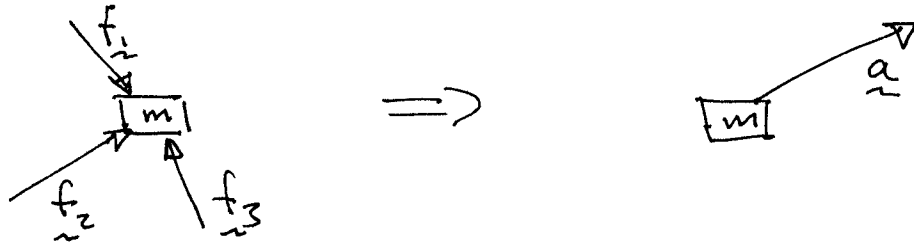


## Newton's Second "Law"



$$\sum_{i=1}^n \vec{f}_i = \vec{f} = \frac{d}{dt} (m \cdot \vec{v})$$

For constant mass

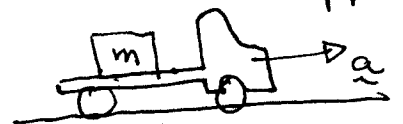
$$\vec{f} = m \cdot \frac{d\vec{v}}{dt} = m \cdot \vec{a}$$

where  $\vec{a}$  is the acceleration of center of mass if the particle is of finite size.

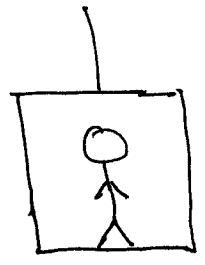
Note that  $\vec{a}$  must be measured from an inertial reference frame!

Ex 1

How fast can the truck accelerate without the box of mass  $m$  slipping off the truck bed? Assume a friction coefficient of  $\mu$ .



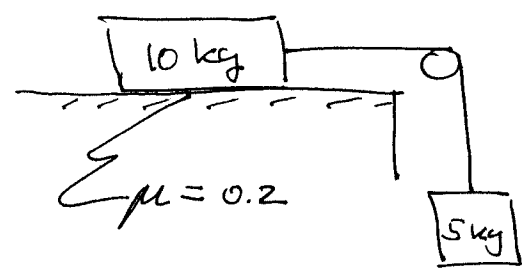
Ex 2



What is the force acting on a person through the floor of the elevator when

$a = 5 \text{ m/s}^2$  downwards. Assume  $m = 60 \text{ kg}$

Ex 3

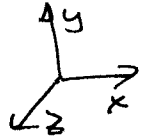


What is the acceleration of the blocks?

In terms of a Cartesian Coordinate System.

$$\vec{F} = \frac{d}{dt}(m \cdot \vec{v}) = m \cdot \vec{a} \quad (\text{for constant mass})$$

Express the vectors with the help of a Cartesian inertial coordinate system

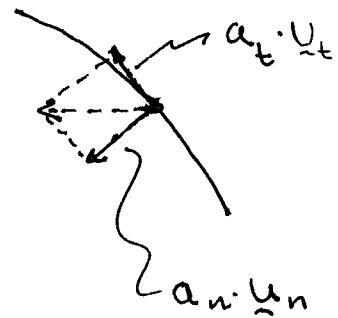
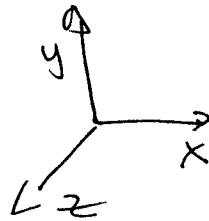
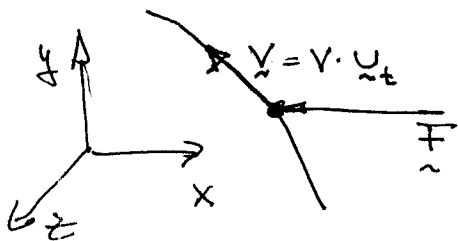


then  $F_x \hat{i} + F_y \hat{j} + F_z \hat{k} = m a_x \hat{i} + m a_y \hat{j} + m a_z \hat{k}$

or  $\boxed{F_x = m a_x}$      $\boxed{F_y = m a_y}$      $\boxed{F_z = m a_z}$

where  $F_x = \sum_{l=1}^n F_{x_l}$ ,  $F_y = \sum_{l=1}^n F_{y_l}$ ,  $F_z = \sum_{l=1}^n F_{z_l}$

In terms of normal and tangential components:



Note that  $\vec{F}$  and  $\vec{a}$  will be in the same direction. (Also note that  $\hat{u}_n = \hat{e}_n$  and  $\hat{u}_t = \hat{e}_t$ )

