## 1 Dimensional Geometry

definitions & theorems from Origametry by Daniel Heath.

While working in a group make sure you:

- Expect to make mistakes but be sure to reflect/learn from them!
- Are civil and are aware of your impact on others.
- Assume and engage with the strongest argument while assuming best intent.

**Postulate L-1.** Given any two distinct points, there is a 1-1 correspondence, called a ruler, between all points with the real numbers that sends one of the two given to 0 and the other to some number x > 0. The number p assigned to a point P by the ruler is called its coordinate.

**Definition 2.1.** If A and B are arbitrary points with coordinates a and b, then the distance AB, from A and B is defined to be AB = |a - b|.

**Definition 2.2.** Let A, B, and C be distince points with coordinates a, b, and c respectively. Then B is between A and C (denoted A-B-C) provided that either a < b < c or c < b < a.

**Theorem 2.1.** If B is between A and C, then AB + BC = AC.

**Definition 2.3.** Given two distince points A and B we define the segment (denoted  $\overline{AB}$ ) to be the set of points C so that either C = A, C = B, or A - C - B, i.e.

$$\overline{AB} = \{C : C = A, C = B, \text{ or } A - C - B\}.$$

The length of a segment is the distance between its endpoints.

**Definition 2.4.** Given two points A and B we define the ray (denoted  $\overrightarrow{AB}$ ) to be the set of points C so that either C = A, C = B, A - C - B, or A - B - C, i.e.

$$\overrightarrow{AB} = \{C : C = A, C = B, A - C - B, \text{ or } A - B - C\}.$$

**Practice 2.4.** Suppose we define "points" as non-vertical lines through the origin in  $\mathbb{R}^2$ .

1. Verify that Postulate L-1 is satisfied.

2. Sketch the segment between 0 and 1.

**Postulate L-2.** Let O be a point. There is a bijective function  $\phi$  from the line to the line called a fold with crease O such that:

- 2.  $\underbrace{Let \ \overrightarrow{OA_0}}_{OA_{1-i}}$  and  $\overrightarrow{OA_1}$  be the two rays determined by O. Then  $B \in \overrightarrow{OA_i}$  implies  $\phi(B) \in \overrightarrow{OA_{1-i}}$ .
- 3. If segment  $\overline{BC} \subset \overrightarrow{OA_i}$ , then  $BC = \phi(B)\phi(C)$ .

**Definition 2.6.** Let A and B be distinct points, and let a and b be their respective coordinates. Let M be the point with coordinate  $\frac{a+b}{2}$ . Then M is called the midpoint of the segment  $\overline{AB}$ .