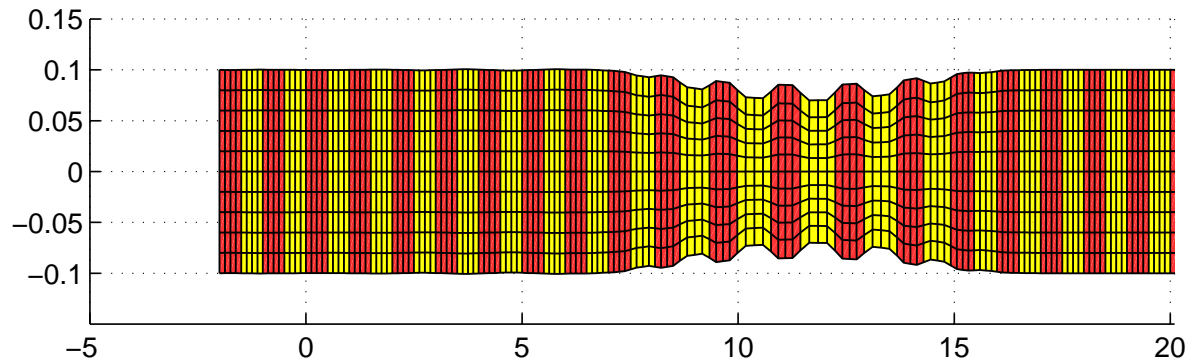


Solitary Waves in Layered Nonlinear Media

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Department of Applied Mathematics
University of Washington



One-dimensional Elasticity

Notation:

$X(x, t)$ = location of particle indexed by x in the reference (unstrained) configuration

$X(x, 0)$ = x if initially unstrained

$\epsilon(x, t)$ = $X_x(x, t) - 1$ = strain

$u(x, t)$ = velocity of particle indexed by x

$\rho(x)$ = density

Constitutive relation

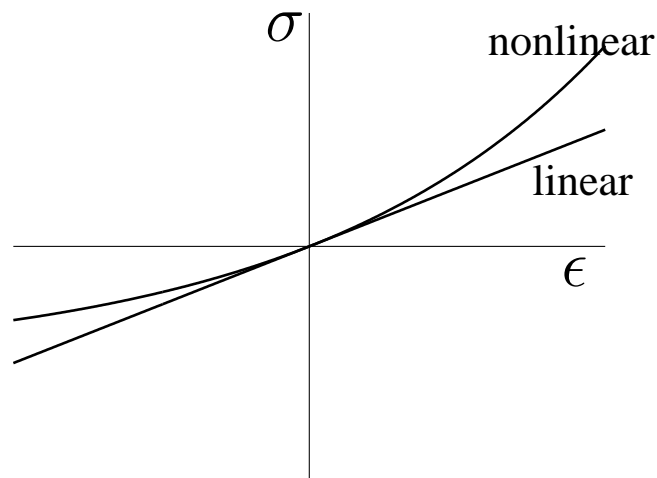
stress = $\sigma(\epsilon, x)$, where ϵ = strain

Heterogeneous \implies explicit dependence on x .

Linear elasticity: (Hooke's law)

$$\sigma(\epsilon, x) = K(x)\epsilon$$

where K is the bulk modulus of compressibility.



System of two conservation laws:

$$\begin{aligned}\epsilon_t - u_x &= 0 \\ (\rho u)_t + \sigma_x &= 0\end{aligned}$$

or $q_t + f(q, x)_x = 0$ with

$$q = \begin{bmatrix} \epsilon \\ \rho u \end{bmatrix} = \begin{bmatrix} q^1 \\ q^2 \end{bmatrix}, \quad f(q, x) = \begin{bmatrix} q^2 / \rho(x) \\ -\sigma(q^1, x) \end{bmatrix}$$

Quasi-linear hyperbolic form:

$$q_t + f_q(q, x)q_x = -f_x(q, x)$$

$$\text{Jacobian: } f_q(q, x) = \begin{bmatrix} 0 & -1/\rho(x) \\ -\sigma_\epsilon(\epsilon, x) & 0 \end{bmatrix}$$

Eigenvalues (wave speeds): $\pm \sqrt{\sigma_\epsilon / \rho}$.

Wave-propagation algorithms for spatially-varying fluxes

$$q_t + f(q, x)_x = 0$$

Work with Derek Bale, Sorin Mitran, and James Rossmannith,

A wave-propagation method for conservation laws and balance laws with spatially varying flux functions, SISC 24 (2002), pp. 955-978

[Connections to relaxation schemes](#) (Jin and Xin):

Work with Marica Pelanti,

A Class of Approximate Riemann Solvers and Their Relation to Relaxation Schemes, J. Comput. Phys., 172 (2001), pp. 572-591.

[Applications:](#)

- Wave propagation in heterogeneous nonlinear media
- Flow in heterogeneous porous media
- Traffic flow with varying road conditions
- Solving conservation laws on curved manifolds

CLAWPACK

<http://www.amath.washington.edu/~claw/>

- Fortran codes with Matlab graphics routines.
- Many examples and applications to run or modify.
- 1d, 2d, and 3d.

User supplies:

- Riemann solver, splitting data into waves and fluctuations
(Need not be in conservation form)
- Boundary condition routine to extend data to ghost cells
Standard `bc1.f` routine includes many standard BC's
- Initial conditions — `qinit.f`

Linear case: $\sigma = K\epsilon$

$$q_t + Aq_x = 0 \quad \text{with } q = \begin{bmatrix} \epsilon \\ m \end{bmatrix}, \quad A = \begin{bmatrix} 0 & -1/\rho \\ -K & 0 \end{bmatrix}.$$

$$\text{Diagonalize } A: R^{-1}AR = \Lambda \text{ where } \Lambda = \begin{bmatrix} -c & 0 \\ 0 & c \end{bmatrix}, \quad c = \sqrt{K/\rho},$$

$$R = \begin{bmatrix} 1 & 1 \\ Z & -Z \end{bmatrix}, \quad R^{-1} = \frac{1}{2Z} \begin{bmatrix} Z & 1 \\ Z & -1 \end{bmatrix}$$

$$Z = \text{impedance} = \rho c = \sqrt{K\rho}.$$

System can be written as

$$R^{-1}q_t + R^{-1}AR R^{-1}q_x = 0 \quad \text{or} \quad w_t + \Lambda w_x = 0.$$

Linear case

With $w = R^{-1}q$,

$$w_t + \Lambda w_x = 0.$$

This is a decoupled pair of advection equations for the characteristic variables:

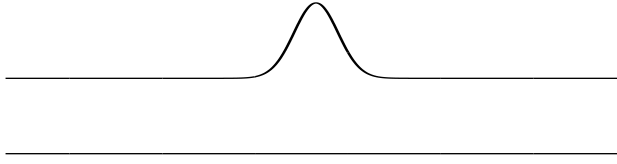
$$w_t^1 - cw_x^1 = 0 \quad \Longrightarrow \quad w^1(x, t) = w^1(x + ct, 0)$$

$$w_t^2 + cw_x^2 = 0 \quad \Longrightarrow \quad w^2(x, t) = w^2(x - ct, 0)$$

$q(x, t)$ is a linear comb. of left-going and right-going waves:

$$q(x, t) = Rw(x, t) = w^1(x, t) \begin{bmatrix} 1 \\ Z \end{bmatrix} + w^2(x, t) \begin{bmatrix} 1 \\ -Z \end{bmatrix}.$$

Example: $q(x, 0) = \begin{bmatrix} H(x) \\ 0 \end{bmatrix}$

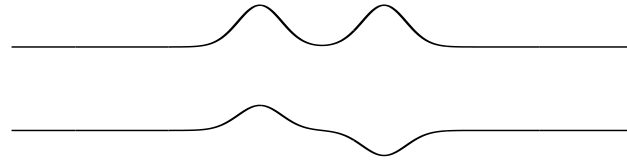


Then

$$w(x, 0) = R^{-1}q(x, 0) = \frac{1}{2} \begin{bmatrix} H(x) \\ H(x) \end{bmatrix}$$

$$\begin{aligned} q(x, t) &= Rw(x, t) = w^1(x, t) \begin{bmatrix} 1 \\ Z \end{bmatrix} + w^2(x, t) \begin{bmatrix} 1 \\ -Z \end{bmatrix} \\ &= \frac{1}{2}H(x + ct) \begin{bmatrix} 1 \\ Z \end{bmatrix} + \frac{1}{2}H(x - ct) \begin{bmatrix} 1 \\ -Z \end{bmatrix} \end{aligned}$$

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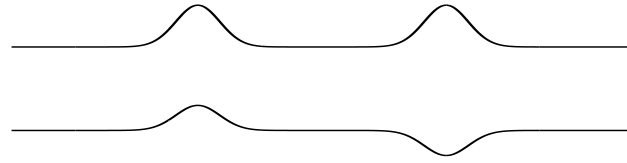


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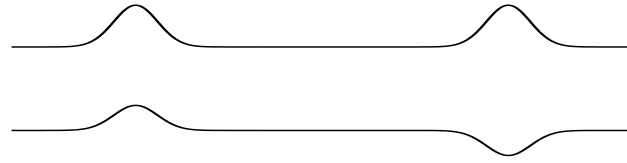


Then

$$w(x, 0) = R^{-1}q(x, 0) = \frac{1}{2} \begin{bmatrix} H(x) \\ H(x) \end{bmatrix}$$

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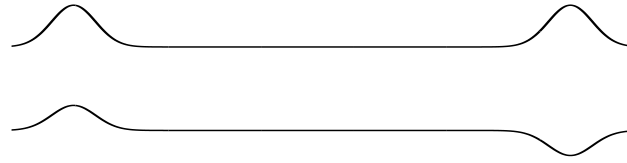


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$$w(x, 0) = R^{-1}q(x, 0) = \frac{1}{2} \begin{bmatrix} H(x) \\ H(x) \end{bmatrix}$$

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Example: $q(x, 0) = \begin{bmatrix} H(x) \\ 0 \end{bmatrix}$



