STRICTLY ANTIPODAL SETS*

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ABSTRACT

A subset A of E^3 is called strictly antipodal provided that for every pair X_1 , X_2 of points of A there is a pair H_1 , H_2 of parallel supporting planes of A such that $H_i \cap A = \{X_i\}$. The main result asserts that a strictly antipodal set has at most five points. This strengthens a recent result of Croft [2].

1. **Introduction.** For a convex polyhedron K let v(K) denote the number of vertices of K. If K_1 and K_2 are convex polyhedra it is clear that $v(K_1 + K_2) \le v(K_1) \cdot v(K_2)$. It is easy to find examples showing that equality may hold for suitable K_1, K_2 in E^3 ; if $K_1, K_2, \subset E^2$, then

$$v(K_1 + K_2) \le v(K_1) + v(K_2).$$

More complicated, and unsolved in the general case, is the following related problem:

If K is a convex polyhedron in E^n , with v = v(K) vertices, how many vertices can $K^* = K + (-K)$ have? It is easily checked that, independent of n, $v(K^*) \le v(v-1)$. However, equality in this relation can take place only if v is not too large with respect to n.

Let f(n) denote the maximal v such that there exists an n-dimensional convex polyhedron K with v = v(K) and $v(K^*) = v(v - 1)$. It is easily seen that f(2) = 3. In Section 2 we shall prove the following result.

THEOREM. f(3) = 5.

As easy corollaries we shall obtain (in Section 3) a simple solution of a problem of Erdös [5] recently solved by Croft [2], as well as a number of results on families of translates of convex polyhedra in E^3 . Some additional remarks and problems are also given in Section 3.

2. **Proof of the Theorem.** For an arbitrary set $A \subset E^n$ let a pair of points $X_1, X_2 \in A$ be called *strictly antipodal* if there exists a pair H_1, H_2 of (distinct) parallel supporting hyperplanes of A such that $A \cap H_i = \{X_i\}$ for i = 1, 2. A set A is called strictly antipodal provided ever A two points of A are strictly

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antipodal. Let g(n) denote the maximal number of points in a strictly antipodal set $A \subset E^n$. The following assertion is obvious:

LEMMA. The set of vertices of a convex polyhedron K is strictly antipodal if and only if $v(K^*) = v(K) \cdot (v(K) - 1)$.

If A is a strictly antipodal set and K its convex hull, then A coincides with the set of vertices of K. Therefore, the lemma implies that f(n) = g(n).

In order to prove the Theorem it is sufficient to show that the common value of f(3) and of g(3) is 5. Since $f(3) \ge 5$ (see Section 3) and since every subset of a strictly antipodal set is strictly antipodal, we have only to show that no 6-pointed set in E^3 is strictly antipodal.

Assuming this to be false, let A be a six-pointed strictly antipodal set in E^3 , with convex hull K. Because of f(2) = g(2) = 3, all the faces of K are triangles. Counting incidences and using Euler's formula it follows at once that K must be a polyhedron of one of the two types represented in Figure 1 by their Schlegel diagrams.

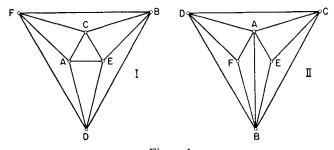


Figure 1

We first note that K cannot have configuration II. Indeed, if there would exist such K, in view of the affine invariance of strict antipodality we could assume that K has the form indicated in Figure 2. Since the segment EF is not an edge of K, $\min\{a,\alpha\}<1$. Without loss of generality we assume that a<1, and we note

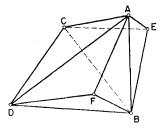


Figure 2

$$A = (1,0,1); B = (1,0,-1); C = (-1,1,0);$$

$$D = (-1, -1, 0); E = (a, b, c); F = (\alpha, \beta, \gamma).$$

that E is contained in the wedge formed by the planes through ACD and BCD. Considering the sections of K by the planes z = 0 resp. z = c it is immediate that C and E are not strictly antipodal.

Thus we may assume, for the remaining part of the proof, that K has configuration I; without loss of generality we may therefore assume that K has the form indicated in Figure 3.

