

**University of Washington  
Department of Chemistry  
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Lecture 16: The Liouville Equation

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Text Reading: Ch. 7.2, 21.7

A. The Liouville Equation

- The function  $f(X,t)$  will be the distribution function in phase space.  $X$  denotes the set of coordinates and momenta that characterize the system at a point in phase space. We can express a conservation equation for  $f(X,t)$  that is analogous to Fick's Law of Diffusion...

$$\frac{\partial f}{\partial t} = -\nabla_X \cdot (V_X f) \quad (16.1)$$

where  $\nabla_X \rightarrow \frac{\partial}{\partial X} \rightarrow \left( \frac{\partial}{\partial q}, \frac{\partial}{\partial p} \right)$  and  $V_X \rightarrow \left( \frac{\partial q}{\partial t}, \frac{\partial p}{\partial t} \right)$

- We can also write (16.1) as

$$\frac{\partial f}{\partial t} = -\frac{\partial}{\partial q} \cdot \left( \frac{dq}{dt} f \right) - \frac{\partial}{\partial p} \cdot \left( \frac{dp}{dt} f \right) \quad (16.2)$$

- Recall Hamilton's canonical equations of motion:

$$\left. \begin{aligned} \dot{q}_i &= \frac{dq_i}{dt} = \frac{\partial H(q_i, p_i)}{\partial p_i} \\ \dot{p}_i &= \frac{dp_i}{dt} = -\frac{\partial H(q_i, p_i)}{\partial q_i} \end{aligned} \right\} i=1, 2, \dots, 3N \quad (16.3)$$

where  $H$  is the classical Hamiltonian

$$H = \sum_i \frac{p_i^2}{2m_i} + U(q_1 \dots q_N) \quad (16.4)$$

- We now substitute Hamilton's equations into (16.4) which directly yields the Liouville equation

$$\frac{\partial f}{\partial t} = -\frac{\partial H}{\partial p} \cdot \frac{\partial f}{\partial q} + \frac{\partial H}{\partial q} \cdot \frac{\partial f}{\partial p} = -L f \quad (16.5)$$

$$\text{where } L = \frac{\partial H}{\partial p} \cdot \frac{\partial}{\partial q} - \frac{\partial H}{\partial q} \cdot \frac{\partial}{\partial p}$$

- (16.5) has the formal solution

$$f(X, t) = e^{-tL} f(X, 0) \quad (16.6)$$

- L is called the Liouvillian operator and  $\exp(-tL)$  is called the time displacement operator.
- (16.5) is also frequently written using Poisson bracket notation:

$$\frac{\partial f}{\partial t} = -\frac{\partial H}{\partial p} \cdot \frac{\partial f}{\partial q} + \frac{\partial H}{\partial q} \cdot \frac{\partial f}{\partial p} = -\{H, f\} = -Lf \quad (17.5)'$$

$$\text{where } \{H, f\} = L = \frac{\partial H}{\partial p} \cdot \frac{\partial f}{\partial q} - \frac{\partial H}{\partial q} \cdot \frac{\partial f}{\partial p}$$

- The Liouvillian is used to determine the time evolution of any dynamical variable, which is any function A of the phase variables X(t):

$$\begin{aligned} \frac{\partial A}{\partial t} &= \left(\frac{\partial q}{\partial t}\right) \left(\frac{\partial A}{\partial q}\right) + \left(\frac{\partial p}{\partial t}\right) \left(\frac{\partial A}{\partial p}\right) \\ &= \left(\frac{\partial H}{\partial p}\right) \left(\frac{\partial A}{\partial q}\right) - \left(\frac{\partial H}{\partial q}\right) \left(\frac{\partial A}{\partial p}\right) = \{H, A\} = LA \end{aligned} \quad (16.7)$$

- Note...some texts, introduce a factor of i into the Liouvillian, thus producing a Liouville equation of the form

$$i \frac{\partial f}{\partial t} = Lf \Rightarrow f(X, t) = e^{-itL} f(X, 0) \quad (16.8)$$

- Note the sign difference between the equations for f(t) and A(t)

$$f(t) = e^{-Lt} f(0) \text{ and } A(t) = e^{Lt} A \quad (16.9)$$

which is a consequence of the equations of motion

$$\frac{\partial f}{\partial t} = -Lf = -\{H, f\} \text{ and } \frac{\partial A}{\partial t} = Lf = \{H, A\} \quad (16.10)$$

- These equations are analogous to the Schroedinger and Heisenberg equations of quantum mechanics.

