## Parabolic Techniques for Elliptic PDEs in Mathematical Physics

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Nonlinear Problems of Mathematical Physics Koç University

> UNIVERSITY of WASHINGTON

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### Ernst Florens Friedrich Chladni (1756 - 1827)





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The elliptic equation

$$-\Delta u = \lambda u$$

is a fixed point (in time) of the parabolic equation

$$\frac{\partial u}{\partial t} = (\Delta + \lambda)u.$$

### **Philosophical Overview**

- hyperbolic PDEs tend to send waves in all directions
- parabolic PDEs make things nice and smooth
- elliptic PDEs minimize some energy functional

Alternatively: any solution of an elliptic equation such as

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Use parabolic techniques to study elliptic problems!

Laplacian Eigenfunctions: Cheng's theorem

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 Energy Landscape of Schrödinger operators and the Filoche-Mayboroda Landscape Function

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- An inequality implying the Lieb inradius bound and the Polya-Szegő conjecture (with Manas Rachh)

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An upper bound on the Hot Spots constant

Laplacian eigenfunctions: a short proof of (Cheng, 1976)

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#### Theorem (Cheng, 1976)

If  $-\Delta u = \lambda u$  on some two-dimensional domain, then any nodal domain – nodal domain being a connected component of

 $\{x: u(x) \neq 0\}$ 

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(see also Lipman Bers, 1955)

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Idea. Start a heat equation with Dirichlet conditions:

$$u(t,x)=e^{-\lambda t}u(x).$$



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At the same time: solve via Brownian motion!

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$$u(t,x) = \mathbb{E} \begin{cases} (u_0(\omega_x(t))) \\ 0 \end{cases}$$

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$$(0,0) \qquad (1,0)$$

Figure: If the angle is too narrow...

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**Suffices:** Let B(t) be a Brownian motion started in (1, 0). Define a stopping time

$$T(r) = \inf \{t \ge 0 : |B(t)| = r\}.$$

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$$T(r) = \inf \{t \ge 0 : |B(t)| = r\}.$$

Then, for r > 1,

$$\mathbb{P}\left(B[0, T(r)] \subset W(\alpha)\right) = \frac{2}{\pi} \arctan\left(\frac{2r^{\frac{\pi}{\alpha}}}{r^{\frac{2\pi}{\alpha}} - 1}\right).$$

Laplacian eigenfunctions: a bound on avoided crossings

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The idea is that nodal lines cannot run in parallel for arbitrarily long time.

# Avoided crossings



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#### Theorem (S, Comm. PDE, 2014)

Suppose  $-\Delta u = \lambda u$  on a two-dimensional manifold and  $\{x : u(x) = 0\}$  has the local structure as seen in the picture.

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Suppose  $-\Delta u = \lambda u$  on a two-dimensional manifold and  $\{x : u(x) = 0\}$  has the local structure as seen in the picture. Then

$$d(a,b) \leq C\lambda^{1/2-lpha}\log\lambda$$

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for some constant  $C < \infty$  depending only on (M, g).



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(see also Donnelly & Fefferman (1990) and Mangoubi (2010))



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Neighboring square has to have slightly larger function values to balance the massive decay induced by absorbtion on the boundary ('rapid growth of elliptic equations in narrow channels', cf. the work of Landis). Energy Landscape of Schrödinger operators
## Schrödinger operators

Consider a nice domain  $\Omega \subset \mathbb{R}^2$  and a potential  $V : \mathbb{R}^2 \to [0, \infty)$ . Where are the eigenfunctions of

 $-\Delta + V?$ 

Figure: Filoche & Mayboroda, (PNAS, 2012)

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Mayboroda & Filoche: associate the solution of

$$(-\Delta + V)v = 1.$$



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Figure: Filoche & Mayboroda, (PNAS, 2012)

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Localization of eigenfunctions respects partition!



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Whenever an eigenfunction crosses a barrier: exponential decay.



Figure: Filoche & Mayboroda, (PNAS, 2012)

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## Known results

Theorem (Arnold, G. David, Filoche, Jerison & Mayboroda, Phys Rev 2016)

Exponential decay related to Agmon's inequality.



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1/v(x) is an effective effective potential.