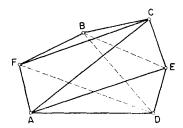


Figure 3

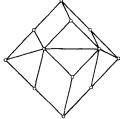
$$A = (-1, -1, 0); B = (-1, 1, 0); C = (1, 0, 1);$$

 $D = (1, 0, -1); E = (a, b, c); F = (\alpha, \beta, \gamma).$

Since sufficiently small displacements of the points of a strictly antipodal set do not destroy strict antipodality, it follows that no generality is lost in assuming that no edge of K is parallel to a face of K, and that $|b| + |c| \neq 1$, $|\beta| + |\gamma| \neq 1$. It follows that $K^* = K + (-K)$ will have 16 triangular faces (called *t*-faces in the sequel), and that all other faces of K^* are parallelograms (called *p*-faces in the sequel). Using again a count of incidences and Euler's formula, it is easily found that K^* has 20 *p*-faces.

We shall end the proof of the Theorem by examining the construction of K^* and by showing that it cannot contain 20 p-faces.

Let K_1 denote the convex hull of $\{A, B, C, D, E\}$. Then K_1^* is a polyhedron with the vertices $\pm (C-A) = \pm (2,1,1), \pm (D-A) = \pm (2,1,-1), \pm (C-B) = \pm (2,-1,1), \pm (D-B) = \pm (2,-1,-1), \pm (B-A) = \pm (0,2,0), \pm (C-D) = \pm (0,0,2), \pm (E-A) = \pm (1+a,1+b,c), \pm (E-B) = \pm (1+a,-1+b,c), \pm (E-C) = \pm (-1+a,b,-1+c).$ Since K is of type I, we have a>1; this and the convexity of K_1^* imply that |b|+|c|<1. (Indeed, by considering the vertices C-A, D-A, C-B, D-B, E-A and E-B it follows from a>1 that |c|<1. Then, assuming without loss of generality that c>0 and b+c>1, a consideration of the vertices C-D, C-B, E-B, E-D, leads to the contradiction that C-A is not a vertex of K_1^*). Projecting orthogonally the part of K_1^* contained in the half-space $E^+=\{(x,y,z)|x\geq 0\}$ onto x=0, we obtain a configuration of the type represented in Figure 4a. Denoting by K_2 the convex hull of $\{A,B,C,D,F\}$, the same reasoning applied to K_2^* leads to a configuration of the type given in Figure 4b.





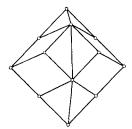


Figure 4b

Now, K^* is the convex hull of $K_1^* \cup K_2^* \cup \{E - F, F - E\}$. Obviously, E - Fand F - E are incident only to t-faces of K^* ; therefore the number of p-faces of K^* at most equals the number of p-faces in the convex hull Q of $K_1^* \cup K_2^*$. But the latter number is at most 12. Indeed, superimposing Figures 4a and 4b, we observe that every p-face of Q is a p-face of either K_1^* or K_2^* , and that only one p-face of Q contained in the half-space E* can be incident to each of the vertices C-A, D-A, C-B, D-B.

Thus Q has at most four p-faces contained in E^+ ; by symmetry the same number of p-faces of Q is contained in the half-space E. Together with the four p-faces parallel to the x-axis, this yields at most 12 p-faces for Q, and thus also for K^* , in contradiction to the former assertion that K^* has 20 p-faces.

This completes the proof of the Theorem.

3. Some related results and problems.

- i) Erdös [5] posed the problem of determining the maximal number e(n) of points in E^n such that all the angles determined by triplets of the points be acute. For n = 3 Croft [2] recently established that e(3) = 5. This results also from our Theorem and from the obvious assertion $e(n) \leq g(n)$.
- ii) The inequality $e(n) \ge 2n-1$ was established in [3] by means of the following example (reproduced here for the sake of completeness): Let $\{e_i\}_{i=1}^n$ be mutually orthogonal unit vectors in E^n . The (2n-1)-pointed set $\{A, B_2, \dots, B_n, \dots, B_n, \dots, B_n, \dots, B_n, \dots, B_n\}$ C_2, \dots, C_n satisfies Erdös' condition if, e. g., $A = e_1, B_k = \alpha_k e_1 + e_k$ $C_k = -\alpha_k e_1 - e_k$, $k = 2, 3, \dots, n$, where all α_k 's satisfy $0 < \alpha_k < 1$ and are different from each other.
- iii) As mentioned (in part) in [3], it is easily shown that g(n) is also the maximal number of members in any family \mathcal{K} of translates of a convex body $K \subset E^n$, provided the family satisfies any of the following conditions:
 - (a) The intersection of any two members of \mathcal{X} is a single point;
- (b) The intersection of all members of \mathcal{K} is a single point, which is also the only common point of any two members of \mathcal{K} ;
 - (c) The intersection of any two members of \mathcal{K} is (n-1)-dimensional.

