

**Exercise 4-1** Consider the differential equation of the periodically forced Duffing oscillator (use ode45):

$$\ddot{x} = -\delta\dot{x} - \beta x - \alpha x^3 + \gamma \cos(\omega t)$$

We may write this as a system of first order differential equations as

$$\begin{aligned}\dot{x} &= v \\ \dot{v} &= -\delta v - \beta x - \alpha x^3 + \gamma \cos(\omega t)\end{aligned}$$

These equations may be used to model a periodically forced beam that is deflected towards two magnets. This was one of the first examples that was used to demonstrate chaos (see [http://www.scholarpedia.org/article/Duffing\\_oscillator](http://www.scholarpedia.org/article/Duffing_oscillator) for historical details and references).

For all of the parts, use  $\alpha = 1$ ,  $\beta = -1$ , and  $d = 0.2$ . You will want to create a MATLAB .m file called `duffing.m` with the following inputs and outputs:

```
function dy = duffing(t,y,a,b,d,g,w)
```

Here `a` is  $\alpha$ , `b` is  $\beta$ , `d` is  $\delta$ , `g` is  $\gamma$  and `w` is  $\omega$ .

- (a) Integrate this ODE with initial condition  $x = 2$  and  $v = 0$  from  $t = 0$  to  $t = 100$  with  $\Delta t = 0.01$ . First, integrate the unforced case with  $\gamma = 0$ . Plot the solution of  $x$  vs  $t$ .
  - (b) Now, lets use a forcing frequency of  $\omega = 1$  and increase  $\gamma$  from 0.1 to 0.5 in increments of 0.1. For each of the five values of  $\gamma$ , plot  $x$  and  $v$  against  $t$ . As you change  $\gamma$ , note that chaos ensues!
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**Exercise 4-2** Derive a  $\mathcal{O}(\Delta t^2)$  accurate forward difference derivative for the function  $f(t)$  at  $t$  using the following three *measurements* or data points:

$$f(t), f(t + \Delta t), \text{ and } f(t + 2\Delta t)$$

Please show that this scheme is really  $\mathcal{O}(\Delta t^2)$  accurate using the Taylor series expansions.

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**Exercise 4-3** Consider a column vector of data  $\mathbf{f}(t)$  with 6 elements. Write down the  $6 \times 6$  matrix  $\mathbf{D}$  that when multiplied by  $\mathbf{f}$  will yield a vector of derivatives of  $\mathbf{f}$  with respect to time:

$$\frac{d\mathbf{f}}{dt} = \mathbf{D}\mathbf{f}.$$

You may assume that all of the data in  $\mathbf{f}$  was collected  $\Delta t = 0.1$  time units apart. Please use forward difference for the first point, backward difference for the last point, and central difference for the four interior points.

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**Exercise 4-4**

Lets say that we are integrating the following stable ODE:

$$\dot{\mathbf{x}} = \begin{bmatrix} -1 & 0 \\ 0 & -2 \end{bmatrix}$$

- (a) If we are using a forward Euler scheme, for what  $\Delta t > 0$  will the resulting simulation become unstable?
- (b) If we use the backward Euler scheme, for what  $\Delta t > 0$  will the simulation become unstable?