


TCSS 422: OPERATING SYSTEMS

Lock-based data structures II,
Condition Variables,
Concurrency Problems



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University of Washington - Tacoma

May 13, 2025

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OBJECTIVES – 5/13

■ Questions from 5/6 & Midterm Distribution

■ Assignment 0 Grades Posted

■ Assignment 1 – May 13 --> May 16

■ Tutorial 2: Pthread Tutorial - to be posted

■ Chapter 29: Lock Based Data Structures

- Approximate Counter (Sloppy Counter)
- Concurrent Structures: Linked List, Queue, Hash Table

■ Chapter 30: Condition Variables

- Producer/Consumer
- Covering Conditions

■ Chapter 32: Concurrency Problems

- Non-deadlock concurrency bugs
- Deadlock causes
- Deadlock prevention

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ONLINE DAILY FEEDBACK SURVEY

■ Daily Feedback Quiz in Canvas – Available After Each Class

■ Extra credit available for completing surveys **ON TIME**

■ Tuesday surveys: due by ~ Wed @ 11:59p

■ Thursday surveys: due ~ Mon @ 11:59p

TCSS 422 A - Assignments

Spring 2025

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TCSS 422 - Online Daily Feedback Survey - 4/1

Available until Apr 3 at 11:59pm | Due Apr 5 at 10pm | /15 pts

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TCSS 422 - Online Daily Feedback Survey - 4/1

Quiz Instructions

Question 1

0.5 pts

On a scale of 1 to 10, please classify your perspective on material covered in today's class:

1

2

3

4

5

6

7

8

9

10

Mostly Review to Me

Equal New and Review

Mostly New to Me

Question 2

0.5 pts

Please rate the pace of today's class:

1

2

3

4

5

6

7

8

9

10

slow

just right

fast

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MATERIAL / PACE

■ Please classify your perspective on material covered in today's class (48 of 63 respondents – 76.2%):

■ 1-mostly review, 5-equal new/review, 10-mostly new

■ Average – 6.08 (↓ - previous 6.70)

■ Please rate the pace of today's class:

■ 1-slow, 5-just right, 10-fast

■ Average – 4.90 (↓ - previous 5.24)

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FEEDBACK FROM 5/6

■ What exactly is the difference between the terms concurrency and parallelism?

■ This depends on if the computer has 1 or more CPU cores

■ On a single CPU core computer:
Concurrency is when multiple tasks can run in overlapping periods. It's an illusion of multiple tasks running in parallel because of a very fast switching by the CPU. The two tasks don't actually run at the same time on a single-core CPU.

■ Parallelism is when tasks actually run in parallel in multiple CPUs (or hyperthreads)

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FEEDBACK - 2

- What would we say the ideal sloppy threshold is?
- It is subject to our needs?
- Or is there a way to find a mid point between accuracy and efficiency?
- The ideal sloppy threshold depends on the goal.
- If your goal is accuracy, chose a low number
- If your goal is performance, chose a high number
- If your goal is both, you'll need to pick a number in-between to balance the trade-off between accuracy and performance

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MIDTERM RESULTS

- **Statistics**
- Average: 78.81
- Mode: 84.0
- Median: 80.0
- Min score: 45
- Lower quartile: 77.00
- 2nd quartile: 80.0
- 3rd quartile: 84
- Max score: 91
- Standard deviation: 8.93
- Curve: +7
- Question 2 Correction: +4

Score Range	# of Students
45-48	1
49-52	7
53-56	7
57-60	11
61-64	14
65-68	9
69-72	5
73-76	5
77-80	14
81-84	4
85-88	3
89-91	1

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OBJECTIVES – 5/13

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GOOGLE BIG TEXTFILE

- <https://faculty.washington.edu/wlloyd/courses/tcss422/assignments/googlebig.txt.gz>

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TUTORIAL 2

- Pthread Tutorial
- Practice using:
 - pthreads
 - Locks
 - Condition variables
- Generate and visualize prime number generation in parallel
- To be posted in next couple of days

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QUIZ 3

- Build a synchronized array thread-safe data structure
- As a class activity (~30 min allocated)
- Thursday May 15
- Bring Laptops
- Groups of 1 or 2

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CATCH UP FROM LECTURE 11

- Switch to Lecture 11 Slides
- Slides L11.20 to L11.40
(Chapter 29 –Lock Based Data Structures)

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OBJECTIVES – 5/13

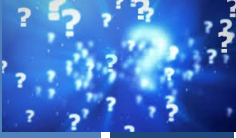
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CHAPTER 30 –
CONDITION VARIABLES

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CONDITION VARIABLES

- There are many cases where a thread wants to wait for another thread before proceeding with execution
- Consider when a precondition must be fulfilled before it is meaningful to proceed ...