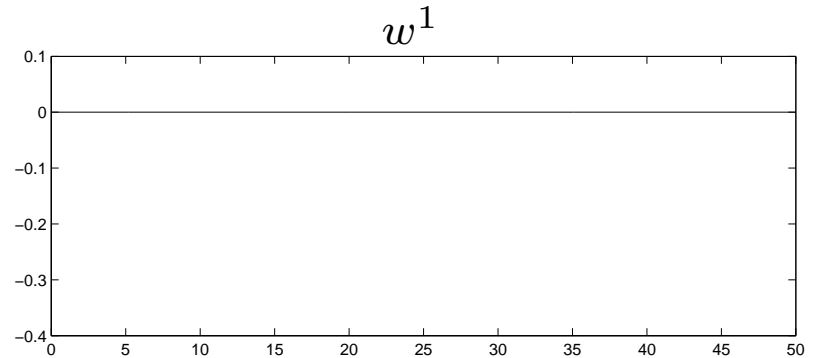
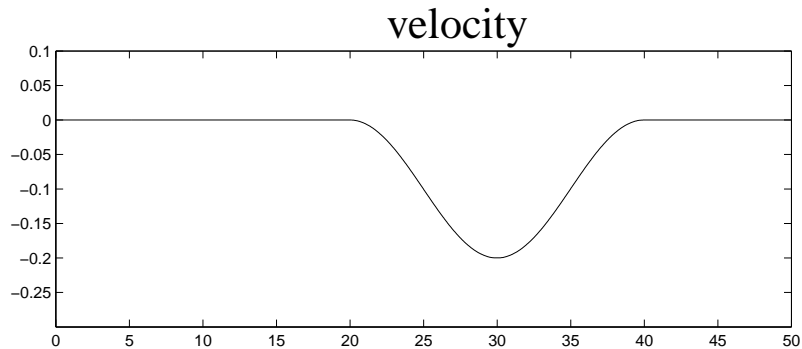
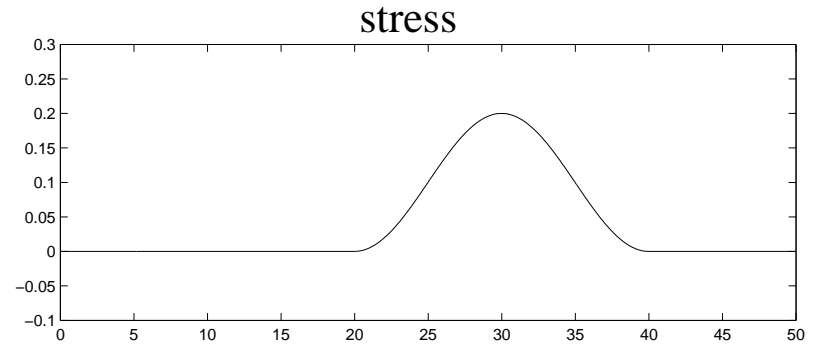
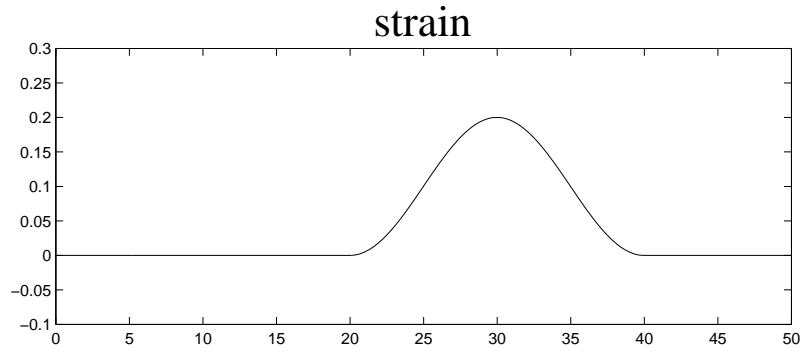
Then

$$w(x, 0) = R^{-1}q(x, 0) = \frac{1}{2} \begin{bmatrix} H(x) \\ H(x) \end{bmatrix}$$

$$q(x, t) = Rw(x, t) = w^1(x, t) \begin{bmatrix} 1 \\ Z \end{bmatrix} + w^2(x, t) \begin{bmatrix} 1 \\ -Z \end{bmatrix}$$

$$= \frac{1}{2}H(x + ct) \begin{bmatrix} 1 \\ Z \end{bmatrix} + \frac{1}{2}H(x - ct) \begin{bmatrix} 1 \\ -Z \end{bmatrix}$$

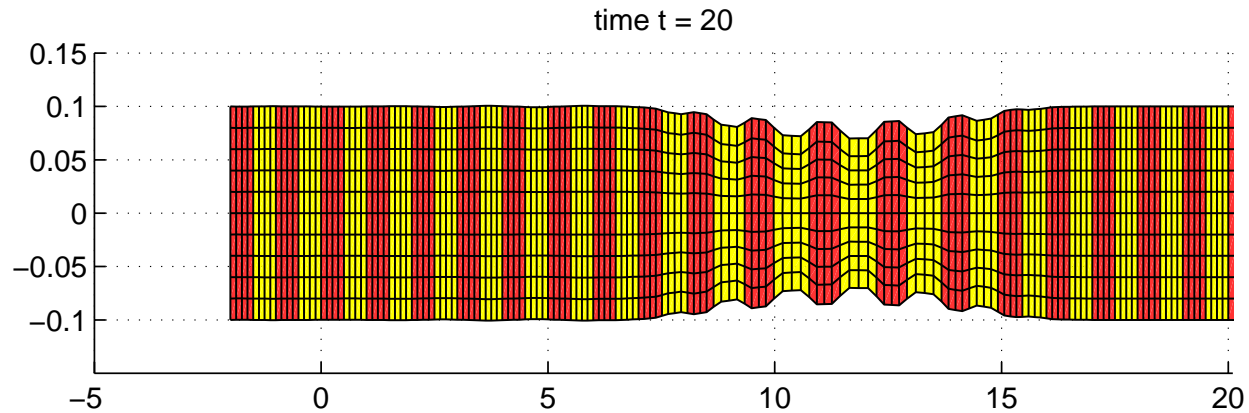
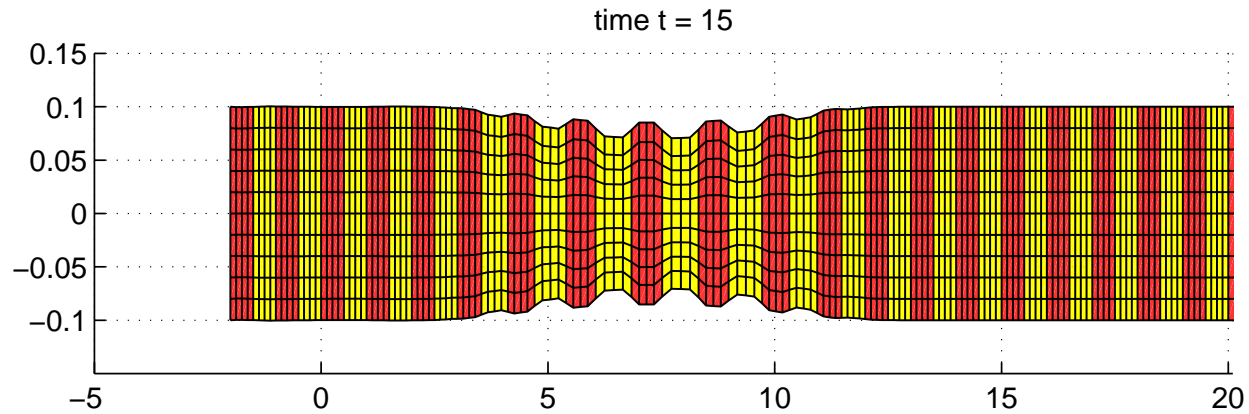
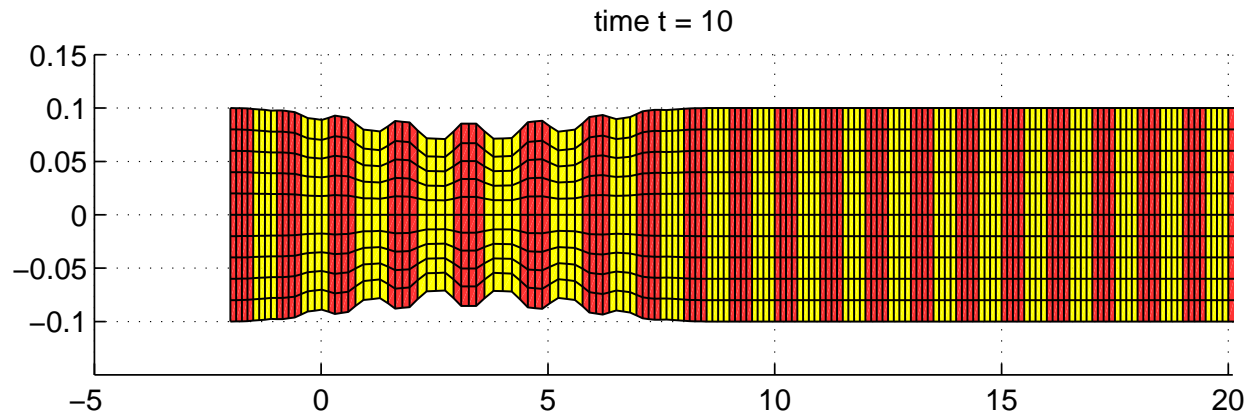
Waves in a homogeneous linear medium



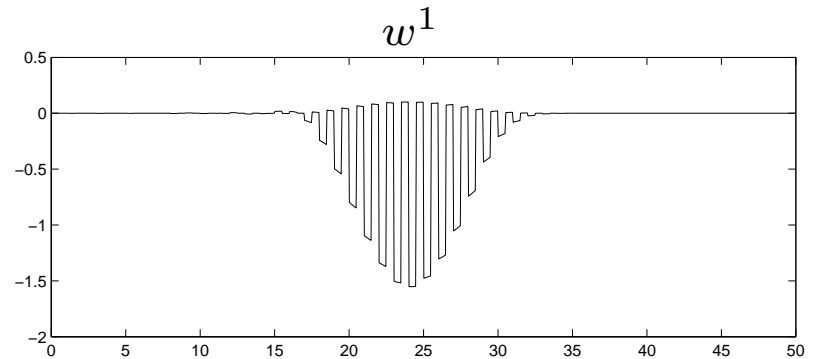
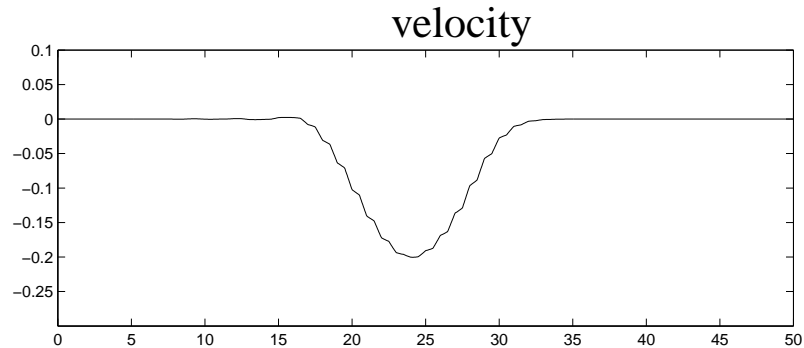
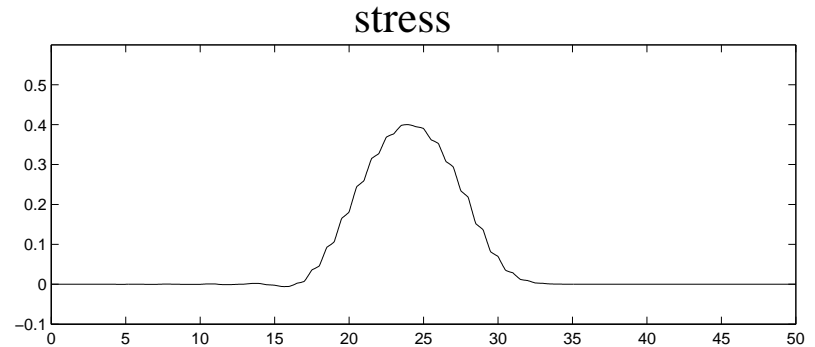
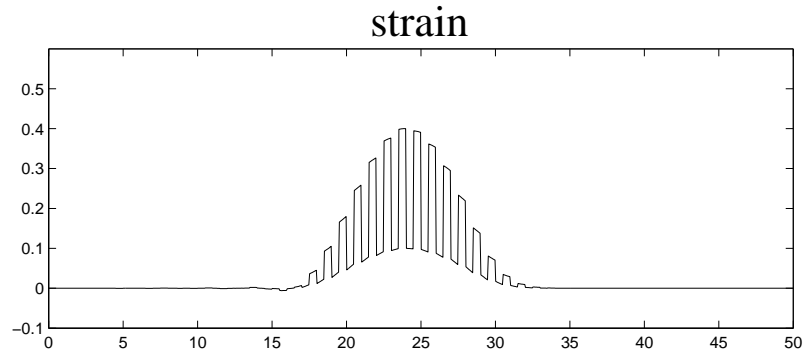
$$c \equiv 1, \quad Z \equiv 1$$

At $t = 40$ the leading edge of wave is at $x = 40$.

