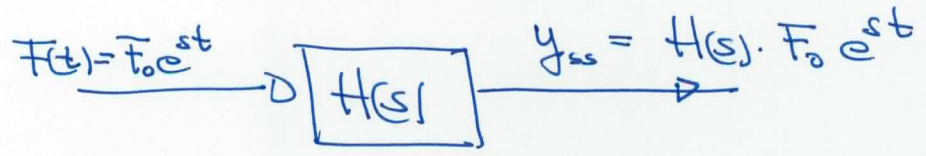


Frequency Response



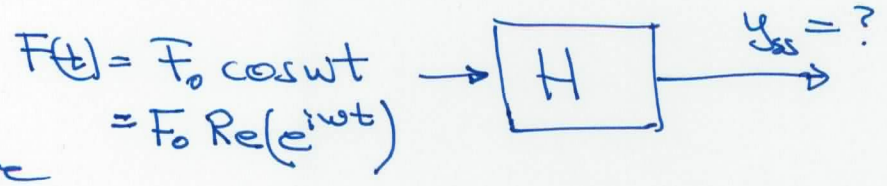
Since $\sin \omega t = \text{Im}(e^{i\omega t})$ and $\cos \omega t = \text{Re}(e^{i\omega t})$

we use $e^{i\omega t}$ as input when the actual input is $\sin \omega t$ and/or $\cos \omega t$.

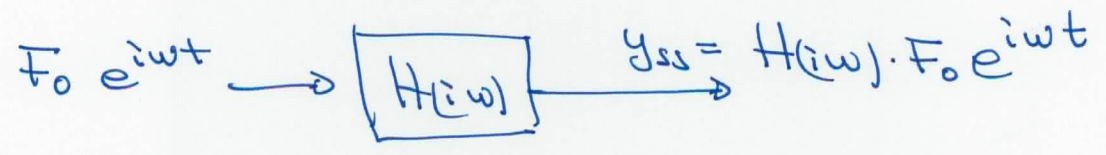
So for sine and cosine input:

$$s = i\omega$$

For



we use



Actual output : $y_{ss} = \text{Re}(H(i\omega) F_0 e^{i\omega t})$

(2)

$$y_{ss} = H(i\omega) \cdot F_0 e^{i\omega t}$$

$$= \frac{N(i\omega)}{D(i\omega)} \cdot F_0 e^{i\omega t} = \frac{|N(i\omega)| e^{i\phi_N}}{|D(i\omega)| e^{i\phi_D}} \cdot F_0 e^{i\omega t}$$

$$= \frac{|N(i\omega)|}{|D(i\omega)|} \cdot F_0 e^{i(\omega t + \phi)} \quad \text{where } \phi = \phi_N - \phi_D$$

$$= |H(i\omega)| \cdot F_0 e^{i(\omega t + \phi)}$$

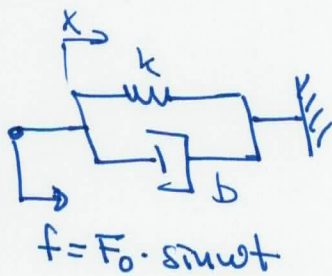
$$= |H(i\omega)| \cdot F_0 (\cos(\omega t + \phi) + i \sin(\omega t + \phi))$$

For $\cos(\omega t)$ input keep $\cos(\omega t + \phi)$ part.

For $\sin \omega t$ input keep $\sin(\omega t + \phi)$ part.

Ex First order system:

Determine the steady state displacement, x .



$$m \ddot{x} + kx = f \Rightarrow \tau \ddot{x} + x = \frac{f}{k} \quad \text{where } f = F_0 \cdot \sin \omega t$$

$$H(s) = \frac{X}{F_0} = \frac{1/k}{\tau s + 1} \quad \text{for sine input:}$$

$$H(i\omega) = \frac{1/k}{i\tau\omega + 1}$$

(3)

$$\begin{aligned}
 X_{ss}(t) &= \frac{1}{k} \frac{1}{i\tau\omega + 1} \cdot F_0 \cdot e^{i\omega t} \\
 &= \frac{1}{k} \frac{1}{\sqrt{(\tau\omega)^2 + 1}} \cdot e^{i\phi_0} \cdot F_0 e^{i\omega t} \\
 &= \frac{1}{k} \frac{1}{\sqrt{(\tau\omega)^2 + 1}} \cdot F_0 e^{i(\omega t + \phi)}
 \end{aligned}$$