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CONDITION VARIABLES - 2



- Support a signaling mechanism to alert threads when preconditions have been satisfied
- Eliminate busy waiting
- Alert one or more threads to “consume” a result, or respond to state changes in the application
- Threads are placed on **(FIFO) queue** to **WAIT** for signals
- **Signal**: wakes one thread (thread waiting longest)
broadcast wakes all threads (ordering by the OS)

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CONDITION VARIABLES - 3

- **Condition variable**

```
pthread_cond_t c;
```

 - Requires initialization
- **Condition API calls**

```
pthread_cond_wait(pthread_cond_t *c, pthread_mutex_t *m); // wait()
pthread_cond_signal(pthread_cond_t *c); // signal()
```
- **wait() accepts a mutex parameter**
 - Releases lock, puts thread to sleep, thread added to FIFO queue
- **signal()**
 - Wakes up thread, awakening thread acquires lock

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CONDITION VARIABLES - QUESTIONS

- **Why would we want to put waiting threads on a queue? why not use a stack?**
 - Queue (FIFO), Stack (LIFO)
- **Why do we want to not busily wait for the lock to become available?**
 - Using condition variables eliminates busy waiting by putting threads to “sleep” and yielding the CPU.
- A program has 10-threads, where 9 threads are waiting. The working thread finishes and broadcasts that the lock is available. **What happens next?**
 - All threads woken up in FIFO order - based on when started to wait

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MATRIX GENERATOR

Matrix generation example

Chapter 30
signal.c

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MATRIX GENERATOR

- The worker thread produces a matrix
 - Matrix stored using shared global pointer
- The main thread consumes the matrix
 - Calculates the average element
 - Display the matrix
- What would happen if we don't use a condition variable to coordinate exchange of the lock?
- Example program: “nosignal.c”

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ATTEMPT TO USE CONDITION VARIABLE WITHOUT A WHILE STATEMENT

```
1 void thr_exit() {           ← Child calls
2   done = 1;
3   pthread_cond_signal(&c);
4 }
5
6 void thr_join() {          ← Parent calls
7   if (done == 0)
8     pthread_cond_wait(&c);
9 }
```

- Subtle race condition introduced
- **Parent** thread calls **thr_join()** and executes comparison (line 7)
- Context switches to the child
- The **child** runs **thr_exit()** and signals the parent, but the parent is not waiting yet. (*parent has not reached line 8*)
- **The signal is lost !**
- The parent deadlocks

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PRODUCER / CONSUMER

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PRODUCER / CONSUMER

- **Producer**
 - Produces items – e.g. child the makes matrices
 - Places them in a buffer
 - Example: the buffer size is only 1 element (single array pointer)
- **Consumer**
 - Grabs data out of the buffer
 - Our example: parent thread receives dynamically generated matrices and performs an operation on them
 - Example: calculates average value of every element (integer)
- Multithreaded web server example
 - Http requests placed into work queue; threads process

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PRODUCER / CONSUMER - 2

- Producer / Consumer is also known as **Bounded Buffer**
- Bounded buffer
 - Similar to piping output from one Linux process to another
 - `grep pthread signal.c | wc -l`
 - Synchronized access:
 - sends output from grep → wc as it is produced
 - File stream

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WE WILL RETURN AT 5:00PM

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PUT/GET ROUTINES

- Buffer is a one element shared data structure (int)
- Producer "puts" data, Consumer "gets" data
- "Bounded Buffer" shared data structure requires **synchronization**

```
1 int buffer;
2 int count = 0; // initially, empty
3
4 void put(int value) {
5   assert(count == 0);
6   count = 1;
7   buffer = value;
8 }
9
10 int get() {
11   assert(count == 1);
12   count = 0;
13   return buffer;
14 }
```

