

Today:

- Heat equation and discretization
- Iterative methods

Friday:

- Iterative methods

Read: Class notes and references

`$CLASSHG/codes/openmp/jacobi1.f90`

`$CLASSHG/codes/openmp/jacobi2_omp.f90`

`$CLASSHG/codes/mpi/jacobi2_mpi.f90`

Heat Equation / Diffusion Equation

Partial differential equation for $u(x, t)$ in one space dimension and time.

u represents temperature in a 1-dimensional metal rod, for example.

Or concentration (density) of a chemical diffusing in a tube of water.

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Or concentration (density) of a chemical diffusing in a tube of water.

The PDE is

$$u_t(x, t) = Du_{xx}(x, t) + f(x, t)$$

where subscripts represent partial derivatives,

D = diffusion coefficient,

$f(x, t)$ = source term.

Steady state diffusion

If $f(x, t) = f(x)$ does not depend on time and if the boundary conditions don't depend on time, then $u(x, t)$ will converge towards steady state distribution satisfying

$$0 = Du_{xx}(x) + f(x)$$

(by setting $u_t = 0$.)

This is now an **ordinary differential equation (ODE)** for $u(x)$.

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This is now an **ordinary differential equation (ODE)** for $u(x)$.

We can solve this on an interval, say $0 \leq x \leq 1$ with

Boundary conditions:

$$u(0) = \alpha, \quad u(1) = \beta.$$

Steady state diffusion

More generally: Take $D = 1$ or absorb in f ,

$$u_{xx}(x) = -f(x) \quad \text{for } 0 \leq x \leq 1,$$

Boundary conditions:

$$u(0) = \alpha, \quad u(1) = \beta.$$

Can be solved exactly if we can integrate f twice and use boundary conditions to choose the two constants of integration.

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Example: $f(x) = 0$, $\alpha = 20$, $\beta = 60$:

Solution: $u(x) = \alpha + x(\beta - \alpha)$.

No heat source \implies **linear variation** in steady state ($u_{xx} = 0$).

Steady state diffusion

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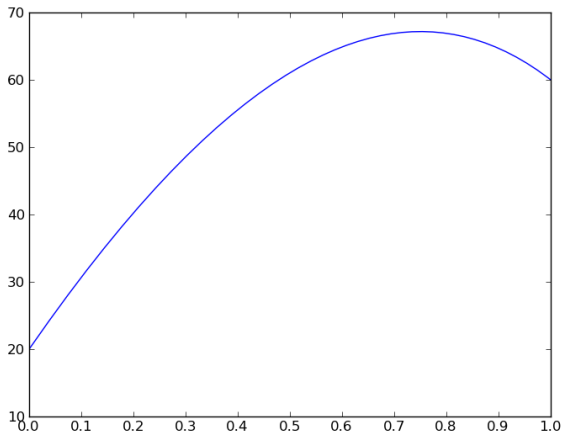
Can be solved exactly if we can integrate f twice and use boundary conditions to choose the two constants of integration.

More interesting example:

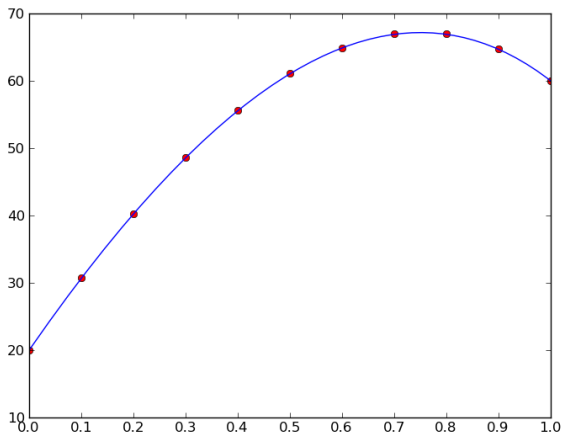
Example: $f(x) = 100e^x$, $\alpha = 20$, $\beta = 60$:

Solution: $u(x) = -100e^x + (100e - 60)x + 120$.

Steady state diffusion



Steady state diffusion



For more complicated equations, **numerical methods** must generally be used, giving approximations at discrete points.