Waves in a layered elastic plate



Waves in a heterogeneous linear medium

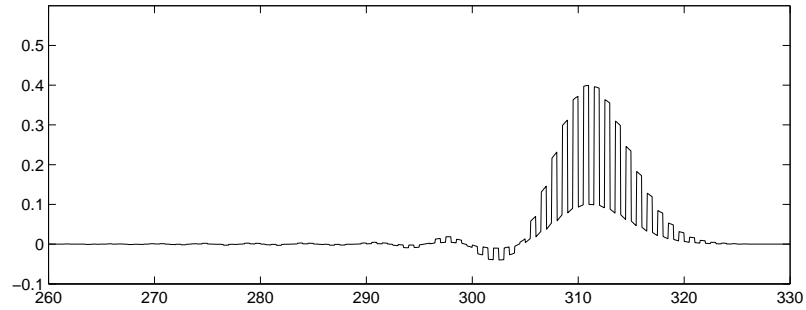


$c \equiv 1$ but Z is different in the layers.

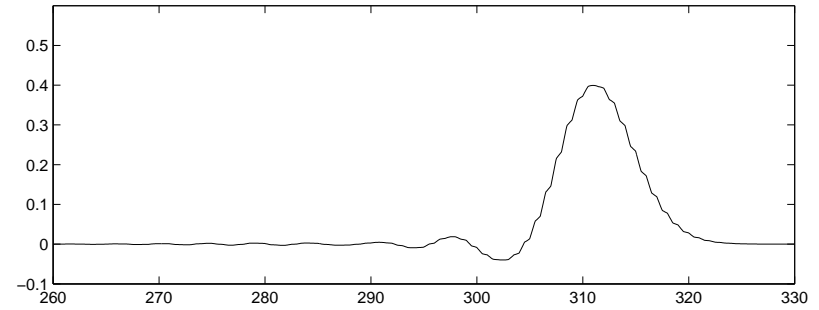
At $t = 40$ the leading edge of wave is at $x \approx 32$.

Waves in a heterogeneous linear medium, $t = 400$

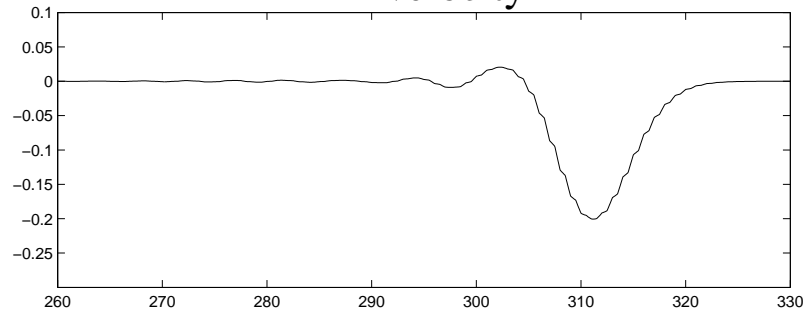
strain



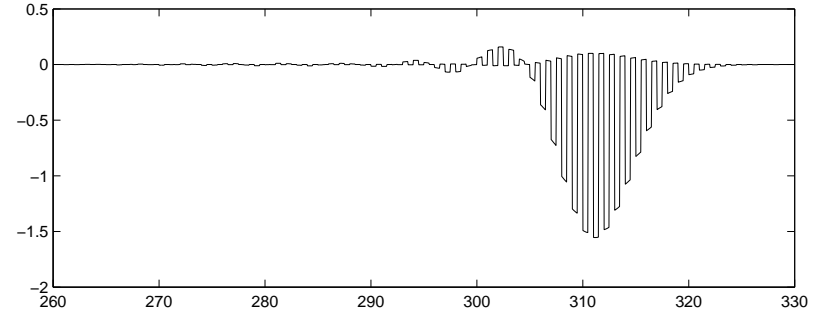
stress at t = 400



velocity



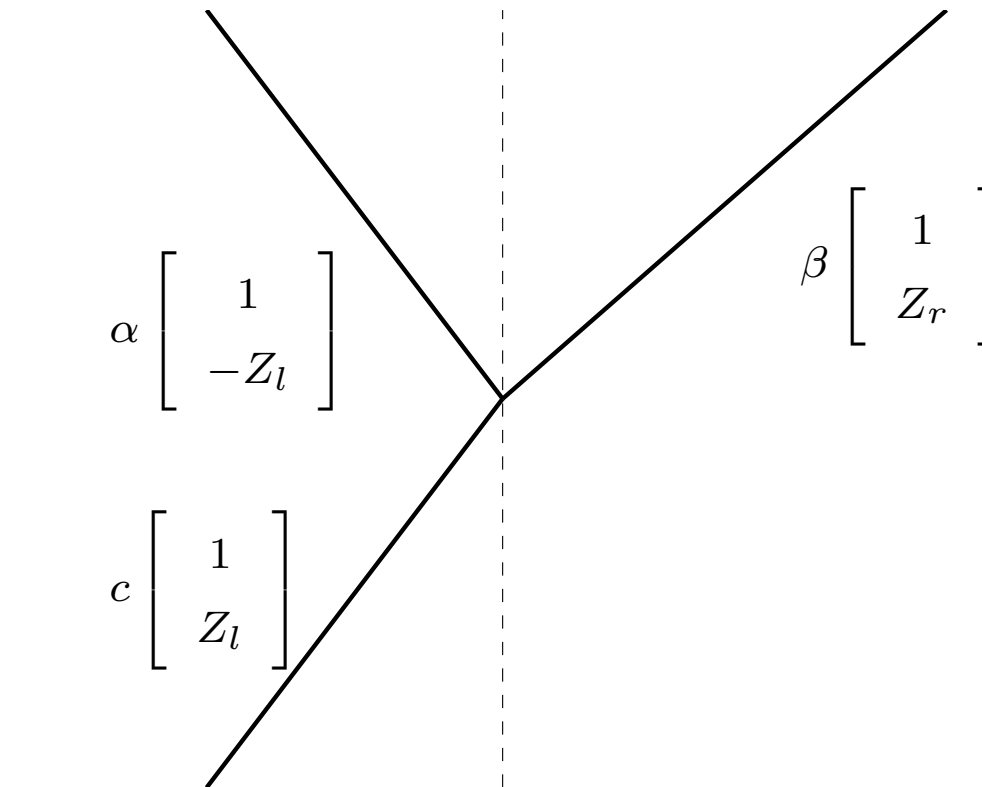
w^1



Waves in layered medium

Note: Form of wave depends on impedance Z .

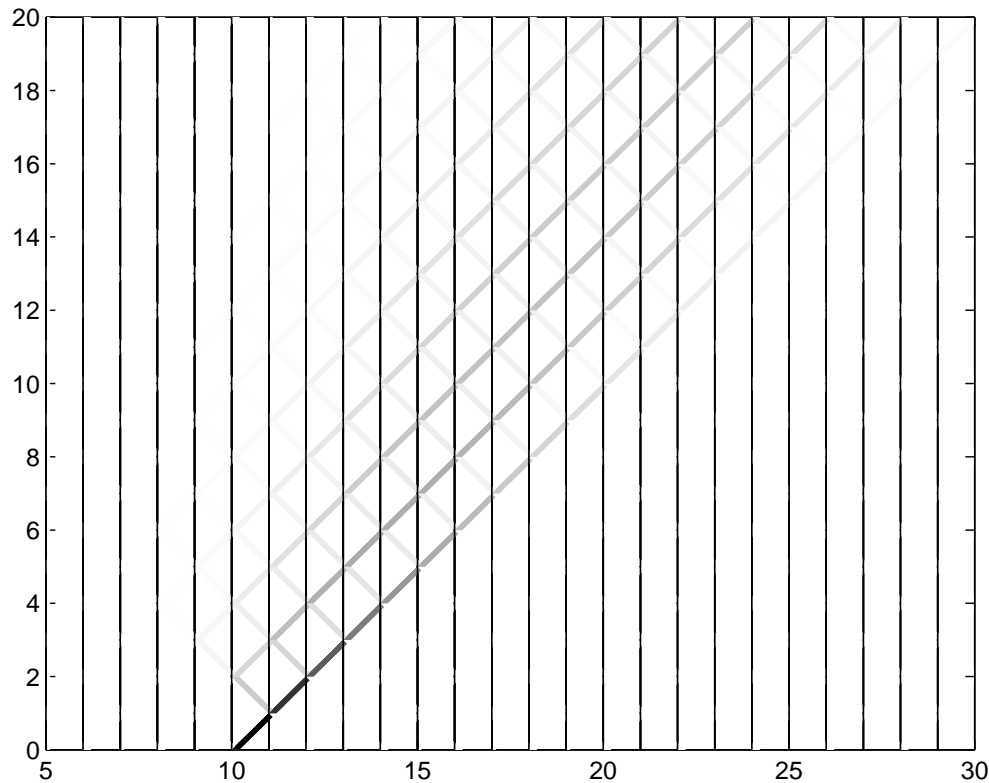
If Z varies with x then we expect reflection at interfaces



Waves in layered medium

Note: Form of wave depends on impedance Z .