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PRODUCER / CONSUMER - 3

- Producer adds data
- Consumer removes data (busy waiting)
- Without synchronization:
 - Producer Function
 - Consumer Function

```
1 void *producer(void *arg) {
2     int i;
3     int loops = (int) arg;
4     for (i = 0; i < loops; i++) {
5         put(i);
6     }
7 }
8
9 void *consumer(void *arg) {
10    int i;
11    while (1) {
12        int tmp = get(i);
13        printf("%d\n", tmp);
14    }
15 }
```

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PRODUCER / CONSUMER - 3

- The shared data structure needs synchronization!

```
1 cond_t cond;
2 mutex_t mutex;
3
4 void *producer(void *arg) {
5     int i;
6     for (i = 0; i < loops; i++) {
7         pthread_mutex_lock(&mutex);
8         if (count == 1)
9             pthread_cond_wait(&cond, &mutex);
10        put(i);
11        pthread_cond_signal(&cond);
12        pthread_mutex_unlock(&mutex);
13    }
14 }
15
16 void *consumer(void *arg) {
17    int i;
18    for (i = 0; i < loops; i++) {
19        pthread_mutex_lock(&mutex);
20        // c1
21    }
22 }
```

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PRODUCER/CONSUMER - 4

```
20 if (count == 0) // c2
21     pthread_cond_wait(&cond, &mutex); // c3
22 int tmp = get(i); // c4
23 pthread_cond_signal(&cond); // c5
24 pthread_mutex_unlock(&mutex); // c6
25 printf("%d\n", tmp);
26 }
27 }
```

- This code as-is works with just:
 - Producer
 - Consumer
- PROBLEM: no while. If thread wakes up it MUST execute
- If we scale to (2+) consumer's it fails
 - How can it be fixed ?

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EXECUTION TRACE:
NO WHILE, 1 PRODUCER, 2 CONSUMERS

Legend

c1/p1- lock
c2/p2- check var
c3/p3- wait
p4- put()
c4- get()
c5/p5- signal
c6/p6- unlock

T _{c1}	State	T _{c2}	State	T _p	State	Count	Comment
c1	Running		Ready		Ready	0	
c2	Running		Ready		Ready	0	
c3	Sleep		Ready		Ready	0	Nothing to get
	Sleep		Ready	p1	Running	0	
	Sleep		Ready	p2	Running	0	
	Sleep		Ready	p4	Running	1	Buffer now full
	Ready		Ready	p5	Running	1	T _{c1} awoken
	Ready		Ready	p6	Running	1	
	Ready		Ready	p1	Running	1	
	Ready		Ready	p2	Running	1	
	Ready		Ready	p3	Sleep	1	Buffer full: sleep
c1	Running		Sleep		Sleep	1	T _{c2} sneaks in ...
c2	Running		Sleep		Sleep	1	
c3	Running		Sleep		Sleep	0	...and grabs data
c4	Running		Sleep		Ready	0	T _p awoken
c5	Running		Sleep		Ready	0	
c6	Running		Sleep		Ready	0	Oh sh! No data

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PRODUCER/CONSUMER
SYNCHRONIZATION

- When producer threads awake, they do not check if there is any data in the buffer...
 - Need "while" statement, "if" statement is *insufficient* ...
- What if T_p puts a value, wakes T_{c1} whom consumes the value
- Then T_p has a value to put, but T_{c1}'s signal on &cond wakes T_{c2}
- There is nothing for T_{c2} consume, so T_{c2} sleeps
- T_{c1}, T_{c2}, and T_p all sleep forever
- T_{c1} needs to wake T_p to T_{c2}

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EXECUTION TRACE:
WHILE, 1 CONDITION, 1 PRODUCER, 2 CONSUMERS

Legend

c1/p1- lock
c2/p2- check var
c3/p3- wait
p4- put()
c4- get()
c5/p5- signal
c6/p6- unlock

One condition can result in waking up wrong thread (consumer instead of producer)

T _{c1}	State	T _{c2}	State	T _p	State	Count	Comment
c1	Running		Ready		Ready	0	
c2	Running		Ready		Ready	0	
c3	Sleep		Ready		Ready	0	Nothing to get
	Sleep		Ready		Ready	0	
	Sleep	c1	Running		Ready	0	
	Sleep	c2	Running		Ready	0	
	Sleep	c3	Sleep		Ready	0	Nothing to get
	Sleep		Sleep	p1	Running	0	
	Sleep		Sleep	p2	Running	0	
	Sleep		Sleep	p4	Running	1	Buffer now full
	Ready		Sleep	p5	Running	1	T _{c1} awoken
	Ready		Sleep	p6	Running	1	
	Ready		Sleep	p1	Running	1	
	Ready		Sleep	p2	Running	1	
	Ready		Sleep	p3	Sleep	1	Must sleep (full)
c2	Running		Sleep		Sleep	1	Recheck condition
c3	Running		Sleep		Sleep	0	T _{c1} grabs data
c5	Running		Sleep		Sleep	0	Oops! Wake T _{c2}

