

L18: November 5, 2014

ME 564, Fall 2014

Overview of Topics

① Runge Kutta Integration

(a) 2nd order

(b) 4th order

② Chaotic Example: Lorenz Equation

(a) Slow: "for" loops

(b) Fast: vectorized

Second-Order Runge-Kutta ('ode23')

$$y_{k+1} = y_k + \Delta t f\left(t_k + \frac{\Delta t}{2}, y_k + \frac{\Delta t}{2} f(t_k, y_k)\right)$$

OR

$$y_{k+1} = y_k + \Delta t f_2$$

$$\text{where } f_1 = f(t_k, y_k)$$

$$f_2 = f\left(t_k + \frac{\Delta t}{2}, y_k + \frac{\Delta t}{2} f_1\right)$$

Fourth-Order Runge-Kutta ('ode45')

$$y_{k+1} = y_k + \frac{\Delta t}{6} [f_1 + 2f_2 + 2f_3 + f_4]$$

$$\text{where } f_1 = f(t_k, y_k)$$

$$f_2 = f\left(t_k + \frac{\Delta t}{2}, y_k + \frac{\Delta t}{2} f_1\right)$$

$$f_3 = f\left(t_k + \frac{\Delta t}{2}, y_k + \frac{\Delta t}{2} f_2\right)$$

$$f_4 = f(t_k + \Delta t, y_k + \Delta t f_3)$$

$$\text{Local error : } \mathcal{O}(\Delta t^5)$$

$$\text{global error : } \mathcal{O}(\Delta t^4).$$

$$\dot{y} = f(t, y)$$

Last time we saw the 4th order Runge-Kutta

integrator (RK4):

$$y_{k+1} = y_k + \frac{\Delta t}{6} (f_1 + 2f_2 + 2f_3 + f_4)$$

$$f_1 = f(t_k, y_k)$$

$$f_2 = f(t_k + \Delta t/2, y_k + (\Delta t/2) f_1)$$

$$f_3 = f(t_k + \Delta t/2, y_k + (\Delta t/2) f_2)$$

$$f_4 = f(t_k + \Delta t, y_k + \Delta t f_3)$$

[evaluate vector field after taking half Euler step using f_1]

[evaluate VF using half Euler step w/ f_2]

[take full Euler step w/ f_3].

RK4
'ode45'
based on this)

- Very accurate ($O(\Delta t^5)$) local accuracy per time step.

- Uses four evaluations of $f(t, y)$, which is typically expensive.

[More evaluations of $f(t, y)$ per timestep than Forward Euler, but, many fewer Δt 's required for same accuracy!]

Example: Lorenz Equation (1963, atmospheric convection model)

$$\dot{x} = \sigma(y - x)$$

$$\dot{y} = x(\rho - z) - y$$

$$\dot{z} = xy - \beta z$$

parameters may lead to 'chaos'

$$\sigma = 10$$

$$\beta = 8/3$$

$$\rho = 28$$

\Rightarrow



'Butterfly effect'

Last time: we wrote codes: `lorenz.m`
`rk4singlestep.m`

Now, we will investigate how to integrate many
initial conditions (trajectories) efficiently

Idea 1: use 'for' loop and integrate each
particle one-at-a-time.

* Very slow in Matlab! Why?

Matlab scripts are not compiled, so every iteration
of the for loop, it re-translates your commands
into machine-code instructions.

Idea 2: * Alternative is to vectorize computation, so all
particles are passed through vector field at
the same time.

* much faster (100-1000x for our example)

