

Example 2

Consider

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -2 & 2 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 3 & 6 \\ 6 & 3 \end{pmatrix} \begin{pmatrix} e^t \\ 0 \end{pmatrix}$$

obtain the total solution if $x(0) = \begin{pmatrix} 3 \\ 3 \end{pmatrix}$

Solution

Diagonal Form (cont)

On the last page of handout ① we said that the state equation $\dot{\underline{x}} = A\underline{x}$ could be ~~put~~ transformed to diagonal form by the transformation $\underline{x} = M \underline{x}'$

then $\dot{\underline{x}}' = \Lambda \underline{x}'$

where $\Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_n \end{bmatrix}$ $\therefore \lambda$'s eigenvalues of A

$M = [m_1 \ m_2 \ \dots \ m_n]$ $\therefore m$'s eigenvectors of A

solve: $\dot{\underline{x}}' = e^{\Lambda t} \cdot \underline{x}'_0 = \begin{bmatrix} e^{\lambda_1 t} & & 0 \\ & e^{\lambda_2 t} & \\ 0 & & \ddots \\ & & & e^{\lambda_n t} \end{bmatrix} \cdot \underline{x}'_0 = \begin{bmatrix} e^{\lambda_1 t} & & 0 \\ & e^{\lambda_2 t} & \\ 0 & & \ddots \\ & & & e^{\lambda_n t} \end{bmatrix} \cdot M^{-1} \cdot \underline{x}(0)$

then $\underline{x} = M \underline{x}'$

For a forced system

(3)

$$\begin{cases} \dot{\underline{x}} = A \underline{x} + B \underline{u} \\ \underline{x}(0) = \underline{x}_0 \end{cases} \quad (1)$$

it works the same way.

Set $\underline{x} = M \underline{x}'$ and plug into (1)

$$M \dot{\underline{x}}' = A M \underline{x}' + B \underline{u} \Rightarrow$$

$$\dot{\underline{x}}' = M^{-1} A M \underline{x}' + M^{-1} B \underline{u}$$

$$\boxed{\dot{\underline{x}}' = \Lambda \underline{x}' + B' \underline{u}} \quad (3)$$

where $\Lambda = \begin{pmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{pmatrix}$

same as before

λ_i 's are the eigenvalues of A .

and

$$B' = M^{-1} \cdot B \quad \text{where } M = \begin{bmatrix} \underline{m}_1 & \underline{m}_2 & \dots & \underline{m}_n \end{bmatrix}$$

Once (3) is solved \underline{x}' is transformed back to \underline{x} through $\underline{x} = M \underline{x}'$.

(3) is solved by:
$$\boxed{\underline{x}' = e^{\Lambda t} \cdot \underline{x}'_0 + \int_0^t e^{\Lambda(t-\tau)} \cdot B' \underline{u}(\tau) d\tau}$$

$$\underline{x}' = \begin{bmatrix} e^{\lambda_1 t} & & & 0 \\ & e^{\lambda_2 t} & & \\ & & \ddots & \\ 0 & & & e^{\lambda_n t} \end{bmatrix} \cdot M^{-1} \underline{x}_0 + \int_0^t \begin{bmatrix} e^{\lambda_1(t-\tau)} & & & 0 \\ & e^{\lambda_2(t-\tau)} & & \\ & & \ddots & \\ 0 & & & e^{\lambda_n(t-\tau)} \end{bmatrix} \cdot B' \underline{u}(\tau) d\tau$$

finally:
$$\boxed{\underline{x} = M \underline{x}'}$$

Example ③: Same as Example ② but
solve it through diagonal form.

④