Finite difference method

Define grid points $x_i = i\Delta x$ in interval $0 \leq x \leq 1$, where

$$\Delta x = \frac{1}{n+1}$$

So $x_0 = 0$, $x_{n+1} = 1$, and the n grid points x_1, x_2, \dots, x_n are equally spaced inside the interval.

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Let $U_i \approx u(x_i)$ denote approximate solution.

We know $U_0 = \alpha$ and $U_{n+1} = \beta$ from boundary conditions.

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Idea: Replace differential equation for $u(x)$ by system of n algebraic equations for U_i values ($i = 1, 2, \dots, n$).

Finite difference method

$$U_i \approx u(x_i)$$

$$u_x(x_{i+1/2}) \approx \frac{U_{i+1} - U_i}{\Delta x}$$

$$u_x(x_{i-1/2}) \approx \frac{U_i - U_{i-1}}{\Delta x}$$

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So we can approximate second derivative at x_i by:

$$\begin{aligned} u_{xx}(x_i) &\approx \frac{1}{\Delta x} \left(\frac{U_{i+1} - U_i}{\Delta x} - \frac{U_i - U_{i-1}}{\Delta x} \right) \\ &= \frac{1}{\Delta x^2} (U_{i-1} - 2U_i + U_{i+1}) \end{aligned}$$

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This gives coupled system of n linear equations:

$$\frac{1}{\Delta x^2} (U_{i-1} - 2U_i + U_{i+1}) = -f(x_i)$$

for $i = 1, 2, \dots, n$. With $U_0 = \alpha$ and $U_{m+1} = \beta$.

Tridiagonal linear system

For $n = 5$:

$$\begin{bmatrix} -2 & 1 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 1 & -2 \end{bmatrix} \begin{bmatrix} U_1 \\ U_2 \\ U_3 \\ U_4 \\ U_5 \end{bmatrix} = -\Delta x^2 \begin{bmatrix} f(x_1) \\ f(x_2) \\ f(x_3) \\ f(x_4) \\ f(x_5) \end{bmatrix} - \begin{bmatrix} \alpha \\ 0 \\ 0 \\ 0 \\ \beta \end{bmatrix} .$$

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General $n \times n$ system requires $O(n^3)$ flops to solve.

Tridiagonal $n \times n$ system requires $O(n)$ flops to solve.

Could use LAPACK routine `dgt sv`.

Heat equation in 2 dimensions

One-dimensional equation generalizes to

$$u_t(x, y, t) = D(u_{xx}(x, y, t) + u_{yy}(x, y, t)) + f(x, y, t)$$

on some domain in the x - y plane, with initial and boundary conditions.

We will only consider rectangle $0 \leq x \leq 1$, $0 \leq y \leq 1$.

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Steady state problem (with $D = 1$):

$$u_{xx}(x, y) + u_{yy}(x, y) = -f(x, y)$$

Finite difference equations in 2D

Let $U_{ij} \approx u(x_i, y_j)$.

Replace differential equation

$$u_{xx}(x, y) + u_{yy}(x, y) = -f(x, y)$$

by algebraic equations

$$\begin{aligned} & \frac{1}{\Delta x^2} (U_{i-1,j} - 2U_{i,j} + U_{i+1,j}) \\ & + \frac{1}{\Delta y^2} (U_{i,j-1} - 2U_{i,j} + U_{i,j+1}) = -f(x_i, y_j) \end{aligned}$$

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If $\Delta x = \Delta y = h$:

$$\frac{1}{h^2} (U_{i-1,j} + U_{i+1,j} + U_{i,j-1} + U_{i,j+1} - 4U_{i,j}) = -f(x_i, y_j).$$

Finite difference equations in 2D

$$\frac{1}{h^2} (U_{i-1,j} + U_{i+1,j} + U_{i,j-1} + U_{i,j+1} - 4U_{i,j}) = -f(x_i, y_j).$$

On $n \times n$ grid ($\Delta x = \Delta y = 1/(n + 1)$) this gives a linear system of n^2 equations in n^2 unknowns.

The above equation must be satisfied for $i = 1, 2, \dots, n$ and $j = 1, 2, \dots, n$.

Matrix is $n^2 \times n^2$,

e.g. on 100 by 100 grid, matrix is $10,000 \times 10,000$.