If Z varies with x then we expect reflection at interfaces



Nonlinear materials

$$\begin{aligned}\epsilon_t - u_x &= 0 \\ (\rho u)_t + \sigma_x &= 0\end{aligned}$$

where

$$\sigma(\epsilon, x) = K(x)\epsilon + \beta K^2(x)\epsilon^2$$

or

$$\sigma(\epsilon, x) = e^{K(x)\epsilon} - 1 \approx K(x)\epsilon + \frac{1}{2}K^2(x)\epsilon^2$$

Layered medium can be related to Toda lattice

Nonlinear materials

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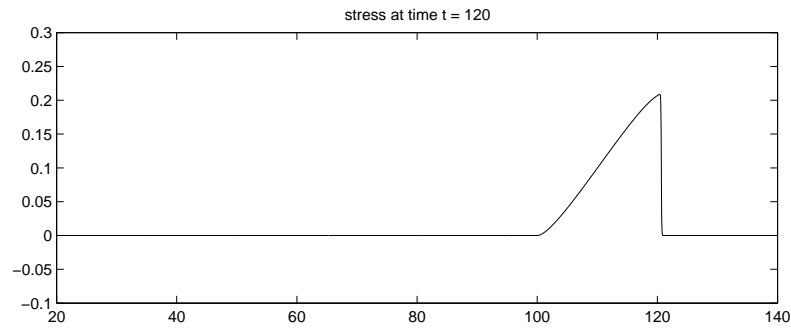
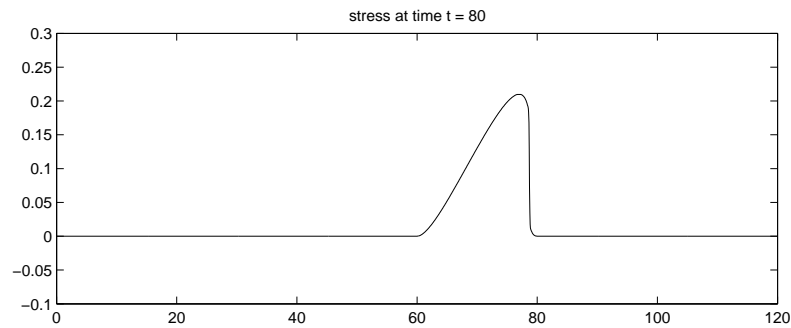
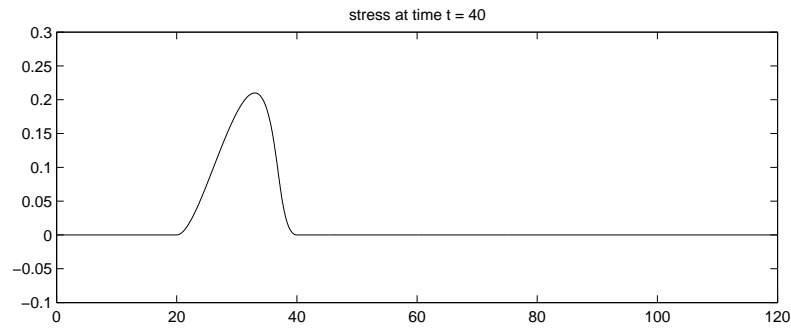
Layered medium can be related to Toda lattice

The wave speed increases with ϵ :

$$c(\epsilon, x) = \sqrt{\frac{\sigma_\epsilon(\epsilon, x)}{\rho(x)}} \approx \sqrt{\frac{K(x)(1 + \epsilon)}{\rho(x)}}$$

Leads to shock formation in a homogeneous medium.

Nonlinear homogeneous medium

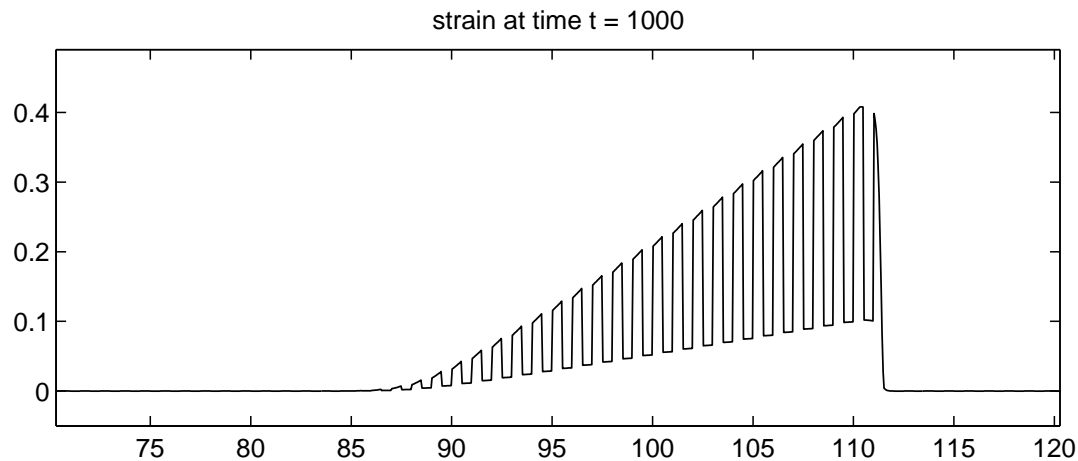


Nonlinear with constant linearized impedance

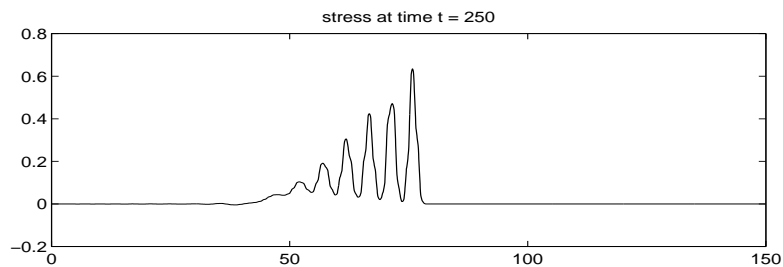
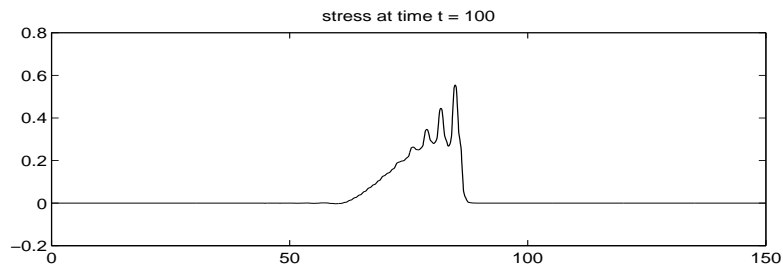
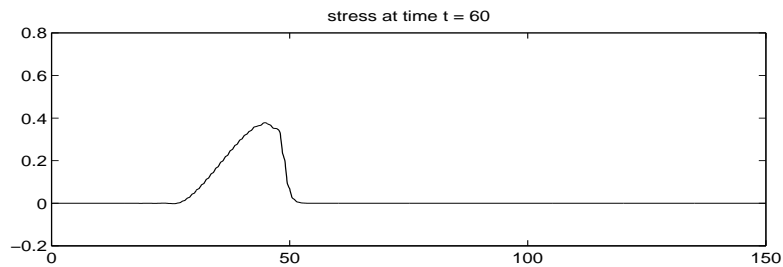
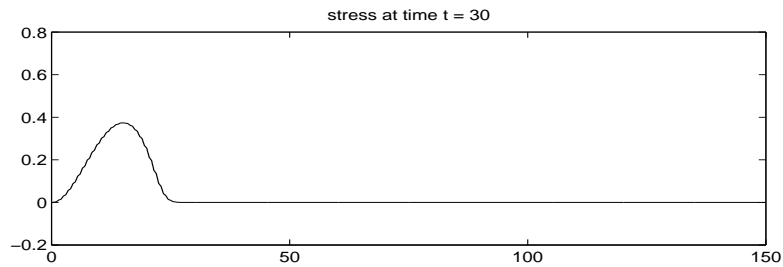
$$Z(x) = \rho(x)c(x) = \sqrt{\rho(x)K(x)(1 + \epsilon)}$$

$$\rightarrow \sqrt{\rho(x)K(x)} \text{ as } \epsilon \rightarrow 0$$

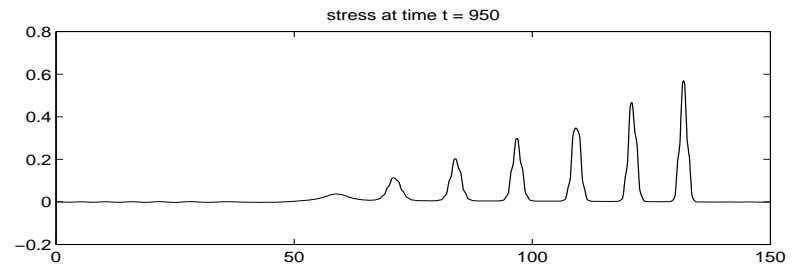
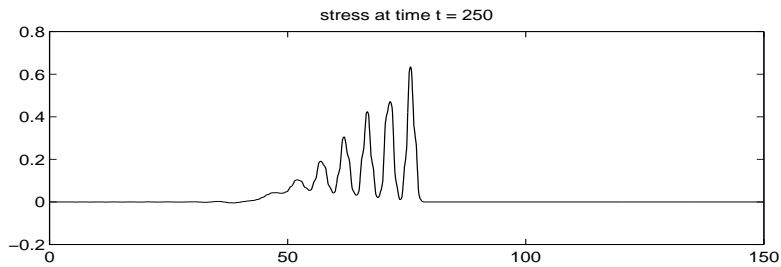
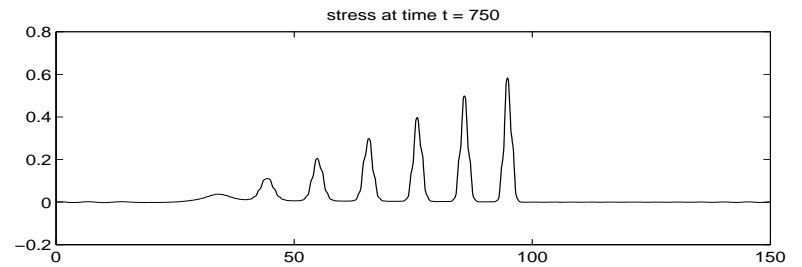
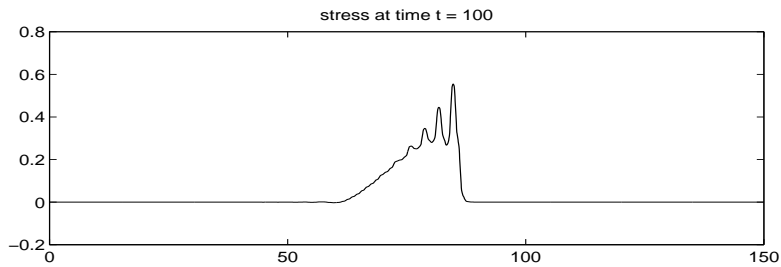
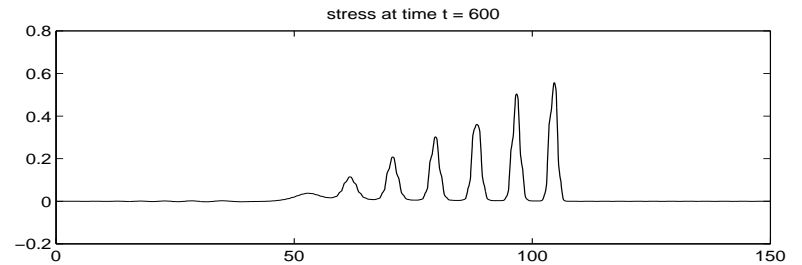
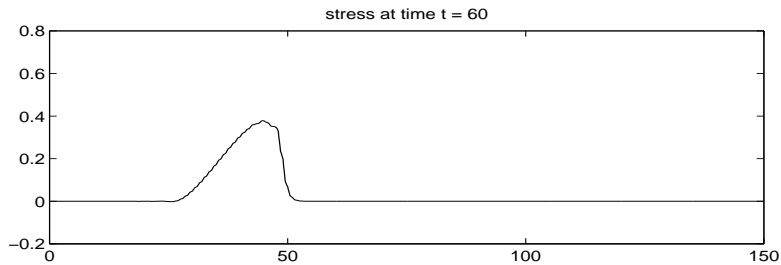
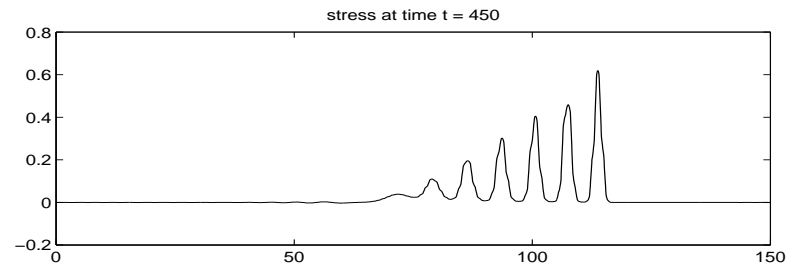
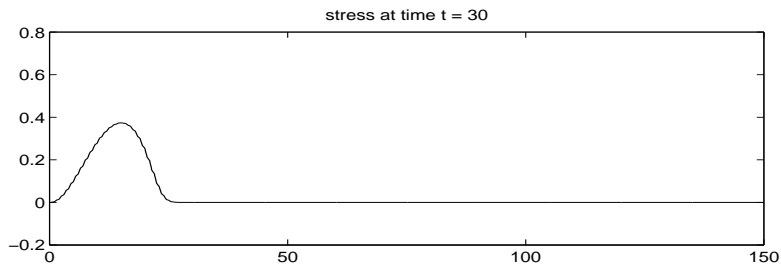
Layered medium with $\rho(x)K(x) \equiv \text{constant}$:



