

OCTAHEDRAL SHEAR STRESS CRITERION (VON MISES)

Since hydrostatic stress alone does not cause yielding, we can find a material plane called the octahedral plane, where the stress state can be decoupled into dilation strain energy and distortion strain energy¹. On the octahedral plane, the octahedral normal stress solely contributes to the dilation strain energy and is

$$\mathbf{s}_h = \frac{\mathbf{s}_1 + \mathbf{s}_2 + \mathbf{s}_3}{3} \quad (1)$$

This is the average of the three principal stresses. For example, if $\sigma_1 = \sigma_2 = \sigma_3 = p$ where p is the pressure, then $\sigma_h = p$. The remaining strain energy in the state of stress is determined by the octahedral shear stress and is given by

$$\mathbf{t}_h = \frac{1}{3} \sqrt{(\mathbf{s}_1 - \mathbf{s}_2)^2 + (\mathbf{s}_2 - \mathbf{s}_3)^2 + (\mathbf{s}_3 - \mathbf{s}_1)^2} \quad (2)$$

We expect yielding when the octahedral shear stress is equal to or exceeds a stress criterion value for failure for a given material, which is the octahedral stress criterion \mathbf{t}_{h0} :

$$\mathbf{t}_h \geq \mathbf{t}_{h0} \quad (\text{failure}) \quad (3)$$

$$\mathbf{t}_h = \mathbf{t}_{h0} \quad (\text{at yielding}) \quad (4)$$

The octahedral stress criterion for say 1080 Al is not likely to be reported in the literature so we need to relate it to the axial yield strength σ_0 . For a given material under axial load where $\sigma_1 = \sigma_0$ and $\sigma_2 = \sigma_3 = 0$, we assume that yielding occurs when the octahedral shear stress is equivalent to the octahedral stress criterion. This means we can combine Eq. 2 and 4 to get the octahedral stress criterion in terms of the yield strength:

$$\mathbf{t}_{h0} = \mathbf{t}_h = \frac{1}{3} \sqrt{(\mathbf{s}_0 - 0)^2 + (0 - 0)^2 + (0 - \mathbf{s}_1)^2} = \frac{\sqrt{2}}{3} \mathbf{s}_0 \quad (5)$$

With $\mathbf{s}_0 = \frac{3}{\sqrt{2}} \mathbf{t}_{h0}$, we expect to observe yielding in a material under 3-D loading when, as before, we combine Eq. 2 and 4 to get

$$\mathbf{s}_0 = \frac{1}{\sqrt{2}} \sqrt{(\mathbf{s}_1 - \mathbf{s}_2)^2 + (\mathbf{s}_2 - \mathbf{s}_3)^2 + (\mathbf{s}_3 - \mathbf{s}_1)^2} \quad (6)$$

As a result, we can define the effective stress for von Mises theory to be equivalent to Eq. 6.

$$\bar{\mathbf{s}}_H = \frac{1}{\sqrt{2}} \sqrt{(\mathbf{s}_1 - \mathbf{s}_2)^2 + (\mathbf{s}_2 - \mathbf{s}_3)^2 + (\mathbf{s}_3 - \mathbf{s}_1)^2} \quad (7)$$

¹ For dilation, stresses are the same in all directions and there is no shear. For distortion, stresses are different in magnitude and/or direction and so there exists shear stress. See full derivation in Popov, E.P., 1968 *Introduction to Mechanics of Solids*, 1st edition, Prentice Hall, Englewood Cliffs, NJ.

