Discrete Optimization Lecture-15

Ngày 6 tháng 12 năm 2011

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- Does the Digraph D have a Hamiltonian cycle?

Our common computing, whether by a computer, calculator, cell-phone or by hand is an execution of sequential operations. Thus to multiply 456301 * 432 we will execute single digit multiplications and additions of single digits (including carry over).

There are alternative computing models. One of them is the **Non-Deterministic** computing model. In a deterministic computing model an algorithm will execute on a given instance the same steps in different runs. In a non-deterministic model it may execute different steps on the same instance.

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There are a few equivalent definitions of the **NP** (non-deterministic) computing model. Before discussing the definition we shall examine an example.

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- 998667686017 is probably prime."

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In the 55th attempt of the fourth run, the algorithm calculated: $737^{998667686016} \mod 998667686017 = 402448171978.$

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- The algorithm 𝔅 runs in polynomial time on the combined instance (*n*, *C*).
- \mathbb{B} returns true if and only if n is a true instance for \mathbb{A} .

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- Decision problem: Input a graph G.
 Output: YES if G is Eulerian.
- Verify that G is connecetd and $d_G(v_i) \equiv 0 \mod 2$

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 - In the first example the first certificate actually identifies a divisor of the input n.
 - The second certificate does not help us find such a divisor.
 - But finding a certificate for the second verification is usually quite easy allowing us to implement the function is_prime(n) in SAGE and other mathematical packages.

The Satifiability Problem

Another computing model (heuristic) of the **NP** computing is the following example. Suppose you wish to decide whether a given boolean function $f(x_1, x_2, ..., x_n)$ in CNF is satisfiable.

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- After 100 assignments there will be 2¹⁰⁰ threads.
- Computation ends when a thread discovers a *T* assignment to all clauses.

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If $f(x_1, x_2, ..., x_n)$ is satisfiable then a path of length $\leq n$ along the "correct" threads will indentify the assignment for which $f(x_1, x_2, ..., x_n) = T$.

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The non-deterministic nature of this process should be clear now. Assume that at every execution we flip a coin and if it falls on HEAD we assign $x_i = T$ and if it is TAIL we assign $x_i = F$.

If we were "lucky" at every step we will identify the answer in no more than n steps. Also, every execution may execute different steps.

The generalization to any other decision problem is straight forward.

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- Example. Suppose we wish to find the chromatic number of a graph G. We can use the decision problem "Is G k-colorable" no more than log n times to determine χ(G).
- Another class of problems is called P-Space problems (again, P stands for polynomial).

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- Another class of problems is called P-Space problems (again, P stands for polynomial).
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This is easily verifiable using less than n additions. But we do not know how to find B.

The class NP-Complete

Question

Among all NP complete problems, are there problems that are more difficult than all other NP problems?

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This means that if you had a "black box" that could efficiently solve any instance of a **SAT** problem then you can efficiently solve any problem in **NP**.

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- 3-SAT.
- 3-colorabilty of graphs.

This means that our class, K53, knows 3 "black boxes" that are NPC.

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Currently, hundreds of such "black boxes" have been identified.

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Another striking example was the chromatic index of a graph. The problem is $\chi_1(G) = \Delta(G)$ is known to be in **NPC**. Yet we identified an efficient algorithm that guaranteed a coloring by no more than $\Delta(G) + 1$ colors.

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Another striking example was the chromatic index of a graph. The problem is $\chi_1(G) = \Delta(G)$ is known to be in **NPC**. Yet we identified an efficient algorithm that guaranteed a coloring by no more than $\Delta(G) + 1$ colors.

Finally, the problem is G_1 isomorphic to G_2 is clearly in **NP**. It is not known whether it is in **NPC** or in **P**. It is suspected that it might be "in between" the two classes if indeed **NP** \neq **P**.

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3-SAT is reducible to the problem:

Input: G, k Output: YES if $\alpha(G) \ge k$.

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Assume that the 3-SAT instance has *n* boolean variables $x_1, x_2, ..., x_n$ and *m* clauses $(v_{i,1} \lor v_{i,2}, \lor v_{i,3})$ i = 1, 2, ..., m. Each $v_{i,i} = x_k$ or $v_{i,j} = \neg x_k$.

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• $(v_{i,j}, v_{i',j'}) \in E(G)$ if $v_{i,j} = x_t$ and $v_{i',j'} = \neg x_t$.

• Clearly $\alpha(G) \leq k$.

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The problem:

Input: (G, m) Output: G has a vertex cover of size $\leq k$ is NPC.

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Corollary

The problem:

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G has a vertex cover of size $\leq m$ if it has an independent set of size $\geq |V(G)| - m$.

So we can use the vertex cover black box to solve the independent set problem.

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Decision problem: are there subsets $S_{i_1}, S_{i_2}, \ldots, S_{i_k}$ such that: $\bigcup_{n=1}^k S_{i_n} = S$?.