Layered nonlinear medium with $Z_A \neq Z_B$

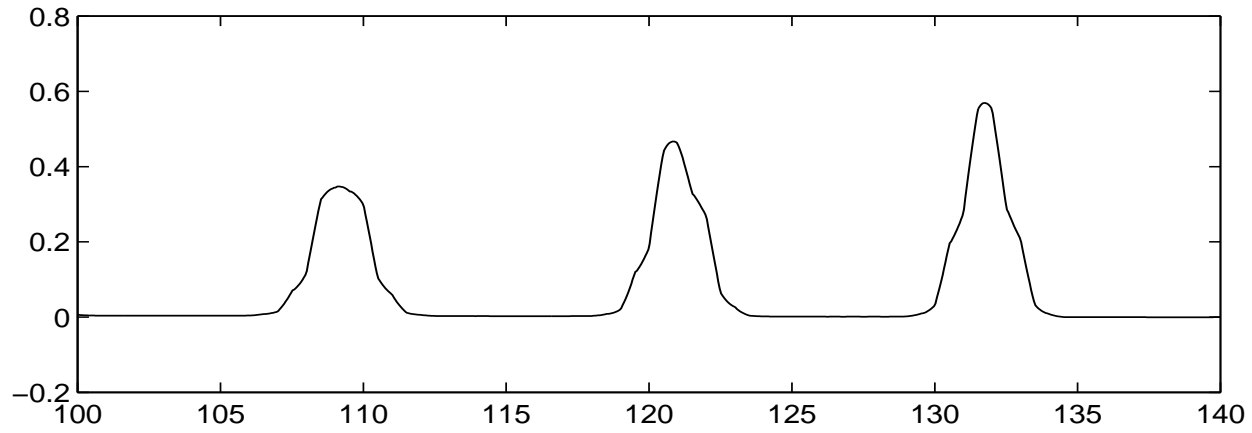


Layered nonlinear medium with $Z_A \neq Z_B$

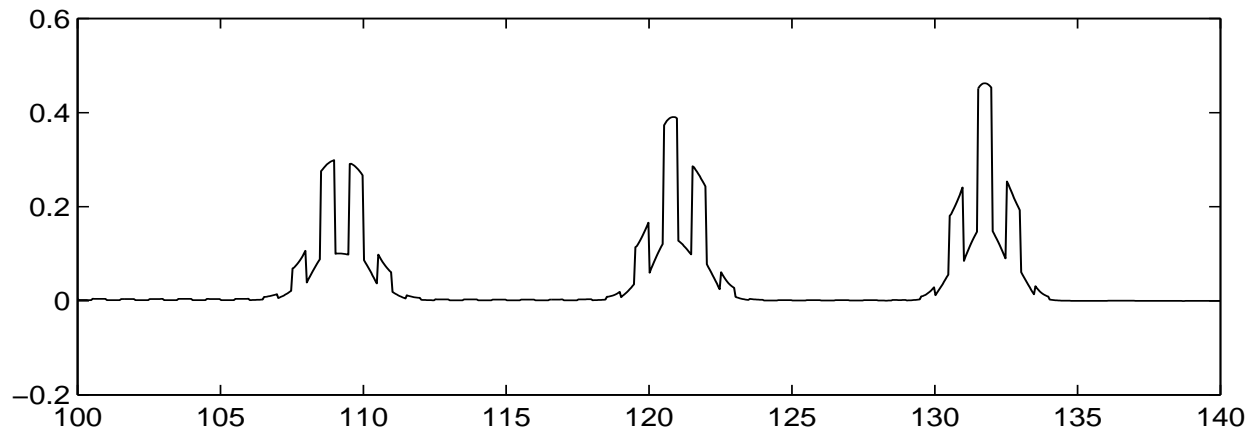


Zoomed view of 3 “stegotons”

