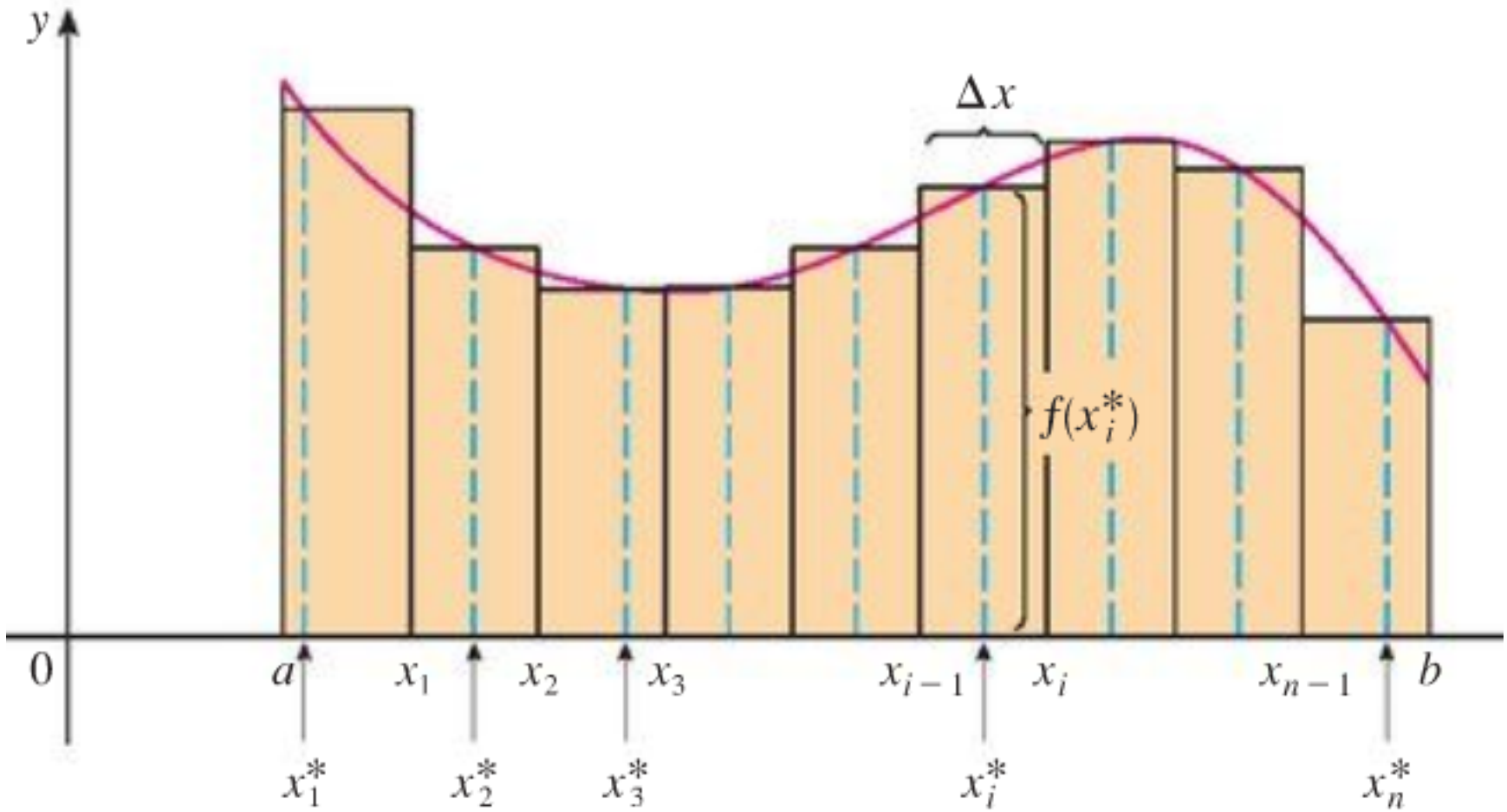
y
Δx
f(x*_i)
0
a
x_1
x_2
x_3
x_{i-1}
x_i
x_{n-1}
b
x*_1
x*_2
x*_3
x*_i
x*_n