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EXECUTION TRACE – 2

WHILE, 1 CONDITION, 1 PRODUCER, 2 CONSUMERS

T_{c2} runs, no data to consume

Legend

c1/p1- lock

c2/p2- check var

c3/p3- wait

c4- put()

p4- get()

c5/p5- signal

c6/p6- unlock

T _{c1}	State	T _{c2}	State	T _p	State	Count	Comment
---	---	---	---	---	---	---	(cont)
c6	Running	---	Ready	---	Sleep	0	
c1	Running	---	Ready	---	Sleep	0	
c2	Running	---	Ready	---	Sleep	0	
c3	Sleep	---	Ready	---	Sleep	0	Nothing to get
---	---	c2	Running	---	Sleep	0	
---	---	c3	Sleep	---	Sleep	0	Everyone asleep ...

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TWO CONDITIONS

Required w/ multiple producer and consumer threads

Use two condition variables: **empty** & **full**

One condition handles the producer

the other the consumer

```
1 cond_t empty, full;
2 mutex_t mutex;
3
4 void *producer(void *arg) {
5     int i;
6     for (i = 0; i < loops; i++) {
7         Pthread_mutex_lock(&mutex);
8         while (count == 1)
9             Pthread_cond_wait(&empty, &mutex);
10        put(i);
11        Pthread_cond_signal(&full);
12        Pthread_mutex_unlock(&mutex);
13    }
14 }
15
```

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FINAL PRODUCER/CONSUMER

Change buffer from int, to int buffer[MAX]

Add indexing variables

>> Becomes **BOUNDED BUFFER**, can store multiple matrices

```
1 int buffer[MAX];
2 int fill = 0;
3 int use = 0;
4 int count = 0;
5
6 void put(int value) {
7     buffer[fill] = value;
8     fill = (fill + 1) % MAX;
9     count++;
10 }
11
12 int get() {
13     int tmp = buffer[use];
14     use = (use + 1) % MAX;
15     count--;
16     return tmp;
17 }
```

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FINAL P/C - 2

```
1 cond_t empty, full;
2 mutex_t mutex;
3
4 void *producer(void *arg) {
5     int i;
6     for (i = 0; i < loops; i++) {
7         Pthread_mutex_lock(&mutex);
8         while (count == MAX)
9             Pthread_cond_wait(&empty, &mutex);
10        put(i);
11        Pthread_cond_signal(&full);
12        Pthread_mutex_unlock(&mutex);
13    }
14 }
15
16 void *consumer(void *arg) {
17     int i;
18     for (i = 0; i < loops; i++) {
19         Pthread_mutex_lock(&mutex);
20         while (count == 0)
21             Pthread_cond_wait(&full, &mutex);
22        int tmp = get(i);
23    }
```

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FINAL P/C - 3

```
(Cont.)
23 Pthread_cond_signal(&empty); // c5
24 Pthread_mutex_unlock(&mutex); // c6
25 printf("kd\n", tmp);
26 }
27 }
```

Producer: only sleeps when buffer is full

Consumer: only sleeps if buffers are empty

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Using one condition variable, and no while loop is sufficient to synchronize access to a bounded buffer shared by:

1 Producer, 1 Consumer Thread

2 Consumers, 1 Producer Thread

2+ Producers, 2+ Consumer Threads

All of the above

None of the above

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Using two condition variables, and a while loop is sufficient to synchronize access to a bounded buffer shared by:

1 Producer, 1 Consumer Thread

2 Consumers, 1 Producer Thread

2+ Producers, 2+ Consumer Threads

All of the above

None of the above

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COVERING CONDITIONS

A condition that covers all cases (conditions):

Excellent use case for `pthread_cond_broadcast`

Consider memory allocation:

- When a program deals with huge memory allocation/deallocation on the heap
- Access to the heap must be managed when memory is scarce

PREVENT: Out of memory:

- queue requests until memory is free

Which thread should be woken up?