Stress

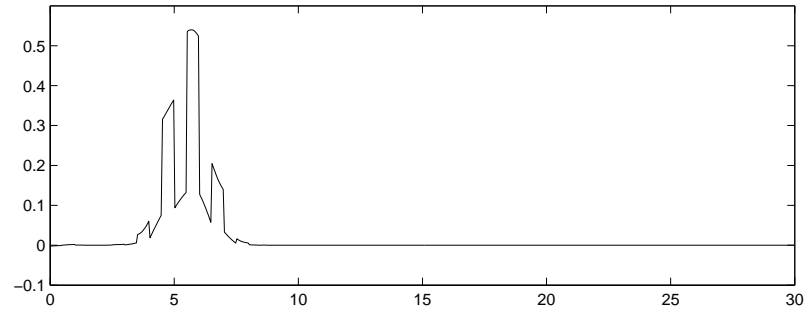


Strain

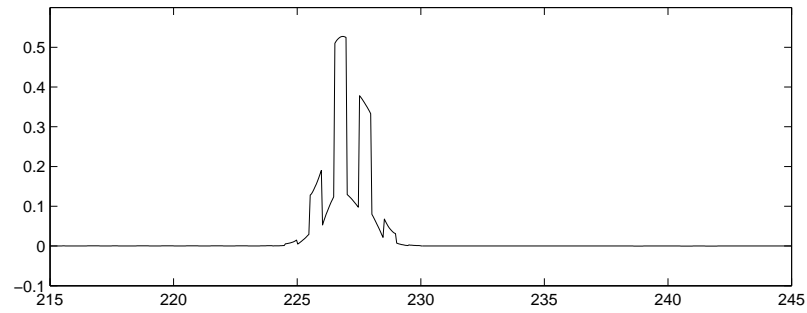


Propagation of a stegeton

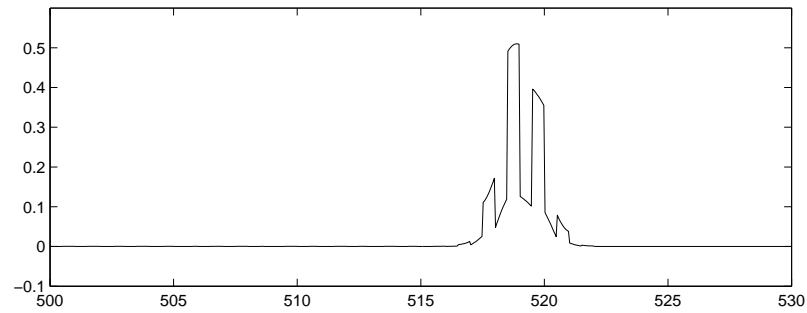
$t = 20$



$t = 270$

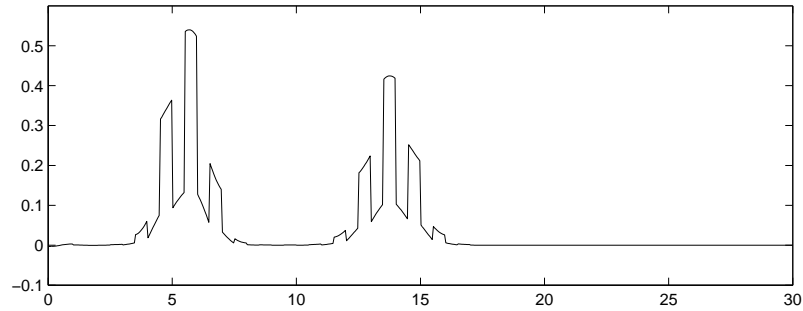


$t = 600$

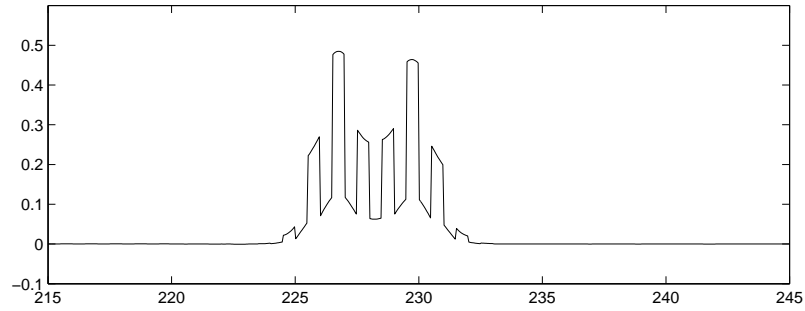


Collision of two stegotons

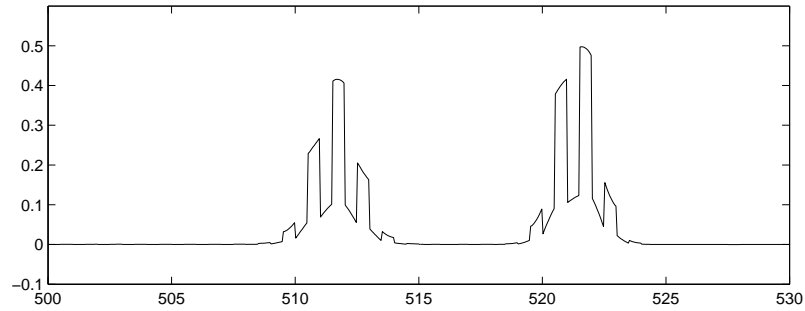
$t = 20$



$t = 270$



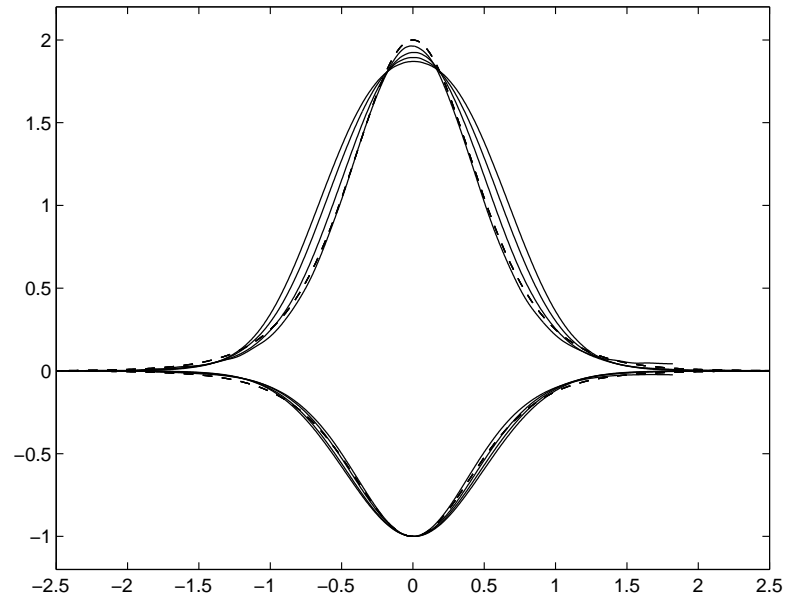
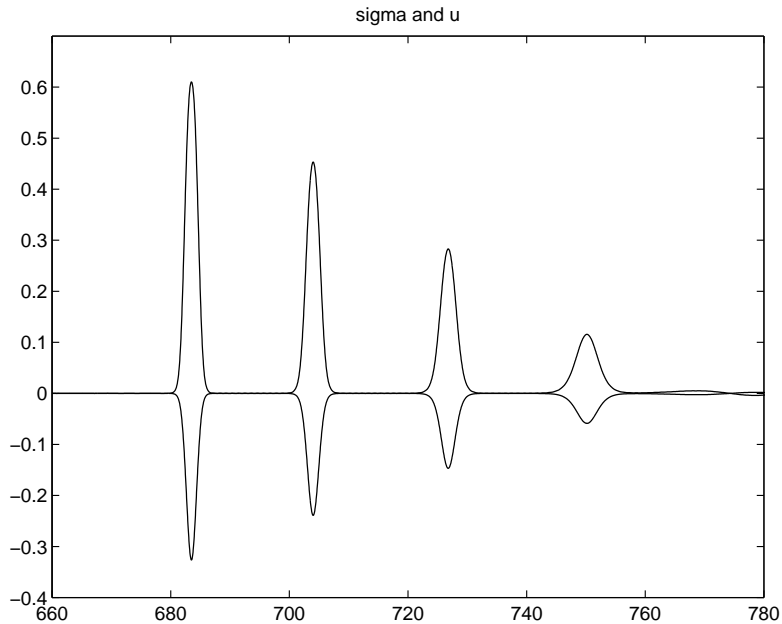
$t = 600$



Collision of two stegotons

Movie:

Solution at fixed point x_0



On the right we plot

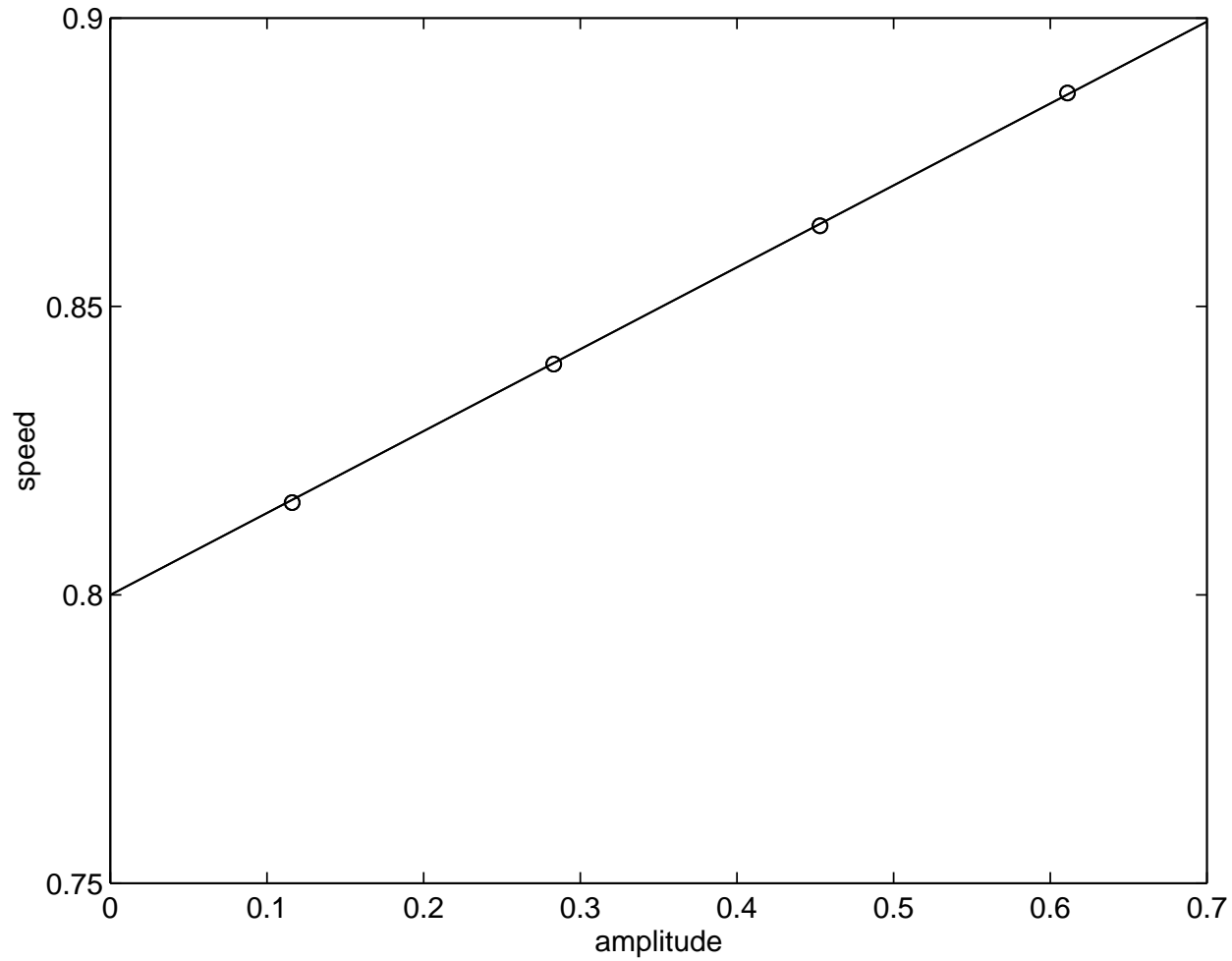
$$\frac{1}{a}\sigma(x_0, \tau) \quad \text{and} \quad \frac{1}{a}u(x_0, \tau)$$

as functions of

$$\tau = \sqrt{a}(t - t_m)$$

and t_m is the time the velocity reaches its peak value $-a$.

Plot of speed vs. amplitude

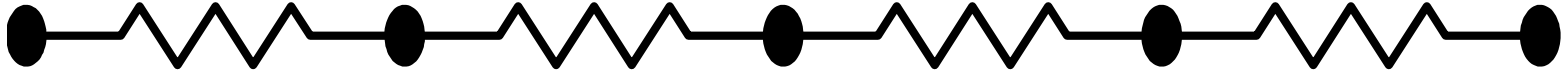


$$v = 0.8 + 0.142a.$$

Soliton behavior?

- Relation of layered medium to Toda lattice.
Discrete nonlinear mass-spring system with soliton solutions.
- Nonlinear homogenization theory.
Reduction to higher order nonlinear PDE with constant coefficients.

Lattice model for vibration of solids



Discrete particles coupled with springs:

$X_k(t)$ = location of k th particle, with mass m_k

$X_k(0) = k\Delta x$ undisturbed configuration ($\Delta x = 1$)

Strain of spring between particle k and $k + 1$:

$$\begin{aligned}\epsilon_{k+1/2}(t) &= \frac{X_{k+1}(t) - X_k(t)}{\Delta x} - 1 \\ &= 0 \text{ if unstretched}\end{aligned}$$

Restoring force (= stress): $\sigma(\epsilon_{k+1/2})$

or $\sigma_{k+1/2}(\epsilon_{k+1/2})$ if heterogeneous

Velocity: $U_k(t) = X'_k(t)$

Lattice model for vibration of solids

With $m_k = \Delta x \rho_k$, the equations of motion are

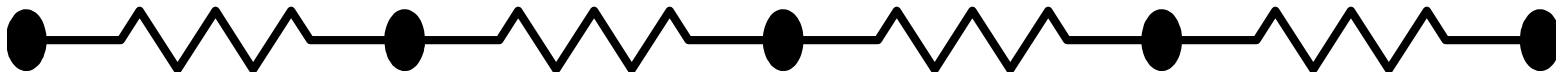
$$\epsilon'_{k+1/2}(t) = \frac{U_{k+1}(t) - U_k(t)}{\Delta x}$$

$$\rho_k U'_k(t) = \frac{\sigma(\epsilon_{k+1/2}(t)) - \sigma(\epsilon_{k-1/2}(t))}{\Delta x}$$

These can be viewed as a discretization of the continuum equations

$$\begin{aligned}\epsilon_t &= u_x \\ \rho u_t &= \sigma_x\end{aligned}$$

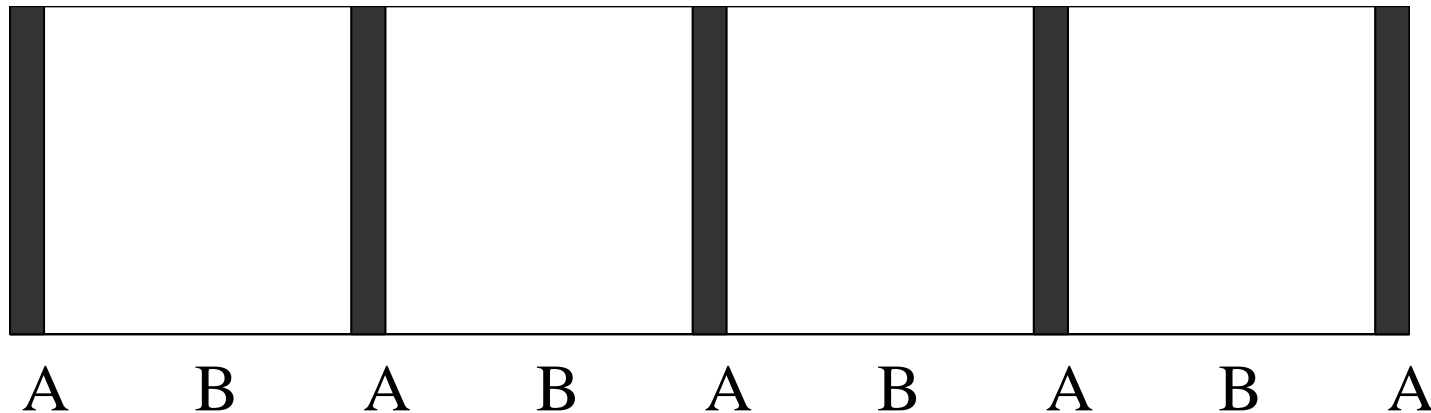
Linear springs: Hooke's law, $\sigma(\epsilon) = K\epsilon$.



