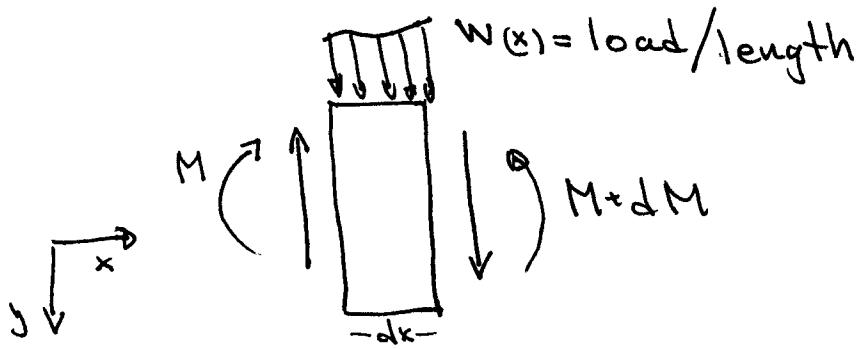


(1)

Lateral Vibrations of a Beam



$$\sum F_y = m \cdot \frac{\partial^2 y}{\partial t^2} \Rightarrow W \cdot dx + dV = \rho A dx \Rightarrow W = -\frac{\partial V}{\partial x} + \rho A \frac{\partial^2 y}{\partial t^2} \quad (1)$$

$$\sum M_{\text{ext}} = 0 \Rightarrow V \cdot \frac{dx}{2} + (V + dV) \frac{dx}{2} = -dM \Rightarrow V(x, t) = -\frac{\partial M}{\partial x} \quad (2)$$

$$(2) \rightarrow (1) \Rightarrow W(x, t) = \frac{\partial^2 M}{\partial x^2} + \rho A \frac{\partial^2 y}{\partial t^2} \quad (3)$$

Beam theory: plane sections remain plane

$$e_x = \frac{\partial u}{\partial x} = \frac{\partial}{\partial x} \left(\frac{\partial y}{\partial x} \cdot \hat{j} \right) = \frac{\partial^2 y}{\partial x^2} \cdot \hat{j}$$

$$\text{Moment} = M = \int_A T_x \cdot \hat{j} \cdot dA =$$

$$M = \int_A E \frac{\partial^2 y}{\partial x^2} \cdot \hat{j}^2 dA = E \frac{\partial^2 y}{\partial x^2} \int_A \hat{j}^2 dA = EI \frac{\partial^2 y}{\partial x^2} \quad (4)$$

$$(4) \rightarrow (3) \Rightarrow W(x, t) = \frac{\partial^2}{\partial x^2} \left[EI \frac{\partial^2 y}{\partial x^2} \right] + \rho A \frac{\partial^2 y}{\partial t^2}$$

Eqn of motion:

$$\boxed{\rho A \frac{\partial^2 y}{\partial t^2} + \frac{\partial^2}{\partial x^2} \left[EI \frac{\partial^2 y}{\partial x^2} \right] = W}$$

(2)

If EI is constant and $W=0$

$$\boxed{EI \frac{\partial^4 y}{\partial x^4} + PA \frac{\partial^2 y}{\partial t^2} = 0}$$

Solution: Use separability of variables

$$\text{Let } y(x,t) = \underline{X}(x) \underline{T}(t) \Rightarrow$$

$$\frac{\partial^4 \underline{X}}{\partial x^4} \cdot \underline{T}(t) + \frac{PA}{EI} \frac{\partial^2 \underline{T}}{\partial t^2} \underline{X}(x) = 0 \Rightarrow$$

$$\underbrace{-\frac{\underline{T}(t)}{\frac{\partial^2 \underline{T}}{\partial t^2}}}_{f(t)} = \underbrace{\frac{PA}{EI} \frac{\underline{X}(x)}{\frac{\partial^4 \underline{X}(x)}{\partial x^4}}}_{g(x)}$$

$$f(t) = g(x) \Rightarrow f(t) = g(x) = \text{constant}$$

call this constant $\frac{1}{\omega^2}$

$$\Rightarrow \begin{cases} \frac{\partial^2 T}{\partial t^2} + \omega^2 T(t) = 0 & \Rightarrow T(t) = E \sin \omega t + F \cos \omega t \\ 2 \left(\frac{\partial^4 X}{\partial x^4} - \beta^4 \underline{X}(x) \right) = 0 & \text{where } \beta^4 = \frac{PA + \omega^2}{EI} \end{cases}$$

$$\text{Let } \underline{X}(x) = e^{\lambda x} \quad \text{substituted into (2)} \Rightarrow \lambda = \pm \beta, \pm i\beta$$

$$\text{so } \underline{X}(x) = C_1 e^{\beta x} + C_2 e^{-\beta x} + C_3 e^{ix} + C_4 e^{-ix}$$

or

$$\underline{X}(x) = A \sinh \beta x + B \cosh \beta x + C \sinh \beta x + D \cosh \beta x$$

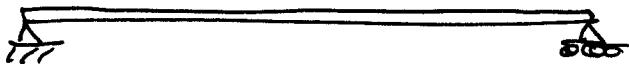
$$\text{where } \sinh \beta x = \frac{e^{\beta x} - e^{-\beta x}}{2}, \quad \cosh \beta x = \frac{e^{\beta x} + e^{-\beta x}}{2}$$

(3)

We have 6 unknowns

But we also have boundary conditions
and 2 initial conditions.

