

## Stability of systems:

The solution of  $\dot{\underline{x}} = A \underline{x}$  is given by

$$\underline{x} = e^{At} \underline{x}_0$$

For stability we want the solution to decay to zero (or at least not grow to  $\infty$ ) as  $t \rightarrow \infty$

Since

$$\underline{x} = e^{At} \underline{x}_0 = M \begin{bmatrix} e^{\lambda_1 t} & & 0 \\ & e^{\lambda_2 t} & \\ 0 & & \ddots & e^{\lambda_n t} \end{bmatrix} M^{-1} \underline{x}_0 \quad \text{it is clear}$$

that for stability we must require

$$\boxed{\operatorname{Re}(\lambda_i) \leq 0} \quad \text{for all } i.$$

# Response of $\dot{\underline{x}} = A\underline{x} + B\underline{u}$ to various input functions <sup>(2)</sup>

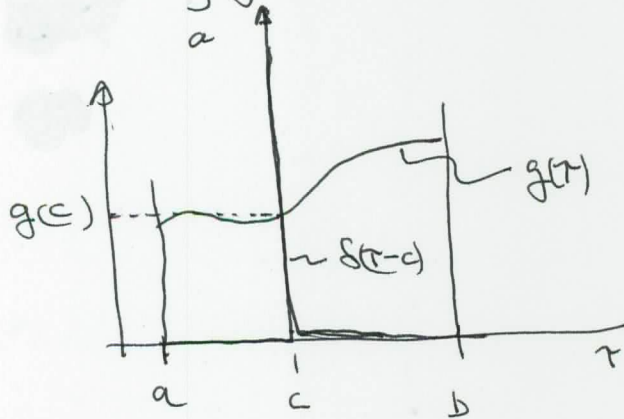
Impulse :

$$\underline{u}(t) = K \cdot \delta(t) = \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{pmatrix} \cdot \delta(t) \quad \text{delta function at } t=0.$$

$$\Rightarrow \underline{x}(t) = e^{At} \cdot x(0) + \int_0^t e^{A(t-\tau)} \cdot B \cdot K \cdot \delta(\tau) d\tau$$

But we know that

$$\int_a^b g(\tau) \cdot \delta(\tau - c) d\tau = g(c) \quad \text{where } a < c < b$$



so

$$\underline{x}(t) = e^{At} \cdot x(0) + e^{At} \cdot B \cdot K$$

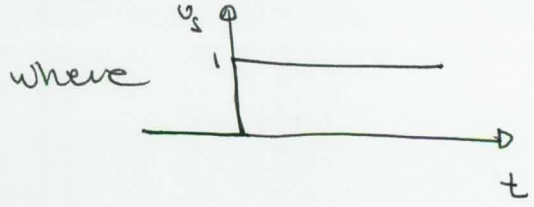
$$\boxed{\underline{x}(t) = e^{At} [x(0) + BK]} \quad \leftarrow \text{For impulse at } t=0$$

also for impulse at  $t=t_0$

$$\boxed{\underline{x}(t) = e^{At} [x(0) + e^{-t_0} \cdot B \cdot K]} \quad \text{for } t > t_0$$

Step:

$$U(t) = K \cdot u_s(t) = \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{pmatrix} \cdot u_s(t)$$



⇒

$$x = e^{At} \cdot \tilde{x}_0 + \int_0^t e^{A(t-\tau)} B \cdot K u_s(\tau) d\tau$$

but  $u_s = 1$  for  $t > 0 \Rightarrow$

$$x = e^{At} \cdot \tilde{x}_0 + \int_0^t e^{A(t-\tau)} \cdot B \cdot K d\tau$$

$$x = e^{At} \cdot \tilde{x}_0 + \int_0^t e^{A(t-\tau)} \cdot d\tau B \cdot K$$

$$x = e^{At} \cdot \tilde{x}_0 + A^{-1} e^{A(t-\tau)} \Big|_0^t B K = e^{At} x_0 + A^{-1} (I - e^{At}) \cdot B \cdot K$$

$x = e^{At} \cdot x_0 + A^{-1} (e^{At} - I) B K$  ← for step

Note:

$$\begin{aligned} \int e^{A\tau} d\tau &= \int M \begin{pmatrix} e^{\lambda_1 \tau} & 0 \\ \vdots & \vdots \\ 0 & e^{\lambda_n \tau} \end{pmatrix} M^{-1} d\tau = M \begin{pmatrix} \frac{1}{\lambda_1} e^{\lambda_1 \tau} & & & 0 \\ & \frac{1}{\lambda_2} e^{\lambda_2 \tau} & & 0 \\ & & \ddots & \\ 0 & & & \frac{1}{\lambda_n} e^{\lambda_n \tau} \end{pmatrix} M^{-1} \\ &= M \begin{pmatrix} \frac{1}{\lambda_1} & & & 0 \\ & \frac{1}{\lambda_2} & & 0 \\ & & \ddots & \\ 0 & & & \frac{1}{\lambda_n} \end{pmatrix} \begin{pmatrix} e^{\lambda_1 \tau} & & & 0 \\ & e^{\lambda_2 \tau} & & 0 \\ & & \ddots & \\ 0 & & & e^{\lambda_n \tau} \end{pmatrix} M^{-1} = M \begin{pmatrix} \frac{1}{\lambda_1} & & & 0 \\ & \frac{1}{\lambda_2} & & 0 \\ & & \ddots & \\ 0 & & & \frac{1}{\lambda_n} \end{pmatrix} M^{-1} M \begin{pmatrix} e^{\lambda_1 \tau} & 0 \\ \vdots & \vdots \\ 0 & e^{\lambda_n \tau} \end{pmatrix} M^{-1} \\ &= \left[ M \begin{pmatrix} \lambda_1 & & & 0 \\ \vdots & \vdots & & \\ 0 & & & \lambda_n \end{pmatrix} M^{-1} \right]^{-1} \cdot M \begin{pmatrix} e^{\lambda_1 \tau} & 0 \\ \vdots & \vdots \\ 0 & e^{\lambda_n \tau} \end{pmatrix} M^{-1} = A^{-1} \cdot e^{A\tau} \end{aligned}$$

# Ramp

$$v(t) = k \cdot t = \begin{pmatrix} k_1 \\ k_2 \\ \vdots \\ k_n \end{pmatrix} \cdot t$$

then

$$x = e^{At} \underline{x}_0 + A^{-1} [A^{-1}(e^{At} - I) - I t] B K$$

This comes from:

$$x = e^{At} \underline{x}_0 + \int_0^t e^{A(t-\tau)} \cdot B K \cdot d\tau$$

$$x = e^{At} \underline{x}_0 + \int_0^t \tau e^{A(t-\tau)} d\tau \cdot B \cdot K \quad \text{integrate by parts!}$$

$$x = e^{At} \underline{x}_0 + \left[ \tau (-A^{-1}) e^{A(t-\tau)} \Big|_0^t - \int_0^t e^{A(t-\tau)} d\tau \right] B \cdot K$$

$$x = e^{At} \underline{x}_0 + \left[ -t A^{-1} - 0 (-A^{-1}) e^{At} - \tau^{-1} e^{A(t-\tau)} \Big|_0^t \right] B K$$

$$x = e^{At} \underline{x}_0 + A^{-1} [-t \cdot I - A^{-1} A \cdot 0 + A^{-1} e^{At}] B \cdot K$$

$$x = e^{At} \underline{x}_0 + A^{-1} [A^{-1}(e^{At} - I) - I t] \cdot B \cdot K$$