

Wavelet-Based Bootstrapping for Non-Gaussian Time Series

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overheads for talk available at

<http://faculty.washington.edu/dbp/talks.html>

Overview

- question of interest: how can we assess the sampling variability in statistics computed from a time series X_0, X_1, \dots, X_{N-1} ?
- start with some background on bootstrapping
- review parametric and block bootstrapping (two approaches for handling correlated time series)
- review previously proposed wavelet-based approach to bootstrapping (Percival, Sardy and Davison, 2001)
- describe a new wavelet-based approach that uses ‘trees’ for resampling and is potentially useful for non-Gaussian time series
- demonstrate methodology on time series related to BMW stock
- conclude with some remarks

Motivating Question

- let $\mathbf{X} = [X_0, \dots, X_{N-1}]^T$ be a portion of a stationary process with autocorrelation sequence (ACS)

$$\rho_\tau = \frac{s_\tau}{s_0}, \quad \text{where } s_\tau = \text{cov} \{X_t, X_{t+\tau}\} \text{ and } s_0 = \text{var} \{X_t\}$$

- given a time series, we can estimate its ACS at $\tau = 1$ using

$$\hat{\rho}_1 = \frac{\sum_{t=0}^{N-2} (X_t - \bar{X})(X_{t+1} - \bar{X})}{\sum_{t=0}^{N-1} (X_t - \bar{X})^2}, \quad \text{where } \bar{X} = \frac{1}{N} \sum_{t=0}^{N-1} X_t$$

- Q: given the amount of data N we have, how close can we expect $\hat{\rho}_1$ to be to the true unknown ρ_1 ?
- i.e., how can we assess the sampling variability in $\hat{\rho}_1$?

Classic Approach – Large Sample Theory

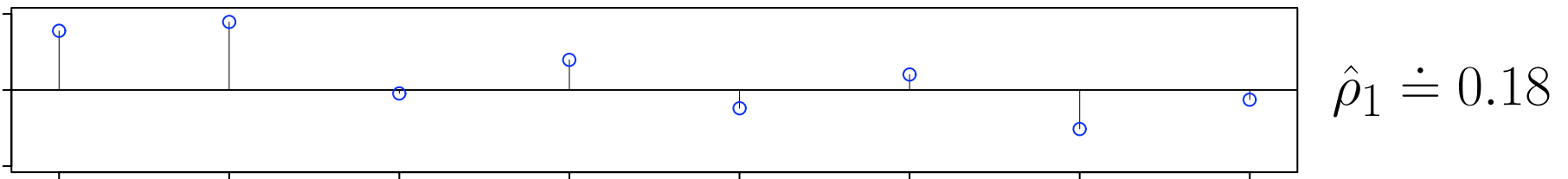
- let $\mathcal{N}(\mu, \sigma^2)$ denote a Gaussian (normal) random variable (RV) with mean μ and variance σ^2
- under suitable conditions (see, e.g., Fuller, 1996), $\hat{\rho}_1$ has a distribution close to that of $\mathcal{N}(\rho_1, \sigma_N^2)$ as $N \rightarrow \infty$, where

$$\sigma_N^2 = \frac{1}{N} \sum_{\tau=-\infty}^{\infty} \left\{ \rho_\tau^2 (1 + 2\rho_1^2) + \rho_{\tau+1}\rho_{\tau-1} - 4\rho_1\rho_\tau\rho_{\tau-1} \right\}$$

- in practice, this result is unappealing because it requires
 - knowledge of theoretical ACS (including the unknown ρ_1 !)
 - ACS to damp down fast, ruling out some processes of interest
- while large sample theory has been worked out for $\hat{\rho}_1$ under certain conditions, similar theory for other statistics can be hard to come by

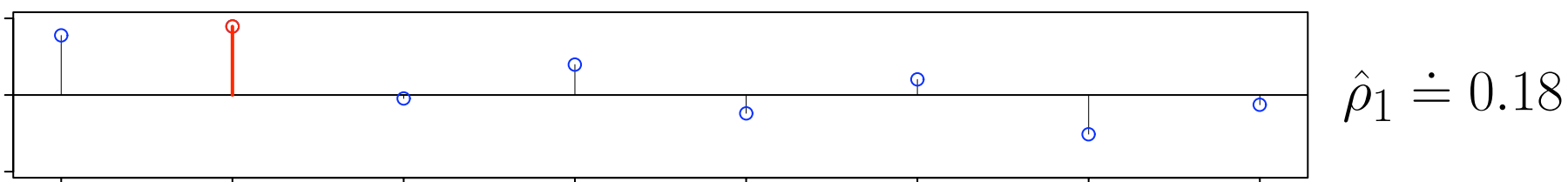
Alternative Approach – Bootstrapping: I

- if X_t 's were IID, we could apply 'bootstrapping' to assess the variability in $\hat{\rho}_1$, as follows
- consider a time series of length $N = 8$ that is a realization of a Gaussian white noise process ($\rho_1 = 0$):

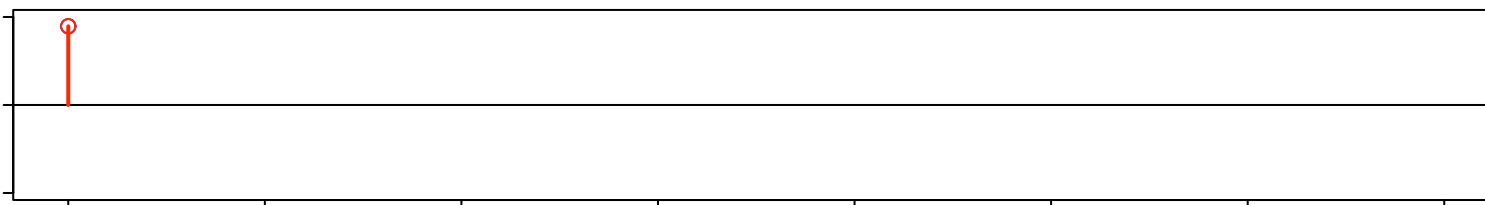


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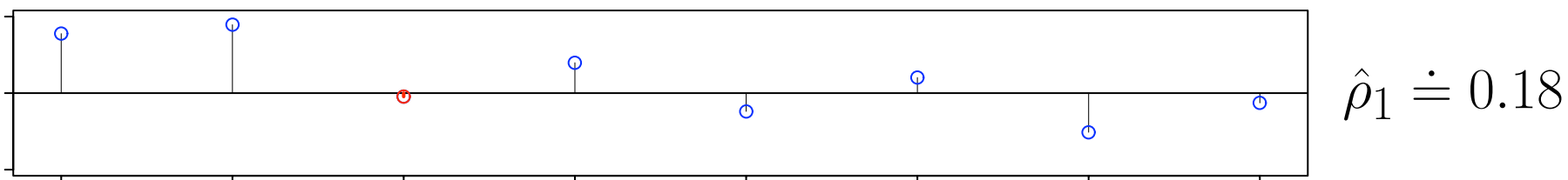


- generate new series by randomly sampling with replacement:

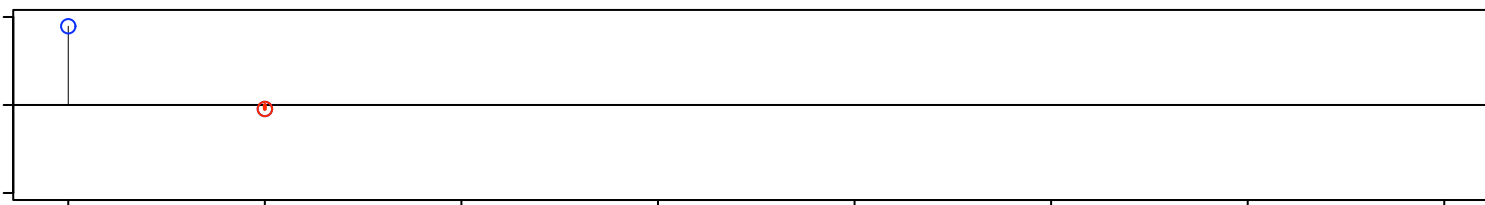


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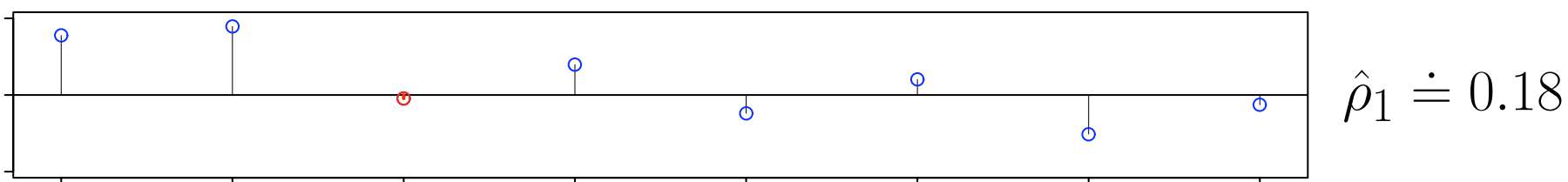


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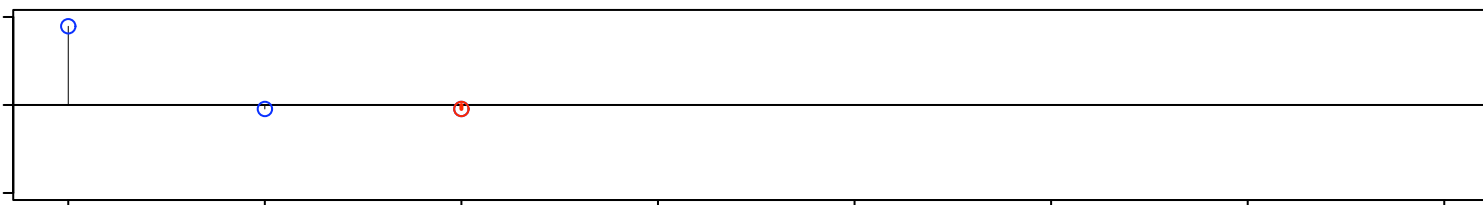


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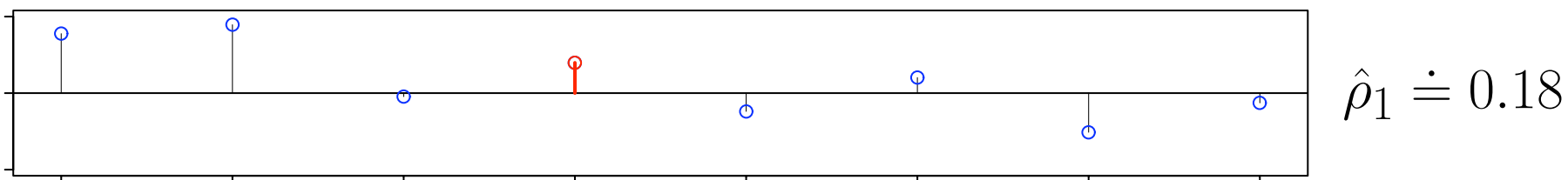


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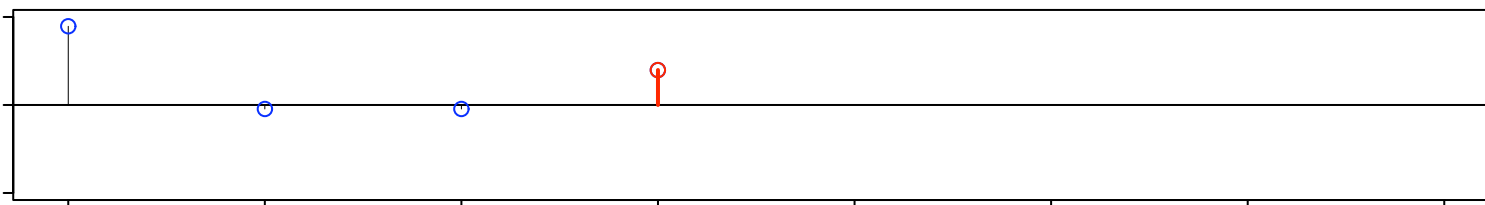


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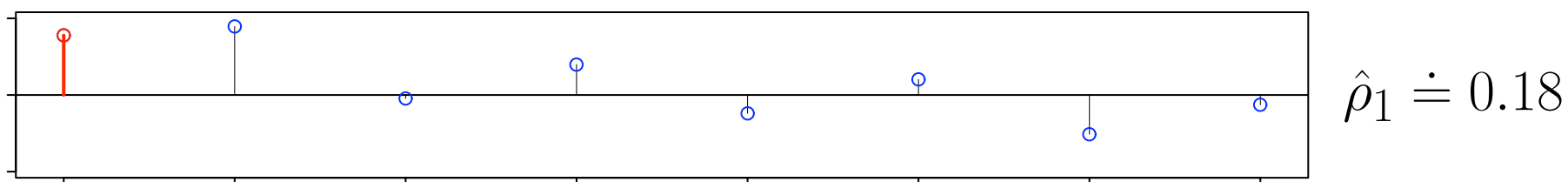


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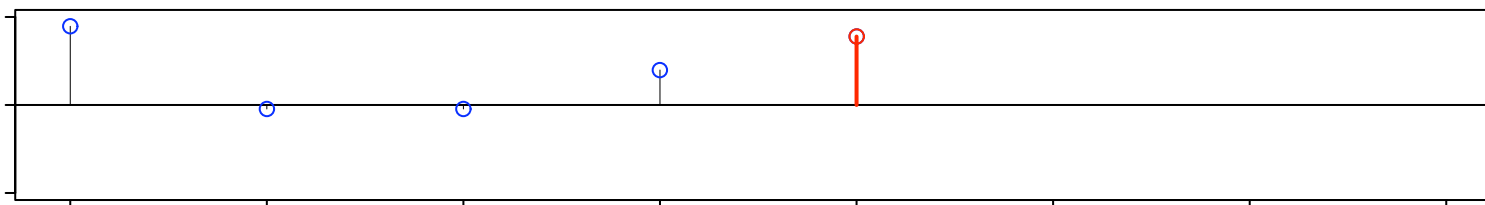


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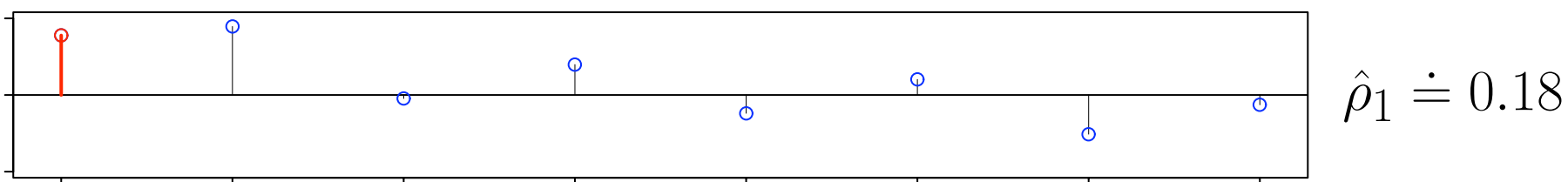


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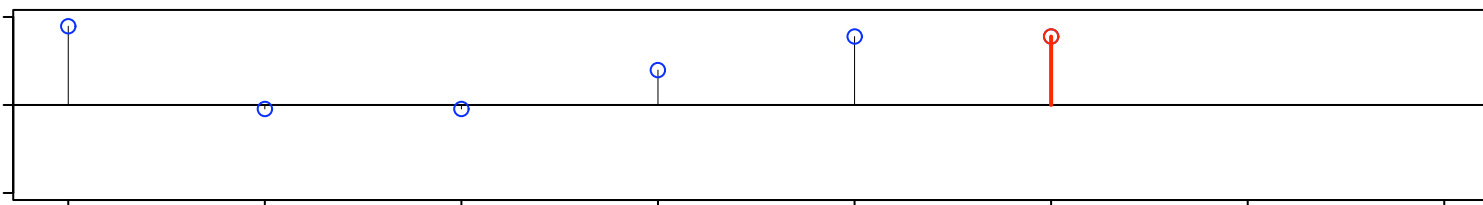


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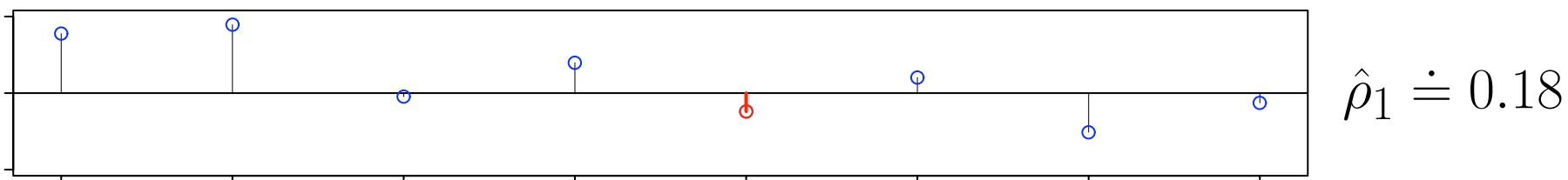


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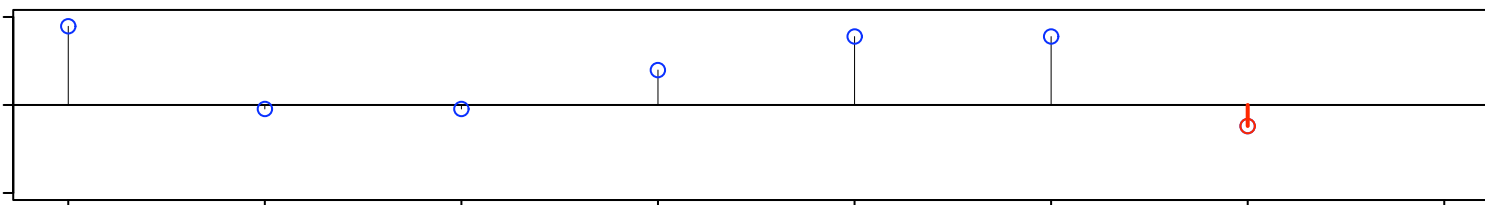