Toda Lattice



Layered Medium



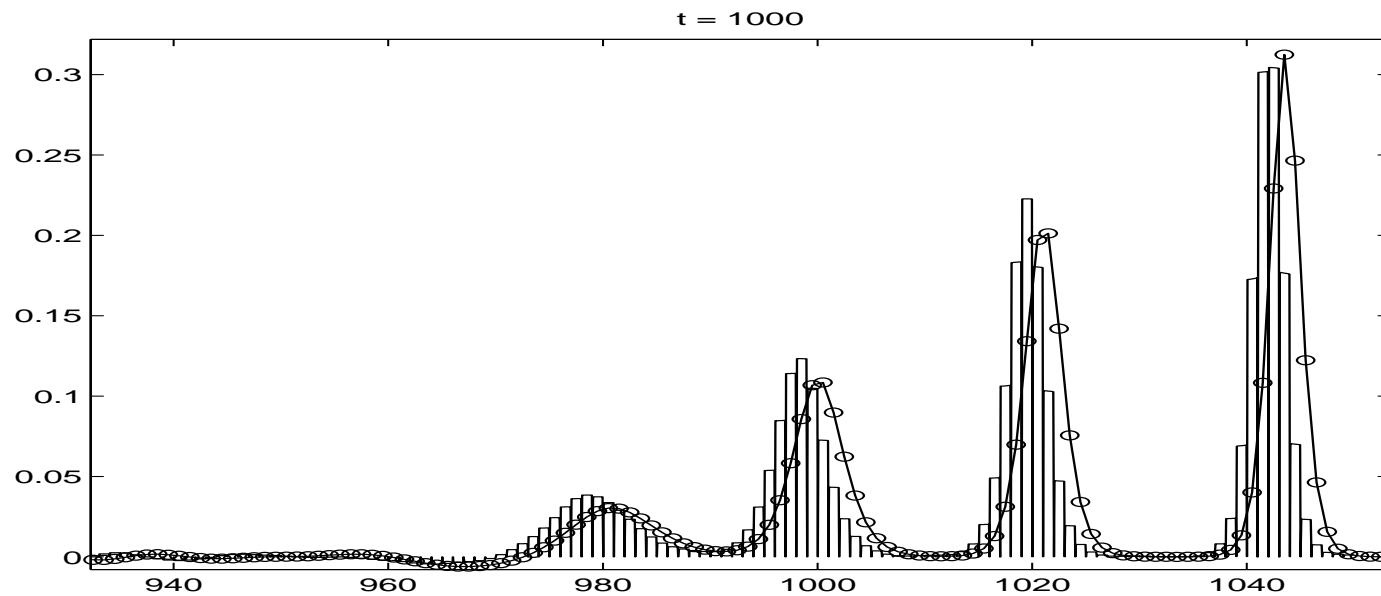
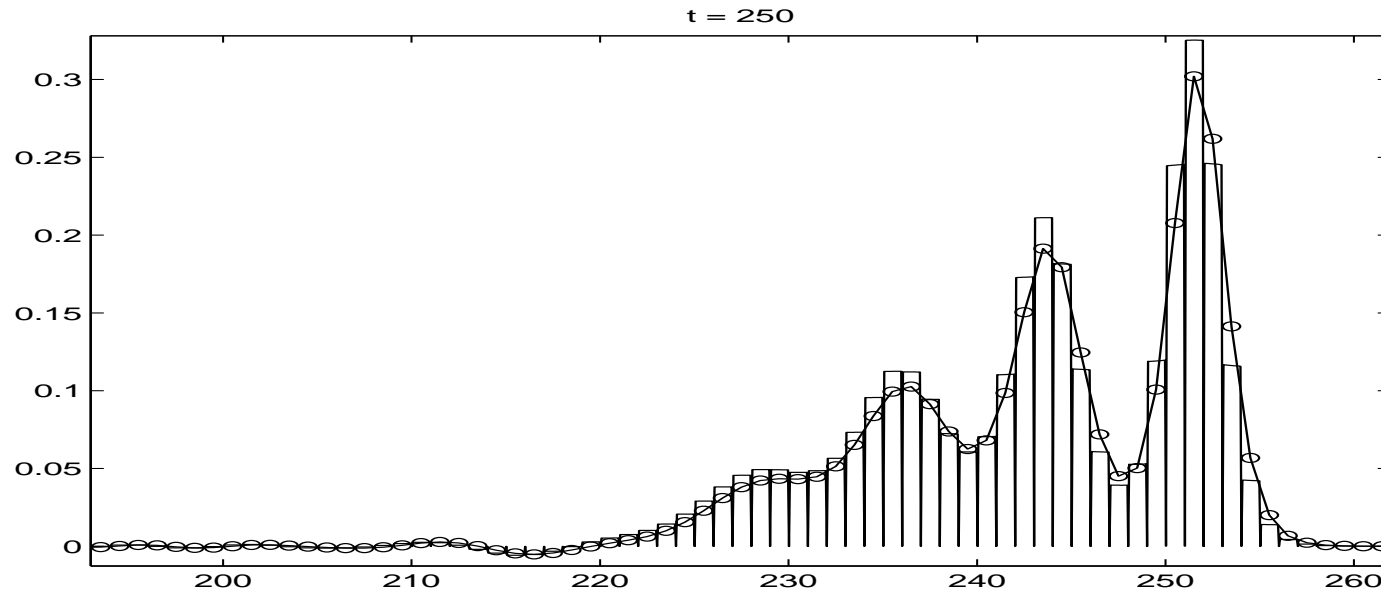
“particle layers:” $\rho_A = O(1/w_A)$, $K_A \gg 1$

“spring layers:” $\rho_B \ll 1$, $K_B = O(1)$,

$$\sigma_B(\epsilon) = \exp(K_B \epsilon) - 1$$

Take $c_A, c_B \gg \bar{c}$ so that states equilibrate quickly within layers.

Comparison of layered medium with Toda lattice



Homogenization theory

for long wavelengths (relative to layer width)

$$\epsilon_t - u_x = 0$$

$$\rho(x)u_t - \sigma_x = 0$$

Rewrite as equations for σ and u since these are continuous.

$$\sigma_t = K(x)\epsilon_t$$

Obtain

$$\frac{1}{K(x)}\sigma_t - u_x = 0$$

$$\rho(x)u_t - \sigma_x = 0$$

Homogenization theory

Average over distance long relative to variation in K, ρ ,
but short relative to variation in u, σ :

$$\left\langle \frac{1}{K(x)} \right\rangle \sigma_t - u_x = 0 + \mathcal{O}(\delta^2)$$

$$\langle \rho(x) \rangle u_t - \sigma_x = 0 + \mathcal{O}(\delta^2)$$

or

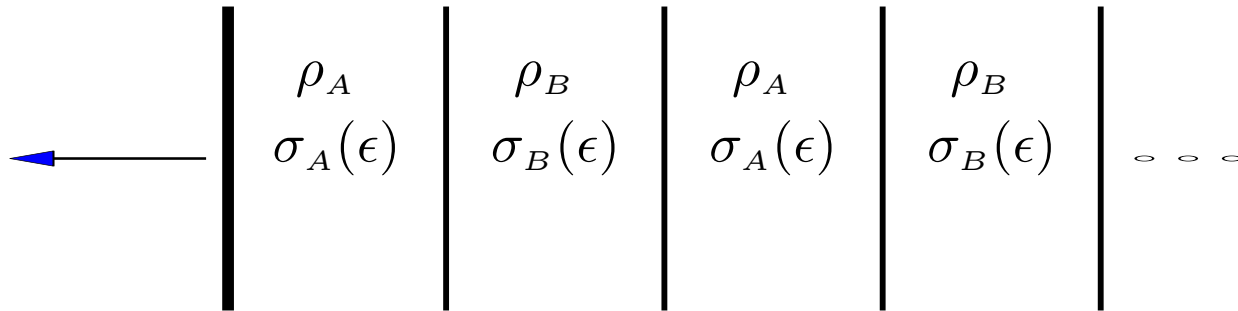
$$\sigma_t - \hat{K} u_x = 0 + \mathcal{O}(\delta^2)$$

$$\bar{\rho} u_t - \sigma_x = 0 + \mathcal{O}(\delta^2)$$

where $\bar{\rho} = \langle \rho \rangle$, $\hat{K} = \langle K^{-1} \rangle^{-1}$ = harmonic average of K .

Wave speeds $\pm \bar{c} = \pm \sqrt{\hat{K} / \bar{\rho}}$.

Linear periodic layered medium



$$\sigma_A = K_A \epsilon, \quad \sigma_B = K_B \epsilon.$$

$$\text{Averaged parameters: } \bar{\rho} = \langle \rho \rangle = w_A \rho_A + w_B \rho_B$$

$$\hat{K} = \left\langle \frac{1}{K} \right\rangle^{-1} = \left(\frac{w_A}{K_A} + \frac{w_B}{K_B} \right)^{-1}$$

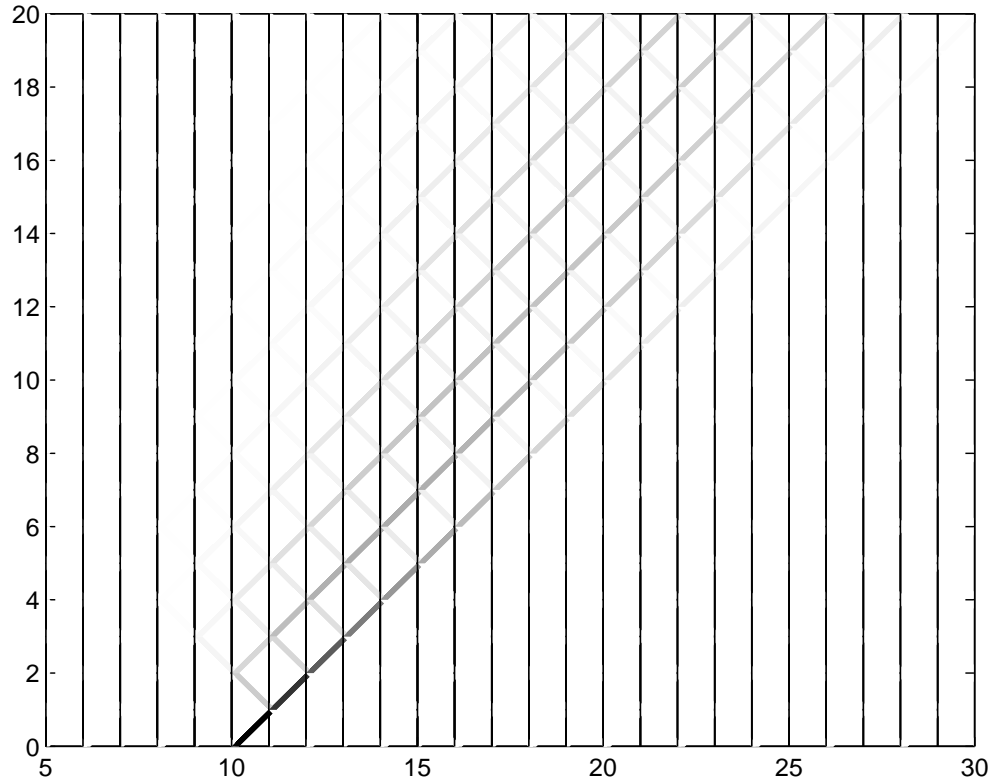
$$\text{Effective wave speed: } \bar{c} = \sqrt{\hat{K} / \bar{\rho}}.$$

Ex: (Santosa & Symes SIAP 51 (1991) p. 984)

$$\rho_A = K_A = 4, \quad \rho_B = K_B = 1, \quad w_A = w_B = 1/2.$$

Then $c \equiv 1$ everywhere but $\bar{c} = 0.8$.