Apply the heat equation and counteract the heat equation at the same time.

$$u(x) = e^{\lambda t}u(t,x)$$

Using Feynman-Kac gives, for every t > 0,

$$u(x) = \mathbb{E}_{x}\left(u(\omega(t))e^{\lambda t - \int_{0}^{t}V(\omega(z))dz}\right).$$



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Apply Feynman-Kac again: compute  $e^{t(\Delta-V)}v(x)$  in two ways.

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Second computation. Feynman-Kac:

$$(e^{t(\Delta-V)}v)(x) \sim v(x) - v(x)\mathbb{E}_x \int_0^t V(\omega(z))dz.$$

This relates the landscape function and the path integral via

$$t \sim v(x)\mathbb{E}_x \int_0^t V(\omega(z))dz.$$

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(S, Proc. Amer. Math. Soc, 2017)

Recall that

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This means we are looking for a type of averaging kernel  $k_t$  such that

$$(k_t * V)(x) = \int V(x+y)k_t(y)dy$$

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describes the local localization energy. There exists a unique optimal  $k_t$ !. And the kernel is naturally related to the Filoche-Mayboroda landscape function!



Figure: The radial profiles of the convolution kernel  $k_t(r)$  in d = 1 dimensions (left) and d = 2 (right).

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Figure: The radial profiles of the convolution kernel  $k_t(r)$  in d = 1 dimensions (left) and d = 2 (right).

These kernels have different closed forms in different dimensions, for example

$$k_t(r) = \frac{1}{\sqrt{\pi t}} \exp\left(-\frac{r^2}{4t}\right) - \frac{r}{2t} \operatorname{erfc}\left(\frac{r}{2\sqrt{t}}\right) \qquad (d=1)$$

$$k_t(r) = \frac{1}{4\pi t} \Gamma\left(0, \frac{r^2}{4t}\right) \qquad (d=2).$$

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In the next picture: we show (1) the behavior of the Filoche-Mayboroda landscape function, (2) the behavior of  $k_t * V$  and (3) the localization of the first few eigenfunctions of  $-\Delta + V$ .

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#### Theorem (S., Comm. PDE, 2021)

Let  $\Omega \subset \mathbb{R}^n$  be an open, bounded domain with smooth boundary, let  $0 \leq V \in C(\overline{\Omega})$  be a continuous potential and let  $\phi$  be a solution of

$$(-\Delta + V)\phi = \lambda\phi$$
 in  $\Omega$   
 $\phi = 0$  on  $\partial\Omega$ .

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Then, for any fixed  $x \in \Omega$ , as  $t \to 0$ , we have, for  $k_t$  as above,

$$-\Delta \phi(x) + (V * k_t)(x)\phi(x) = \lambda \phi(x) + \mathcal{O}_{\phi, \|V\|_{L^{\infty}}}(t),$$

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where the implicit constant depends only on  $\phi$  and  $\|V\|_{L^{\infty}}$ .

## Lieb's inradius result and the Polya-Szegő conjecture



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If a two-dimensional drum produces low frequency, the drum is 'big'.

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Mathematically, for  $\Omega \subset \mathbb{R}^2$ , we have the lowest frequency

$$\lambda_1(\Omega) = \inf_{f \neq 0} \frac{\int_{\Omega} |\nabla u|^2 dx}{\int_{\Omega} |u|^2 dx} \sim \frac{1}{\text{inradius}^2}$$

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The Orchester Principle (Makai 1965, Hayman 1978)

There exist constants  $c_1, c_2$  such that

$$\frac{c_1}{\mathsf{inradius}^2} \leq \lambda_1(\Omega) \leq \frac{c_2}{\mathsf{inradius}^2}.$$

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Theorem (M. Rachh and S, Comm. Pure Applied Math. 2017)

Let  $\Omega \subset \mathbb{R}^2$  be simply connected and  $u: \Omega \to \mathbb{R}^2$  vanish on  $\partial \Omega$ . If u assumes a global extremum in  $x_0 \in \Omega$ , then

$$\inf_{y\in\partial\Omega}\|x_0-y\|\geq c\left\|\frac{\Delta u}{u}\right\|_{L^{\infty}(\Omega)}^{-1/2}$$





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$$\inf_{y \in \partial \Omega} \|x_0 - y\| \ge c \left\| \frac{\Delta u}{u} \right\|_{L^{\infty}(\Omega)}^{-1/2}$$

Idea behind the proof. If an eigenfunction assumes a maximum in  $x_0 \in \Omega$ , then any Brownian motion started there has likelihood < 70% of hitting the boundary within time  $t = \lambda^{-1}$ .