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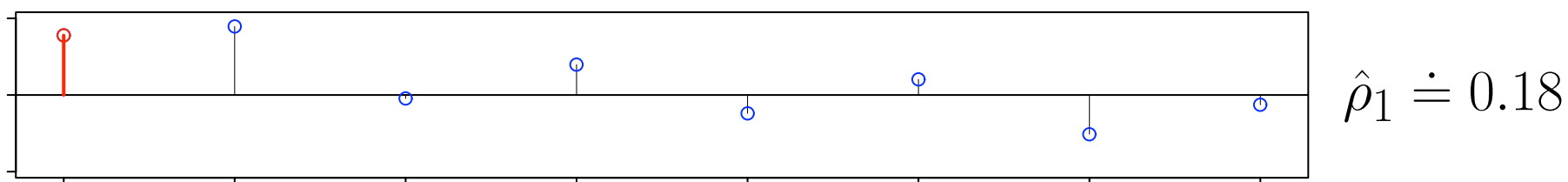


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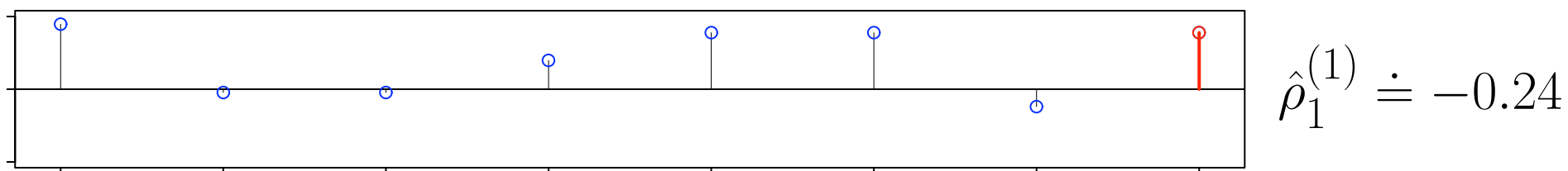


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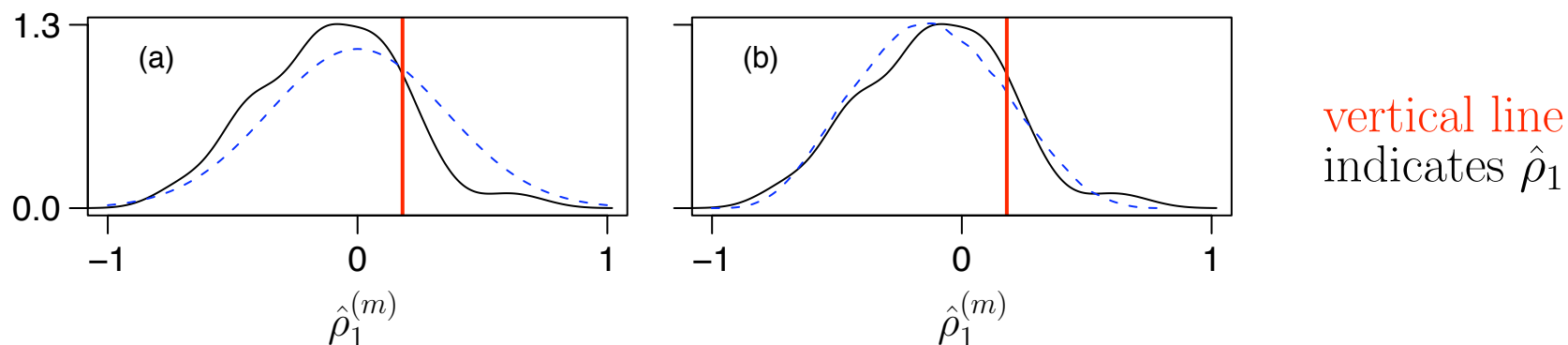


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Alternative Approach – Bootstrapping: II

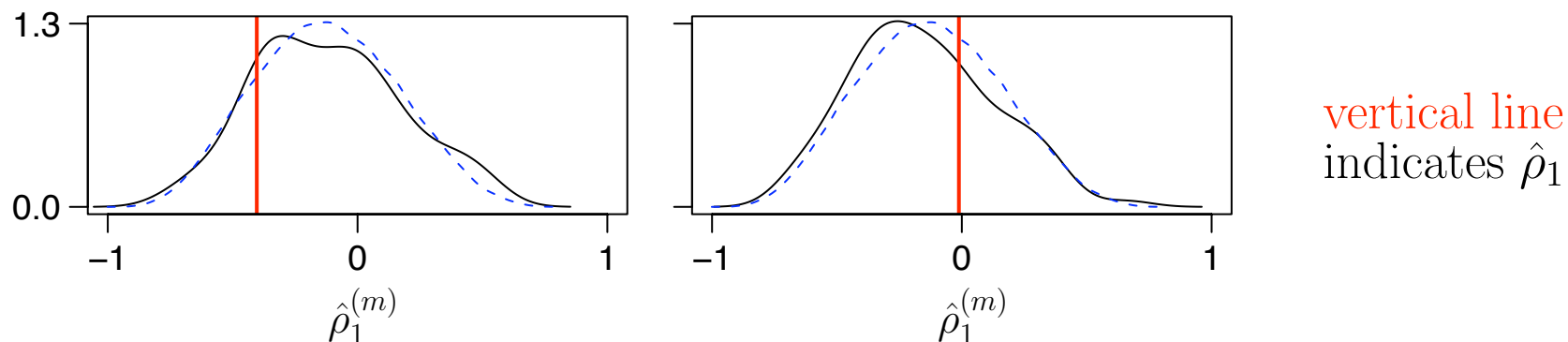
- repeat a large number of times M to get $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(M)}$
- plots shows estimated probability density function (PDF) for $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(100)}$, along with (a) PDF for $\mathcal{N}(0, \frac{1}{8})$ and (b) approximation to the true PDF for $\hat{\rho}_1$



- can regard sample distribution of $\{\hat{\rho}_1^{(m)}\}$ as an approximation to the unknown distribution of $\hat{\rho}_1$

Alternative Approach – Bootstrapping: III

- quality of approximation depends upon particular time series
- here are bootstrap approximations to PDF of $\hat{\rho}_1$ based upon two other time series of length $N = 8$, along with true PDF



- repeating the above for 50 time series yields 50 bootstrap PDFs
- summarize via sample means and standard deviations (SDs):

average of 50 sample means $\doteq -0.127$ (truth $\doteq -0.124$)

average of 50 sample SDs $\doteq 0.280$ (truth $\doteq 0.284$)

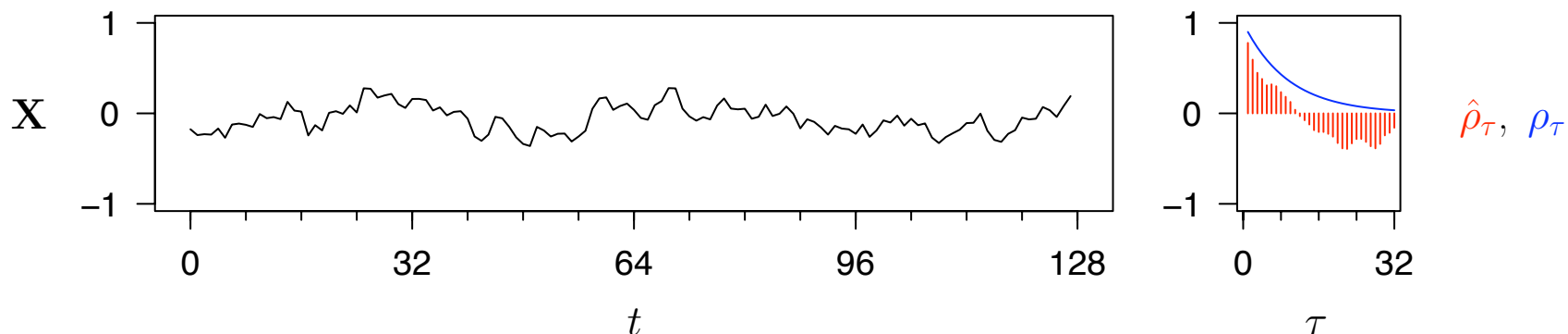
Bootstrapping Correlated Time Series: I

- key assumption: \mathbf{X} contains IID RVs
- if not true (as for most time series!), sample distribution of $\{\hat{\rho}_1^{(m)}\}$ can be a poor approximation to distribution of $\hat{\rho}_1$
- as an example, consider first order autoregressive (AR) process:

$$X_t = \phi X_{t-1} + \epsilon_t,$$

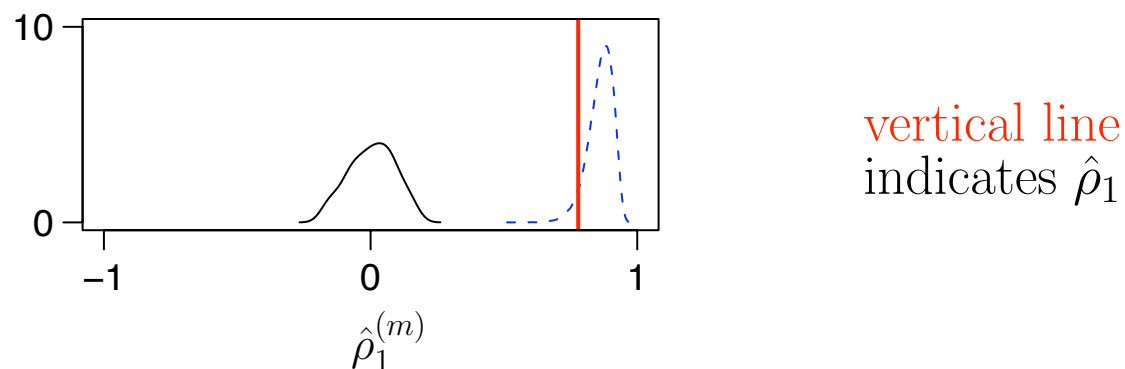
where $\phi = 0.9$ and $\{\epsilon_t\}$ is zero mean Gaussian white noise

- AR time series of length $N = 128$ with **sample** and **true** ACSs:



Bootstrapping Correlated Time Series: II

- use same procedure as before to get $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(100)}$
- bootstrap approximation to PDF of $\hat{\rho}_1$ along with true PDF:



- bootstrap approximation gets even worse as N increases
- to correct the problem caused by correlation in time series, can use specialized time- or frequency-domain bootstrapping (assuming true ACS damps downs sufficiently fast)

Parametric Bootstrapping: I

- one well-known time-domain bootstrapping scheme is the parametric (or residual) bootstrap
- suppose \mathbf{X} is a realization of AR process $X_t = \phi X_{t-1} + \epsilon_t$
- note that $\text{var} \{X_t\} = \text{var} \{\epsilon_t\} / (1 - \phi^2)$ and $\rho_\tau = \phi^{|\tau|}$
- in particular, $\rho_1 = \phi$, so can estimate ϕ using $\hat{\phi} = \hat{\rho}_1$
- since $\epsilon_t = X_t - \phi X_{t-1}$, can form residuals

$$r_t = X_t - \hat{\phi} X_{t-1}, \quad t = 1, \dots, N - 1,$$

with the idea that r_t will be a good approximation to ϵ_t

- let $r_0^{(1)}, r_1^{(1)}, \dots, r_{N-1}^{(1)}$ be a random sample from r_1, r_2, \dots, r_{N-1}
- let $X_0^{(1)} = r_0^{(1)} / (1 - \hat{\phi}^2)^{1/2}$ ('stationary initial condition')

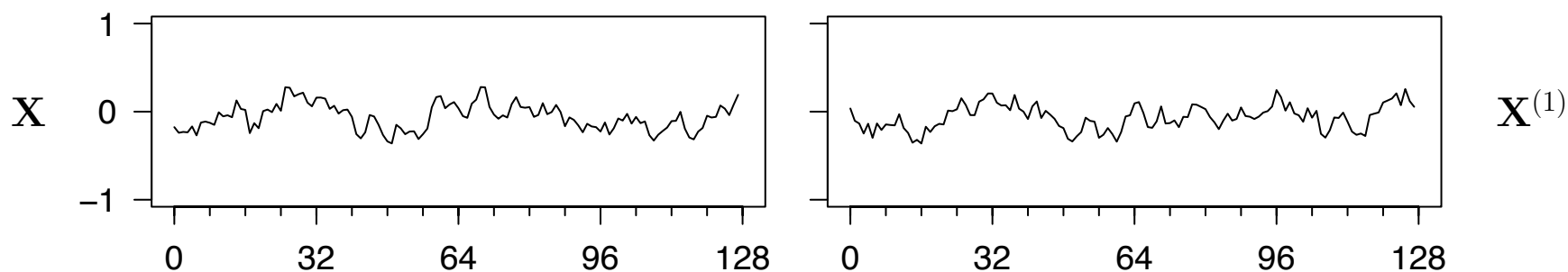
Parametric Bootstrapping: II

- form

$$X_t^{(1)} = \hat{\phi} X_{t-1}^{(1)} + r_t^{(1)}, \quad t = 1, \dots, N - 1,$$

yielding the bootstrapped time series $X_0^{(1)}, X_1^{(1)}, \dots, X_{N-1}^{(1)}$

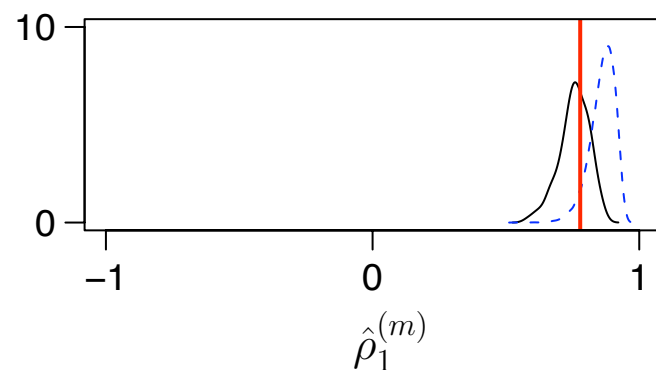
- AR time series (left-hand plot) and bootstrapped series (right):



- use bootstrapped series to compute $\hat{\rho}_1^{(1)}$
- repeat this procedure M times to get $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(M)}$

Parametric Bootstrapping: III

- bootstrap approximation to PDF of $\hat{\rho}_1$ along with true PDF:



vertical line
indicates $\hat{\rho}_1$

- repeating the above for 50 AR time series yields:

average of 50 sample means $\doteq 0.83$ (truth $\doteq 0.86$)

average of 50 sample SDs $\doteq 0.053$ (truth $\doteq 0.048$)

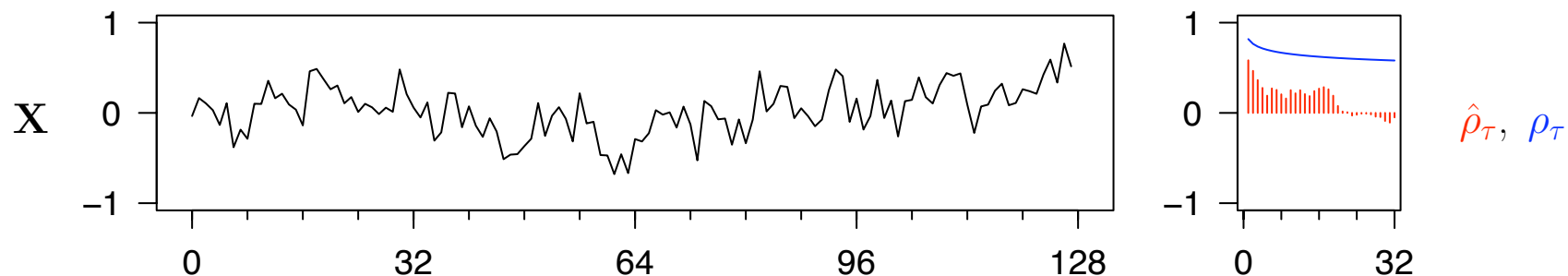
Parametric Bootstrapping: IV

- important assumption: \mathbf{X} generated by AR process
- to see what happens if assumption fails, consider a fractionally differenced (FD) process

$$X_t = \sum_{k=0}^{\infty} \frac{\Gamma(1 - \delta)}{\Gamma(k + 1)\Gamma(1 - \delta - k)} \epsilon_{t-k},$$

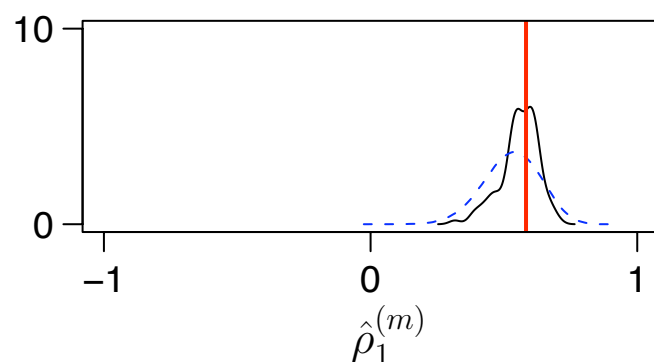
where $\delta = 0.45$ and $\{\epsilon_t\}$ is zero mean Gaussian white noise

- FD time series of length $N = 128$ with **sample** and **true** ACSs:



Parametric Bootstrapping: V

- AR process has ‘short-range’ dependence, whereas FD process exhibits ‘long-range’ (or ‘long-memory’) dependence
- bootstrap approximation to PDF of $\hat{\rho}_1$ along with true PDF:



- repeating the above for 50 FD time series yields:

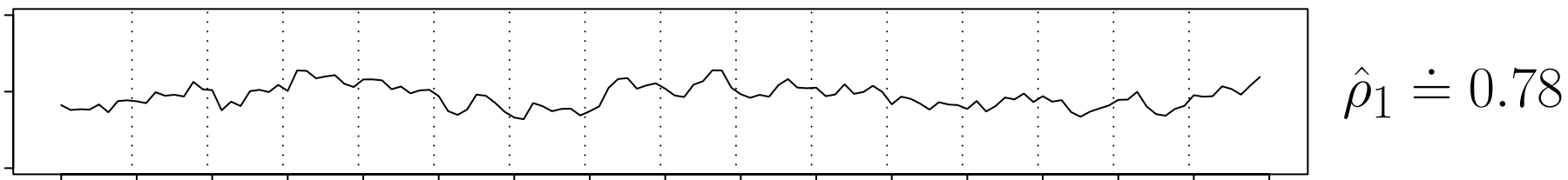
average of 50 sample means $\doteq 0.49$ (truth $\doteq 0.53$)

average of 50 sample SDs $\doteq 0.078$ (truth $\doteq 0.107$)

note: $\rho_1 \doteq 0.82$ for this FD process; agreement in SD gets worse (better) as N increases (decreases)

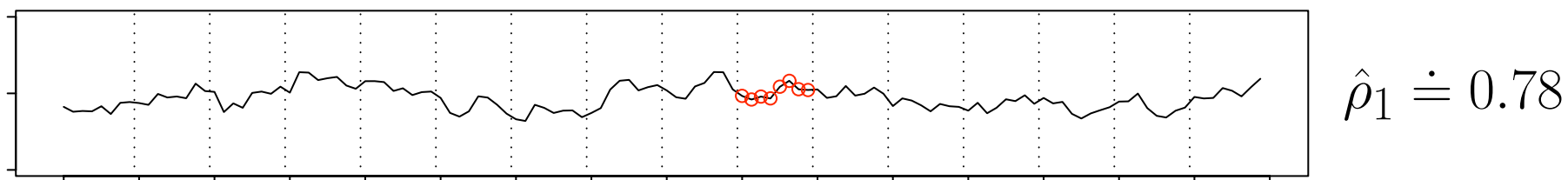
Block Bootstrapping: I

- another time-domain approach is block bootstrapping, which has many variations, of which the following is the simplest
- break time series up into B blocks (subseries) of equal length:

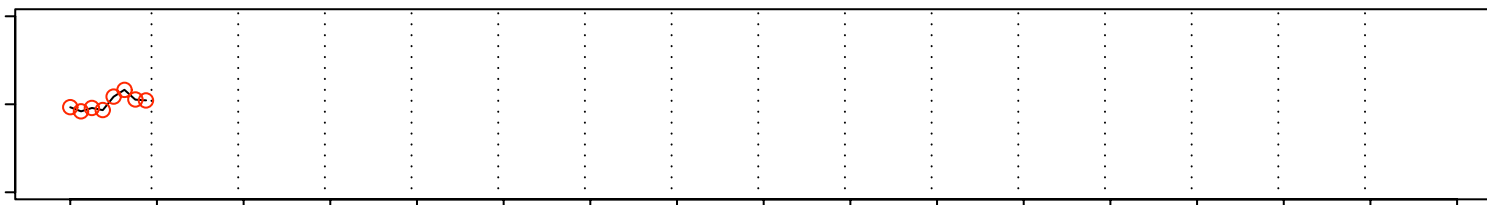


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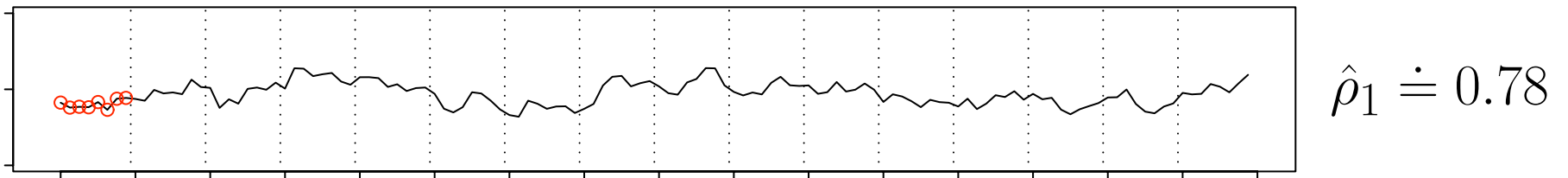


- generate bootstrapped AR series by randomly sampling blocks:

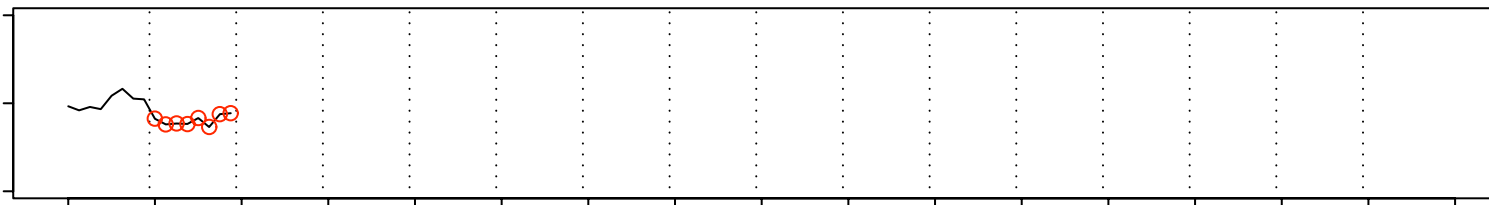


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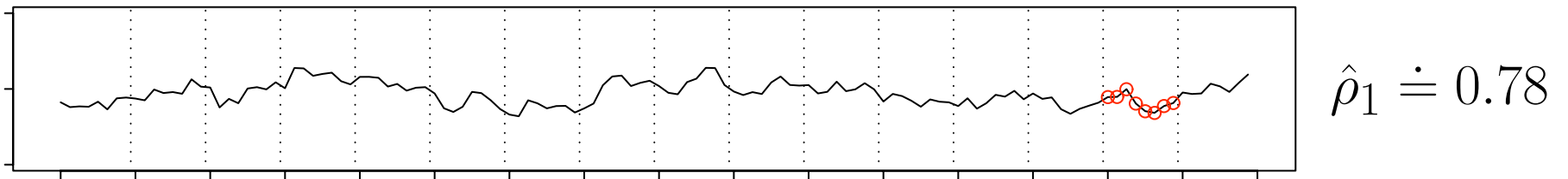


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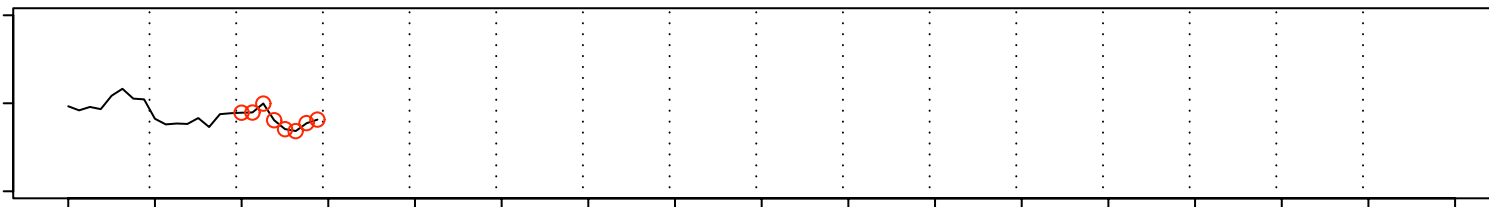


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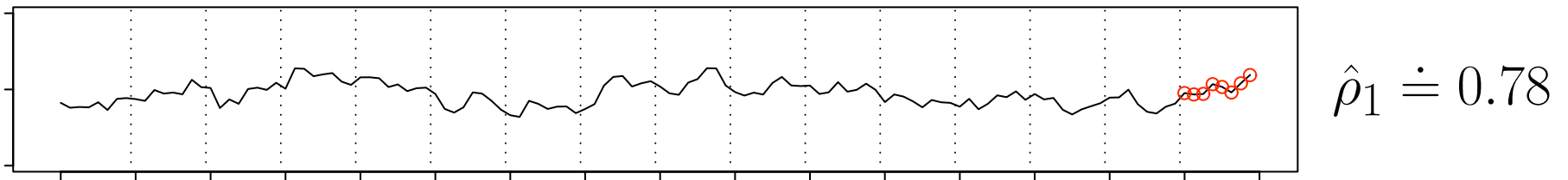


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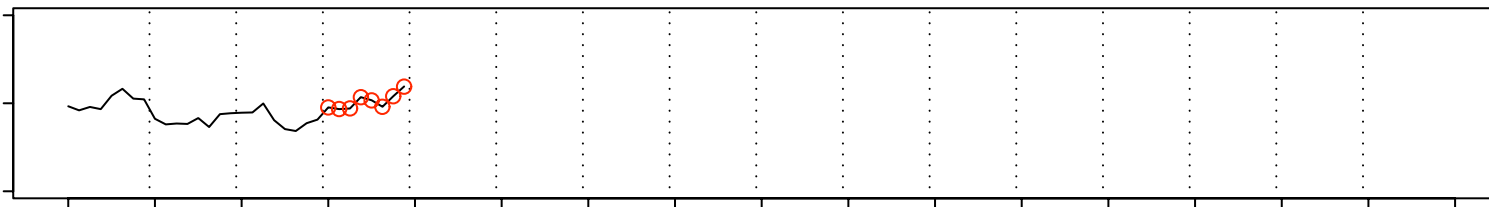


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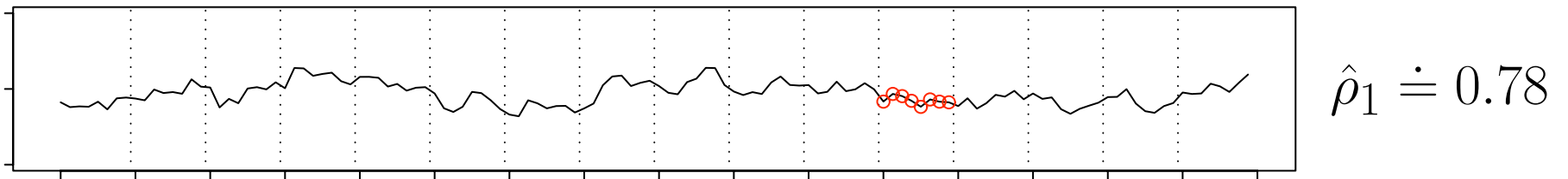


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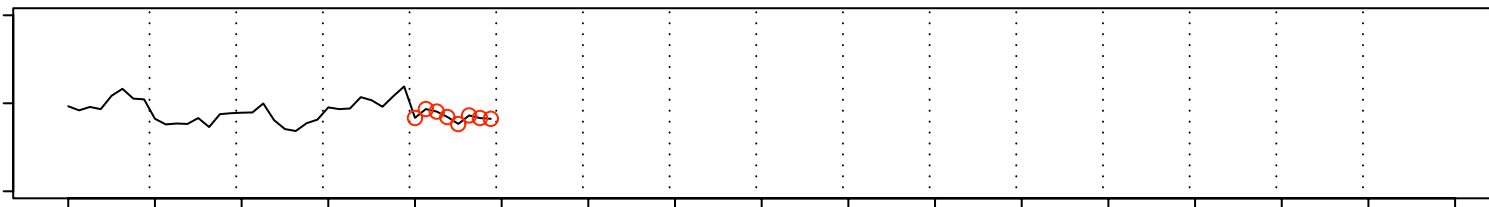


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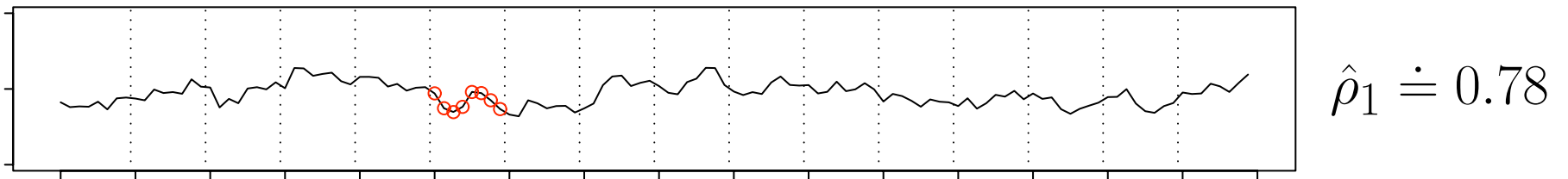


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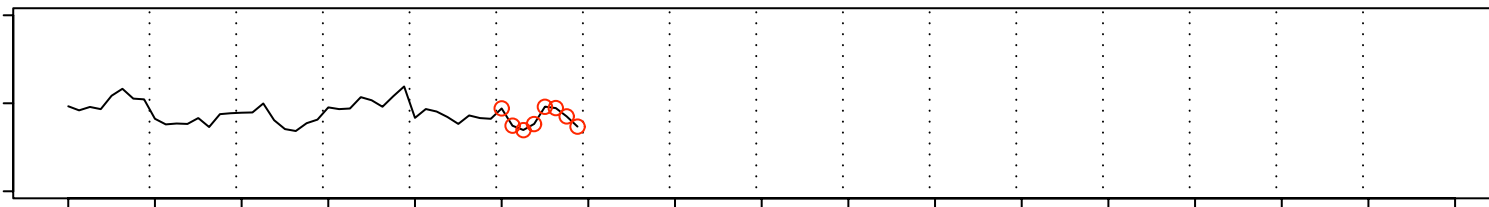


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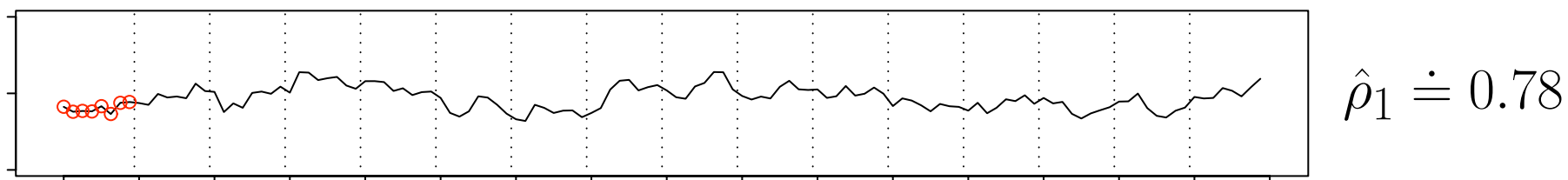


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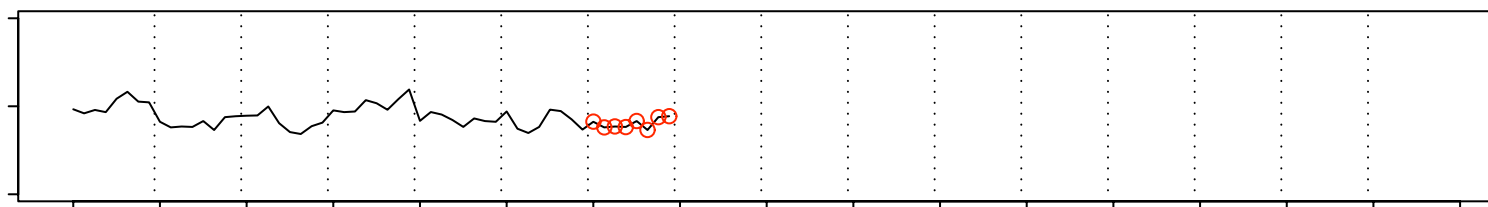


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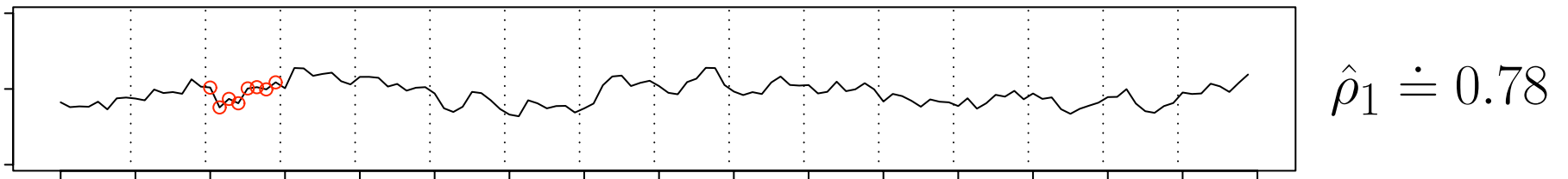


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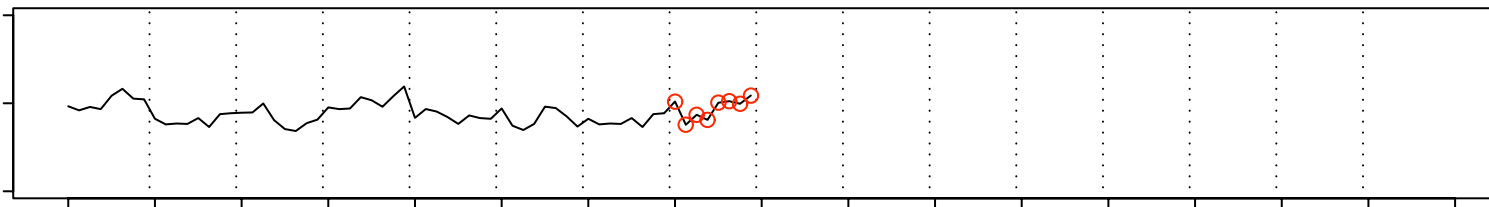


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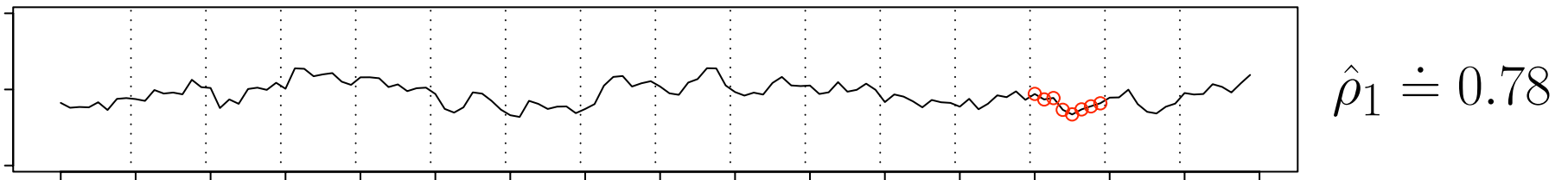


