

§ 3.4 #1, 2, 3, 5, 6, 7, 8, 9, 10, 11, 12, 16

1a) $\begin{bmatrix} 2 & -1 & 0 & 3 & | & 0 \\ 4 & -2 & 1 & 3 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 2 & -1 & 0 & 3 & | & 0 \\ 0 & 0 & 1 & -3 & | & 0 \end{bmatrix}$ $\{(x_1, x_2, x_3, x_4) \mid x_1 - x_2 + 3x_4 = 0, x_3 - 3x_4 = 0\}$
 $\{(x_1, x_2, x_3, x_4) \mid x_1 - x_2 + 3x_4 = 0, x_3 - 3x_4 = 0\}$ so $\left\{ \begin{bmatrix} 5 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 3 \\ 1 \end{bmatrix} \right\}$

b) $\begin{bmatrix} 1 & 4 & | & 0 \\ -1 & -4 & | & 0 \\ -4 & -4 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & | & 0 \\ 0 & 0 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$ $\{(x_1, x_2) \mid x_1 + 4x_2 = 0\} = \{(-4x_2, x_2) \mid x_2 \in \mathbb{R}\}$

3a) $\text{span} \left\{ \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \begin{bmatrix} -1 \\ -2 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 3 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix} \right\}$ by above res
 so $\left\{ \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix} \right\}$

b) $\text{span} \left\{ \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ -4 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\}$ basis: $\left\{ \begin{bmatrix} -1 \\ -1 \end{bmatrix} \right\}$

5) a) $\text{span} \left\{ \begin{bmatrix} 2 \\ -1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 1 \\ 3 \end{bmatrix} \right\}$ note $\begin{bmatrix} 2 & 4 \\ -1 & -2 \\ 0 & 1 \\ 3 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 \\ 0 & 0 \\ 0 & 1 \\ 0 & -3 \end{bmatrix}$ lin. ind. basis: $\left\{ \begin{bmatrix} 2 \\ -1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \\ 1 \\ 3 \end{bmatrix} \right\}$

b) $\text{span} \left\{ \begin{bmatrix} 4 \\ -4 \end{bmatrix}, \begin{bmatrix} -4 \\ 4 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 4 \\ -4 \end{bmatrix} \right\}$ basis: $\left\{ \begin{bmatrix} 4 \\ -4 \end{bmatrix} \right\}$

7a) null space of $I - A$ $I - A = \begin{bmatrix} .5 & 0 & -1 \\ -.5 & .5 & 0 \\ 0 & -.5 & 1 \end{bmatrix}$

$I - A \xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 0 & .5 & -1 \\ .5 & 0 & -1 \\ 0 & -.5 & 1 \end{bmatrix} \xrightarrow{R_2 + R_1} \begin{bmatrix} .5 & 0 & -1 \\ 0 & .5 & -1 \\ 0 & -.5 & 1 \end{bmatrix} \xrightarrow{R_3 + R_2} \begin{bmatrix} .5 & 0 & -1 \\ 0 & .5 & -1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 \times 2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & .5 & -1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 \times 2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{bmatrix}$

sol. set = $\{(x_1, x_2, x_3) \mid x_1 = 2x_3, x_2 = 2x_3, x_3 \in \mathbb{R}\}$
 $= \{(2x_3, 2x_3, x_3) \mid x_3 \in \mathbb{R}\}$

$= \text{span} \left\{ \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$

we are looking for $\vec{y} \in \text{span} \left\{ \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\}$ whose entries are nonnegative
 ie looking for scalar c so that $\begin{bmatrix} 2c \\ 2c \\ c \end{bmatrix}$ has the property

that $2c + 2c + c = 1 \Rightarrow 5c = 1 \Rightarrow c = 1/5$
 try $\vec{y} = 1/5 \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/5 \\ 2/5 \\ 1/5 \end{bmatrix}$ \Downarrow

9) a) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \mapsto \begin{bmatrix} x_1 - 2x_2 + x_3 \\ x_1 + x_2 + x_3 \\ 2x_1 - x_2 + 2x_3 \end{bmatrix} = \begin{bmatrix} 1 & -2 & 1 \\ 1 & 1 & 1 \\ 2 & -1 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad \text{let } A$$

note that there is a matrix we can assoc with T
 & thus we can use the identifications listed on pg 189
 that will make the computations easier

$$A := \begin{bmatrix} 1 & -2 & 1 \\ 1 & 1 & 1 \\ 2 & -1 & 2 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 1 \\ 0 & 3 & 0 \\ 0 & 3 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{Ker } T = \mathcal{N}(A) = \left\{ (x_1, x_2, x_3) \mid x_1 = -x_3, x_2 = 0, x_3 \in \mathbb{R} \right\}$$

$$= \left\{ (-x_3, 0, x_3) \mid x_3 \in \mathbb{R} \right\}$$

$$\text{range } T = \mathcal{C}(A) = \text{span} \left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \right\} \quad \text{not one-to-one by ref above}$$

$$= \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ -1 \end{bmatrix} \right\} \quad \text{not onto}$$