Again:  $\vec{F} = m \cdot \vec{a}$  or

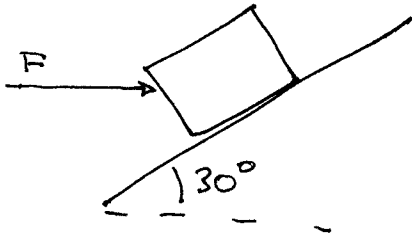
$$F_n \hat{u}_n + F_t \hat{u}_t = m(a_n \hat{u}_n + a_t \hat{u}_t)$$

$$\Rightarrow F_n = m \cdot a_n, \quad F_t = m \cdot a_t$$

$$\Rightarrow \boxed{F_n = m \frac{v^2}{\rho}}, \quad \boxed{F_t = m \cdot \frac{dv}{dt}}$$

Ex 4

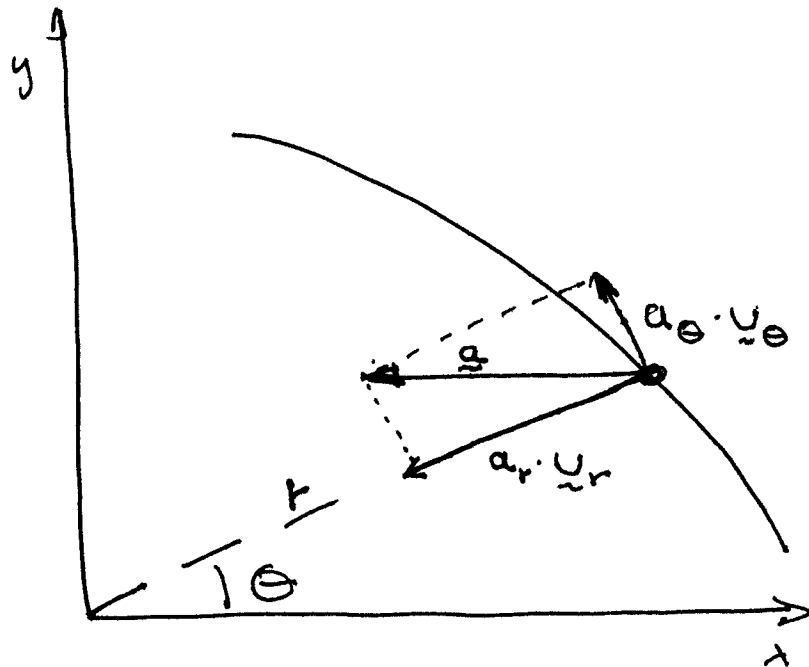
4



The 100 lb crate is initially stationary. The coefficients of friction between the crate and the surface are  $\mu_s = 0.2$  and  $\mu_k = 0.16$ .

Determine how far the crate moves from its initial position in 2 sec if the horizontal force  $F = 90$  lb.

# Polar and Cylindrical Coordinates



$$\vec{F} = m \cdot \vec{a}$$

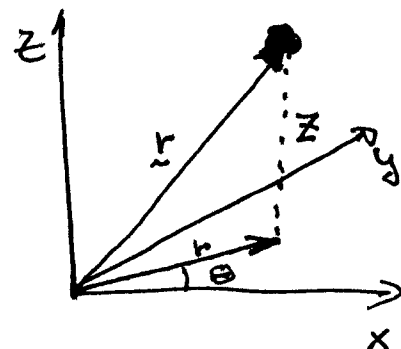
$$\vec{F}_r \cdot \vec{u}_r + \vec{F}_\theta \cdot \vec{u}_\theta = m \left( \frac{d^2 r}{dt^2} - r\omega^2 \right) \cdot \vec{u}_r + m \left( r\alpha + 2 \frac{dr}{dt} \cdot \omega \right) \vec{u}_\theta$$

$$\Rightarrow \boxed{\vec{F}_r = m \left( \frac{d^2 r}{dt^2} - r\omega^2 \right)}$$

$$\boxed{\vec{F}_\theta = m \left( r\alpha + 2 \frac{dr}{dt} \cdot \omega \right)}$$

If one adds a z-direction (cylindrical coord.) then in addition

$$\boxed{\vec{F}_z = m \frac{d^2 z}{dt^2}}$$



# EX 5

Small parts on a conveyer belt moving with constant velocity  $v$  are allowed to drop into a bin. Show that the angle  $\alpha$  at which the parts start sliding on the belt satisfies the equation

$$\cos \alpha - \frac{1}{\mu_s} \sin \alpha = \frac{v^2}{gR}$$

where  $\mu_s$  is the coefficient of static friction between the parts and the belt.