We can express Eq. 7 in terms of the stress invariants (I_1 and I_2):

$$\bar{s}_H = \frac{1}{\sqrt{2}} \sqrt{2(I_1 - 3I_2)^2} \quad (8)$$

Failure is likely when

$$\bar{s}_H \geq s_0 \quad (9)$$

For plane stress ($s_3 = 0$), we expect yielding when $\bar{s}_H = s_0$ and so

$$\begin{aligned} s_0 &= \frac{1}{\sqrt{2}} \sqrt{(s_1 - s_2)^2 + (s_2 - 0)^2 + (0 - s_1)^2} \\ s_0^2 &= \frac{1}{2} [(s_1 - s_2)^2 + s_2^2 + s_1^2] \\ s_0^2 &= \frac{1}{2} [s_1^2 - 2s_1s_2 + s_2^2 + s_2^2 + s_1^2] \\ s_0^2 &= s_1^2 - s_1s_2 + s_2^2 \end{aligned} \quad (10)$$

The last form in Eq. 10 is an ellipse with its major axis along the $\sigma_1 = \sigma_2$ line. We can solve this and graph it in MATHEMATICA:

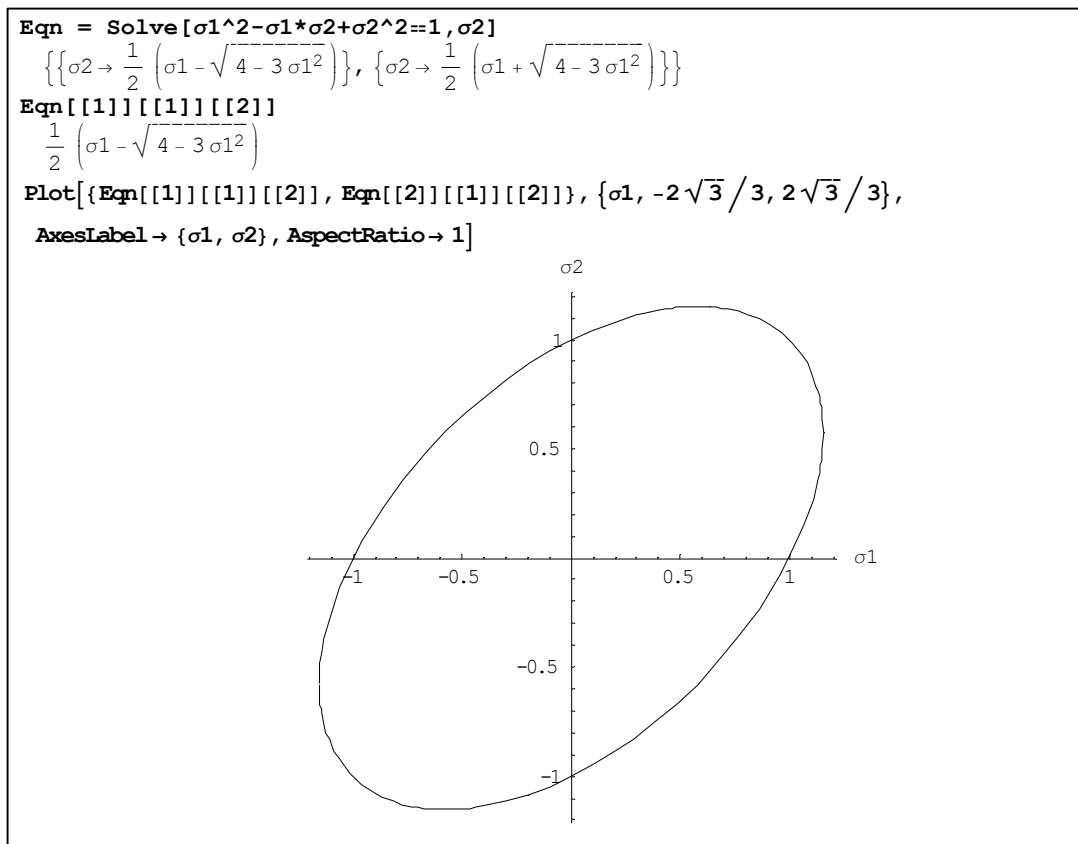


Figure 1. Mathematica code to plot octahedral stress failure for plane stress.