Contains $(10,000)^2 = 100,000,000$ elements.

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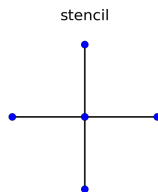
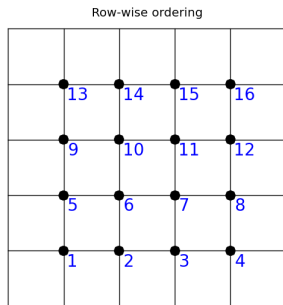
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e.g. on 100 by 100 grid, matrix is $10,000 \times 10,000$.

Contains $(10,000)^2 = 100,000,000$ elements.

Matrix is **sparse**: each row has at most 5 nonzeros out of n^2 elements! But structure is no longer tridiagonal.

Finite difference equations in 2D



Matrix has block tridiagonal structure:

$$A = \frac{1}{h^2} \begin{bmatrix} T & I & & \\ I & T & I & \\ & I & T & I \\ & & I & T \end{bmatrix} \quad T = \begin{bmatrix} -4 & 1 & & \\ 1 & -4 & 1 & \\ & 1 & -4 & 1 \\ & & 1 & -4 \end{bmatrix}$$

Iterative methods

Back to one space dimension first...

Coupled system of n linear equations:

$$(U_{i-1} - 2U_i + U_{i+1}) = -\Delta x^2 f(x_i)$$

for $i = 1, 2, \dots, n$. With $U_0 = \alpha$ and $U_{m+1} = \beta$.

Iterative method starts with initial guess $U^{[0]}$ to solution and then improves $U^{[k]}$ to get $U^{[k+1]}$ for $k = 0, 1, \dots$

Note: Generally does not involve modifying matrix A .

Do not have to store matrix A at all, only know about stencil.

Jacobi iteration

$$(U_{i-1} - 2U_i + U_{i+1}) = -\Delta x^2 f(x_i)$$

Solve for U_i :

$$U_i = \frac{1}{2} (U_{i-1} + U_{i+1} + \Delta x^2 f(x_i)) .$$

Note: With no heat source, $f(x) = 0$,
the temperature at each point is average of neighbors.

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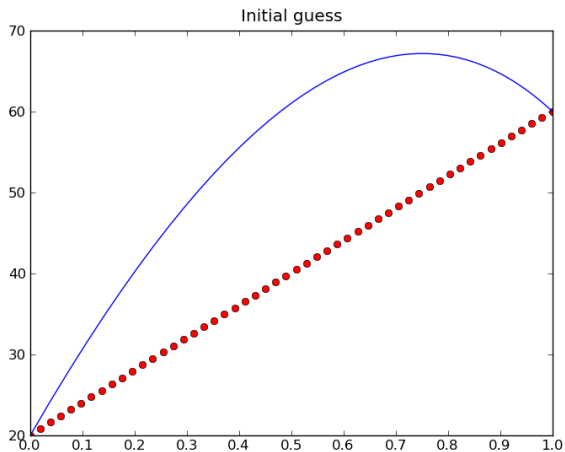
Suppose $U^{[k]}$ is a approximation to solution. Set

$$U_i^{[k+1]} = \frac{1}{2} \left(U_{i-1}^{[k]} + U_{i+1}^{[k]} + \Delta x^2 f(x_i) \right) \quad \text{for } i = 1, 2, \dots, n.$$

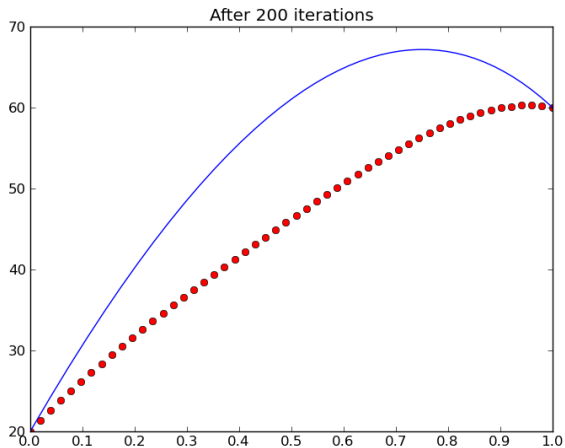
Repeat for $k = 0, 1, 2, \dots$ until convergence.