because matrix operations in Matlab
are built on LAPACK, a highly optimized,
compiled Fortran package.

```
function dy = lorenz(t,y,sigma,beta,rho)
% y is a three dimensional state-vector
dy = [
sigma*(y(2)-y(1));
y(1)*(rho-y(3))-y(2);
y(1)*y(2)-beta*y(3);
1];
```

```
function yout = rk4singlestep(fun,dt,t0,y0)
```

```
f1 = fun(t0,y0);
```

```
f2 = fun(t0+dt/2,y0+(dt/2)*f1);
```

```
f3 = fun(t0+dt/2,y0+(dt/2)*f2);
```

```
f4 = fun(t0+dt,y0+dt*f3);
```

```
yout = y0 + (dt/6)*(f1+2*f2+2*f3+f4);
```

```
clear all

% Lorenz's parameters (chaotic)
sigma = 10;
beta = 8/3;
rho = 28;

% Initial condition
y0=[-8; 8; 27];

% Compute trajectory
dt =0.01;
tspan=[0:dt:4];

Y(:,1)=y0;
yin = y0;
for i=1:tspan(2)/dt
    time = i*dt;
    yout = rk4singlestep(@(t,y)lorenz(t,y,sigma,beta,rho),dt,time,yin);
    Y = [Y yout];
    yin = yout;
end
plot3(Y(1,:),Y(2,:),Y(3,:), 'b')
hold on
[t,y] = ode45(@(t,y)lorenz(t,y,sigma,beta,rho),tspan,y0);
plot3(y(:,1),y(:,2),y(:,3), 'r')
```

```
clear all

% Lorenz's parameters (chaotic)
sigma = 10;
beta = 8/3;
rho = 28;

% Initial condition - large cube of points
xvec = -20:2:20;
yvec = -20:2:20;
zvec = -20:2:20;
[x0,y0,z0] = meshgrid(xvec,yvec,zvec);
yIC(1,:::,) = x0;
yIC(2,:::,) = y0;
yIC(3,:::,) = z0;

plot3(yIC(1,:),yIC(2,:),yIC(3,:), 'r.', 'LineWidth',2, 'MarkerSize',4)
axis([-40 40 -40 40 -40 40])
view(20,40);
drawnow

%% Compute trajectory
dt =0.01;
duration = 4
tspan=[0,duration];
L = duration/dt;
yparticles = yIC;

% this code is slow because MATLAB is not compiled
% we use nested for loops to step through every single IC in the cube
% one at a time...
for step=1:L
    time = step*dt
    for i=1:length(xvec)
        for j=1:length(yvec)
            for k=1:length(zvec)
                yin = yparticles(:,i,j,k);
                yout = rk4singlestep(@(t,y)lorenz(t,y,sigma,beta,rho),dt,time,yin);
                yparticles(:,i,j,k) = yout;
            end
        end
    end
    plot3(yparticles(1,:),yparticles(2,:),yparticles(3,:), 'r.', 'LineWidth',2, 'MarkerSize',4)
    view(20,40);
    axis([-40 40 -40 40 -10 40])
    drawnow
end
```



```
function dy = lorenz3D(t,y,sigma,beta,rho)
% y is a three dimensional state-vector
dy = [
sigma*(y(2,::,::)-y(1,::,::));
y(1,::,::).*(rho-y(3,::,::))-y(2,::,::);
y(1,::,::).*y(2,::,::)-beta*y(3,::,::);
1];
```

```
clear all

% Lorenz's parameters (chaotic)
sigma = 10;
beta = 8/3;
rho = 28;

% Initial condition 1 - Large cube of data
y0=[0 0 0];
xvec = -20:2:20;
yvec = -20:2:20;
zvec = -20:2:20;
% % Initial condition 2 - small cube around initial condition from last class
% y0=[-8; 8; 27];
% xvec = -1:.1:1;
% yvec = -1:.1:1;
% zvec = -1:.1:1;
% % Initial condition 3 - even smaller cube around initial condition
% y0=[-8; 8; 27];
% xvec = -.1:.01:.1;
% yvec = -.1:.01:.1;
% zvec = -.1:.01:.1;
[x0,y0,z0] = meshgrid(xvec+y0(1),yvec+y0(2),zvec+y0(3));
yIC(1,::,::) = x0;
yIC(2,::,::) = y0;
yIC(3,::,::) = z0;

plot3(yIC(1,:),yIC(2,:),yIC(3,:), 'r.', 'LineWidth',2, 'MarkerSize',10)
axis([-40 40 -40 40 -40 40])
view(20,40);
drawnow

%% Compute trajectory
dt =0.01;
duration = 4
tspan=[0,duration];
L = duration/dt;
yin = yIC;

for step = 1:L
    time = step*dt
    yout = rk4singlestep(@(t,y)lorenz3D(t,y,sigma,beta,rho),dt,time,yin);
    yin = yout;
    plot3(yout(1,:),yout(2,:),yout(3,:), 'r.', 'LineWidth',2, 'MarkerSize',10)
    view(20+360*step/L,40);
    axis([-40 40 -40 40 -10 40])
    drawnow
end
```