

Proposition 4.5 (Kallenberg) Let $\{\mathcal{A}_t : t \geq 0\}$ denote an \nearrow sequence of σ -fields on the probability space (Ω, \mathcal{A}, P) ; that is, the \mathcal{A}_t 's form a filtration. Consider the null sets $\mathcal{N} \equiv \{N \in \mathcal{A} : P(N) = 0\}$. Define $\widehat{\mathcal{A}}_t \equiv \sigma[\mathcal{A}_t, \mathcal{N}]$.

(a) Then the \nearrow collection of σ -fields $\widehat{\mathcal{A}}_{t+}$ necessarily equals the completion $\widehat{\widehat{\mathcal{A}}_{t+}}$ of the right-continuous filtration \mathcal{A}_{t+} , and so forms an augmented filtration for $(\Omega, \widehat{\mathcal{A}}, P)$. Moreover, this is the minimal augmented filtration.

(b) If the $\mathcal{A}_t \equiv \sigma_t$ denote the histories of a right-continuous process $X : (\Omega, \mathcal{A}, P) \rightarrow (D_{[0, \infty)}, \mathcal{D}_{[0, \infty)})$, then the completion of the right-continuized histories necessarily forms the minimal augmented filtration. (That is, complete each $\sigma_{t+} \equiv \bigcap_{n=1}^{\infty} \sigma_{t+1/n}$.)

(c) If $S \leq T$ a.s. then $\mathcal{A}_S \subset \mathcal{A}_T$ relative to the augmented filtration $\widehat{\sigma}_{t+} = \widehat{\sigma}_{t+}$.

Proof. It is trivial that $\widehat{\mathcal{A}}_{t+} \subset \widehat{\widehat{\mathcal{A}}_{t+}} = \widehat{\mathcal{A}}_{t+}$. To show the converse, consider a set $A \in \widehat{\widehat{\mathcal{A}}_{t+}}$. Then for each $n \geq 1$ we have $A \in \widehat{\mathcal{A}}_{t+1/n}$, so $P(A \Delta A_n) = 0$ for some set $A_n \in \mathcal{A}_{t+1/n}$. Note that $A^* \equiv \overline{\lim}_n A_n$ is in \mathcal{A}_{t+} , while $P(A \Delta A^*) = 0$ since $A \Delta A^* \subset \bigcup_1^{\infty} (A \Delta A_n) = \bigcup \{\text{null}\}_n = \{\text{null}\}$; thus $A \in \widehat{\mathcal{A}}_{t+}$. Thus the main claim in (a) is established. Let \mathcal{F}_t denote any other augmented filtration for which all $\mathcal{F}_t \supset \mathcal{A}_t$. Then $\widehat{\mathcal{A}}_{t+} = \widehat{\mathcal{A}}_{t+} \subset \widehat{\mathcal{F}}_{t+} = \mathcal{F}_{t+} = \mathcal{F}_t$, as claimed. Part (b) follows at once. Part (c) follows from exercise 12.4.1 on properties of stopping times. \square

Example 4.1 (Haeusler) Let both A and A^c be measurable subsets of some (Ω, \mathcal{A}, P) that have probability exceeding 0. Define $X_t(\omega)$ on $0 \leq t \leq 1$ to be identically 0 if $\omega \in A$ and to equal $(t - 1/2) \cdot 1_{[1/2, 1]}(t)$ if $\omega \in A^c$. All paths of this X -process are continuous. Since X_t is always 0 for $0 \leq t \leq 1/2$, we have $\sigma_t = \{\emptyset, \Omega\}$ for $0 \leq t \leq 1/2$. However, $\sigma_t = \{\emptyset, A, A^c, \Omega\}$ for $1/2 < t \leq 1$. These histories σ_t are not right continuous at $t = 1/2$. The right continuized histories σ_{t+} equal $\{\emptyset, \Omega\}$ for $0 \leq t < 1/2$ and equal $\{\emptyset, A, A^c, \Omega\}$ for $1/2 \leq t \leq 1$. They are already complete, so $\widehat{\sigma}_{t+} = \widehat{\sigma}_{t+} = \sigma_{t+}$. Now, proposition 4.5(c) could be applied. \square

5 Strong Markov Property

We now extend the strong Markov property (which was proved for discrete-time processes in section 8.6) to processes with stationary and independent increments.

