

# ME 599/AA 546/EE 546: **Biology-inspired robot control**

Lecture 9

Sawyer B. Fuller

Goals:

- address feedback/questions
- points to include in mid-quarter updates, schedule
- Presentation and discussion of Paper 5 by Evan Schuster and Carl Svanevik

# Office Hours time change

- old: Thurs 3:30-4:30
- new: Thurs 2:30-3:30
- Location: MEB321
- (updated on online syllabus)

# learning objectives for the course

## **paper readings and presentation**

- tools, methods, and approaches in academic research
- how to read a paper

- presentation skills

## **term project**

- experience creating a simulated world
- good software practices

# how to read a paper

1. read the abstract - 2-5 min
2. look through the figures - 5-10 min
3. read the introduction - 5-20 min
4. read the conclusion - 10 min
5. read the rest of the paper - 1-10 hrs

# midterm project presentations Friday and Wednesday

- outline of what to include:
  - **goal(s)**: high-level.
    - example: “my vehicle will be able to alternate between different food sources that replenish at different rates using simple rules”
    - this is research, so keep your goal in mind to inform exploration, but you don’t have to stick to it if a different direction seems more promising. there is value in open-ended research!
  - **objectives**: measurable outcomes
    - example: “vehicle visits each site at least twice. it will spend a longer time at the larger food source”
  - **initial results**, such as a simulation
  - **timeline** for rest of the term
- 10 min each + 2-5 min questions
- Friday, October 28:
  - 1. Sam and Nathaniel, 2. Tianqi, 3. Qiong, 4. Bryan
- Wednesday, November 2:
  - 1. Evan, 2. Siva, Joon, Liam, 3. Carl, 4. Yogesh