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COVERING CONDITIONS - 2

```
1 // how many bytes of the heap are free?
2 int bytesLeft = MAX_HEAP_SIZE;
3
4 // need lock and condition too
5 cond_t c;
6 mutex_t m;
7
8 void *
9 allocate(int size) {
10     pthread_mutex_lock(&m);
11     while (bytesLeft < size)
12         pthread_cond_wait(&c, &m);
13     void *ptr = ...; // get mem from heap
14     bytesLeft -= size;
15     pthread_mutex_unlock(&m);
16     return ptr;
17 }
18
19 void free(void *ptr, int size) {
20     pthread_mutex_lock(&m);
21     bytesLeft += size;
22     pthread_cond_signal(&c);
23     pthread_mutex_unlock(&m);
24 }
```

Check available memory

Broadcast

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COVER CONDITIONS - 3

Broadcast awakens all blocked threads requesting memory

Each thread evaluates if there's enough memory: (`bytesLeft < size`)

- Reject: requests that cannot be fulfilled-go back to sleep
 - Insufficient memory
- Run: requests which can be fulfilled
 - with newly available memory!

Another use case: coordinate a group of busy threads to gracefully end, to EXIT the program

Overhead

- Many threads may be awoken which can't execute

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CHAPTER 31: SEMAPHORES

Offers a combined C language construct that can assume the role of a lock or a condition variable depending on usage

- Allows fewer concurrency related variables in your code
- Potentially makes code more ambiguous
- For this reason, with limited time in a 10-week quarter, we do not cover

Ch. 31.6 – Dining Philosophers Problem

- Classic computer science problem about sharing eating utensils
- Each philosopher tries to obtain two forks in order to eat
- Mimics deadlock as there are not enough forks
- Solution is to have one left-handed philosopher that grabs forks in opposite order

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OBJECTIVES – 5/13


- Questions from 5/6 & Midterm Distribution
- Assignment 0 Grades Posted
- Assignment 1 – May 13 --> May 16
- Tutorial 2: Pthread Tutorial - to be posted
- Chapter 29: Lock Based Data Structures
 - Sloppy Counter
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- Chapter 32: Concurrency Problems**
 - Non-deadlock concurrency bugs
 - Deadlock causes
 - Deadlock prevention

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CHAPTER 32 –
CONCURRENCY
PROBLEMS

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CONCURRENCY BUGS IN
OPEN SOURCE SOFTWARE

- “Learning from Mistakes – A Comprehensive Study on Real World Concurrency Bug Characteristics”
 - Shan Lu et al.
- Architectural Support For Programming Languages and Operating Systems (ASPLOS 2008), Seattle WA

Application	What it does	Non-Deadlock	Deadlock
MySQL	Database Server	14	9
Apache	Web Server	13	4
Mozilla	Web Browser	41	16
Open Office	Office Suite	6	2
Total		74	31

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OBJECTIVES – 5/13

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NON-DEADLOCK BUGS

- Majority of concurrency bugs
- Most common:
 - Atomicity violation: forget to use locks
 - Order violation: failure to initialize lock/condition before use

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ATOMICITY VIOLATION - MYSQL

- Two threads access the `proc_info` field in struct `thd`
- `NULL` is 0 in C
- Mutually exclusive access to shared memory among separate threads is not enforced (e.g. non-atomic)
- Simple example: **`proc_info` deleted**

1
2
3
4
5
6
7
8
9

```
thread1:
{
  if(!thd->proc_info)
    fputs(thd->proc_info, ...);
}

thread2:
{
  thd->proc_info = NULL;
}
```

Programmer intended
variable to be accessed
atomically...

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ATOMICITY VIOLATION - SOLUTION

■ Add locks for all uses of: `thd->proc_info`

```
1 pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
2
3 Thread1::
4 pthread_mutex_lock(&lock);
5 if(thd->proc_info){
6     -
7     fputs(thd->proc_info , -);
8     -
9 }
10 pthread_mutex_unlock(&lock);
11
12 Thread2::
13 pthread_mutex_lock(&lock);
14 thd->proc_info = NULL;
15 pthread_mutex_unlock(&lock);
```

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ORDER VIOLATION BUGS

■ Desired order between memory accesses is flipped

■ E.g. something is checked before it is set

■ Example:

```
1 Thread1::
2 void init(){
3     mThread = PR_CreateThread(mMain, -);
4 }
5
6 Thread2::
7 void mMain(..){
8     mState = mThread->State
9 }
```

■ What if mThread is not initialized?