Theorem 5.1 (Strong Markov property) Consider the stochastic process $X : (\Omega, \mathcal{A}, P) \rightarrow (D_{[0, \infty)}, \mathcal{D}_{[0, \infty)})$ adapted to right-continuous \mathcal{A}_t 's. Suppose that $X(0) = 0$, X has stationary and independent increments, and suppose that the increment $X(t+s) - X(t)$ is independent of \mathcal{A}_t for all $s \geq 0$. Let τ be an extended stopping time for the \mathcal{A}_t 's, and suppose $P(\tau < \infty) > 0$. For some $t \geq 0$ we define

$$(1) \quad Y(t) \equiv \begin{cases} X(\tau+t) - X(\tau) & \text{on } [\tau < \infty], \\ 0 & \text{on } [\tau = \infty]. \end{cases}$$

Then $Y : ([\tau < \infty] \cap \Omega, [\tau < \infty] \cap \mathcal{A}, P(\cdot | [\tau < \infty])) \rightarrow (D_{[0, \infty)}, \mathcal{D}_{[0, \infty)})$ and

$$(2) \quad P(Y \in F | [\tau < \infty]) = P(X \in F) \quad \text{for all } F \in \mathcal{D}_{[0, \infty)}.$$

Moreover, for all $F \in \mathcal{D}_{[0, \infty)}$ and for all $A \in \mathcal{A}_\tau$, we have

$$(3) \quad P([Y \in F] \cap A | [\tau < \infty]) = P([X \in F]) \times P(A | [\tau < \infty]).$$

Thus if $P(\tau < \infty) = 1$, then X and Y are equivalent processes and the process Y is independent of the σ -field \mathcal{A}_τ .

Proof. That $Y : (\Omega \cap [\tau < \infty], \mathcal{A} \cap [\tau < \infty], P(\cdot | [\tau < \infty])) \rightarrow (D_{[0, \infty)}, \mathcal{D}_{[0, \infty)})$ follows from proposition 12.4.3. This proposition and exercise 12.4.1 show that

$$(4) \quad \mathcal{A}'_t \equiv \mathcal{A}_{\tau+t} \text{ are } \nearrow \text{ and right continuous, with } Y \text{ adapted to the } \mathcal{A}'_t \text{'s.}$$

Case 1. Suppose the finite part of the range of τ is a countable subset $\{s_1, s_2, \dots\}$ of $[0, \infty)$. Let $t_1, \dots, t_m \geq 0$, let B_1, \dots, B_m be Borel subsets of the real line, and let $A \in \mathcal{A}_\tau$. Then

$$\begin{aligned} & P([Y(t_1) \in B_1, \dots, Y(t_m) \in B_m] \cap A \cap [\tau < \infty]) \\ &= \sum_k P([Y(t_1) \in B_1, \dots] \cap A \cap [\tau = s_k]) \\ &= \sum_k P([X(t_1 + s_k) - X(s_k) \in B_1, \dots] \cap A \cap [\tau = s_k]) \\ &= \sum_k P(X(t_1 + s_k) - X(s_k) \in B_1, \dots) P(A \cap [\tau = s_k]) \\ &= P(X(t_1) \in B_1, \dots) \sum_k P(A \cap [\tau = s_k]) \end{aligned}$$

$$(a) \quad = P(X(t_1) \in B_1, \dots, X(t_m) \in B_m) P(A \cap [\tau < \infty]),$$

where the third equality holds as $A \cap [\tau = s_k] = (A \cap [\tau \leq s_k]) \cap [\tau = s_k]$ is in \mathcal{A}_{s_k} , and is thus independent of the other event by the independent increments of X .

Putting $A = [\tau < \infty]$ in (a) yields

$$(b) \quad \begin{aligned} & P(Y(t_1) \in B_1, \dots, Y(t_m) \in B_m | [\tau < \infty]) \\ &= P(X(t_1) \in B_1, \dots, X(t_m) \in B_m); \end{aligned}$$

substituting (b) into (a) and dividing by $P(\tau < \infty)$ yields

$$(c) \quad \begin{aligned} & P([Y(t_1) \in B_1, \dots, Y(t_m) \in B_m] \cap A | [\tau < \infty]) \\ &= P(Y(t_1) \in B_1, \dots, Y(t_m) \in B_m | [\tau < \infty]) P(A | [\tau < \infty]). \end{aligned}$$

Thus (b) and (c) hold for the class \mathcal{G} of sets of the form $[Y(t_1) \in B_1, \dots, Y(t_m) \in B_m]$ and for all sets A in \mathcal{A}_τ . Since \mathcal{G} generates $Y^{-1}(\mathcal{D}_{[0, \infty)})$, equation (b) implies (2). Since \mathcal{G} is also closed under finite intersections (that is, it is a $\bar{\pi}$ -system), (c) and proposition 7.1.1 imply the truth of (3).

