

T/F for quiz
find counterex if false

§ 3.5 # 3, 8, 9, 10, 11, 12, 20, 23

3) $[v_1, v_2, w_1] = \begin{bmatrix} 1 & 4 & 2 \\ 3 & 2 & 1 \\ 1 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 3 & 2 & 1 \\ 0 & 4 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 4 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

so $2v_2 = w_1$
 v_2 can be replaced with w_1 & retain lin. ind. of resulting set

8) let $w_1 = x+1$
 note $\mathcal{P}_2 = \text{span}\{1, x, x^2\}$
 So $\mathcal{P}_2 = \text{span}\{x+1, 1, x, x^2\}$
 I'll now use S. algorithm to reduce the set to a lin. indep set
 $1 \notin \text{span}\{x+1\}$
 $x \in \text{span}\{x+1, 1\}$
 $x^2 \notin \text{span}\{x+1, 1\}$
 So basis: $\{x+1, 1, x^2\}$

9) a) True since $\text{span } S \supset V \Rightarrow K \geq n$
 since $\text{span } S \subset V \Rightarrow K \leq n \quad \therefore K = n$

b) False let $V = \mathbb{R}^2$ $n=2$
 $S = \{ \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \}$ $K=3$

c) True $\dim(\text{span } S) = K$ & since $\text{span } S$ is a subspace of V
 $K \leq n$

d) True $\dim(\text{span } S) = K$ so $K \leq n$ & Cor 3.4
 $\Rightarrow \text{span } S = V$

e) True if S spans $V \Rightarrow K \geq n$
 but $K = n$ so minimal spanning set $\Rightarrow S$ is a basis

f) True Since $\det A \neq 0$ A is invertible
 \Leftrightarrow the columns of A are lin. indep
 So the first 4 col. cover a 4 dim. subspace.

10) a) false let $V = \mathbb{R}^2$ $S = \{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \}$
 S is lin. ind. but not a basis

b) true the counterexample was on a quiz
 redundant vectors \Rightarrow lin. dep.

c) True

Since $V = \text{span}\{\vec{v}_1, \vec{v}_3\}$ and $S \subseteq V$

\exists scalars $c_1, c_3 \ni v_1 = c_1 \vec{v}_1 + c_3 \vec{v}_3 \Rightarrow \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is indep

e) False

Consider the set of polynomials.

d) False

Given the set, reorder them so you have

$\{\vec{0}, \vec{v}_1, \vec{v}_2, \vec{v}_3\}$ note $2 \cdot \vec{0} + 0 \vec{v}_1 + \dots + 0 \vec{v}_k = \vec{0}$

but not all the scalars are zero.

f) true

We need to check for lin. ind. of the 3 vectors.

$$\left[\begin{array}{ccc|c} i & 0 & 1 & 0 \\ 0 & i & i & 0 \end{array} \right] \xrightarrow{-iR_1} \left[\begin{array}{ccc|c} 1 & 0 & -i & 0 \\ 0 & 1 & 1 & 0 \end{array} \right]$$

$$\text{so } -i \begin{bmatrix} i \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ i \end{bmatrix} + \begin{bmatrix} 1 \\ i \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ but the scalars are not all zero}$$

11) Given $V = \{\vec{0}\}$ we'd like to show $S = \{\vec{0}\}$ is not a basis.

Notice $1 \cdot \vec{0} = \vec{0}$

so we've written a linear combo of vectors from S with scalars that are not all zero but

whose sum is $\vec{0}$. Thus S is lin. dep.

Since a basis is lin. independent $\vec{0}$ is not a basis

Since V consists of only the $\vec{0}$ element

the basis must be empty $\Rightarrow \dim V = 0$.

12)

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12) Let $\vec{w}_1, \dots, \vec{w}_r$ be lin. indep. vectors in W .
Let $\vec{w} \in W$ and $\vec{w} \notin \text{span}\{\vec{w}_1, \dots, \vec{w}_r\}$
We want to show the set $\{\vec{w}_1, \dots, \vec{w}_r, \vec{w}\}$ is lin. indep.

I'll use a proof by contradiction: that is I'll assume the hypotheses and the opposite of the conclusion & bump into a contradiction.

Assume towards contradiction that $\{\vec{w}_1, \dots, \vec{w}_r, \vec{w}\}$ is not linearly independent.