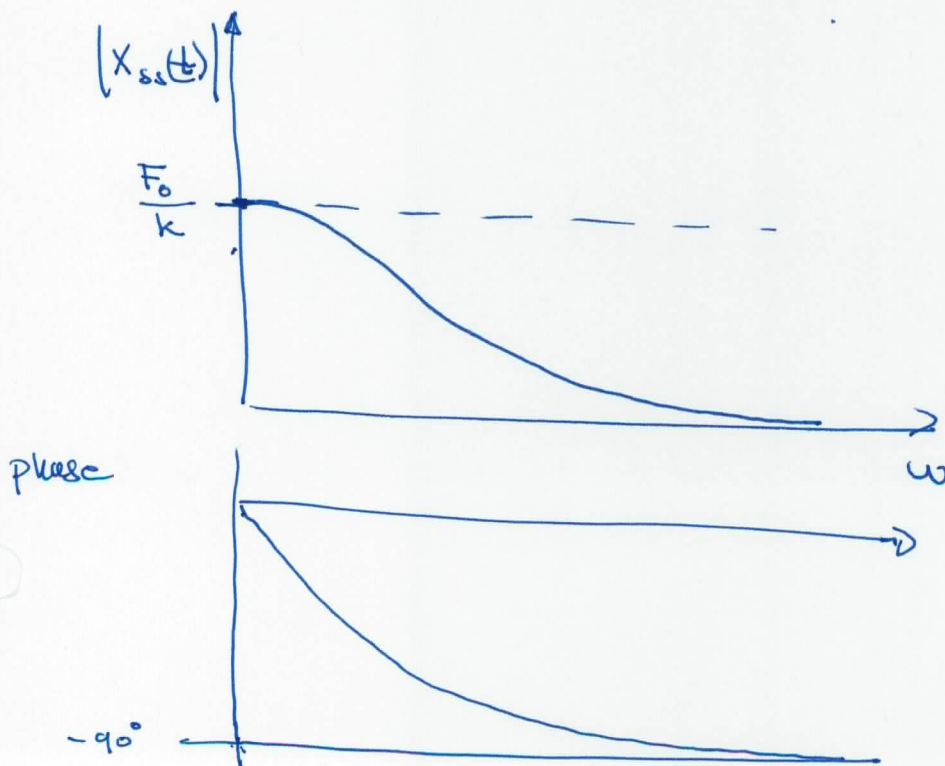
where $\phi = -\phi_0 = -\tan^{-1}\left(\frac{\tau\omega}{1}\right)$

$$X_{ss}(t) = \frac{1}{k} \frac{1}{\sqrt{(\tau\omega)^2 + 1}} \cdot F_0 (\cos(\omega t + \phi) + i \sin(\omega t + \phi))$$

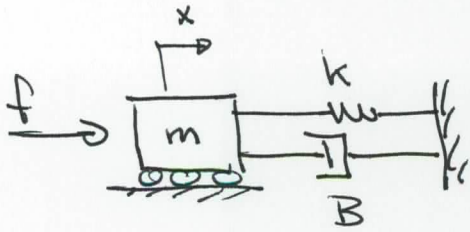
We have sine input so take imaginary part:

$$X_{ss}(t) = \frac{1}{k} \frac{1}{\sqrt{(\tau\omega)^2 + 1}} F_0 \sin(\omega t + \phi)$$

plot amplitude:



Second order system



$$m\ddot{x} + kx + B\dot{x} = f = F \cdot e^{st}$$
$$ms^2X + BsX + kX = F$$

$$H(s) = \frac{X}{F} = \frac{1}{ms^2 + Bs + k} =$$

$$= \frac{1}{m} \frac{1}{s^2 + \frac{B}{m}s + \frac{k}{m}} = \frac{1}{m} \frac{1}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$= \frac{1}{m \cdot \omega_n^2} \frac{1}{\frac{s^2}{\omega_n^2} + \frac{2\zeta}{\omega_n} s + 1}$$

where

$$\omega_n = \sqrt{\frac{k}{m}}$$
$$\zeta = \frac{B}{2\sqrt{k \cdot m}}$$

$$H(s) = \frac{1}{k} \frac{1}{\frac{s^2}{\omega_n^2} + \frac{2\zeta}{\omega_n} s + 1}$$

For sinusoidal input:

$$H(i\omega) = \frac{1}{k} \frac{1}{\left[1 - \left(\frac{\omega}{\omega_n}\right)^2\right] + i 2\zeta \frac{\omega}{\omega_n}}$$

$$H(i\omega) = \frac{1}{k} \frac{1}{\left\{\left[1 - \left(\frac{\omega}{\omega_n}\right)^2\right]^2 + \left(2\zeta \left(\frac{\omega}{\omega_n}\right)\right)^2\right\}^{1/2}} \cdot e^{-i\phi_D}$$

For $f = F e^{i\omega t}$ we get

$$x = \frac{1}{k} \frac{1}{\left\{ \left[1 - \left(\frac{\omega}{\omega_n} \right)^2 \right]^2 + \left(2 \zeta \left(\frac{\omega}{\omega_n} \right) \right)^2 \right\}^{1/2}} e^{-i\phi} \cdot F e^{i\omega t}$$

$$\Rightarrow x = \frac{1}{k} \frac{F}{\left\{ \left[1 - \left(\frac{\omega}{\omega_n} \right)^2 \right]^2 + \left(2 \zeta \left(\frac{\omega}{\omega_n} \right) \right)^2 \right\}^{1/2}} e^{i(\omega t + \phi)}$$

where $\phi = -\phi_0 = \tan^{-1} \left(\frac{2 \zeta \frac{\omega}{\omega_n}}{1 - \left(\frac{\omega}{\omega_n} \right)^2} \right)$

for $f = F \sin(\omega t)$

$$x = \frac{F}{k} \frac{1}{\left\{ \left[1 - \left(\frac{\omega}{\omega_n} \right)^2 \right]^2 + \left(2 \zeta \frac{\omega}{\omega_n} \right)^2 \right\}^{1/2}} \cdot \sin(\omega t + \phi)$$

$$x = x_{STAT} \cdot AF \sin(\omega t + \phi)$$

AF = amplification factor = $\frac{1}{\left\{ \left[1 - \left(\frac{\omega}{\omega_n} \right)^2 \right]^2 + \left(2 \zeta \frac{\omega}{\omega_n} \right)^2 \right\}^{1/2}}$