Case 2. Now consider a general stopping time τ . For $n \geq 1$, define

$$(d) \quad \tau_n \equiv \begin{cases} k/n & \text{for } (k-1)/n < \tau \leq k/n \text{ and } k \geq 1, \\ 1/n & \text{for } \tau = 0, \\ \infty & \text{for } \tau = \infty. \end{cases}$$

Note that $\tau_n(\omega) \searrow \tau(\omega)$ for $\omega \in [\tau < \infty]$. For $k/n \leq t < (k+1)/n$ we have

$$[\tau_n \leq t] = [\tau \leq k/n] \in \mathcal{A}_{k/n} \subset \mathcal{A}_t$$

(so that τ_n is a stopping time), and also for A in \mathcal{A}_τ that

$$A \cap [\tau_n \leq t] = A \cap [\tau \leq k/n] \in \mathcal{A}_{k/n} \subset \mathcal{A}_t$$

(so that $\mathcal{A}_\tau \subset \mathcal{A}_{\tau_n}$). Define

$$(e) \quad Y_n(t) = X(\tau_n + t) - X(\tau_n) \quad \text{on } [\tau_n < \infty] = [\tau < \infty],$$

and let it equal 0 elsewhere. By case 1 results (b) and (c), both

$$(f) \quad P(Y_n \in F | [\tau < \infty]) = P(X \in F) \quad \text{and}$$

$$(g) \quad P([Y_n \in F] \cap A | [\tau < \infty]) = P(Y_n \in F | [\tau < \infty]) P(A | [\tau < \infty])$$

hold for all F in $\mathcal{D}_{[0, \infty)}$ and all A in \mathcal{A}_τ (recall that $\mathcal{A}_\tau \subset \mathcal{A}_{\tau_n}$ as shown above, and $[\tau < \infty] = [\tau_n < \infty]$). Let (r_1, \dots, r_m) denote any continuity point of the joint df of the finite dimensional random vector $(Y(t_1), \dots, Y(t_m))$, and define

$$(h) \quad \begin{aligned} G_n &\equiv [Y_n(t_1) < r_1, \dots, Y_n(t_m) < r_m, \tau < \infty], \\ G &\equiv [Y(t_1) < r_1, \dots, Y(t_m) < r_m, \tau < \infty], \\ G^* &\equiv [Y(t_1) \leq r_1, \dots, Y(t_m) \leq r_m, \tau < \infty], \\ H &\equiv [X(t_1) < r_1, \dots, X(t_m) < r_m]. \end{aligned}$$

By the right continuity of the sample paths, $Y_n(t) \rightarrow Y(t)$ for every t and every ω in $[\tau < \infty]$; thus

$$(i) \quad G \subset \underline{\lim} G_n \subset \overline{\lim} G_n \subset G^*$$

Thus

$$\begin{aligned} P(G | \tau < \infty) &\leq P(\underline{\lim} G_n | \tau < \infty) \leq \underline{\lim} P(G_n | \tau < \infty) \quad \text{by (i), then DCT} \\ &= P(H) = \overline{\lim} P(G_n | \tau < \infty) \quad \text{by using (f) twice} \\ &\leq P(\overline{\lim} G_n | \tau < \infty) \leq P(G^* | \tau < \infty) \quad \text{by the DCT and (i)} \\ &\leq P(G | \tau < \infty) + \sum_{i=1}^m P(Y(t_i) = r_i | \tau < \infty) \end{aligned}$$

$$(j) \quad = P(G|\tau < \infty),$$

since (r_1, \dots, r_m) is a continuity point. Thus (j) implies

$$(k) \quad P(G|\tau < \infty) = P(H),$$

and this is sufficient to imply (2). Likewise, for $A \in \mathcal{A}_\tau \subset \mathcal{A}_{\tau_n}$,

$$\begin{aligned} P(G \cap A | [\tau < \infty]) &\leq P(\underline{\lim} G_n \cap A | \tau < \infty) && \text{by (i)} \\ &\leq \underline{\lim} P(G_n \cap A | \tau < \infty) && \text{by the DCT} \\ &= \underline{\lim} P(G_n | \tau < \infty) P(A | \tau < \infty) && \text{by (c), with } [\tau < \infty] = [\tau_n < \infty] \\ &= P(G | \tau < \infty) P(A | \tau < \infty) && \text{by (j)} \\ &= \overline{\lim} P(G_n | \tau < \infty) P(A | \tau < \infty) && \text{by (j)} \\ &= \overline{\lim} P(G_n \cap A | \tau < \infty) && \text{by (c), with } [\tau < \infty] = [\tau_n < \infty] \\ &\leq P(\overline{\lim} G_n \cap A | \tau < \infty) \leq P(G^* \cap A | \tau < \infty) && \text{by the DCT, then (i)} \\ &\leq P(G \cap A | \tau < \infty) + \sum_{i=1}^m P(Y(t_i) = r_i | \tau < \infty) \end{aligned}$$

$$(l) \quad = P(G \cap A | \tau < \infty),$$

since (r_1, \dots, r_m) is a continuity point. Thus (l) implies

$$(m) \quad P(G \cap A | \tau < \infty) = P(G | \tau < \infty) P(A | \tau < \infty);$$

and using proposition 7.1.1 again, we see that this is sufficient to imply (3).

The final statement is immediate, since when $P(\tau < \infty) = 1$ we must have $P(A | \tau < \infty) = P(A)$ for all $A \in \mathcal{A}$. \square