Such results are impossible in dimensions  $\geq$  3: one can take a ball and remove one-dimensional lines without affecting the PDE.



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#### Theorem (Elliott Lieb, 1984, Inventiones)

 $\Omega$  contains a  $(1-\varepsilon)\text{-}\mathsf{fraction}$  of a ball with radius

$$r \sim rac{c_{arepsilon}}{\sqrt{\lambda_1(\Omega)}}$$

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#### Theorem (Rachh and S, Comm. Pure Applied Math. 2017)

Let  $-\Delta u = Vu$  with Dirichlet conditions. Then  $\Omega$  contains a  $(1 - \varepsilon)$ -fraction of a ball with radius

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(Lierl & S, Comm. PDE 2018: the  $L^{\infty}$  can, in some sense, be replaced by the Lorentz space  $L^{n/2,1}$ )

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Quantilized Donsker-Varadhan estimates

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M. Donsker and S. Varadhan, On a variational formula for the principal eigenvalue for operators with maximum principle,  $\rm PNAS$  1975

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Setup:  $\Omega \subset \mathbb{R}^n$  and

$$Lu = -\operatorname{div}(a(x)\nabla u) + \nabla V \cdot \nabla u.$$

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Setup:  $\Omega \subset \mathbb{R}^n$  and

$$Lu = -\operatorname{div}(a(x)\nabla u) + \nabla V \cdot \nabla u.$$

**Question.** What is the smallest  $\lambda > 0$  for which

$$Lu = \lambda u$$
 has a solution with  $u|_{\partial \Omega} = 0$ ?

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Donsker-Varadhan: associate a drift diffusion process.

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#### J. Lu and S., Proc. Royal Soc. 2016

$$\lambda_1 \geq rac{\log(1/p)}{\sup_{x \in \Omega} d_{p,\partial\Omega}(x)}.$$

Moreover, as  $p \rightarrow 0$ , the lower bound converges to  $\lambda_1$ .

Let us consider  $L = -\Delta$  on [0, 1]. Then  $\lambda_1 = \pi^2$ . 1/2 1/4  $10^{-1}$   $10^{-2}$   $10^{-8}$  | Donsker-Varadhan р lower bound 7.28 8.40 8.92 9.39 9.74

#### Let us consider

$$L = -\Delta + \nabla \left( rac{1}{2} x^2 
ight)$$
 on  $[0,1].$ 

Then  $\lambda_1 = 2$ .

 p
 0.5
 0.3
 0.2
 0.1
 0.05
 Donsker-Varadhan

 lower bound
 1.52
 1.67
 1.74
 1.79
 1.83
 1.678

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An upper bound on the Hot Spots constant

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$$-\Delta u = \lambda_2 u$$
 in  $\Omega$   
 $rac{\partial u}{\partial n} = 0$  on  $\partial \Omega$ 

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#### Hot Spots Conjecture (Rauch, 1974)

For 'nice' domains, the maxima and minima of a solution of this equation are 'usually' on the boundary.

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Question: what is 'nice'? Probably convex is enough, maybe even simply connected.

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In summary, we sometimes have

$$\max_{x\in\Omega} u(x) = \max_{x\in\partial\Omega} u(x)$$

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$$\max_{x\in\Omega} u(x) \ge 1.001 \cdot \max_{x\in\partial\Omega} u(x).$$

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and sometimes not. An example of Kleefeld (arXiv, 2021) gives

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So a natural question is: can the maximum be a lot bigger?

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Theorem (S, arXiv 2021) Let  $\Omega \subset \mathbb{R}^d$  be simply connected with smooth boundary. Then  $\max_{x \in \Omega} u(x) \leq 60 \cdot \max_{x \in \partial \Omega} u(x).$ 

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What is really nice is that the result is uniform in the domain and the dimension.

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What is really nice is that the result is uniform in the domain and the dimension. As  $d \to \infty$ , the constant converges to  $\sqrt{e^e} \sim 3.89 \dots$ 



## THANK YOU!

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