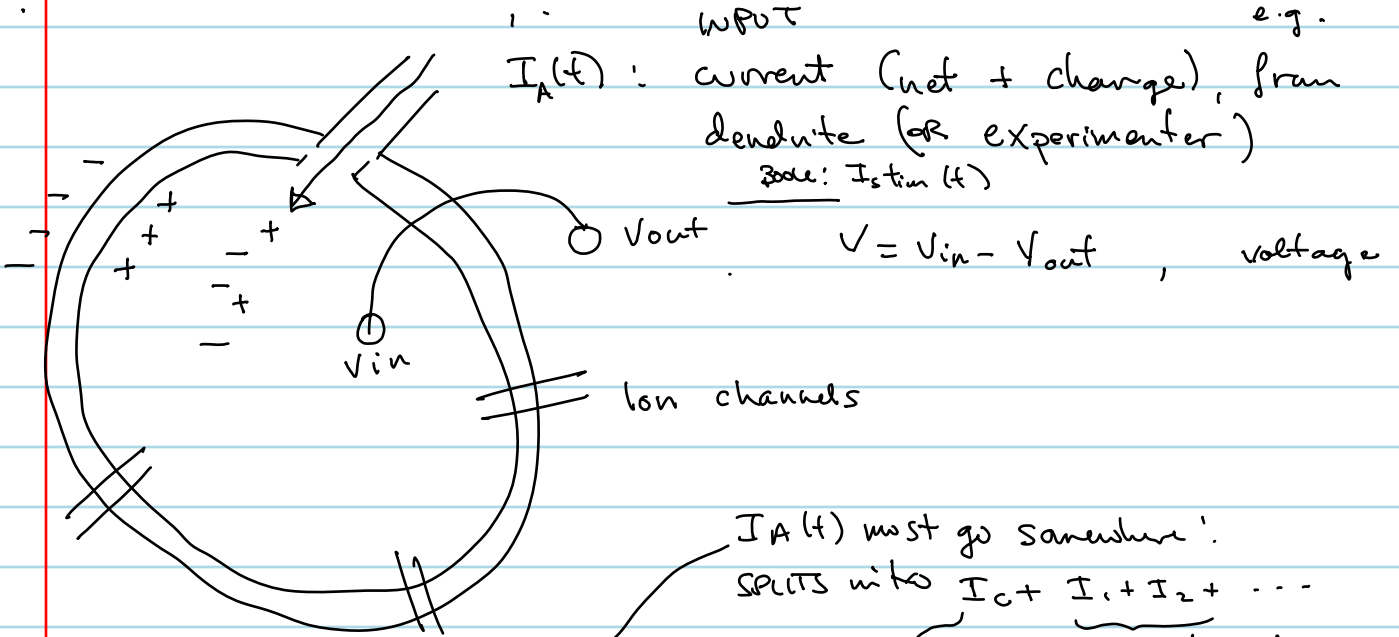


Equiv. circuit

model of single neuron dynamics

①



$I_A(t)$  must go somewhere!

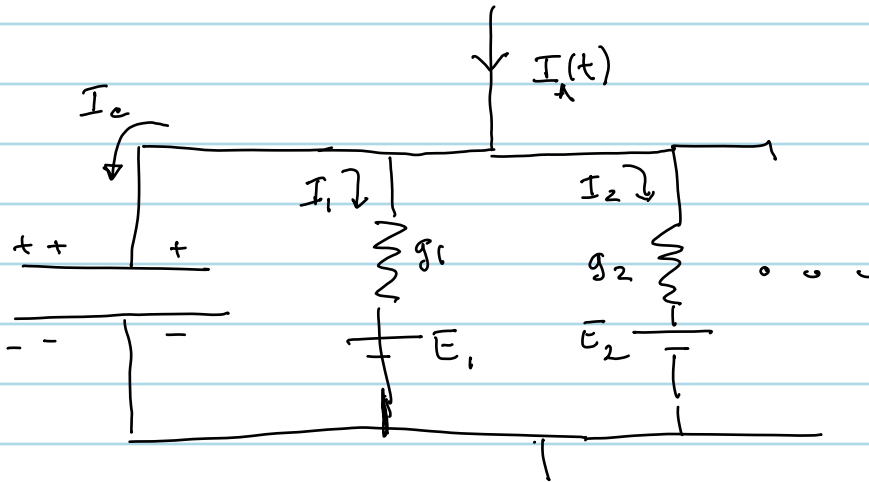
SPLITS into  $I_c + I_1 + I_2 + \dots$

Capacitive current

ion channel currents

②

C



IN

OUT

CAPACITOR:

