages
- 2^32 / 2^8 = 2^24 pages
- None of the above

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For the 4GB computer example, how many bits are required for the VPN?

- 24 VPN bits (indexes 2^24 locations)
- 16 VPN bits (indexes 2^16 locations)
- 20 VPN bits (indexes 2^20 locations)
- 12 VPN bits (indexes 2^12 locations)
- None of the above

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For the 4GB computer example, how many bits are available for page status bits?

- 32 - 12 VPN bits = 20 status bits
- 32 - 24 VPN bits = 8 status bits
- 32 - 16 VPN bits = 16 status bits
- 32 - 20 VPN bits = 12 status bits
- None of the above

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For the 4GB computer, how much space does this page table require? (number of page table entries x size of page table entry)

- 2^20 entries x 4b = 4 MB
- 2^12 entries x 4b = 16 KB
- 2^16 entries x 4b = 256 KB
- 2^24 entries x 4b = 64 MB
- None of the above

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For the 4GB computer, how many page tables (for user processes) would fill the entire 4GB of memory?

- 4 GB / 16 KB = 65,536
- 4 GB / 64 MB = 256
- 4GB / 256 KB = 16,384
- 4GB / 4MB = 1,024
- None of the above

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PAGING SYSTEM EXAMPLE

- Consider a 4GB Computer:
- With a 4096-byte page size (4KB)
- How many pages would fit in physical memory?

- Now consider a page table:
- For the page table entry, how many bits are required for the VPN?
- If we assume the use of 4-byte (32 bit) page table entries, how many bits are available for status bits?
- How much space does this page table require?
  # of page table entries x size of page table entry
- How many page tables (for user processes) would fill the entire 4GB of memory?

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QUESTIONS

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