Linear periodic layered medium



Also dispersive, with dispersion relation

$$\omega(\xi) = \bar{c}\xi + d\xi^3 + \dots$$

Ref: Santosa & Symes SIAP 51 (1991) p. 984

Nonlinear homogenization theory

Work of Darryl Yong, based on his thesis with J. Kevorkian.

For the nonlinear stress strain relation

$$\sigma(\epsilon, x) = K(x)\epsilon + \beta K^2(x)\epsilon^2$$

and layers of equal width $\delta/2$, small relative to the wavelength.

$$\bar{\rho}u_t - \sigma_x = \delta^2 \left(\frac{(\rho_A - \rho_B)(Z_A^2 - Z_B^2)}{24(K_A + K_B)(\rho_A + \rho_B)^2} \right) \sigma_{xxx} + O(\delta^3)$$

$$\begin{aligned} \sigma_t - \hat{K}u_x &= 2\hat{K}(\beta\sigma - \beta^2\sigma^2)u_x \\ &+ \delta^2 \left(\frac{\hat{K}(K_A - K_B)(Z_A^2 - Z_B^2)}{24(K_A + K_B)^2(\rho_A + \rho_B)} \right) u_{xxx} + O(\delta^3). \end{aligned}$$

$Z = \sqrt{K\rho} = \text{impedance}$

- $\beta = 0 \implies$ linear result of Santosa-Symes,
- $Z_A = Z_B \implies$ dispersive terms vanish.

Homogenized equations for exponential stress-strain

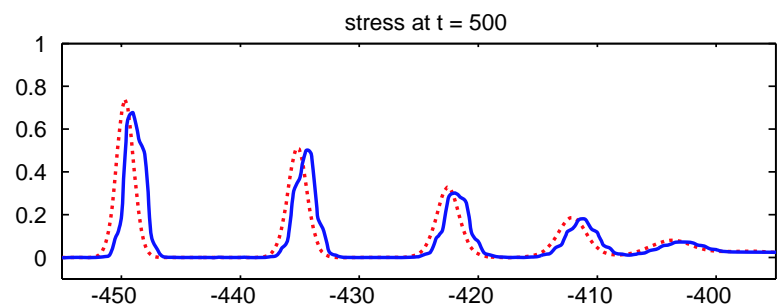
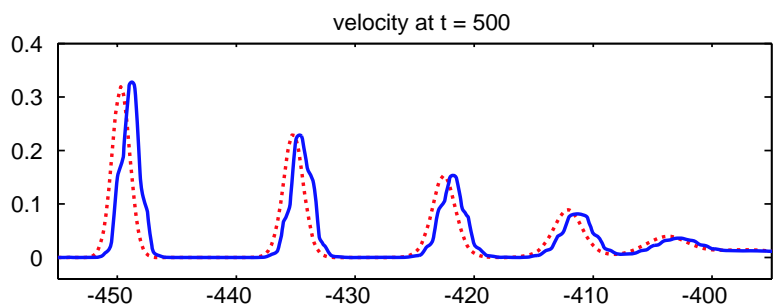
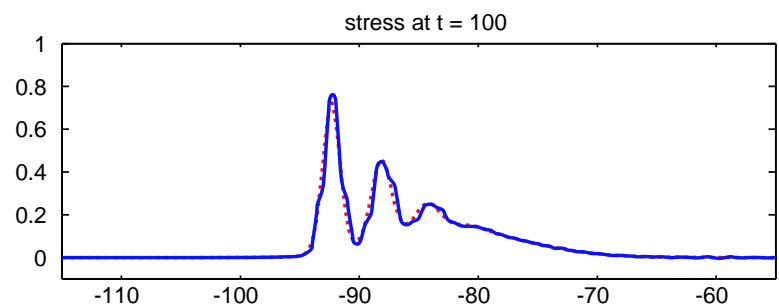
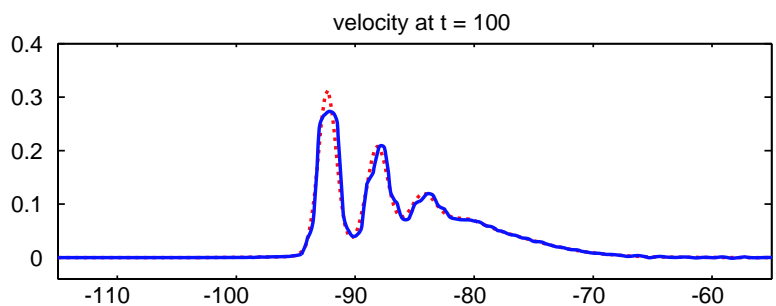
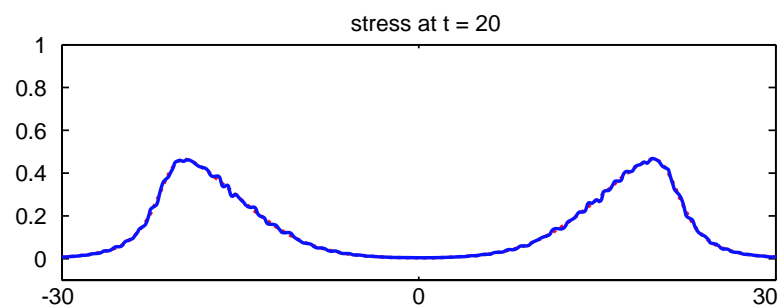
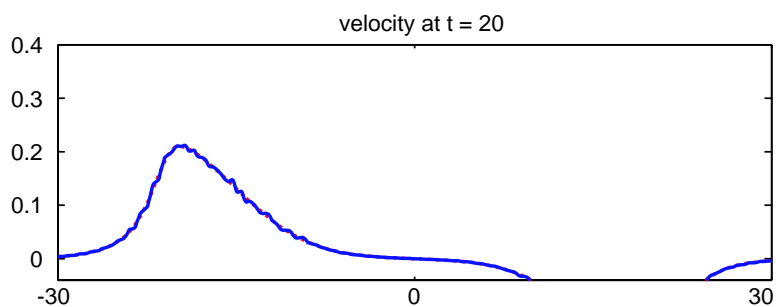
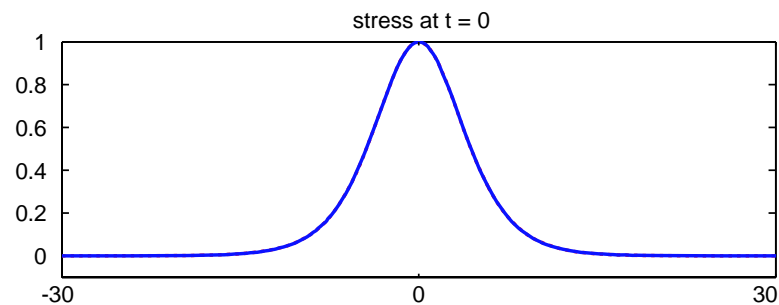
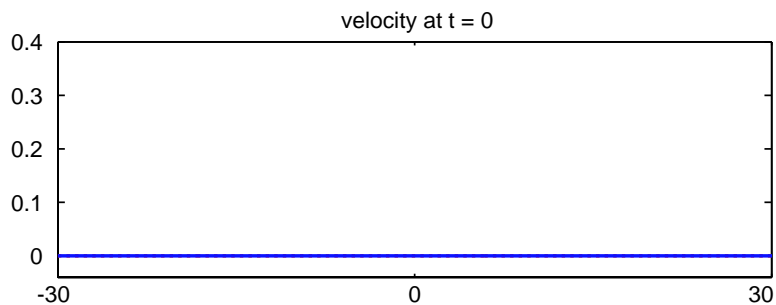
$$\sigma(\epsilon, x) = e^{\epsilon K(x)} - 1$$

$$\rho_A = K_A = 4, \quad \rho_B = K_B = 1, \quad w_A = w_B = 1/2.$$

$$u_t = \frac{2\sigma_x}{5} + \frac{3\delta^2\sigma_{xxx}}{500} + \delta^4 \left(\frac{3\sigma_{xxx}\sigma_x^2}{15625(\sigma+1)^2} - \frac{72u_{xx}^2\sigma_x}{15625(\sigma+1)} - \frac{12\sigma_{xxxx}\sigma_x}{15625(\sigma+1)} \right. \\ \left. - \frac{96u_{xx}u_{xxx}}{15625} - \frac{12\sigma_{xx}\sigma_{xxx}}{15625(\sigma+1)} - \frac{357\sigma_{xxxxx}}{1000000} \right) + \mathcal{O}(\delta^6)$$

$$\sigma_t = \frac{8(\sigma+1)u_x}{5} + \delta^2 \left(\frac{3(\sigma+1)u_{xxx}}{125} + \frac{3u_{xx}\sigma_x}{50} \right) \\ + \delta^4 \left(\frac{48u_x u_{xx}^2}{15625} - \frac{48\sigma_x\sigma_{xx}u_{xx}}{15625(\sigma+1)} - \frac{4761\sigma_{xxx}u_{xx}}{500000} - \frac{72u_{xxx}\sigma_x^2}{15625(\sigma+1)} \right. \\ \left. - \frac{357(\sigma+1)u_{xxxxx}}{250000} - \frac{3543u_{xxxx}\sigma_x}{500000} - \frac{3891u_{xxx}\sigma_{xx}}{500000} \right) + \mathcal{O}(\delta^6).$$

Comparison of homogenized solution to DNS



Summary

- Elastic wave equations in one dimension
- Hyperbolic in homogeneous medium
- Layered medium with impedance mismatch leads to dispersion
- Dispersion plus nonlinearity leads to solitary waves
- Relation to discrete solitons in Toda lattice
- Homogenized equations can be derived

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Many open questions, e.g.,

- Are there exact “solitons” for the layered media equations for particular choice of $\sigma(\epsilon, x)$?
- Behavior with other layer parameters, smooth periodic, random media, ...
- Multidimensional