$$Q = CV$$

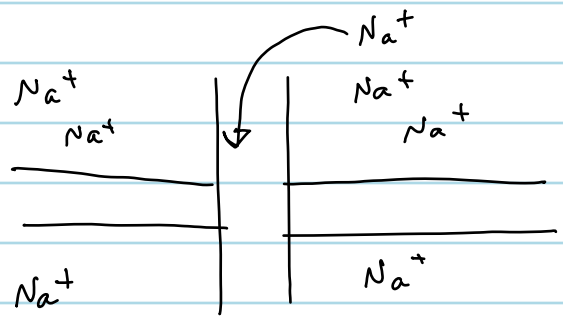
$$\frac{dQ}{dt} = I_C$$

Q: Charge on "top" wall / plate  
 C: Capacitance  
 Current: Change in charge / unit time

$$\Rightarrow I_C = \frac{d}{dt}(CV) = C \frac{dV}{dt}$$

Ohm's law

② Ion channel:  $I_i = g_i (V - E_i)$



• passes specific type or types of ions only, eg  $Na^+$

• conductance  $g = \frac{1}{R}$

"how open it is"

• Two "forces" drive current:

(1) Diffusion: is there more  $Na^+$  inside or outside

(2) Voltage  $V$ , which pushes on charges

$E_i$  is "reversal" potential where these balance.

• Repeat for other channels. Pass different ions  $\rightarrow$  different  $E_k$

•  $I_A(t) = I_C(t) + \sum_k I_k(t)$

$$I_A(t) = C \frac{dV}{dt} + \sum_k g_k (V - E_k) \quad \dots \text{so} \dots$$

(1)  $C \frac{dV}{dt} = I_A(t) + \sum_k g_k (E_k - V)$

- Passive Membrane / "RC Circuit" form of (1).

Combine all currents  $k$  that have  $g_k$  conductances that are approximately constant over time  $\rightarrow$

"net" current

$$C \frac{dV}{dt} = I_A(t) + g_L (E_L - V) \dots$$

AND ignore other "spike generating," etc currents.

(Formally, redefine  $V \rightarrow V - E_L$ )

- For convenience, set  $E_L = 0$ .

$\rightarrow$  RC circuit eq<sup>s</sup> below

$$C \frac{dV}{dt} = I_A(t) - gV = I_A(t) - \frac{1}{R} V$$

$$\frac{dV}{dt} = -\frac{1}{RC} V + \frac{I_A(t)}{C}$$

• Differential equations + linear systems.

$$\frac{dy}{dt} = f(y, t)$$

[...rule / rate of change...]

$$\frac{y(t + \Delta t) - y(t)}{\Delta t} = f(y, t)$$

$$y(t + \Delta t) = y(t) + f(y, t) \cdot \Delta t \quad ; \quad y(0) = y_0.$$

Euler method! Works for ANY f(y, t).  
(often only option...)

• Example:

$$\frac{dv}{dt} = v \quad ; \quad v(0) = v_0 = 1.$$

Solution:  $v(t) = v_0 e^t$  (check).

Euler - illustrate v. m

(use  $\Delta t = 0.1, 0.001 + \text{zoom}$ )

Accuracy?

Each timestep, make local error =  $k \cdot \Delta t^2$

→ Challenge:  
Use T-series  
to show  
this...

Global error:  $\frac{T_{\max}}{\Delta t} \cdot k \Delta t^2 = k_2 \cdot \underline{\underline{\Delta t}}$

↓  
# timesteps

" $\downarrow^{\text{ST}}$  order accurate  
method"

(R-K methods - like ode45 - get  $k \Delta t^4$  - explain why important)