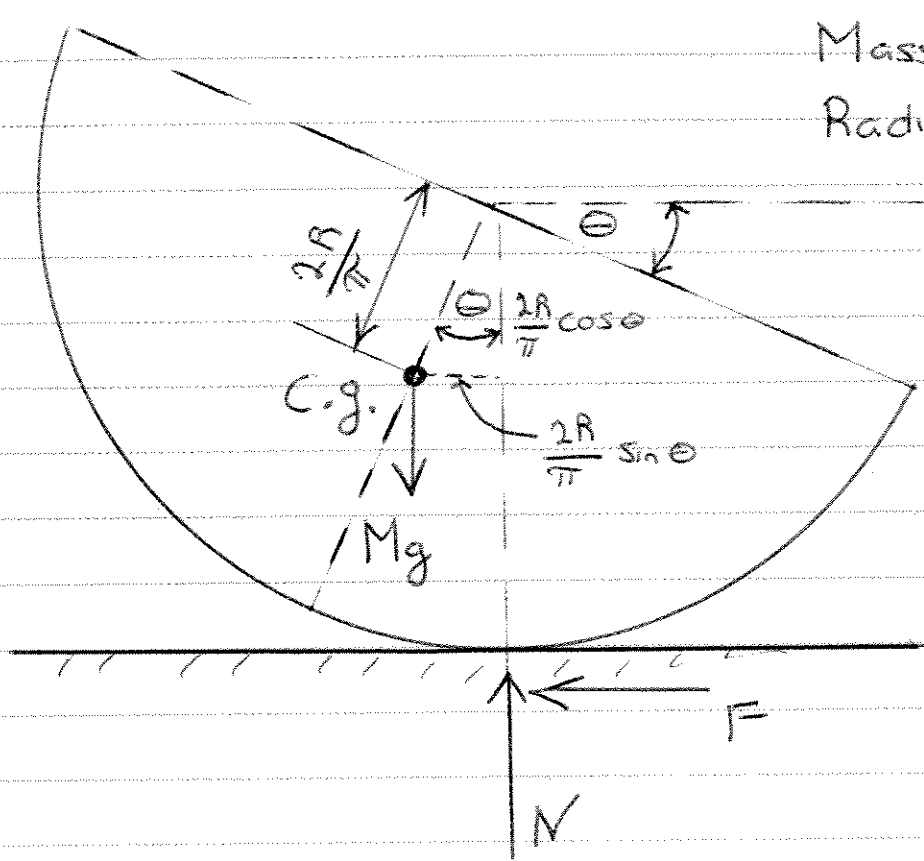


EOM Example

Rocking of Semi circular Thin Plate

1/3



Mass = M

Radius = R

Using Linear & Angular Momentum Relationships

$$1) F_{ext_x} = -F = M a_x = M \left(\ddot{\theta} \left(R - \frac{2R}{\pi} \cos \theta \right) \right)$$

$$2) F_{ext_y} = N - Mg = M a_y = M \left(\ddot{\theta} \frac{2R}{\pi} \sin \theta \right)$$

$$3) M_{cm} = F \left(R - \frac{2R}{\pi} \cos \theta \right) - N \left(\frac{2R \sin \theta}{\pi} \right) = I_{zz} \ddot{\theta}$$

Where

$$I_{zz_{cm}} = I_{center \text{ of circle}} - M \bar{y}^2$$

$$= MR^2 - M \left(\frac{2R}{\pi} \right)^2 = MR^2 \left(1 - \frac{4}{\pi^2} \right)$$

Substitute ① & ② into ③

$$- M \ddot{\theta} \left(R - \frac{2R}{\pi} \cos \theta \right) \left(R - \frac{2R}{\pi} \cos \theta \right)$$

$$- \underbrace{\left(M \ddot{\theta} \frac{2R}{\pi} \sin \theta + Mg \right)}_N \left(\frac{2R \sin \theta}{\pi} \right) = MR^2 \left(1 - \frac{4}{\pi^2} \right) \ddot{\theta}$$

$$\ddot{\theta} R^2 \left[-1 + \frac{4}{\pi} \cos \theta - \frac{4}{\pi^2} \cos^2 \theta - \frac{4}{\pi^2} \sin^2 \theta - 1 + \frac{4}{\pi^2} \right] = \frac{-2}{\pi} g R \sin \theta$$

$$\ddot{\theta} R^2 \left[-2 + \frac{4}{\pi} \cos \theta \right] = \frac{-2gR \sin \theta}{\pi}$$

$$\sin \theta + \left[\pi - 2 \cos \theta \right] \frac{R}{g} \ddot{\theta} = 0$$

For small θ :

$$\theta + \left[\pi - 2 \right] \frac{R}{g} \ddot{\theta} = 0$$

Work & Kinetic Energy

Consider system at ① ($\theta = 0^\circ$)
and ② $\theta = \theta(+)$

$$W_{1 \rightarrow 2} = -Mg \left[\frac{2R}{\pi} - \frac{2R}{\pi} \cos \theta \right] = -\frac{2MgR}{\pi} (1 - \cos \theta)$$

@ ①, $T_1 = KE_1$

$$\begin{aligned} \text{@ ② } T_2 &= \frac{1}{2} M v_{cm}^2 + \frac{1}{2} I_{zz} \dot{\theta}^2 \\ &= \frac{1}{2} M \dot{\theta}^2 \left[\left(\frac{2R}{\pi} \sin \theta \right)^2 + \left(R - \frac{2R}{\pi} \cos \theta \right)^2 \right] + \frac{1}{2} MR^2 \left(1 - \frac{4}{\pi^2} \right) \dot{\theta}^2 \\ &= \frac{1}{2} M \dot{\theta}^2 \left[\frac{4R^2}{\pi^2} + R^2 - \frac{4R^2}{\pi} \cos \theta \right] + \frac{1}{2} MR^2 \left(1 - \frac{4}{\pi^2} \right) \dot{\theta}^2 \end{aligned}$$

$$\begin{aligned} \circ W_{1 \rightarrow 2} &= T_2 - T_1 \\ -\frac{2MgR}{\pi} (1 - \cos \theta) &= \frac{1}{2} M \overbrace{\left[\left(R - \frac{2R}{\pi} \right) \dot{\theta} \right]^2}^{\text{small } \theta} + \frac{1}{2} MR^2 \left(1 - \frac{4}{\pi^2} \right) \dot{\theta}^2 - KE_1 \end{aligned}$$

Take derivatives respect to time.

$$-\frac{2MgR}{\pi} (\sin \theta) \dot{\theta} = M \left(R - \frac{2R}{\pi} \right)^2 \dot{\theta} \ddot{\theta} + MR^2 \left(1 - \frac{4}{\pi^2} \right) \dot{\theta} \ddot{\theta} - 0$$

$$0 = \left[\frac{2MgR}{\pi} \right] \sin \theta + M \left[2R^2 - \frac{4R^2}{\pi} \right] \ddot{\theta}$$

Let θ be small.

$$\boxed{\ddot{\theta} = -\frac{R}{g} [\pi - 2] \ddot{\theta}} \leftarrow \text{Same as before.}$$