This means there exist scalars c_1, \dots, c_r, c that are not all zero with the property $c_1\vec{w}_1 + \dots + c_r\vec{w}_r + c\vec{w} = \vec{0}$
Subtracting $c\vec{w}$ from both sides we see

$$c_1\vec{w}_1 + \dots + c_r\vec{w}_r = -c\vec{w}$$

If $c \neq 0$ we could mult both sides by $-1/c$

$$\Rightarrow -c_1/c\vec{w}_1 + \dots + -c_r/c\vec{w}_r = \vec{w}$$

$\Rightarrow \vec{w} \in \text{span}\{\vec{w}_1, \dots, \vec{w}_r\}$ but that contradicts our assumption that $\vec{w} \notin \text{span}\{\vec{w}_1, \dots, \vec{w}_r\}$.

If $c = 0$ then we'd have

$$c_1\vec{w}_1 + \dots + c_r\vec{w}_r = \vec{0}$$

where not all the c_i are zero but that contradicts our assumption that $\{\vec{w}_1, \dots, \vec{w}_r\}$ is lin. indep.

Thus such c_i cannot exist $\Rightarrow \{\vec{w}_1, \dots, \vec{w}_r, \vec{w}\}$ is lin. ind.

20) Let $T: V \rightarrow W$ be a lin. operator s.t. $\text{range } T = W$ & $\text{Ker } T = \{\vec{0}\}$. Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ be a basis of V .

To show $\{T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n)\}$ is a basis of W
we show it is both a spanning set & lin. indep.

Spanning set: let $\vec{w} \in W$, we want to find scalars d_1, \dots, d_n so that $\vec{w} = d_1 T(\vec{v}_1) + \dots + d_n T(\vec{v}_n)$.

Since $\text{range } T = W$, there exists a $\vec{v} \in V$ so that $T(\vec{v}) = \vec{w}$.

Since $\{\vec{v}_1, \dots, \vec{v}_n\}$ forms a basis for V there exists scalars c_1, \dots, c_n so we can write $\vec{v} = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n$.

Consider

$$\begin{aligned} \vec{w} &= T(\vec{v}) = T(c_1 \vec{v}_1 + \dots + c_n \vec{v}_n) && \text{b/c } T \text{ is linear} \\ &= c_1 T(\vec{v}_1) + \dots + c_n T(\vec{v}_n) \end{aligned}$$

Thus we have what we needed.

Linear independent: Recall the def. of lin. indep.

We want to show if we are given $a_1 T(\vec{v}_1) + \dots + a_n T(\vec{v}_n) = \vec{0}$ that $0 = a_1 = \dots = a_n$.

Notice since T is linear

$$\vec{0} = a_1 T(\vec{v}_1) + \dots + a_n T(\vec{v}_n) = T(a_1 \vec{v}_1 + \dots + a_n \vec{v}_n)$$

So $a_1 \vec{v}_1 + \dots + a_n \vec{v}_n \in \text{Ker } T = \{\vec{0}\}$

Since $\vec{v}_1, \dots, \vec{v}_n$ is a basis

$$a_1 \vec{v}_1 + \dots + a_n \vec{v}_n = \vec{0} \Rightarrow a_1 = 0 = a_2 = \dots = a_n$$

Thus we have our conclusion.

23) Let $T: V \rightarrow W$ be a linear operator
where V is fin. dim space & U is a subspace of V .
Show $\dim T(U) \leq \dim(U)$.

Let $\{\vec{u}_1, \dots, \vec{u}_n\}$ be a basis of U . So $\dim(U) = n$

I claim $T(U) = \text{image } T = \text{span}\{T(\vec{u}_1), \dots, T(\vec{u}_n)\}$.
Once this is shown, Gaussian algorithm will
be able to find a basis by eliminating
vectors thus $\dim T(U) \leq n = \dim(U)$.

Pr of claim: Let $\vec{w} \in T(U)$. We need to show
that there exist scalars a_1, \dots, a_n that will
allow us to write $\vec{w} = a_1 T(\vec{u}_1) + \dots + a_n T(\vec{u}_n)$

Since $\vec{w} \in T(U)$ by definition of image there
exists a $\vec{u} \in U$ so that $T(\vec{u}) = \vec{w}$.

$\{\vec{u}_1, \dots, \vec{u}_n\}$ is a basis of U so there are scalars b_1, \dots, b_n
such that $\vec{u} = b_1 \vec{u}_1 + \dots + b_n \vec{u}_n$

Consider then

$$\vec{w} = T(\vec{u}) = T(b_1 \vec{u}_1 + \dots + b_n \vec{u}_n) \quad \text{by linearity}$$

$$= b_1 T(\vec{u}_1) + \dots + b_n T(\vec{u}_n)$$

thus $\vec{w} \in \text{span}\{T(\vec{u}_1), \dots, T(\vec{u}_n)\}$

$\Rightarrow \{T(\vec{u}_1), \dots, T(\vec{u}_n)\}$ is a spanning set //

