

Math 341: Quiz 5

Name: **KEY**

True/False: If the statement is true, give a brief explanation of why it is. If the statement is false, give a counterexample.

1. [3] A list of vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ with repeated vectors is linearly dependent.

True let $\vec{v}_i, \vec{v}_j \in \{\vec{v}_1, \dots, \vec{v}_n\}$ be ~~the~~ the repeated vectors. That is $i \neq j$, but $\vec{v}_i = \vec{v}_j$.

Then $0\vec{v}_1 + \dots + 0\vec{v}_i + \vec{v}_i + 0\vec{v}_{i+1} + \dots + 0\vec{v}_j - \vec{v}_j + 0\vec{v}_{j+1} + \dots + 0\vec{v}_n$ equals $\vec{0}$ but not all the scalars are zero. Thus $\{\vec{v}_1, \dots, \vec{v}_n\}$ is lin. dep.

know (1)
started (2)
got it (3)

2. [3] The set $\{1-x, x-x^2, 1-x\}$ is linearly independent in the vector space of all polynomials of degree 2 or less.

False see above

$$(1-x) + 0(x-x^2) - (1-x) = \vec{0}$$

but not all the scalars are zero

3. [3] If $V = \text{span}\{\vec{v}_1, \dots, \vec{v}_n\}$, then $\{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis of V .

False $\mathbb{R}^2 = \text{span}\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\}$
but $\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}\right\}$ is lin. dep
and is not a basis.

4. [3] Linear operators preserve linear independence. That is given a linear operator $T: V \rightarrow W$ and a linearly independent set $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\} \in V$, the set $\{T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n)\}$ is linearly independent.

False let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

note $\left\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right\} \subset \mathbb{R}^2$ is lin indep. but
 $\{T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right), T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)\} = \left\{\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}\right\}$ is lin dep.

False (2)
lookalike counter
got it (3)

5. Let $V = \{\vec{T} : \mathbb{R}^3 \rightarrow \mathbb{R}^2 \mid \vec{T} \text{ is a linear function}\}$. The elements in our set are thus *linear maps*. Define vector addition and scalar multiplication by the following:

$$(\vec{T} + \vec{R}) \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \vec{T} \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) + \vec{R} \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) \quad (\alpha \vec{T}) \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \alpha \left(\vec{T} \left(\begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) \right)$$

where $\alpha \in \mathbb{R}$, and $\vec{T}, \vec{R} \in V$.

It is given that V forms a vector space under the defined operations above. In particular note that the zero vector is the linear map defined by $\vec{0}([x \ y \ z]^T) = [0 \ 0]^T$ for all $[x \ y \ z]^T \in \mathbb{R}^3$.

Recall on last weeks quiz that you showed

$$S = \{\vec{T} \in V \mid \exists A \in \text{Mat}_{2 \times 3}(\mathbb{R}) \text{ so that } \vec{T}([x \ y \ z]^T) = A[x \ y \ z]^T \text{ for all } [x \ y \ z]^T \in \mathbb{R}^3\}$$

forms a subspace of V . We will now show that $V \subset S$ and thus V actually *equals* S .

You have two options:

- (a) Show that $V \subset S$. That is, given an arbitrary linear operator $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$, construct a 2×3 matrix A that has the property that $\vec{T}([x \ y \ z]^T) = A[x \ y \ z]^T$ for *any* vector $[x \ y \ z]^T$ in \mathbb{R}^3 .
- (b) Follow the steps on the next page that will walk you through the proof.

(a) [4] The trick is to make use of a basis of \mathbb{R}^3 .

Let $\{e_1, e_2, e_3\}$ be a standard basis for \mathbb{R}^3 and T be an arbitrary linear operator in V . Let A_1 be the 2×1 vector in \mathbb{R}^2 that results from T acting on e_1 , that is $A_1 = T(e_1)$. Similarly let $A_2 = T(e_2)$ and $A_3 = T(e_3)$. Define $A = [A_1 \ A_2 \ A_3]$. Verify that T and A send the standard basis to the same element in \mathbb{R}^2 . (ie. Verify that $T(e_i) = Ae_i$ for $i=1,2$ or 3 by making use of matrix multiplication.)

Started (4)
Should understand (3)
right now (1)

$$Ae_1 = [A_1 \ A_2 \ A_3] \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 1A_1 + 0A_2 + 0A_3 = A_1 = T(e_1)$$

$$Ae_2 = [A_1 \ A_2 \ A_3] \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = 0A_1 + 1A_2 + 0A_3 = A_2 = T(e_2)$$

$$Ae_3 = [A_1 \ A_2 \ A_3] \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = 0A_1 + 0A_2 + 1A_3 = A_3 = T(e_3)$$

(b) [4] Let $[x \ y \ z]^T \in \mathbb{R}^3$. Since $\{e_1, e_2, e_3\}$ is a spanning set, we can write $[x \ y \ z]^T$ as $c_1e_1 + c_2e_2 + c_3e_3$. Use linearity, properties of matrix multiplication, and part a) to show that $A[x \ y \ z]^T = T([x \ y \ z]^T)$.

Started (1)
Should understand (2)
right now (1)

$$\begin{aligned} A \begin{bmatrix} x \\ y \\ z \end{bmatrix} &= A(c_1e_1 + c_2e_2 + c_3e_3) = \\ &= c_1Ae_1 + c_2Ae_2 + c_3Ae_3 \\ &= c_1T(e_1) + c_2T(e_2) + c_3T(e_3) \\ &= T(c_1e_1 + c_2e_2 + c_3e_3) \\ &= T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right) \end{aligned}$$

by prop of matrix mult.

by part a

since T is linear

by choice of c_1, c_2, c_3