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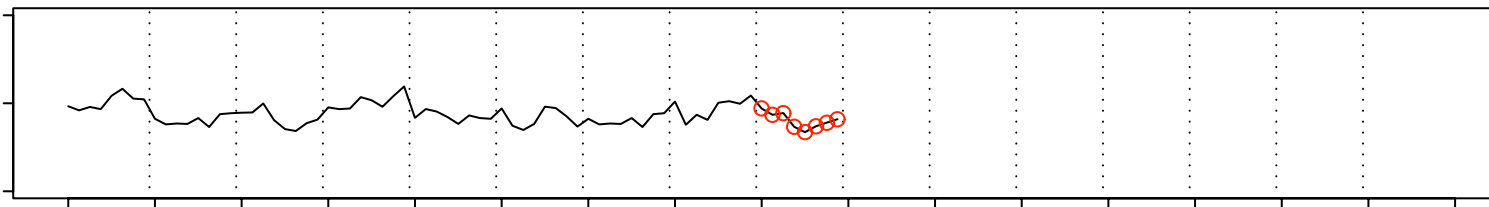


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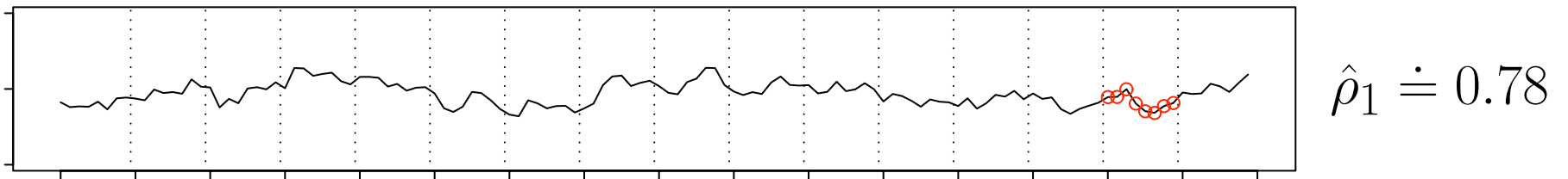


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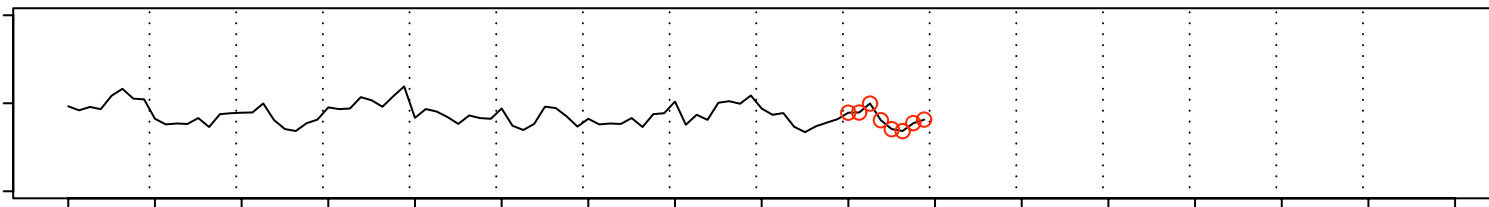


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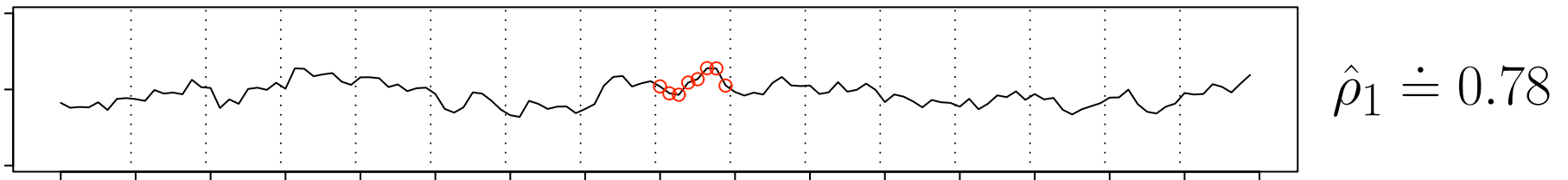


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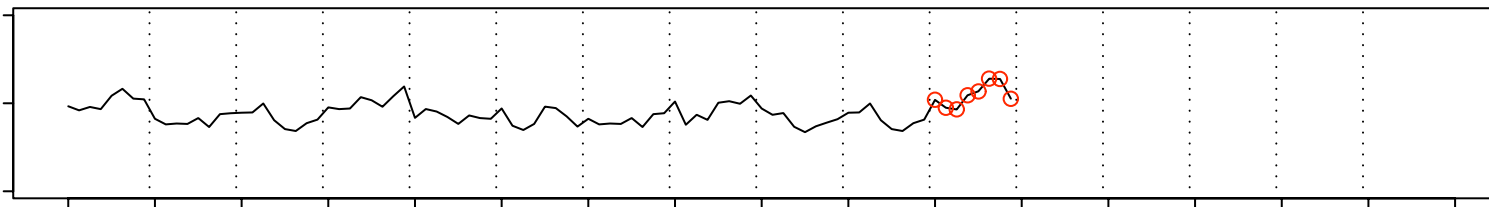


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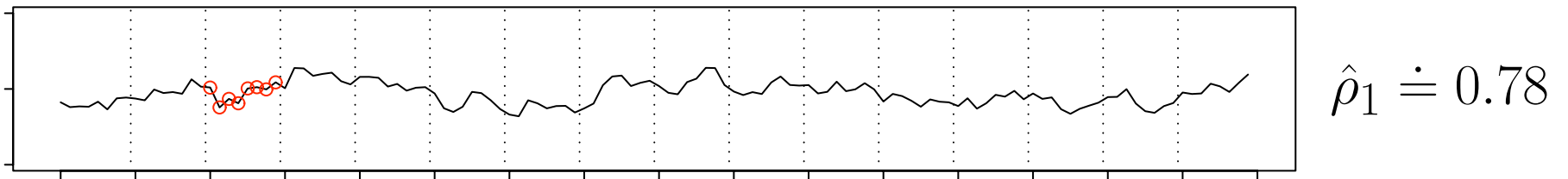


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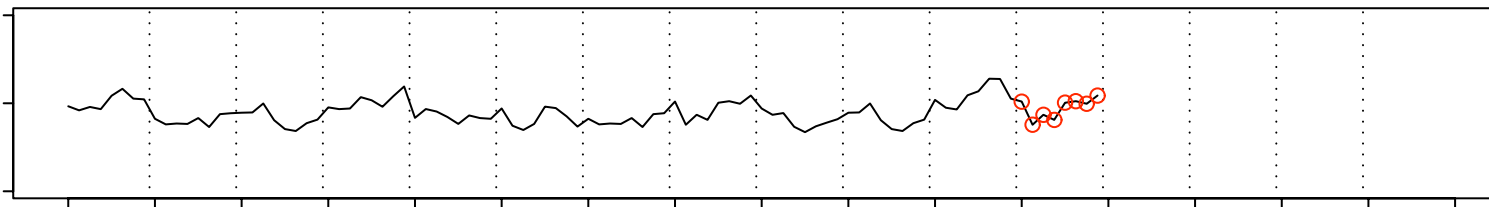


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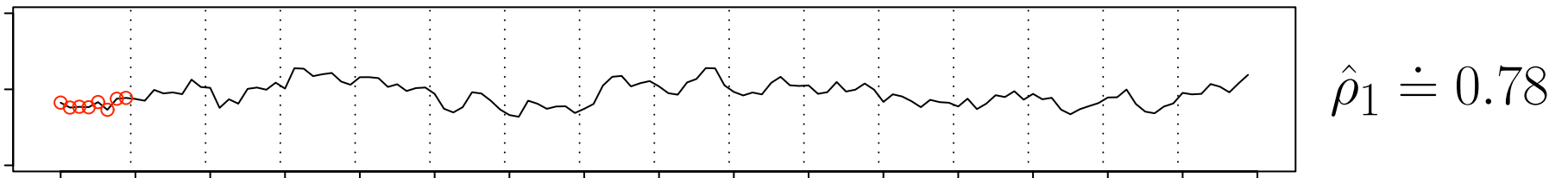


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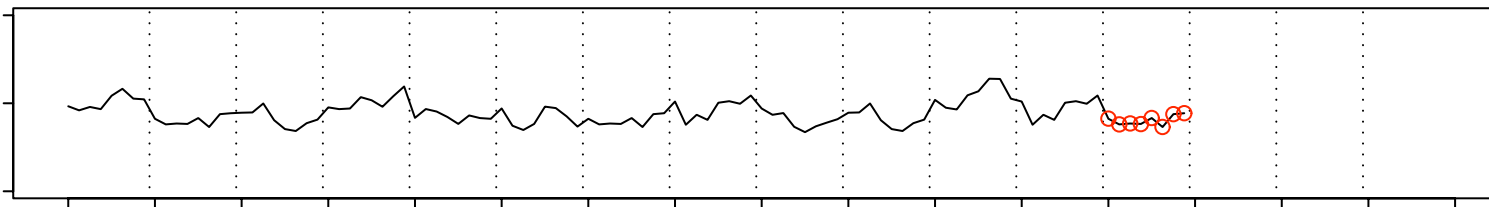
Block Bootstrapping: I

- another time-domain approach is block bootstrapping, which has many variations, of which the following is the simplest
- break time series up into B blocks (subseries) of equal length:



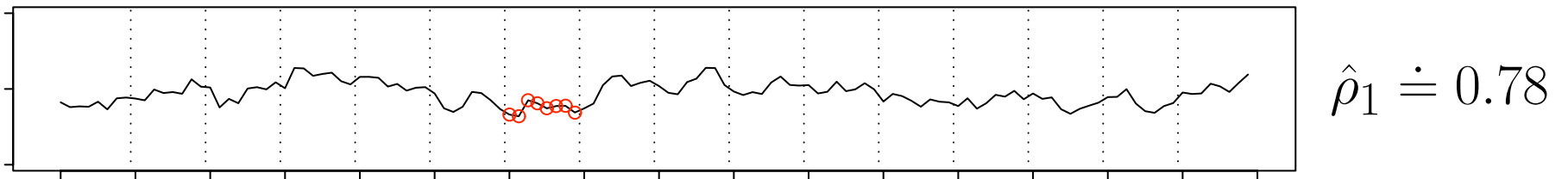
$$\hat{\rho}_1 \doteq 0.78$$

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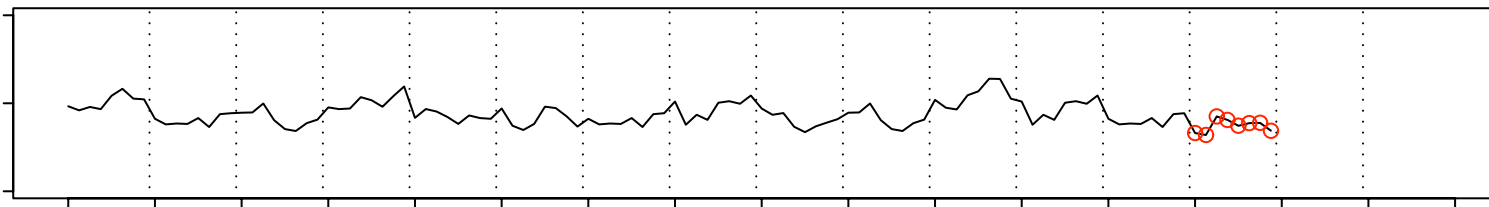


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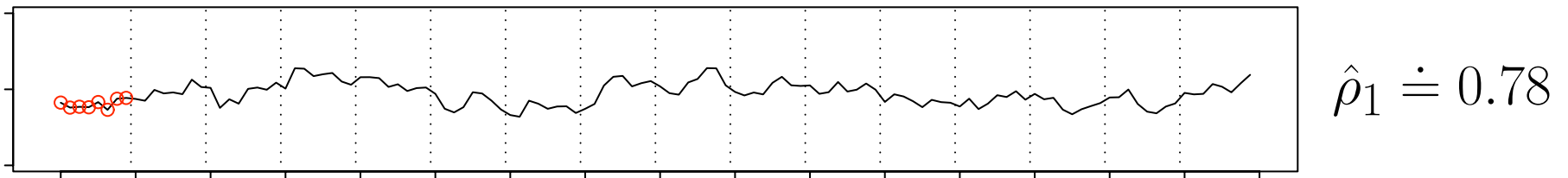


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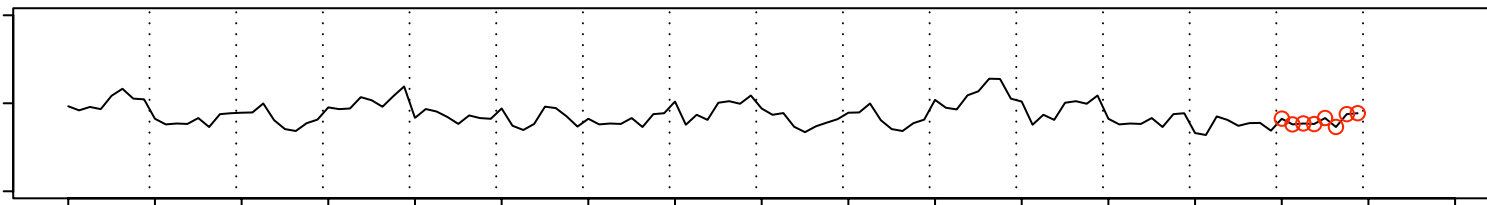


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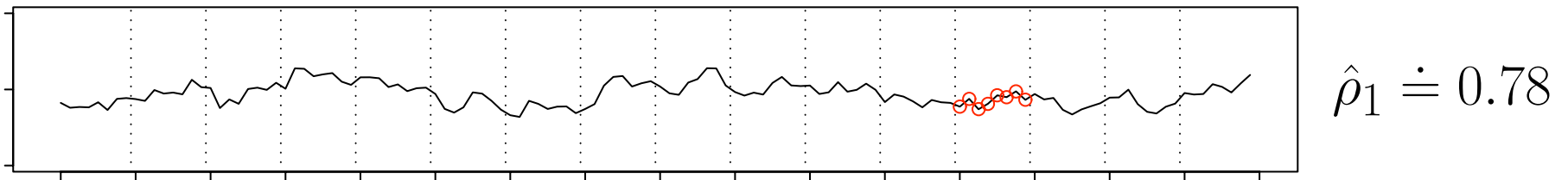


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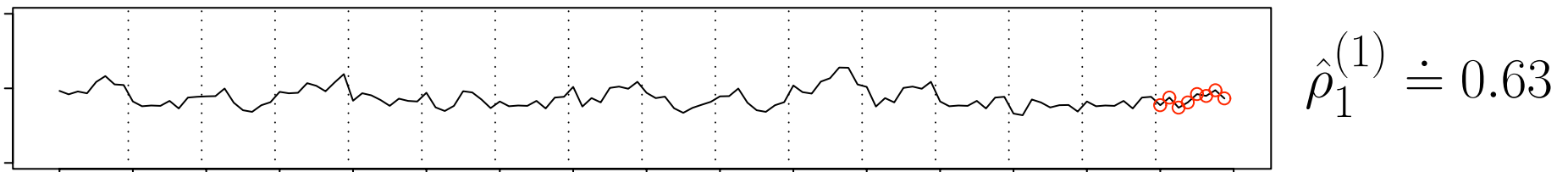


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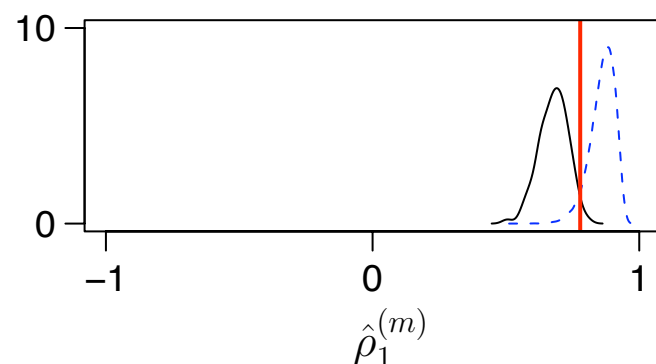


- generate bootstrapped AR series by randomly sampling blocks:



Block Bootstrapping: II

- bootstrap approximation to PDF of $\hat{\rho}_1$ along with true PDF:



vertical line
indicates $\hat{\rho}_1$

- repeating the above for 50 AR time series yields:
 - average of 50 sample means $\doteq 0.75$ (truth $\doteq 0.86$)
 - average of 50 sample SDs $\doteq 0.049$ (truth $\doteq 0.048$)
- repeating the above for 50 FD time series yields:
 - average of 50 sample means $\doteq 0.46$ (truth $\doteq 0.53$)
 - average of 50 sample SDs $\doteq 0.082$ (truth $\doteq 0.107$)

Frequency-Domain Bootstrapping

- again, many variations, including the following three
- ‘phase scramble’ discrete Fourier transform (DFT)

$$\mathcal{X}_k = \sum_{t=0}^{N-1} X_t e^{-i2\pi kt/N} = A_k e^{i\theta_k}$$

of \mathbf{X} and apply inverse DFT to create new series

- periodogram-based bootstrapping: in addition to phase scrambling, evoke large sample result that $|A_k|$'s are approximately uncorrelated with distribution related to a chi-square RV with 2 degrees of freedom
- circulant embedding bootstrapping: form nonparametric estimate of spectral density function and generate realizations using circulant embedding (Percival and Constantine, 2006)

Critique of Time/Frequency-Domain Bootstrapping

- time- and frequency-domain approaches are mainly designed for series with short-range dependence (e.g., AR) and are problematic for those exhibiting long-range dependence (e.g., FD)
- parametric and frequency-domain bootstraps work best for series that obey a Gaussian distribution, but can be problematic for non-Gaussian series
- non-Gaussian series better handled by block bootstrapping, but quality of this approach depends critically on chosen size for blocks (*ad hoc rule* is to set size close to \sqrt{N})
- room for improvement: will consider wavelet-based approaches