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ORDER VIOLATION - SOLUTION

■ Use condition & signal to enforce order

```
1 pthread_mutex_t mLock = PTHREAD_MUTEX_INITIALIZER;
2 pthread_cond_t mCond = PTHREAD_COND_INITIALIZER;
3 int mInit = 0;
4
5 Thread 1::
6 void init(){
7     -
8     mThread = PR_CreateThread(mMain,-);
9
10    // signal that the thread has been created.
11    pthread_mutex_lock(&mLock);
12    mInit = 1;
13    pthread_cond_signal(&mCond);
14    pthread_mutex_unlock(&mLock);
15    -
16 }
17
18 Thread2::
19 void mMain(..) {
20    -
```

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ORDER VIOLATION - SOLUTION - 2

■ Use condition & signal to enforce order

```
21 // wait for the thread to be initialized -
22 pthread_mutex_lock(&mLock);
23 while(mInit == 0)
24     pthread_cond_wait(&mCond, &mLock);
25 pthread_mutex_unlock(&mLock);
26
27 mState = mThread->State;
28
29 )
```

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NON-DEADLOCK BUGS - 1

■ 97% of Non-Deadlock Bugs were

■ Atomicity

■ Order violations

■ Consider what is involved in “spotting” these bugs in code

■ >> no use of locking constructs to search for

■ Desire for automated tool support (IDE)

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NON-DEADLOCK BUGS - 2

■ Atomicity

■ How can we tell if a given variable is shared?

■ Can search the code for uses

■ How do we know if all instances of its use are shared?

■ Can some non-synchronized, non-atomic uses be legal?

■ Legal uses: before threads are created, after threads exit

■ Must verify the scope

■ Order violation

■ Must consider all variable accesses

■ Must know desired order


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DEADLOCK BUGS



- Presence of a cycle in code
- Thread 1 acquires lock L1, waits for lock L2
- Thread 2 acquires lock L2, waits for lock L1

Thread 1:

lock (L1);

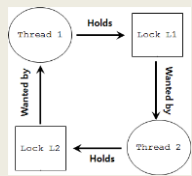
lock (L2);

Thread 2:

lock (L2);

lock (L1);

- Both threads can block, unless one manages to acquire both locks



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 - Non-deadlock concurrency bugs
 - **Deadlock causes**
 - Deadlock prevention

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REASONS FOR DEADLOCKS

- Complex code
 - Must avoid circular dependencies – can be hard to find...
- Encapsulation hides potential locking conflicts
 - Easy-to-use APIs embed locks inside
 - Programmer doesn't know they are there
 - Consider the Java Vector class:

```
1 Vector v1,v2;  
2 v1.addAll(v2);
```

 - Vector is thread safe (synchronized) by design
 - If there is a v2.addAll(v1); call at nearly the same time deadlock could result

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CONDITIONS FOR DEADLOCK

- **Four conditions** are required for dead lock to occur

Condition	Description
Mutual Exclusion	Threads claim exclusive control of resources that they require.
Hold-and-wait	Threads hold resources allocated to them while waiting for additional resources
No preemption	Resources cannot be forcibly removed from threads that are holding them.
Circular wait	There exists a circular chain of threads such that each thread holds one more resources that are being requested by the next thread in the chain

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PREVENTION – MUTUAL EXCLUSION

- Build wait-free data structures
 - Eliminate locks altogether
 - Build structures using CompareAndSwap atomic CPU (HW) instruction
- C pseudo code for CompareAndSwap
- Hardware executes this code atomically

```
1 int CompareAndSwap(int *address, int expected, int new){  
2     if(*address == expected){  
3         *address = new;  
4         return 1; // success  
5     }  
6     return 0;  
7 }
```

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PREVENTION – MUTUAL EXCLUSION - 2

Recall atomic increment

```
1 void AtomicIncrement(int *value, int amount){
2     do{
3         int old = *value;
4     }while( CompareAndSwap(value, old, old+amount)==0);
5 }
```

Compare and Swap tries over and over until successful

CompareAndSwap is guaranteed to be atomic

When it runs it is **ALWAYS** atomic (at HW level)

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MUTUAL EXCLUSION: LIST INSERTION