The same is true if in (a) or in (c) the attention is restricted to centrally symmetric K.

iv) The restriction of \mathcal{X} to families of translates of one convex body is essential in iii). This is obvious in case of conditions (a) and (b); in the case of (c) the bound is 4 for n=2 (while g(2)=3); already for n=3 it has been proved repeatedly (e.g. by Tietze, Besicovitch, Rado; see [4] for references to these and some related results) that there exists no finite bound. In [4] it is also pointed out that arbitrarily large families \mathcal{X} in E^3 , any two of whose members have a 2-dimensional intersection, are obtainable as the Schlegel-diagrams of the duals of 4-dimensional "neighborly polytopes" (see [7]). This was known, however, already to Brûckner [1].

Nevertheless, the following question seems to be open even for n = 3: How many members can a family of centrally symmetric convex bodies in E^n have, if every two have an (n-1)-dimensional intersection?

- v) Among unsolved problems related to the Theorem of the present paper we mention:
- (a) The determination of e(n) and of f(n) = g(n) for n > 3; in particular, is e(n) = g(n) for all n?
- (b) The determination of $h(k,n) = \max\{v(K+(-K)) \mid K \subset E^n, v(K) = k\}$ for $k \ge 2n, n \ge 3$.

REMARK. The example ii) above implies h(k,n) = k(k-1) for $n+1 \le k \le 2n-1$; for k > n = 2, we have h(k,2) = 2k. This follows from the observation that h(k,n) = 2s(k,n), where s(k,n) is the maximal number of strictly antipodal pairs of vertices for a convex polyhedron $K \subset E^n$ with v(K) = k, and the assertion s(k,2) = k. To prove this latter assertion assume that s(k,2) > k for some k. Let k_0 be the minimal k with this property and let K, with $v(K) = k_0$, be a k_0 -gon such that more than k_0 pairs of vertices of K are strictly antipodal. Then at least one vertex V_0 is antipodal to some three consecutive vertices V_{i-1} , V_i , V_{i+1} of K; but then V_i is easily seen to be strictly antipodal only to V_0 . Thus the convex hull of the $k_0 - 1$ vertices of K different from V_i yields an example showing $s(k_0 - 1, 2) > k_0 - 1$, in contradiction to the minimality of k_0 .

It is worth mentioning that $s(k,3) \ge \lfloor k/2 \rfloor \cdot \lfloor k(+1)/2 \rfloor + 2$ for $k \ge 4$, the difference in behavior between s(k,2) and s(k,3) being similar to the jump in the number of times the diameter of a set is assumed in 3- and 4-dimensional sets (Erdös [6]). The above inequality is easily established by placing approximately half of the points on each of two suitable circular arcs.

vi) Klee [8] defined a pair of points X_1 , X_2 of a set $A \subset E^n$ to be antipodal provided there exist distinct parallel supporting hyperplanes H_1 , H_2 of A such that $X_i \in A \cap H_i$, i = 1, 2; he also asked about the maximal number of points in a set $A \subset E^n$ such that every two points of A are antipodal. It was established in [3] that the required number is 2^n . In analogy to the above definition of s(k, n) one may ask what is the maximal number a(k, n) of pairs of antipodal points in k-pointed sets in E^n . While the problem is open for $n \ge 3$, it can be shown by

arguments similar to those used above in connection with s(k, 2) that a(k, 2) = [3k/2].

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Added in proof (June 13, 1963):

The result of Croft [2] that e(3) = 5 was recently established also by Schütte, K., 1963, Minimale Durchmesser endlicher Punktmengen mit vorgeschriebenem Mindestabstand, Math. Annalen, 150, 91-98.