Ex



Pinned-Pinned beam

$$y(0,t) = 0$$

$$y(l,t) = 0$$

$$M(0,t) = \frac{\partial^2 y}{\partial x^2} \Big|_{x=0} = 0$$

$$M(l,t) = \frac{\partial^2 y}{\partial x^2} \Big|_{x=l} = 0$$

where

$$\frac{\partial^2 y}{\partial x^2} = T(t) \left[-A\beta^2 \sin \beta x - B\beta^2 \cos \beta x + C\beta^2 \sinh \beta x + D\beta^2 \cosh \beta x \right]$$

$$\text{at } x=0 \quad y(0,t) = 0 \Rightarrow B + D = 0$$

$$\frac{\partial^2 y}{\partial x^2} \Big|_{x=0} \Rightarrow -B + D = 0 \Rightarrow \boxed{B = D = 0}$$

$$\text{at } x=l \quad y(l,t) = 0 = A \sinh \beta l + C \sinh \beta l$$

$$\frac{\partial^2 y}{\partial x^2} \Big|_{x=l} = 0 = A \sinh \beta l + C \sinh \beta l$$

$$\Rightarrow \begin{cases} A \sinh \beta l = 0 \\ C \sinh \beta l = 0 \end{cases}$$

(4)

But $\sin \beta l > 0$ $\nabla \beta l > 0$

$$\Rightarrow \boxed{C = 0}$$

and $A \sin \beta l = 0 \Rightarrow$

$A=0 \rightarrow$ trivial solutions

or

$$\sin \beta l = 0 \Rightarrow \beta_n \cdot l = n \cdot \pi \Rightarrow \beta_n = \frac{n\pi}{l}$$

$$\rightarrow \boxed{\omega_n = \frac{n^2 \pi^2}{l^2} \sqrt{\frac{EI}{\rho A}}} \quad (\text{since } \beta^4 = \frac{\rho A \omega^2}{EI})$$

natural frequency of
the beam

and since $\ddot{x}(x) = A \sin p x + B \cos p x + C \sinh p x + D \cosh p x$

we get

$$\ddot{x}_n(x) = A_n \sin \beta_n x \quad \leftarrow \text{nth mode shape}$$

or

$$\boxed{\ddot{x}_n(x) = A_n \sin \frac{n\pi}{l} x}$$

and the displacement of the beam :

$$y = \sum_{s=c}^{\infty} \ddot{x}_s t_s = \sum_{s=c}^{\infty} \sin \frac{n\pi}{l} x \times (E \sin \omega_s t + F \cos \omega_s t)$$

E and F are determined the same way
as for the bar. I.e. given the initial shape
and velocity. $y(x, 0) = H(x)$ and $\dot{y}(x, 0) = G(x)$ multiply
each side by $\sin \beta_s x$ and integrate over the length.

Forced Oscillation of a Beam

Eqn of motion

$$EI \frac{d^4y}{dx^4} + \rho A \frac{d^2y}{dt^2} = W(x,t)$$

Let $y(x,t) = \sum_{n=1}^{\infty} T_n(t) \cdot X_n(x)$

↑ modes

Substitute into DEQ:

$$\sum_{n=1}^{\infty} [T_n(t) EI \frac{d^4X_n}{dx^4} + \rho A \ddot{T}_n(t) X_n] = W(x,t) \quad (1)$$

But from the unforced problem we know:

$$\frac{d^4X_n}{dx^4} - \beta_n^4 X_n = 0 \Rightarrow \frac{d^4X_n}{dx^4} = \beta_n^4 X_n$$

$$\Rightarrow \frac{d^4X_n}{dx^4} = \frac{\rho A}{EI} \omega_n^2 X_n$$

so equation (1) becomes

$$\sum_{n=1}^{\infty} \rho A X_n \left(\ddot{T}_n + \omega_n^2 T_n \right) = W(x,t)$$

Multiply by X_m and integrate over the length

$$\sum_{n=1}^{\infty} \left(\ddot{T}_n + \omega_n^2 T_n \right) \cdot \underbrace{\int_0^l \rho A X_n(x) \cdot X_m(x) dx}_{\begin{cases} = 0 & n \neq m \\ \neq 0 & n = m \end{cases}} = \int_0^l X_m(x) \cdot W(x,t) \cdot dx$$

(6)

$$\Rightarrow \frac{\infty}{T_m + \omega_m^2 T} = \frac{\int_0^L I_m(x) \cdot W(x, t) dx}{\int_0^L \rho A I_m^2(x) dx} = f_m(t), m=1, 2 \dots$$

 \Rightarrow

$$T_m = A_m \sin \omega_m t + B_m \cos \omega_m t + \frac{1}{\rho A \omega_m} \int_0^t f(\tau) \cdot \sin \omega_m (t-\tau) d\tau$$

The A's and B's are determined by the initial conditions.

so the matrix of the beam becomes:

$$y(x, t) = \sum_{n=1}^{\infty} \left\{ [A_n \sin \omega_n t + B_n \cos \omega_n t + \frac{1}{\rho A \omega_n} \int_0^t f(\tau) \cdot \sin \omega_n (t-\tau) d\tau] \Xi_n \right\}$$