Overview of Discrete Wavelet Transform (DWT): I

- DWT is an orthonormal transform \mathcal{W} that reexpresses a time series \mathbf{X} of length N as a vector of DWT coefficients \mathbf{W} :

$$\mathbf{W} = \mathcal{W}\mathbf{X},$$

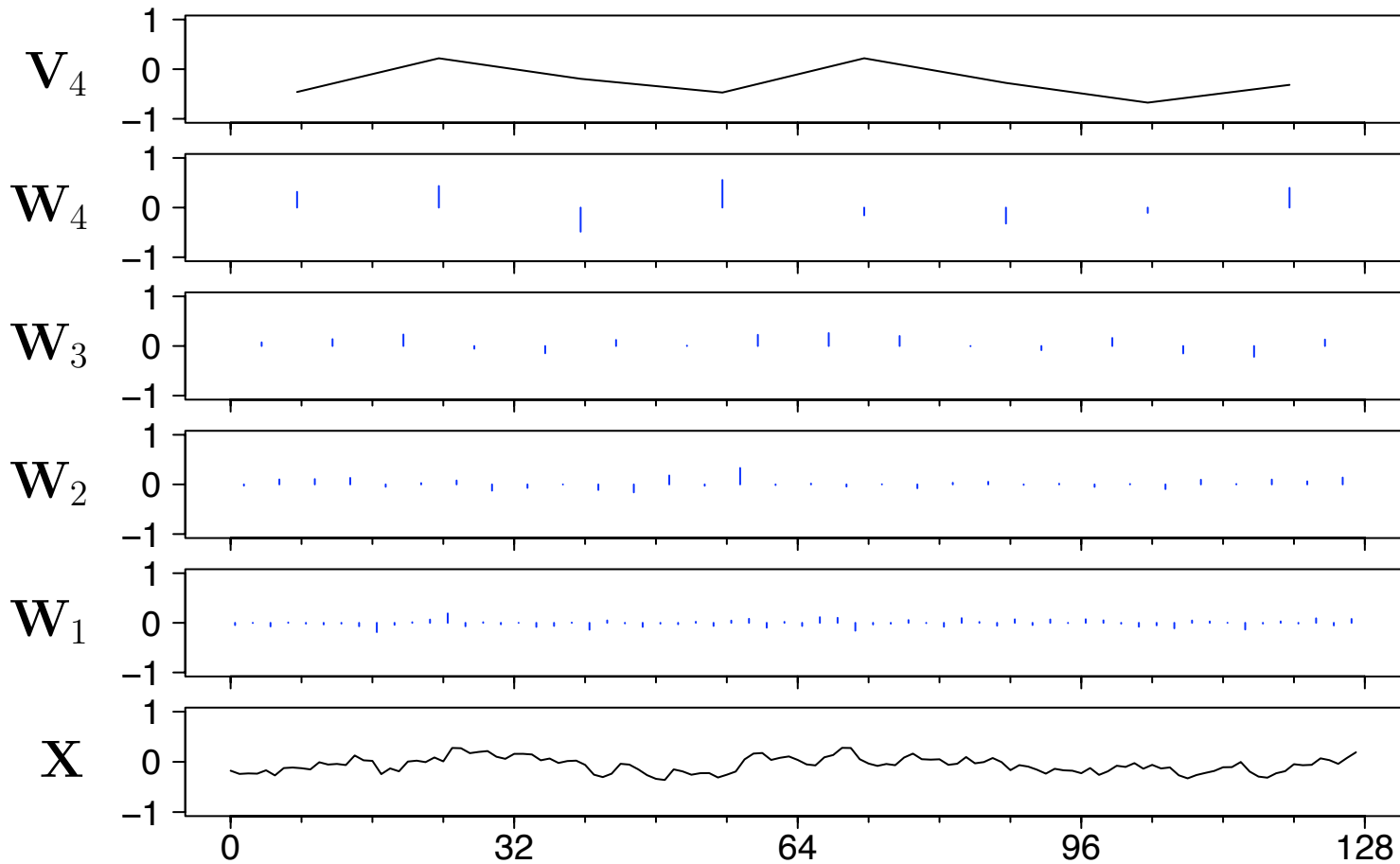
where \mathcal{W} is an $N \times N$ matrix such that $\mathbf{X} = \mathcal{W}^T \mathbf{W}$

- particular \mathcal{W} depends on the choice of
 - wavelet filter, the most basic of which is the Haar filter (fancier filters include the Daubechies family of ‘least asymmetric’ filters of width L – denoted by $\text{LA}(L)$, with $L = 8$ being a popular choice)
 - level J_0 , which determines the number of dyadic scales $\tau_j = 2^{j-1}$, $j = 1, 2, \dots, J_0$, involved in the transform

Overview of Discrete Wavelet Transform (DWT): II

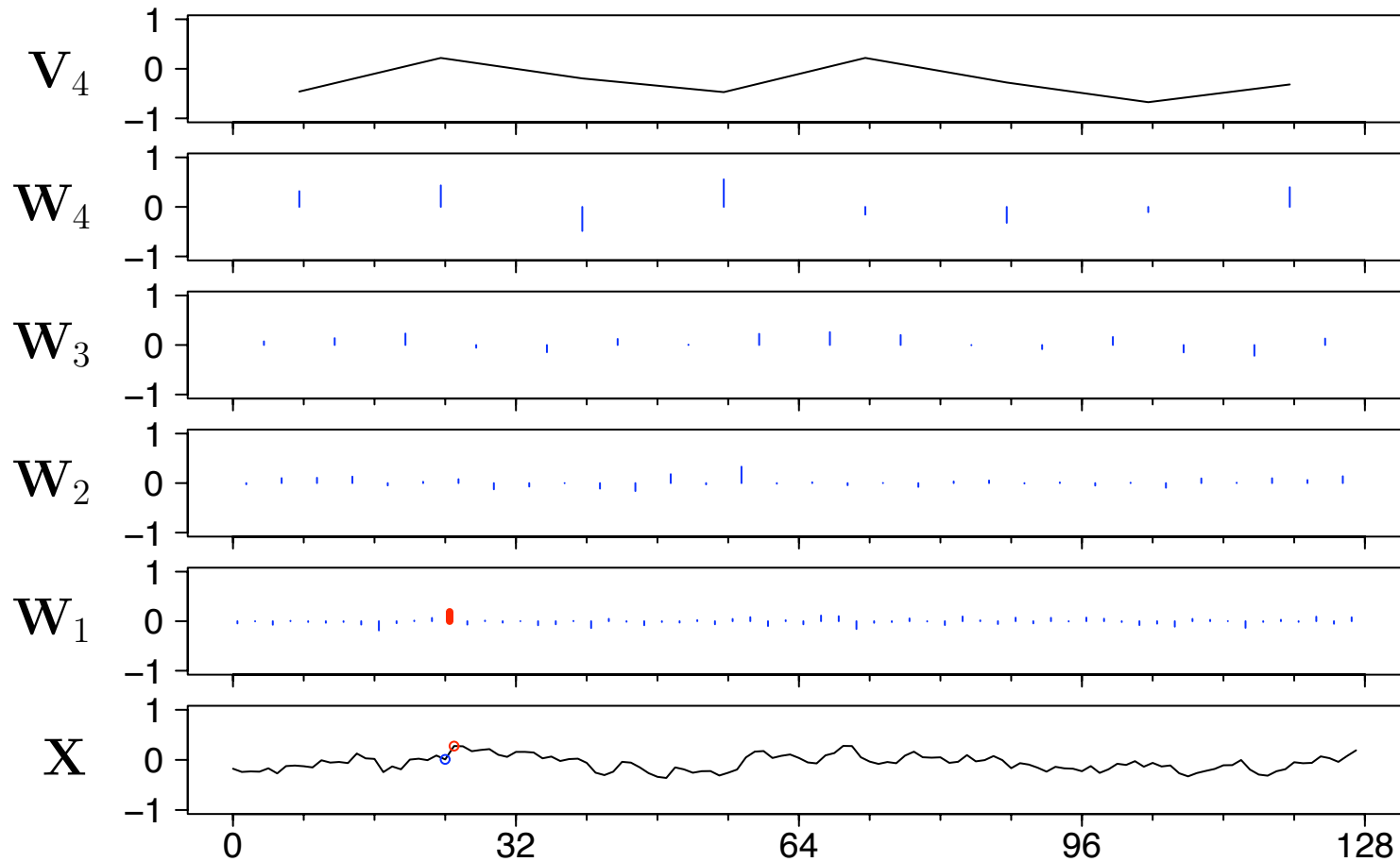
- DWT coefficient vector \mathbf{W} can be partitioned into J_0 sub-vectors of wavelet coefficients \mathbf{W}_j , $j = 1, 2, \dots, J_0$, along with one sub-vector of scaling coefficients \mathbf{V}_{J_0}
- wavelet coefficients in \mathbf{W}_j are associated with changes in averages over a scale of τ_j , whereas the scaling coefficients in \mathbf{V}_{J_0} are associated with averages over a scale of $2\tau_{J_0}$
- as a concrete example, let's look at a level $J_0 = 4$ Haar DWT of the AR time series

DWT of Autoregressive Process: I



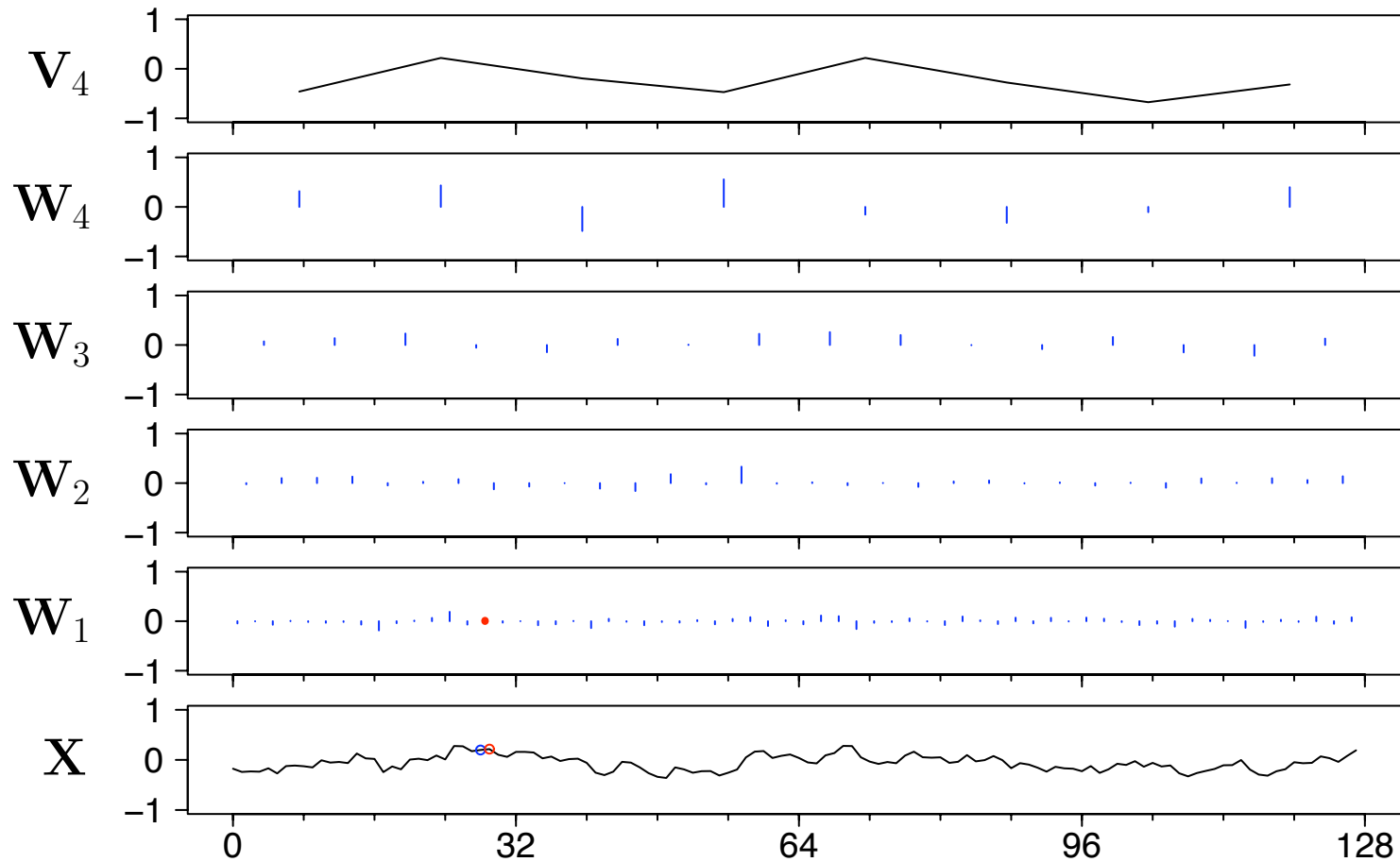
● level $J_0 = 4$ Haar DWT of AR series \mathbf{X}

DWT of Autoregressive Process: I



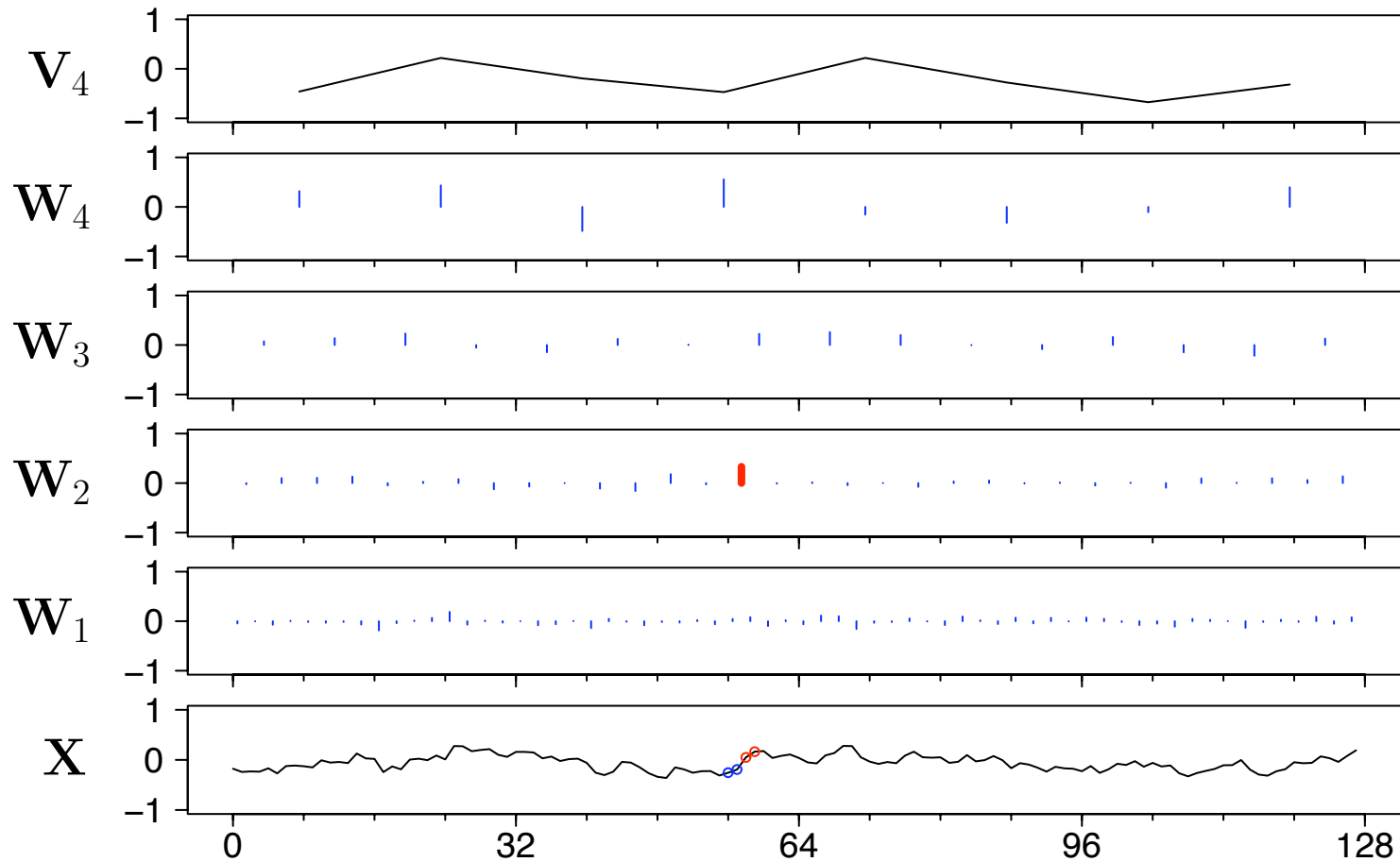
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $\tau_1 = 1$
wavelet coefficient highlighted