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## B. The Linear Response Function

- Assume the (classical) Hamiltonian of the system has the form

$$H = H_0 - A(X, t) F(t) \quad (16.11)$$

where A is a function of the coordinates of the system and F(t) is the applied force.  $H_0$  is the Hamiltonian of the unperturbed system.

- Suppose f is the ensemble distribution function. In classical mechanics f obeys the Liouville equation

$$\begin{aligned} \frac{\partial f}{\partial t} &= -Lf = \{f, H_0 - A(X, t) F(t)\} \\ &= \{f, H_0\} - \{f, A(X, t) F(t)\} = -L_0 f - \{f, A(X, t) F(t)\} \end{aligned} \quad (16.12)$$

$$\therefore \frac{\partial f}{\partial t} + L_0 f = \{A(X, t) F(t), f\}$$

- Equation (16.12) has the solution:

$$f(t) = e^{-tL_0} \left[ f_0 + \int_{-\infty}^t e^{t'L_0} \{A(X, t'), f(t')\} F(t') dt' \right] \quad (16.13)$$

$$f(t) = f_0 + \int_{-\infty}^t e^{-(t-t')L_0} \{A(X, t'), f(t')\} F(t') dt'$$

where  $f_0$  is the equilibrium distribution of the ensemble. Note in deriving (16.13) we used the fact that...

$$e^{-L_0 t} f_0 = f_0 \quad (16.14)$$

- We can use (16.13) to calculate the ensemble response of a system property B to the applied force

$$\int dX f(t) B = \int dX f_0 B + \int_{-\infty}^t dt' F(t') \int dX B e^{-(t-t')L_0} \{A(X, t'), f(t')\} \quad (16.15)$$

where  $dX = dq_1 \dots dp_N$ .

- Now (16.15) may be rewritten as

$$\langle B(t) \rangle = \langle B \rangle_0 + \int_{-\infty}^t dt' F(t') \int dX B e^{-(t-t')L_0} \{A(X, t'), f(t')\} \quad (16.16)$$

$$\text{or } \dots \Delta B(t) = \langle B(t) \rangle - \langle B \rangle_0 = \int_{-\infty}^t dt' F(t') \int dX B e^{-(t-t')L_0} \{A(X, t'), f(t')\}$$

- If we assume the applied force is small, the displacement from equilibrium is also small so  $f(t) \approx f_0$  and (16.14) becomes

$$\begin{aligned} \Delta B(t) &= \int_{-\infty}^t dt' F(t') \int dX B e^{-(t-t')L} \{A, f\} \\ &= \int_{-\infty}^t dt' F(t') \int dX e^{(t-t')L} B \{A, f\} \\ &\approx \int_{-\infty}^t dt' F(t') \int dX B(t-t') \{A, f_0\} \end{aligned} \quad (16.17)$$

- The second step in (16.17) is a result of the unitary nature of the time displacement operator. That is

$$\int dX B e^{-(t-t')L} \{A, f\} = \int dX \left( e^{-(t-t')L} \right)^\dagger B \{A, f\} \quad (16.18)$$

where  $U^\dagger$  is the adjoint of  $U$ . However the time displacement operator is unitary which by definition means  $U^\dagger = U^{-1}$ , which proves the second step of 16.17.

- After an integration by parts, (16.17) can be rearranged to

$$\Delta B(t) \approx \int_{-\infty}^t dt' F(t') \int dX f_0 \{B(t-t'), A(t')\} = \int_{-\infty}^t dt' F(t') \phi_{BA}(t-t') \quad (16.19)$$

where

$$\phi_{BA}(t) = \int dX f_0 \{B(t), A(0)\} = \langle \{B(t), A(0)\} \rangle \quad (16.20)$$

$\phi_{BA}(t)$  is the linear response or after-effect function. The after-effect function is causal in the sense that  $\phi_{BA}(t-t') = 0$  if  $t < t'$ . This means the response of the system cannot precede in time the application of the perturbing field F.