$\dim \text{range } T = 2$ but $\dim \text{target} = 3$

also note $\begin{bmatrix} 0 & 0 & 1 \end{bmatrix}^T$ is not in the range

b/c $\begin{bmatrix} 1 & -2 & 1 \\ 1 & 1 & 1 \\ 2 & -1 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 1 \\ 0 & 3 & 0 \\ 0 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -2 & 1 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ incorrect

b) $T: \mathcal{P}_2 \rightarrow \mathbb{R}$

$$ax^2 + bx + c \mapsto a(1)^2 + b(1) + c = a + b + c$$

I could use the identification with \mathcal{P}_2 and \mathbb{R}^3
 but I'll try doing this with just the definition.

just give \rightarrow

$$\text{Ker } T = \{ ax^2 + bx + c \in \mathcal{P}_2 \mid a(1)^2 + b(1) + c = 0 \}$$

$$= \{ ax^2 + bx + c \in \mathcal{P}_2 \mid a = -b - c \} = \{ (-b-c)x^2 + bx + c \mid c, b \in \mathbb{R} \}$$

$$= \{ (-x^2 + x)b + (-x^2 + 1)c \mid c, b \in \mathbb{R} \}$$

$$= \text{span} \{ -x^2 + x, -x^2 + 1 \} \quad \text{so not one-to-one}$$

$$\begin{aligned} \text{range } T &= \{z \in \mathbb{R} \mid \exists ax^2+bx+c \in \mathcal{P}_2 \text{ with } T(ax^2+bx+c) = z\} \\ &= \{a+b+c \mid a, b, c \in \mathbb{R}\} \\ &= \text{span} \{1\} \end{aligned}$$

is onto

10) a) $T: \mathcal{P}_2 \rightarrow \mathcal{P}_3$ and
 $ax^2+bx+c \mapsto ax + \frac{b}{2}x^2 + \frac{c}{3}x^3$

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} \mapsto \begin{bmatrix} 0 \\ a \\ b/2 \\ c/3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

Given 9b I think I'll record the polynomials as vectors and find a matrix that records my linear transform as matrix mult from left.

$$A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1/3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\text{Ker } T = \mathcal{N}(A) = \{(y_1, y_2, y_3) \mid y_1 = 0 = y_2 = y_3\} = \{0\} \quad T \text{ is one-to-one}$$

$$\text{range } T = \mathcal{C}(A) = \text{span} \{x, x^2, x^3\}$$

T is not onto.

again an argument of dim or the fact $2 \in \mathcal{P}_3$ but $2 \notin \text{range } T$.

b) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} 2x_2 \\ 3x_3 \end{bmatrix} = \begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \quad \text{let } A = \begin{bmatrix} 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$\begin{aligned} \text{Ker } T = \mathcal{N}(A) &= \{(x_1, x_2, x_3) \mid x_2 = 0 = x_3, x_1 \in \mathbb{R}\} = \{(x, 0, 0) \mid x \in \mathbb{R}\} \\ &= \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\} \end{aligned}$$

$$\text{range } T = \mathcal{C}(A) = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix} \right\} = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 3 \end{bmatrix} \right\}$$

is onto

Started ①
 Ker ①-1 ①
 range ①

11) $T: V \rightarrow \mathbb{R}^2$

$T(\vec{v}_1) = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ $T(\vec{v}_2) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ $T(\vec{v}_3) = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$
 where $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is a basis of V .

