AMATH 352 Coding Final

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Due Friday, August 17

Rules:

- Absolutely no late submissions will be accepted. This part of the exam is due Friday, August 17 by 10:50am.
- NO COLLABORATION. This exam should be your own work. You may not discuss the problems or results with anyone other than our TA or myself. Violating this has serious consequences, see http://www.washington.edu/uaa/advising/help/academichonesty.php.
- This exam is worth 20% of your grade (2/3 of the whole final).
- Choose **THREE** of the four problems below. If you do all four I will just grade the first three I see.
- All code written should be uploaded on the Moodle page. Filenames MUST be of the form LastName_ExerciseNumber.m. Points will be deducted for not following this convention.

Exercise 1

In this question we consider applying Gram-Schmidt to the inverse of the Hilbert matrix. In MATLAB this matrix is constructed by calling invhilb(n) for an integer n. For any given n, write code that will orthonormalize the columns of invhilb(n) using the following algorithms:

- 1. Using formula (5.19) in the text and normalizing all the columns after making them orthogonal (Classical GS).
- 2. Using the more stable version (page 234, see also homework 6) of Gram-Schmidt (Modified GS).
- 3. Applying Classical GS twice to the same matrix (Two Step GS).
- 4. Using MATLAB 's built-in QR algorithm [Q,R] = qr(A) (Built-in GS).

Now, apply each of these algorithms to to invhilb(n) for n in $\mathbb{N} = 2:20$. If \mathbb{Q} is the othogonalized matrix then measure the error by $norm(\mathbb{Q}'*\mathbb{Q} - eye(n))$. For each algorithm and each n you will have an associated error. Plot these errors on a semilog plot versus n using

```
clf
figure(1)
hold on
semilogy(N,ModifiedError,'.g')
semilogy(N,ClassicalError,'.r')
semilogy(N,TwoStepError,'.b')
semilogy(N,BuiltinError,'.k')
```

Also include the plot of the condition number cond(invhilb(n)) of the inverse Hilbert matrix on the same figure. Comment on what you see and rank the algorithms in terms of effectiveness/efficiency.

Exercise 2

Code the full PA = LU algorithm (pseudo code given in the text). Apply your algorithm to the matrices

```
%(a)
```

```
a = [0, 1, 1, 0, 10;
    0,1,2,5,4;
    1,-1,0,0,11;
    3,1,1,-15,1;
    1, -1, -1, 1, -1];
%(b)
b = [0, 1, 1, 0, 10;
    0,1,2,5,4;
    1,-1,0,0,11;
    3,1,1,-15,1;
    1,3,4,5,45];
%(c)
c = [1,1,1,0,10;
    0, 1, 2, 5, 4;
    1,-1,0,0,11;
    3,1,1,-15,1;
    1,2,4,5,0];
```

Comment on what you see for each matrix. You can find these matrices in an m-file on the Moodle page.

Exercise 3

Code the following algorithm for computing the largest (in modulus) eigenvalue of a matrix A.

Choose a vector v randomly set ratio to be zero for i = 1 to max set v_{new} to be Av

```
set rationew to be \langle v_{new}, v \rangle / \langle v, v \rangle
if rationew differs from ratio by less than 10^{-15} then break out of loop
set ratio to be rationew
set v to be v_{new}/||v_{new}||
end
print out ratio
```

Note: This can also be done with a while loop.

The variable **ratio** will be an approximation of the largest eigenvalue and v will be an approximate eigenvector. Additionally, when you break out of the loop i will give you the number of iterations you needed. Apply this algorithm to A = rand(10) many times and comment on what you see in terms of the eigenvalue found and i. Running the full algorithm many times and then averaging the output may help.

Exercise 4

In this exercise we will numerically solve the differential equation

$$\Psi''(x) - \sin^2(x)\Psi(x) = \cos(x), \ x \in [0, 2\pi],$$

for a periodic solution $\Psi(x)$. You do not need to know how to solve differential equations to do this problem!

- MATLAB has an implementation of the Fast Fourier Transform (FFT), called by fft(v) for a vector $v \in \mathbb{C}^n$. The FFT is a linear function. Write code to find its matrix representation for any given n by applying the FFT to each basis vector. Use the variable FFTMAT to denote this matrix.
- The inverse FFT (iFFT) is called by ifft(v) so that v ifft(fft(v))
 = 0. Write code to find the matrix representation of the iFFT. Call this matrix iFFTMAT.
- Check that iFFTMAT*FFTMAT produces the identity matrix.
- Use the code

```
X = linspace(0,2*pi,n+1);
x = X(1:n);
d = diag([0 1:floor(n/2) -fliplr(1:floor((n-1)/2))]);
a = -diag(sin(x).^2);
diffop = -iFFTMAT*d*d*FFTMAT+a;
rhs = cos(x)';
sol = diffop\rhs;
plot(x,sol)
```

to obtain and plot an approximate solution sol. Plot this solution for n = 5, 10, 20, 40 on this same figure.