DWT of Autoregressive Process: I



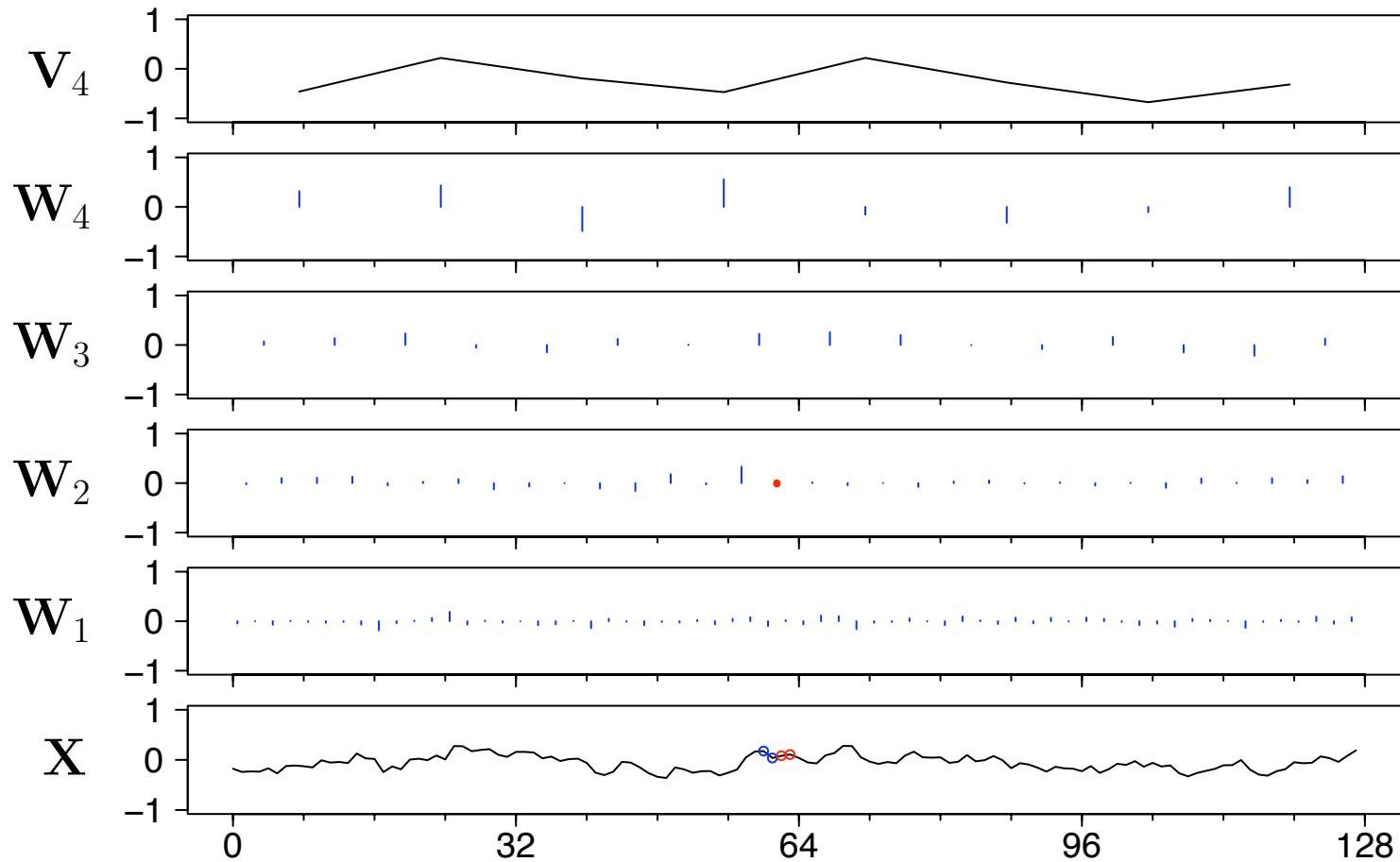
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $\tau_1 = 1$ wavelet coefficient highlighted

DWT of Autoregressive Process: I



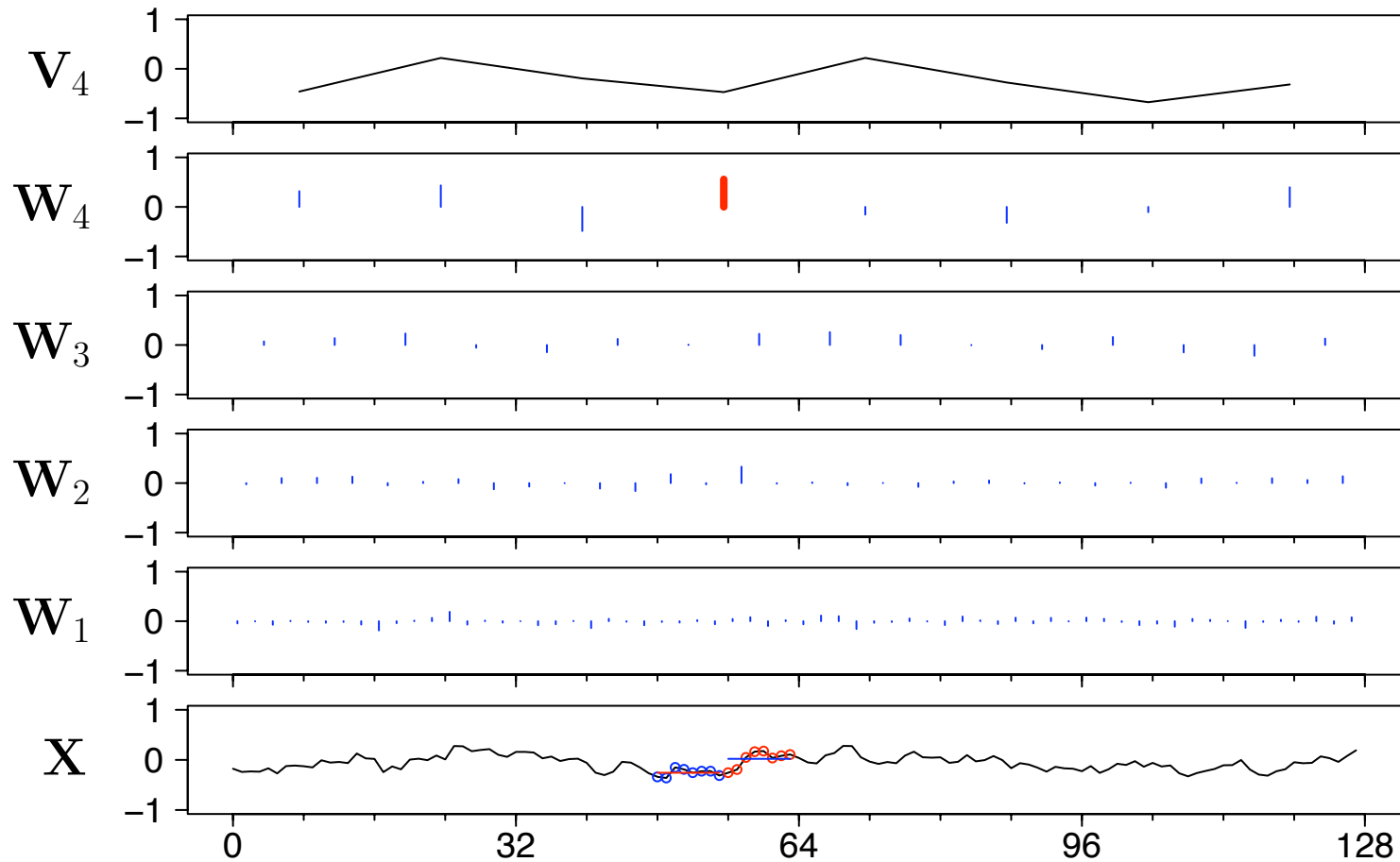
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $\tau_2 = 2$ wavelet coefficient highlighted

DWT of Autoregressive Process: I



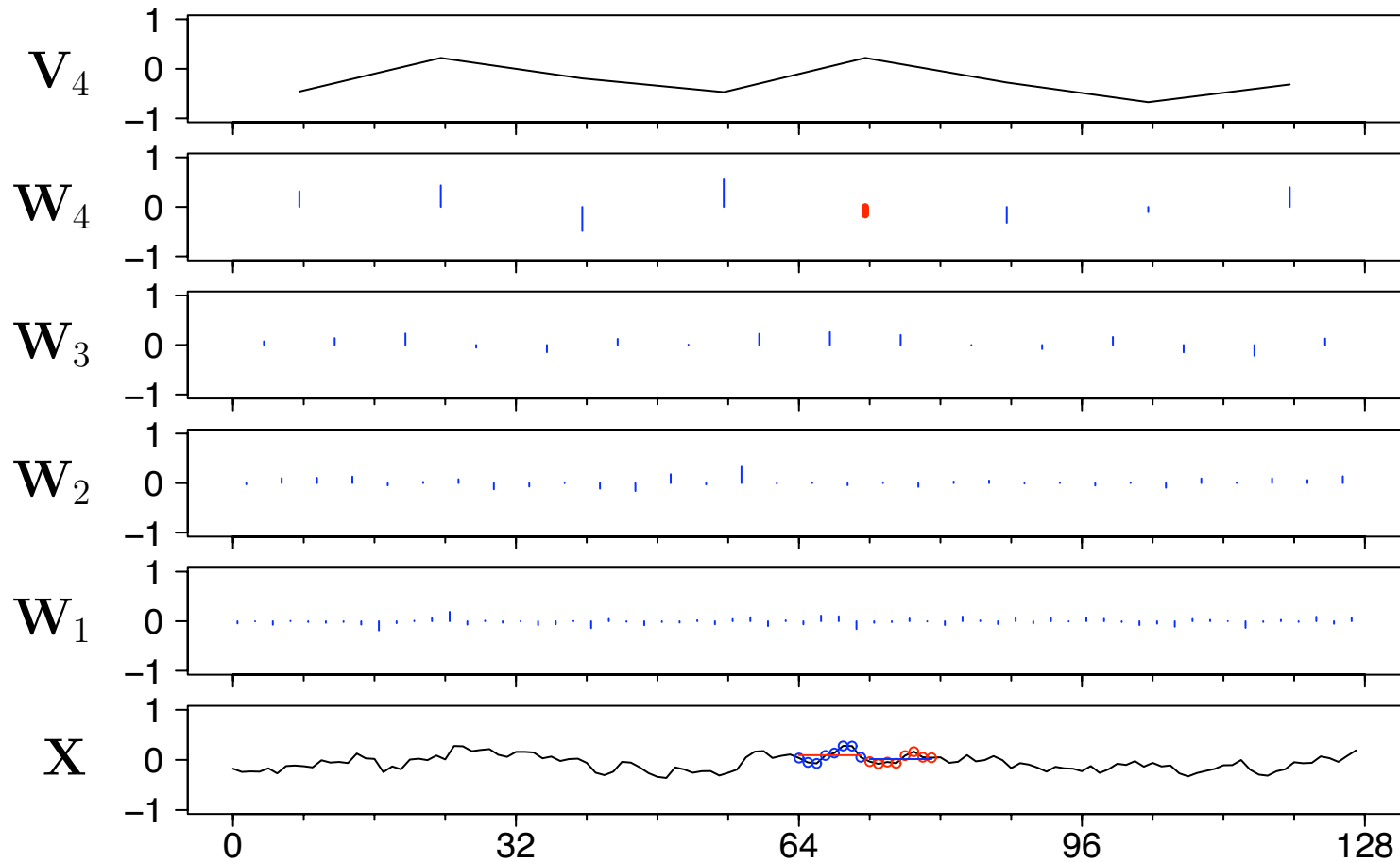
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DWT of Autoregressive Process: I



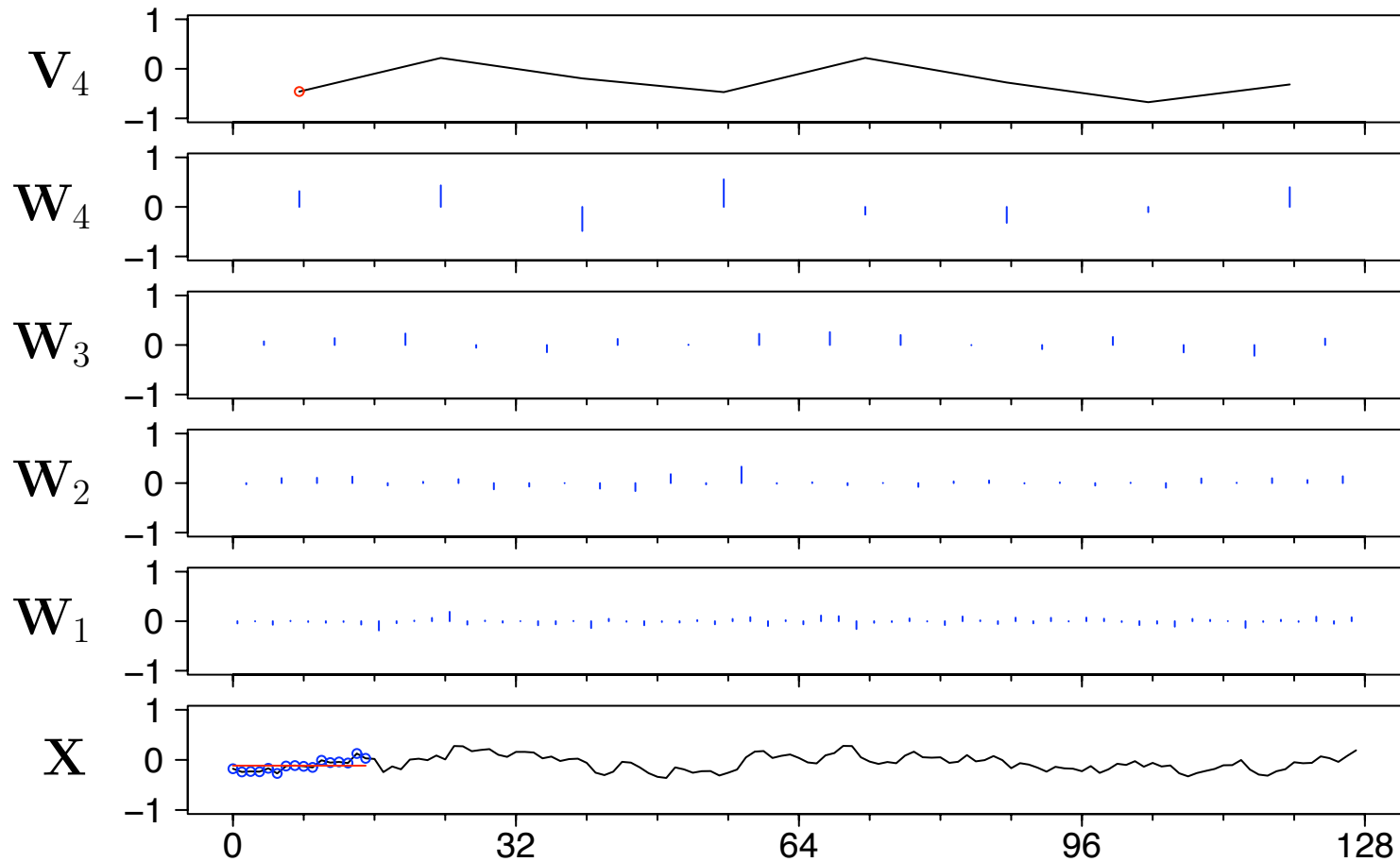
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $\tau_4 = 8$ wavelet coefficient highlighted

DWT of Autoregressive Process: I



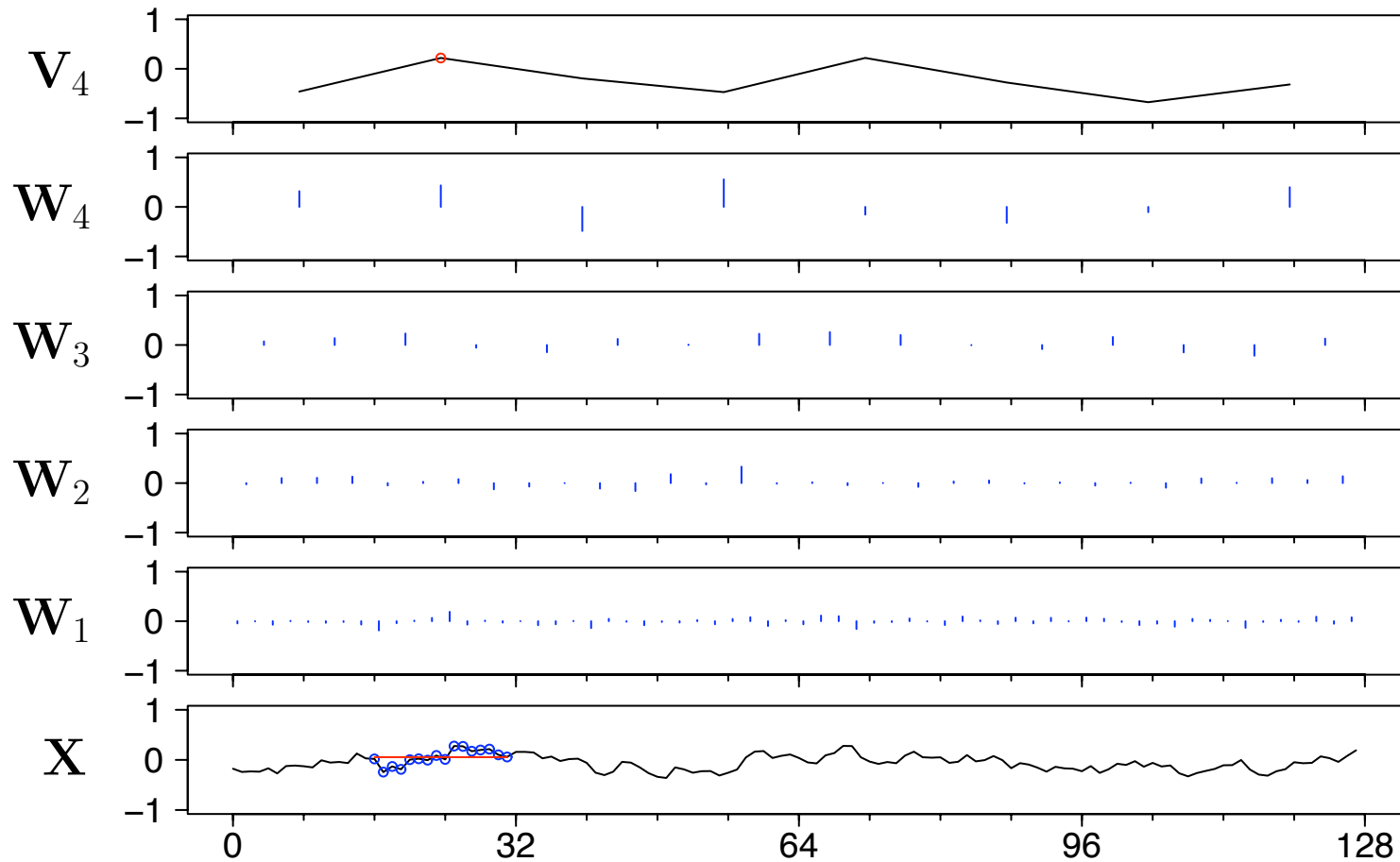
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DWT of Autoregressive Process: I