Since $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ every vector in V can be expressed uniquely with a set of coordinates c_1, c_2, c_3 .
 Thus

• $\text{Ker } T = \{ \vec{v} \in V \mid T(\vec{v}) = \vec{0} \}$
 $= \{ c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 \in V \mid T(c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3) = \vec{0} \}$
 by lin. of T $= \{ c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 \in V \mid c_1 T(\vec{v}_1) + c_2 T(\vec{v}_2) + c_3 T(\vec{v}_3) = \vec{0} \}$
 $= \{ \quad \quad \quad \mid c_1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \vec{0} \}$

we are thus looking for all solutions to the lin sys.

$$\begin{bmatrix} -1 & 1 & 2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \vec{0}$$

$$\left[\begin{array}{ccc|c} -1 & 1 & 2 & 0 \\ 1 & 1 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & -1 & -2 & 0 \\ 0 & 2 & 2 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & -1 & -2 & 0 \\ 0 & 1 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 1 & 0 \end{array} \right]$$

so sol set is $\{ (c_1, c_2, c_3) \mid c_1 = -c_3, c_2 = -c_3, c_3 \in \mathbb{R} \}$
 $\{ (c_3, -c_3, c_3) \mid c_3 \in \mathbb{R} \} = S$

Any set of coordinates from S will thus
 $\Rightarrow c_1 \begin{bmatrix} -1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_3 \begin{bmatrix} 2 \\ 0 \end{bmatrix} = \vec{0}$
 i.e. the vector assoc. with these coordinates is in the kernel

$\text{Ker } T = \{ c_3 \vec{v}_1 - c_3 \vec{v}_2 + c_3 \vec{v}_3 \mid c_3 \in \mathbb{R} \}$ not one-to-one
 $= \text{span} \{ -\vec{v}_1 - \vec{v}_2 + \vec{v}_3 \}$

• $\text{range } T = \text{span} \{ T(\vec{v}_1), T(\vec{v}_2), T(\vec{v}_3) \} = \text{span} \{ \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \end{bmatrix} \}$
 $= \text{span} \{ \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \}$

note $\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \}$ forms a basis for \mathbb{R}^2 is onto
 $\begin{bmatrix} -1 & 1 \\ 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -1 \\ 0 & 2 \end{bmatrix}$

started (+1)
 Ker = 1-1 (+1)
 range = 0 (+1)

2) $T: V \rightarrow \mathbb{R}^3$ $T(\vec{v}_1) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ $T(\vec{v}_2) = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ $T(\vec{v}_3) = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

where $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is a basis of V

We'll use the same trick we did in #11

$\text{Ker } T = \{c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 \mid T(c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3) = \vec{0}\}$
 $= \{c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 \mid c_1 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \vec{0}\}$

looking at the lin. system

$$\left[\begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 1 & 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

so $c_1 = -c_3, c_2 = c_3$ if $c_1 \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \vec{0}$

thus $\text{Ker } T = \text{span}\{-\vec{v}_1 + \vec{v}_2 + \vec{v}_3\} = \text{span}\left\{\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}\right\} \subset V$ is not one-to-one

range $T = \text{span}\{T(\vec{v}_1), T(\vec{v}_2), T(\vec{v}_3)\}$
 $= \text{span}\left\{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}\right\}$
 $= \text{span}\left\{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}\right\} \subset \mathbb{R}^3$

the above ref shows the third vector is redundant
 thus a dim. argument
 \Rightarrow not onto

16) Show that if $T: V \rightarrow W$ is a linear operator, then the Kernel of T is a subspace of V .

started (+1)
 looked for 3 (+1)
 got it (+1)

We need to check that the 3 conditions to be a subspace hold:

(1) Note $\vec{0}_V \in V$ is in the Kernel of T since
 $T(\vec{0}_V) = T(0 \cdot \vec{0}_V) = 0T(\vec{0}_V)$ since T is linear
 $= \vec{0}_W$ b/c $0 \cdot \vec{w} = \vec{0} \forall \vec{w} \in W$

(2) Let $\vec{v}_1, \vec{v}_2 \in \text{Ker } T$, we need to show $\vec{v}_1 + \vec{v}_2 \in \text{Ker } T$,

$T(\vec{v}_1 + \vec{v}_2) = T(\vec{v}_1) + T(\vec{v}_2)$ since T is linear
 $= \vec{0}_W + \vec{0}_W$ since $\vec{v}_1, \vec{v}_2 \in \text{Ker } T$
 $= \vec{0}_W$ so $\vec{v}_1 + \vec{v}_2 \in \text{Ker } T$.

(3). Let c be a scalar and $\vec{v}_1 \in \text{Ker } T$.
We need to show $c\vec{v}_1 \in \text{Ker } T$.

$$\begin{aligned} T(c\vec{v}_1) &= cT(\vec{v}_1) && \text{since } T \text{ is linear} \\ &= c\vec{0}_W && \text{since } \vec{v}_1 \in \text{Ker } T \\ &= \vec{0}_W \end{aligned}$$

Thus $c\vec{v}_1 \in \text{Ker } T$.

So $\text{Ker } T$ is a subspace of V . //

① Laplace
② Cramer's rule
③ minor signs

① Laplace
② Cramer's rule
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