Consider list insertion

```
1 void insert(int value){
2     node_t * n = malloc(sizeof(node_t));
3     assert( n != NULL );
4     n->value = value ;
5     n->next = head;
6     head = n;
7 }
```

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MUTUAL EXCLUSION – LIST INSERTION - 2

Lock based implementation

```
1 void insert(int value){
2     node_t * n = malloc(sizeof(node_t));
3     assert( n != NULL );
4     n->value = value ;
5     lock(listlock); // begin critical section
6     n->next = head;
7     head = n;
8     unlock(listlock); //end critical section
9 }
```

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MUTUAL EXCLUSION – LIST INSERTION - 3

Wait free (no lock) implementation

```
1 void insert(int value) {
2     node_t *n = malloc(sizeof(node_t));
3     assert(n != NULL);
4     n->value = value;
5     do {
6         n->next = head;
7     } while (CompareAndSwap(&head, n->next, n));
8 }
```

Assign &head to n (new node ptr)

Only when head = n->next

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CONDITIONS FOR DEADLOCK

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PREVENTION LOCK – HOLD AND WAIT

Problem: acquire all locks atomically

Solution: use a "lock" "lock"... (like a guard lock)

```
1 lock(prevention);
2 lock(l1);
3 lock(l2);
4 -
5 unlock(prevention);
```

Effective solution – guarantees no race conditions while acquiring L1, L2, etc.

Order doesn't matter for L1, L2

Prevention (GLOBAL) lock decreases concurrency of code

- Acts Lowers lock granularity

Encapsulation: consider the Java Vector class...

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CONDITIONS FOR DEADLOCK

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PREVENTION – NO PREEMPTION

- When acquiring locks, don't BLOCK forever if unavailable...
- pthread_mutex_trylock() - try once
- pthread_mutex_timedlock() - try and wait awhile

```
1 top:
2   lock(L1);
3   if( trylock(L2) == -1 ){
4       unlock(L1);
5       goto top;
6   }
```

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NO PREEMPTION – LIVELOCKS PROBLEM

- Can lead to livelock

```
1 top:
2   lock(L1);
3   if( trylock(L2) == -1 ){
4       unlock(L1);
5       goto top;
6   }
```

- Two threads execute code in parallel → always fail to obtain both locks
- Fix: add random delay
 - Allows one thread to win the livelock race!

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CONDITIONS FOR DEADLOCK

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PREVENTION – CIRCULAR WAIT

- Provide total ordering of lock acquisition throughout code
 - Always acquire locks in same order
 - L1, L2, L3, ...
 - Never mix: L2, L1, L3; L2, L3, L1; L3, L1, L2....
- Must carry out same ordering through entire program

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CONDITIONS FOR DEADLOCK

- If any of the following conditions DOES NOT EXSIST, describe why deadlock can not occur?

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Mutual Exclusion	Threads claim exclusive control of resources that they require.
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The dining philosophers problem where 5 philosophers compete for 5 forks, and where a philosopher must hold two forks to eat involves which deadlock condition(s)?

Mutual Exclusion

Hold-and-wait

No preemption

Circular wait

All of the above

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DEADLOCK AVOIDANCE VIA INTELLIGENT SCHEDULING

■ Consider a [smart scheduler](#)

- Scheduler knows which locks threads use

■ Consider this scenario:

- 4 Threads (T1, T2, T3, T4)
- 2 Locks (L1, L2)

■ Lock requirements of threads:

	T1	T2	T3	T4
L1	yes	yes	no	no
L2	yes	yes	yes	no

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INTELLIGENT SCHEDULING - 2

■ Scheduler produces schedule:

CPU 1

T3

T4

CPU 2

T1

T2

■ No deadlock can occur

■ Consider:

	T1	T2	T3	T4
L1	yes	yes	yes	no
L2	yes	yes	yes	no

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INTELLIGENT SCHEDULING - 3

■ Scheduler produces schedule

CPU 1

T4

CPU 2

T1

T2

T3

■ Scheduler must be conservative and not take risks

■ Slows down execution – many threads

■ There has been limited use of these approaches given the difficulty having intimate lock knowledge about every thread

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DETECT AND RECOVER

■ Allow deadlock to occasionally occur and then take some action.

- Example: When OS freezes, reboot...

■ How often is this acceptable?

- Once per year
- Once per month
- Once per day
- Consider the effort tradeoff of finding every deadlock bug

■ Many database systems employ deadlock detection and recovery techniques.

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QUESTIONS

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