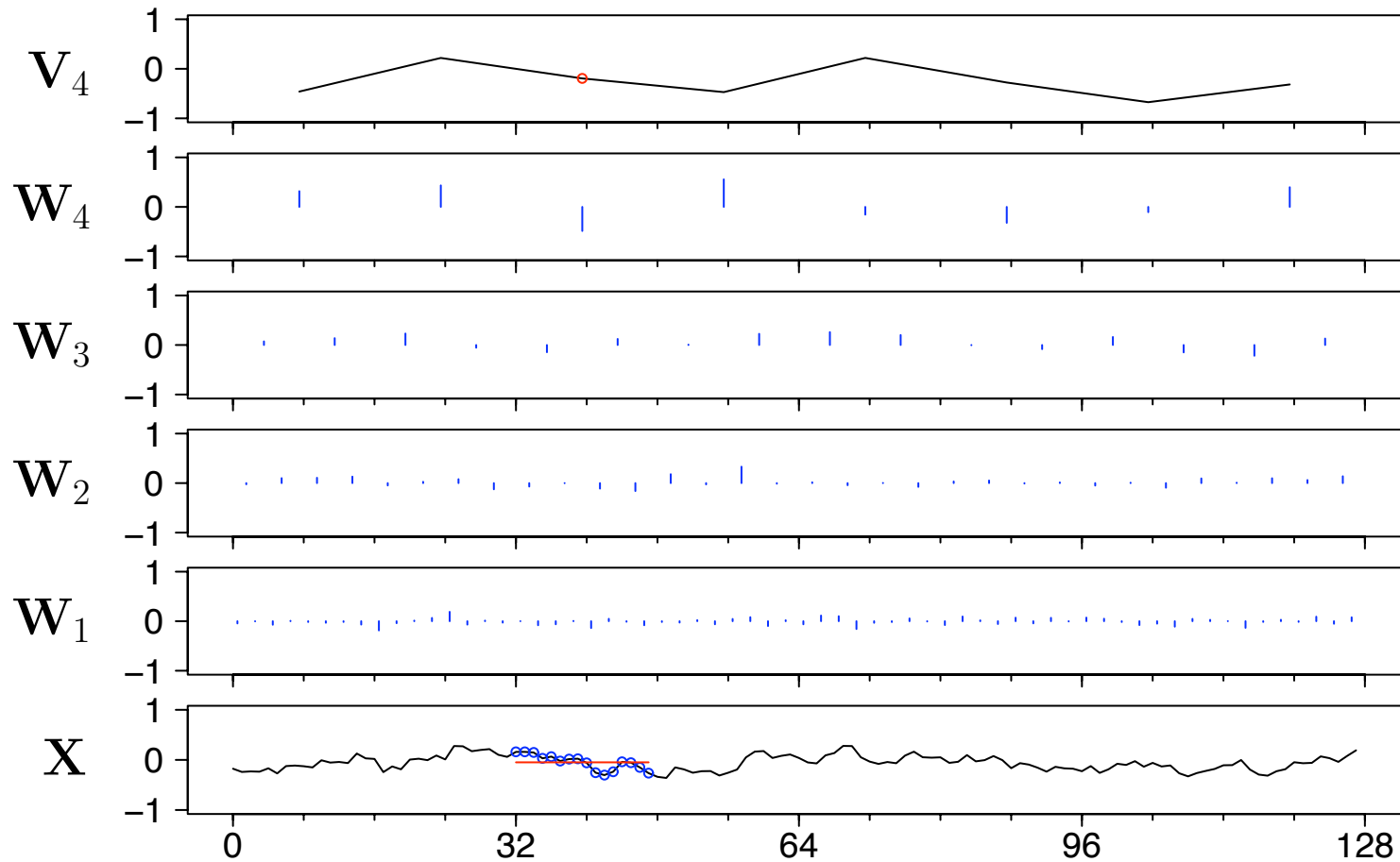
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $2 * \tau_4 = 16$ scaling coefficient highlighted

DWT of Autoregressive Process: I



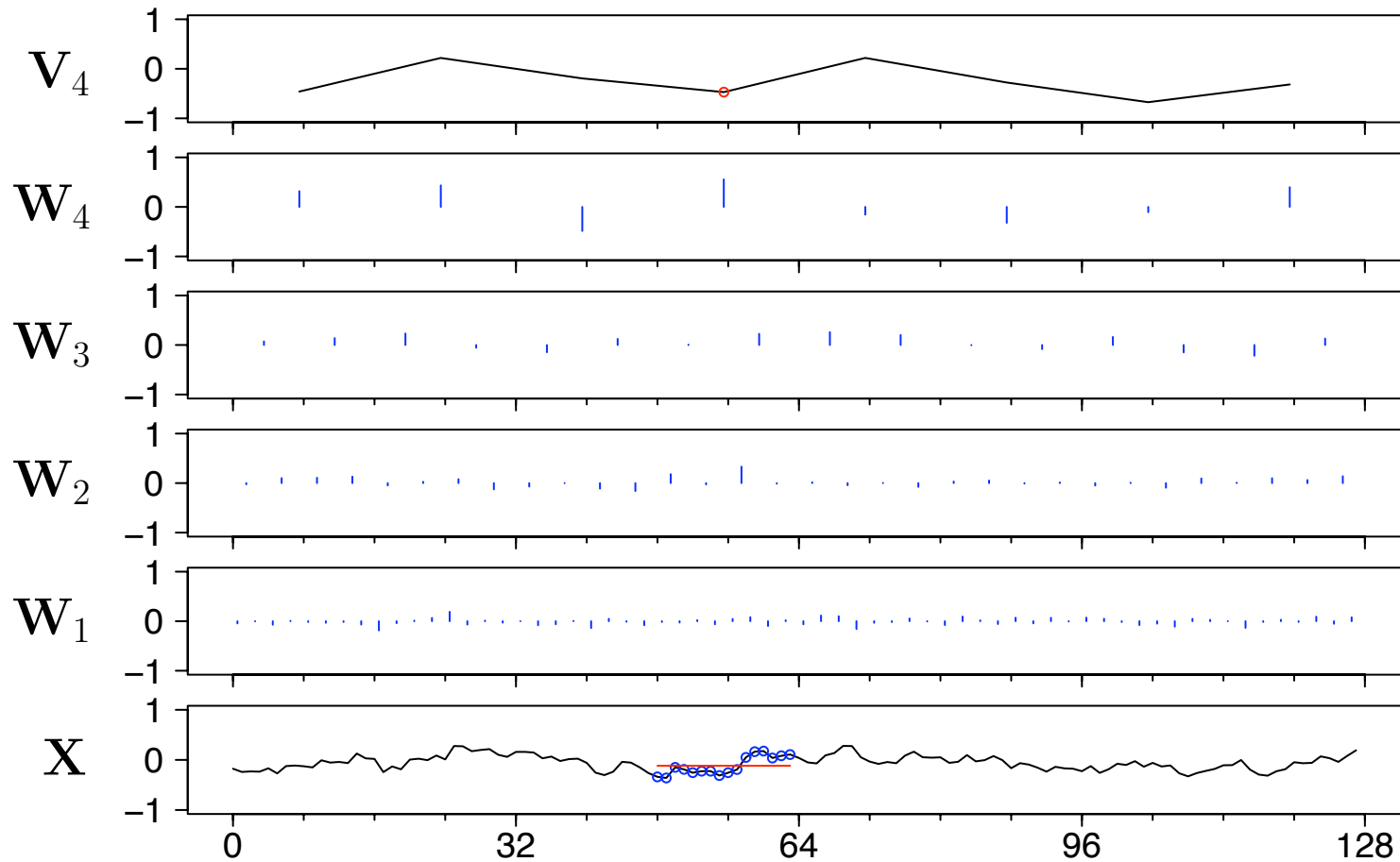
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DWT of Autoregressive Process: I



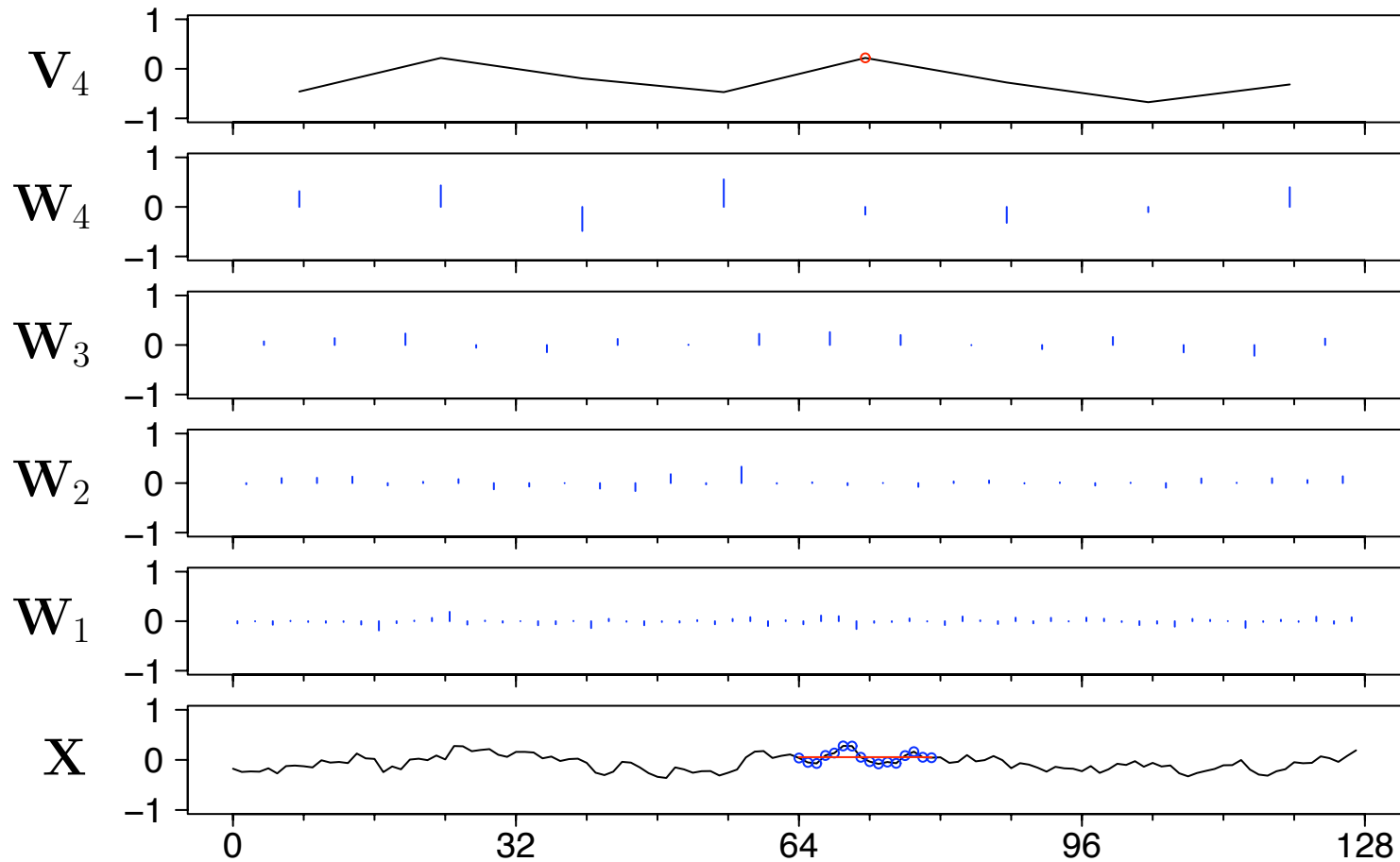
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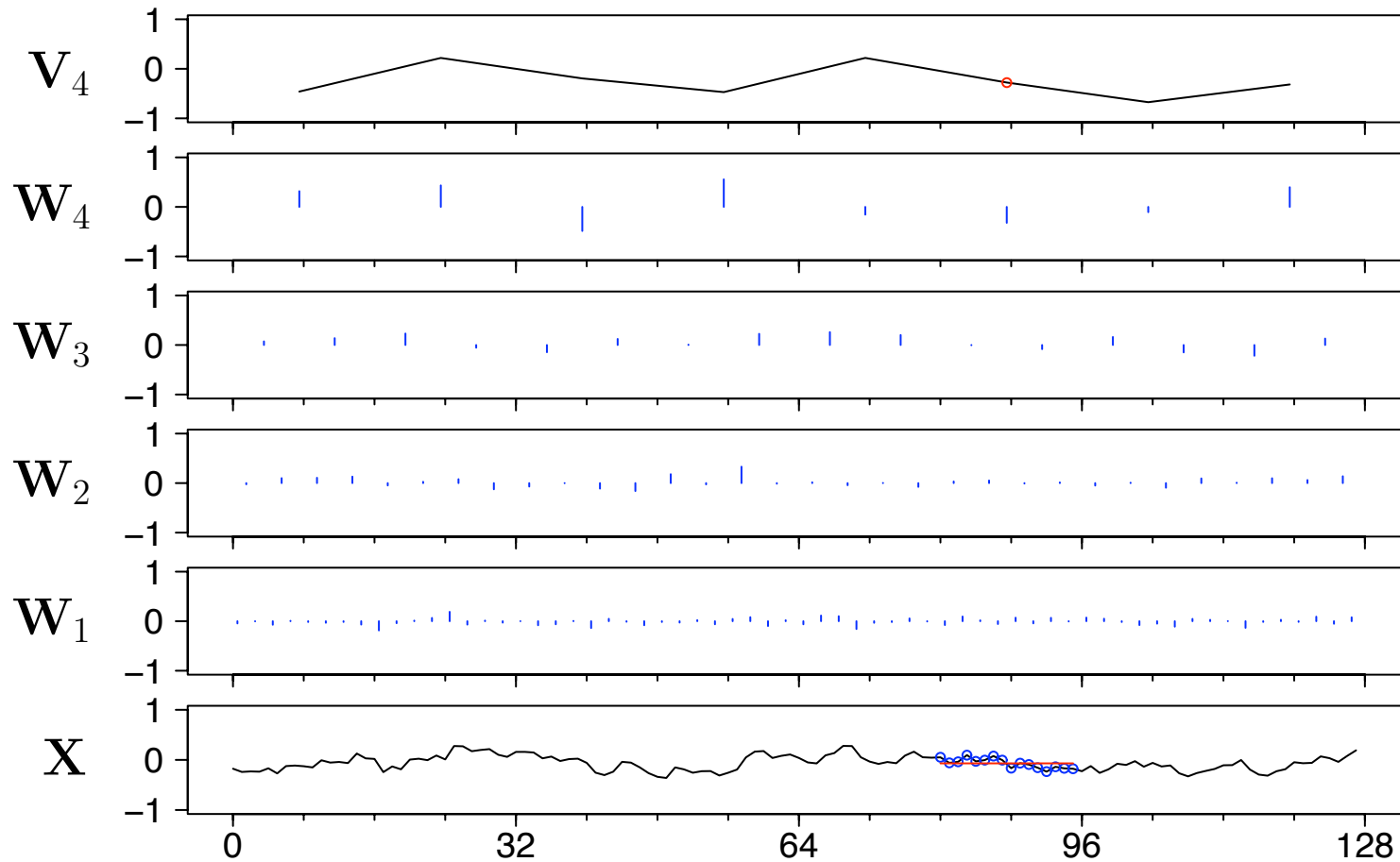
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DWT of Autoregressive Process: I