Can be shown to converge (eventually... **very slow!**)

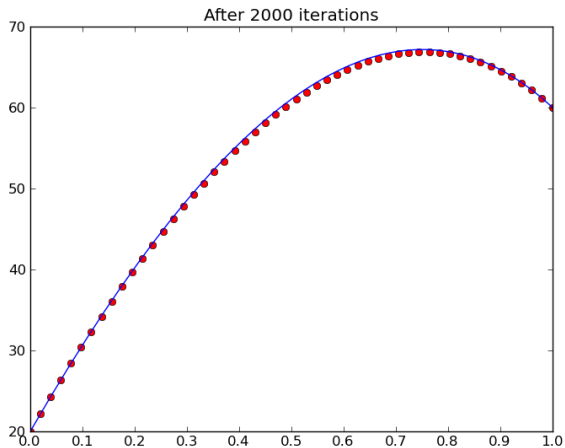
Slow convergence of Jacobi



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Slow convergence of Jacobi



Iterative methods

Jacobi iteration is about the worst possible iterative method.
But it's very simple, and useful as a test for parallelization.

Better iterative methods:

- Gauss-Seidel
- Successive Over-Relaxation (SOR)
- Conjugate gradients
- Preconditioned conjugate gradients
- Multigrid

Speedup for problems like steady state heat equation

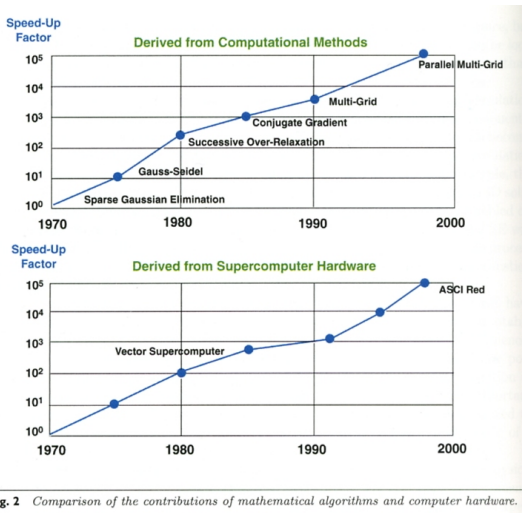


Fig. 2 Comparison of the contributions of mathematical algorithms and computer hardware.

Source: SIAM Review

Iterative methods – initialization

```
! allocate storage for boundary points too:  
allocate(x(0:n+1), u(0:n+1), f(0:n+1))
```

```
dx = 1.d0 / (n+1.d0)
```

```
!$omp parallel do  
do i=0,n+1  
    ! grid points:  
    x(i) = i*dx  
    ! source term:  
    f(i) = 100.*exp(x(i))  
    ! initial guess (linear function):  
    u(i) = alpha + x(i)*(beta-alpha)  
enddo
```

Jacobi iteration in Fortran

```
uold = u  ! starting values before updating
do iter=1,maxiter
  dumax = 0.d0
  do i=1,n
    u(i) = 0.5d0*(uold(i-1) + uold(i+1) + dx**2*f(i))
    dumax = max(dumax, abs(u(i)-uold(i)))
  enddo

  ! check for convergence:
  if (dumax .lt. tol) exit

  uold = u  ! for next iteration
enddo
```

Note: we must use old value at $i - 1$ for Jacobi.

Otherwise we get the **Gauss-Seidel** method.

Jacobi with OpenMP `parallel do` (fine grain)

```
uold = u ! starting values before updating
do iter=1,maxiter
    dumax = 0.d0
    !$omp parallel do reduction(max : dumax)
    do i=1,n
        u(i) = 0.5d0*(uold(i-1) + uold(i+1) + dx**2*f(i))
        dumax = max(dumax, abs(u(i)-uold(i)))
    enddo
    ! check for convergence:
    if (dumax .lt. tol) exit
    !$omp parallel do
    do i=1,n
        uold(i) = u(i) ! for next iteration
    enddo
enddo
```

Note: Forking threads twice each iteration.