Theorem

The set cover "black box" can efficiently solve the vertex cover problem.

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Decision problem: are there subsets $S_{i_1}, S_{i_2}, \ldots, S_{i_k}$ such that: $\bigcup_{n=1}^k S_{i_n} = S$?.

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The set cover "black box" can efficiently solve the vertex cover problem.

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Question

Is this problem similar to any of the problems we discussed so far?

Answer

Indeed it is! and it is easy to reduce the vertex cover to it.

Except for the 3– colorability, all reductions we studied were quite simple. We will end our discussion by studying a more complicated example: the **TSP**.

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Except for the 3– colorability, all reductions we studied were quite simple. We will end our discussion by studying a more complicated example: the **TSP**. We first show that the problem:

Input: digraph G.

Output: YES if G has a Hamitonian cycle.

Is in NPC.

We shall show how a black-box that can effciently find Hamiltonian cycles in A Digraph can decide whether a given instance of 3-SAT is satisfiable.

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Let $F(x_0, x_1, ..., x_{n-1})$ be a given 3-SAT instance with *k* clauses. The graph that will help us decide whether *F* is satisfiable will be constructed in two steps.

• We start with *n* bi-diretional paths, each of length 3k + 3.

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• For i = 0, 1, ..., n - 1 we add edges $v_{i,1} \rightarrow \{v_{i+1,1}, v_{i+1,3k+3}\}$ and $v_{i,1} \leftarrow \{v_{i+1,1}, v_{i+1,3k+3}\}$ (index arithmetic is done mod n).

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- We add two additional vertices:

 $t, s: t \to s, s \to \{v_{0,1}, v_{0,3k+3}\} \text{ and } \{v_{n-1,1}, v_{n-1,3k=3}\} \to t.$

So far our graph has n(3k+3)+2 vertices. It has many different Hamiltonian cycles, 2^n of them.

There are 2^n possible truth assignment to the variables x_1, x_2, \ldots, x_n . The idea is to associate every truth assignment with one of the cycles and use the clauses to "force" a Hamiltonian cycle if and only if $F(x_0, x_1, \ldots, x_{n-1})$ is satisfiable.

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Also since $t \rightarrow s$ is the only edge entering *s* it must be contained in every Hamiltonian cycle.

We now add *k* vertices corresponding to the *k* clauses C_1, C_2, \ldots, C_k . We use the following example to describe the edges connecting these vertices to the current vertices.

Assume that $C_i = (x_3 \lor \neg x_9 \lor \neg x_{67})$. We add the edges: $V_{i,9} \rightarrow C_i, \ C_i \rightarrow V_{i,10}, C_i \rightarrow V_{i,27}, \ C_i \leftarrow V_{i,28}, \ C_i \rightarrow V_{i,201}, C_i \leftarrow V_{i,202}.$ Assume that $F(x_1, x_2, ..., x_n)$ is satisfiable. For instance assume that $x_0 = T, x_1 = T, x_2 = F$ etc. and assume that $C_i = (x_0 \lor \neg x_i \lor x_j)$ is a clause which is satisfied by the choice $x_0 = T$.

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Our graph will have the following Hamiltonian cycle:

$$t
ightarrow s
ightarrow v_{i,3}
ightarrow c_i
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ightarrow \ldots
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Our graph will have the following Hamiltonian cycle:

 $t \rightarrow s \rightarrow v_{i,3} \rightarrow c_i \rightarrow v_{i,4} \rightarrow \ldots \rightarrow v_{i,3k+3} \rightarrow \ldots \rightarrow t$

Conversely, if the graph is Hamiltonian, for every path P_i traversed by the cycle either the vertex c_i is traversed from right to left (we will assign it the value F) or from left to right (in which case it will be assigned F). It is easy to see that each clause C_i will be satisfied by this assignment.

The TSP is NPC

This is a real easy reduction to the Hamiltonian cycle problem.

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Given a diGraph D(V, E). Construct a TSP instance with "cities" v_i and $\omega(v_i, v_j) = 1$ if $(v_i, v_j) \in E(D)$ and $\omega(v_i, v_j) = 10$ otherwise. Now ask the TSP blackbox whether this instance has a tour of weight $\leq n$.

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This brings us back to the first lecture. We started with two problems that looked almost identical.

Given a diGraph D(V, E). Construct a TSP instance with "cities" v_i and $\omega(v_i, v_i) = 1$ if $(v_i, v_i) \in E(D)$ and $\omega(v_i, v_i) = 10$ otherwise. Now ask the TSP blackbox whether this instance has a tour of weight < n.

Clearly, this TSP instance has a tour of weight *n* if and only if *D* is Hamiltonian.

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And now we learned that one, the assignment problem can be solved effciently while the TSP problem is very difficult.

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