Jacobi with OpenMP – coarse grain

General Approach:

- Fork threads only once at start of program.
- Each thread is responsible for some portion of the arrays, from `i=istart` to `i=iend`.
- Each iteration, must copy `u` to `uold`, update `u`, check for convergence.
- Convergence check requires coordination between threads to get global `dumax`.
- Print out final result after leaving parallel block

See code in the repository or the notes:

[\\$CLASSHG/codes/openmp/jacobi2_omp.f90](#)

Jacobi with MPI

Each process is responsible for some portion of the arrays,
from $i=i_{\text{start}}$ to $i=i_{\text{end}}$.

No shared memory: each process only has part of array.

Updating formula:

$$u(i) = 0.5d0*(uold(i-1) + uold(i+1) + dx**2*f(i))$$

Need to exchange values at boundaries:

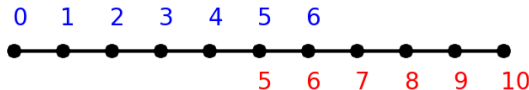
Updating at $i=i_{\text{start}}$ requires $uold(i_{\text{start}}-1)$

Updating at $i=i_{\text{end}}$ requires $uold(i_{\text{start}}+1)$

Example with $n = 9$ interior points (plus boundaries):

Process 0 has $i_{\text{start}} = 1$, $i_{\text{end}} = 5$

Process 1 has $i_{\text{start}} = 6$, $i_{\text{end}} = 9$



Jacobi with MPI

Other issues:

- Convergence check requires coordination between processes to get global `dumax`.
Use `MPI_ALLREDUCE` so all process check same value.
- Part of final result must be printed by each process (into common file `heatsoln.txt`), in proper order.

See code in the repository or the notes:

`$CLASSHG/codes/mpi/jacobi2_mpi.f90`

Jacobi with MPI — Sending to neighbors

```
call mpi_comm_rank(MPI_COMM_WORLD, me, ierr)
...
do iter = 1, maxiter
  uold = u

  if (me > 0) then
    ! Send left endpoint value to "left"
    call mpi_isend(uold(istart), 1, MPI_DOUBLE_PRECISION,
                  me - 1, 1, MPI_COMM_WORLD, req1, ierr)
  end if

  if (me < ntasks-1) then
    ! Send right endpoint value to "right"
    call mpi_isend(uold(iend), 1, MPI_DOUBLE_PRECISION,
                  me + 1, 2, MPI_COMM_WORLD, req2, ierr)
  end if
end do
```

Note: Non-blocking `mpi_isend` is used,

Different tags (1 and 2) for left-going, right-going messages.

Jacobi with MPI — Receiving from neighbors

Note: `uold(istart)` from `me+1` goes into `uold(iend+1)`:
`uold(iend)` from `me-1` goes into `uold(istart-1)`:

```
do iter = 1, maxiter
  ! mpi_send's from previous slide
  if (me < ntasks-1) then
    ! Receive right endpoint value
    call mpi_recv(uold(iend+1), 1, MPI_DOUBLE_PRECISION,
                 me + 1, 1, MPI_COMM_WORLD, mpistatus, ierr)
  end if

  if (me > 0) then
    ! Receive left endpoint value
    call mpi_recv(uold(istart-1), 1, MPI_DOUBLE_PRECISION,
                 me - 1, 2, MPI_COMM_WORLD, mpistatus, ierr)
  end if

  ! Apply Jacobi iteration on my section of array
  do i = istart, iend
    u(i) = 0.5d0*(uold(i-1) + uold(i+1) + dx**2*f(i))
    dumax_task = max(dumax_task, abs(u(i) - uold(i)))
  end do
end do
```

Jacobi with MPI — Writing solution in order

Want to write table of values $x(i), u(i)$ in `heatsoln.txt`.

Need them to be in proper order, so Process 0 must write to this file first, then Process 1, etc.

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Approach:

Each process m_e waits for a message from m_e-1 indicating that it has finished writing its part. (Contents not important.)

Each process must open the file (without clobbering values already there), write to it, then close the file.

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Assumes all processes share a file system!

On cluster or supercomputer, need to either:
send all results to single process for writing, or
write distributed files that may need to be combined later
(some visualization tools handle distributed data!)