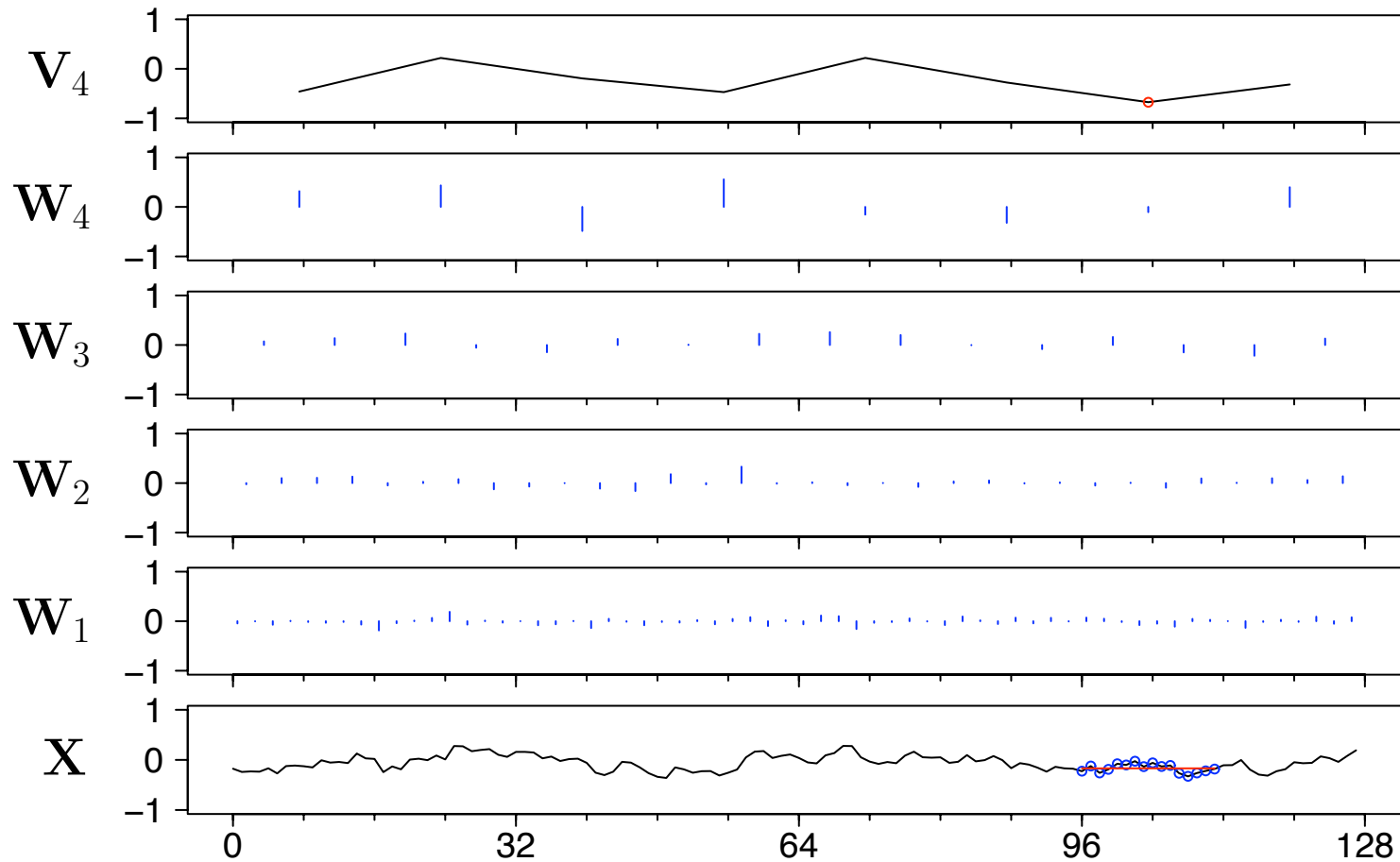
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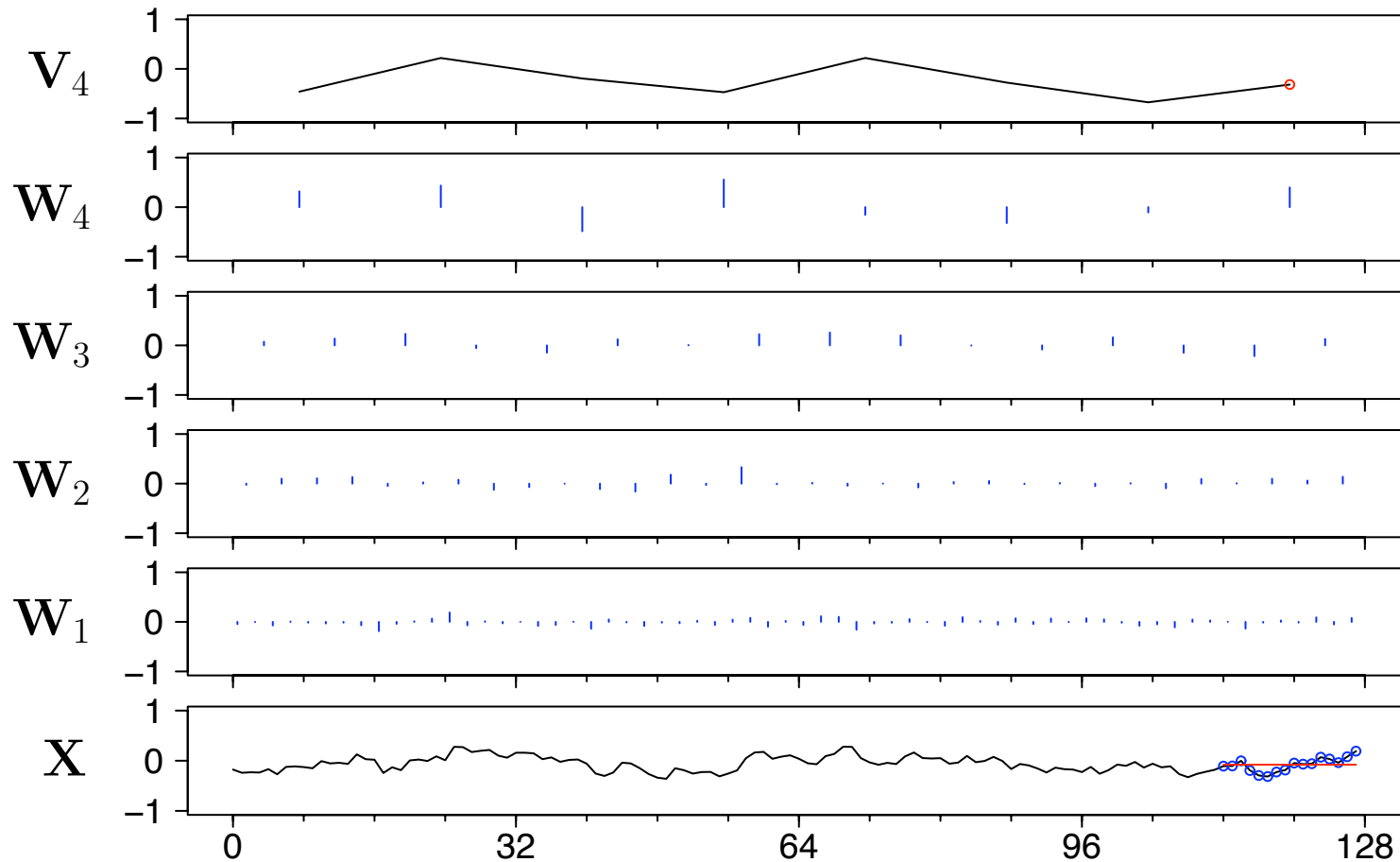
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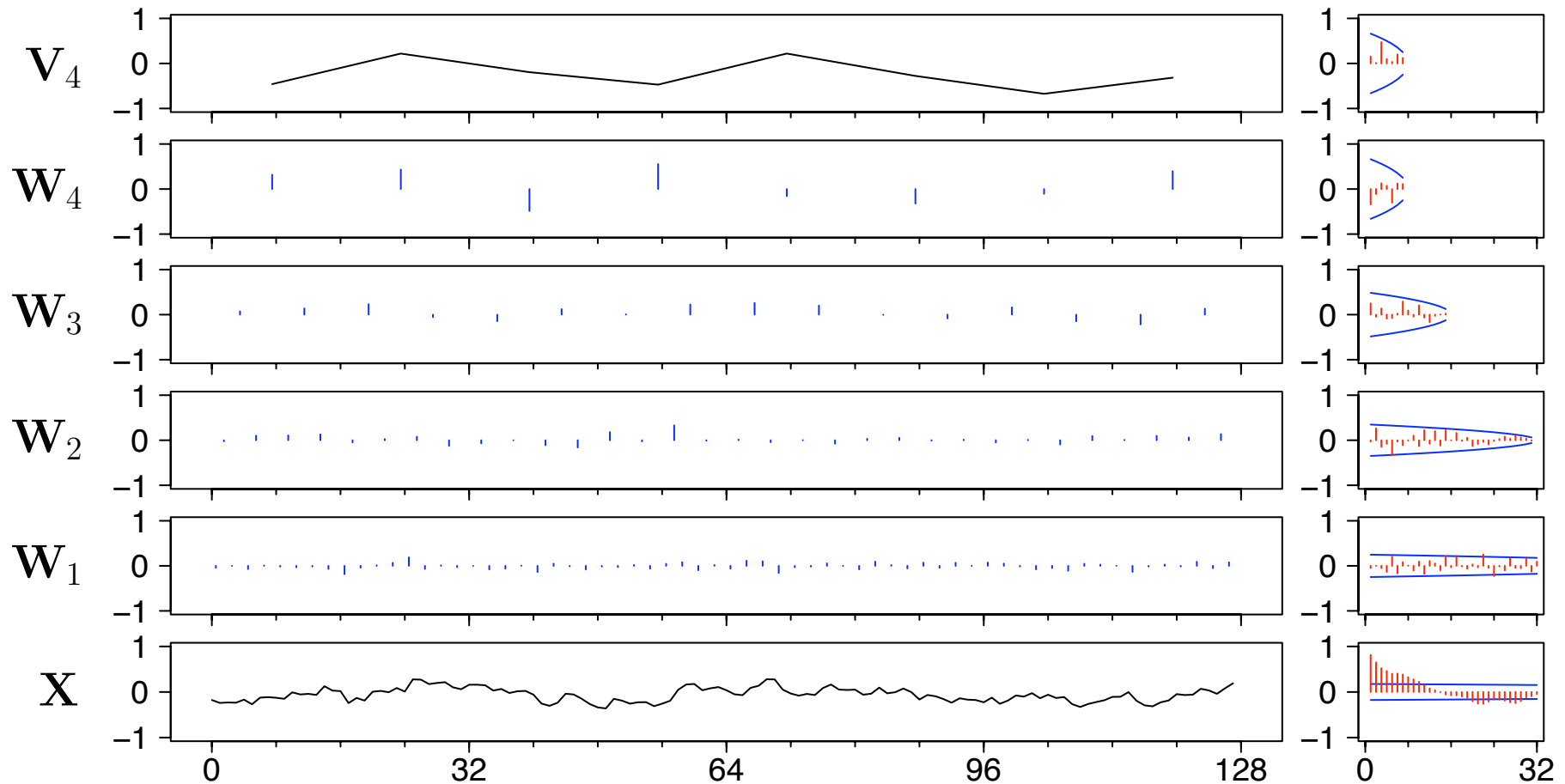
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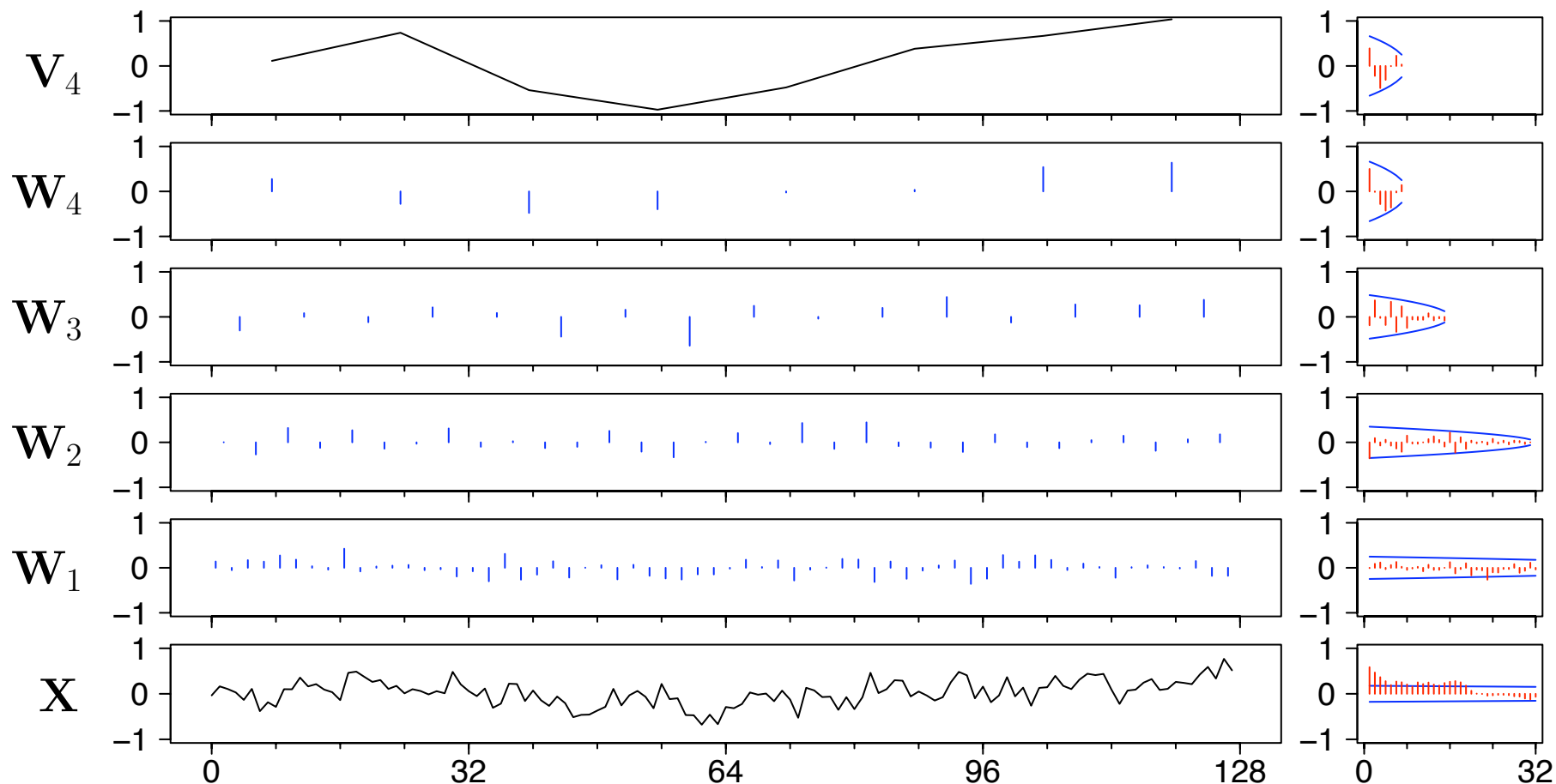
- level $J_0 = 4$ Haar DWT of AR series \mathbf{X} , with scale $2 * \tau_4 = 16$ scaling coefficient highlighted

DWT of Autoregressive Process: II



- Haar DWT of AR series \mathbf{X} and sample ACSs for each \mathbf{W}_j & \mathbf{V}_4 , along with 95% confidence intervals for white noise

DWT of Fractionally Differenced Process



- Haar DWT of FD series \mathbf{X} and sample ACSs for each \mathbf{W}_j & \mathbf{V}_4 , along with 95% confidence intervals for white noise

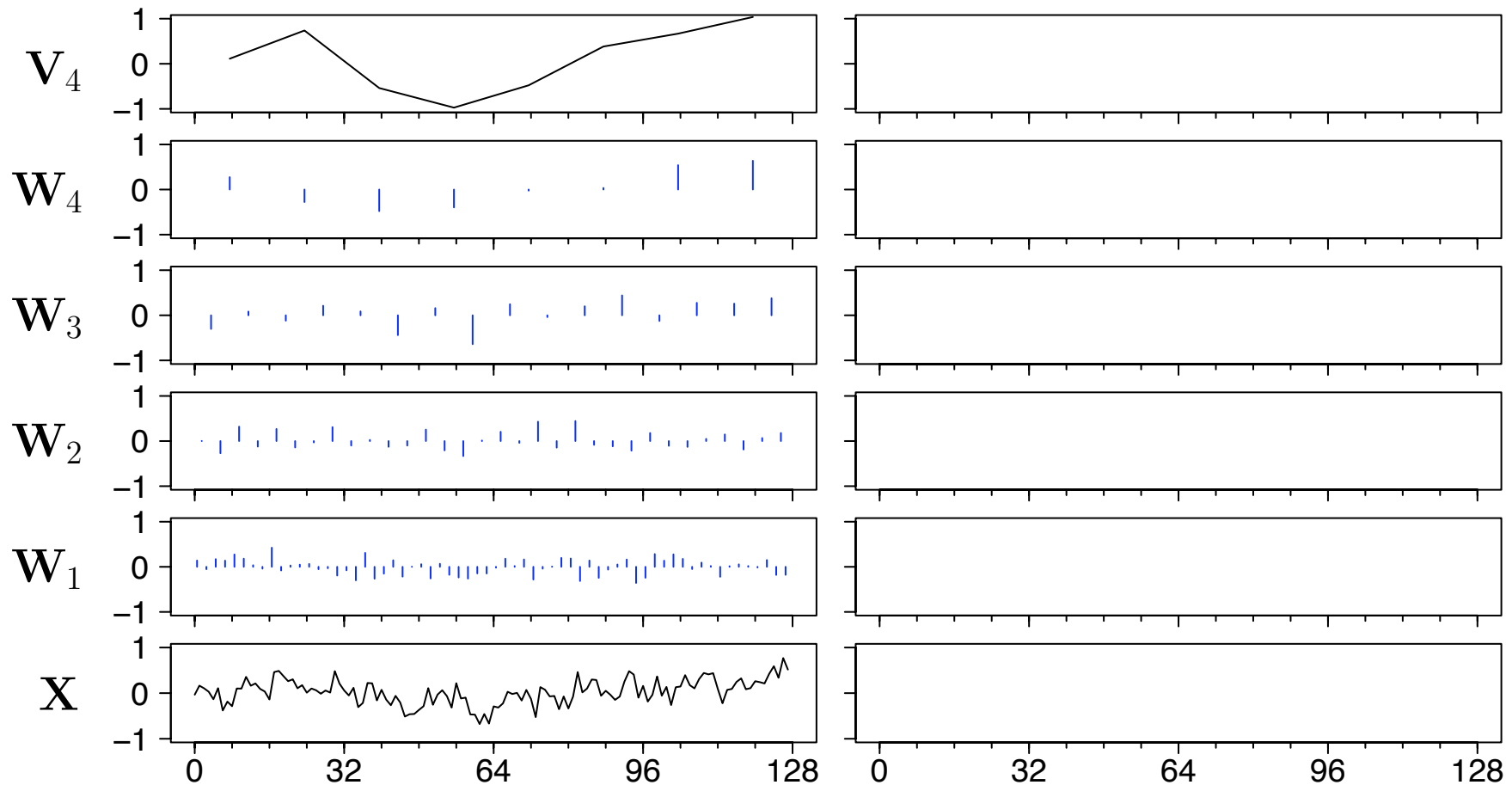
DWT as a Decorrelating Transform

- for many (but not all!) time series, DWT acts as a decorrelating transform: to a good approximation, each \mathbf{W}_j is a sample of a white noise process, and coefficients from different sub-vectors \mathbf{W}_j and $\mathbf{W}_{j'}$ are also pairwise uncorrelated
- variance of coefficients in \mathbf{W}_j depends on j
- scaling coefficients \mathbf{V}_{J_0} are still autocorrelated, but there will be just a few of them if J_0 is selected to be large
- decorrelating property holds particularly well for FD and other processes with long-range dependence
- above suggests the following recipe for wavelet-domain bootstrapping

Recipe for Wavelet-Domain Bootstrapping

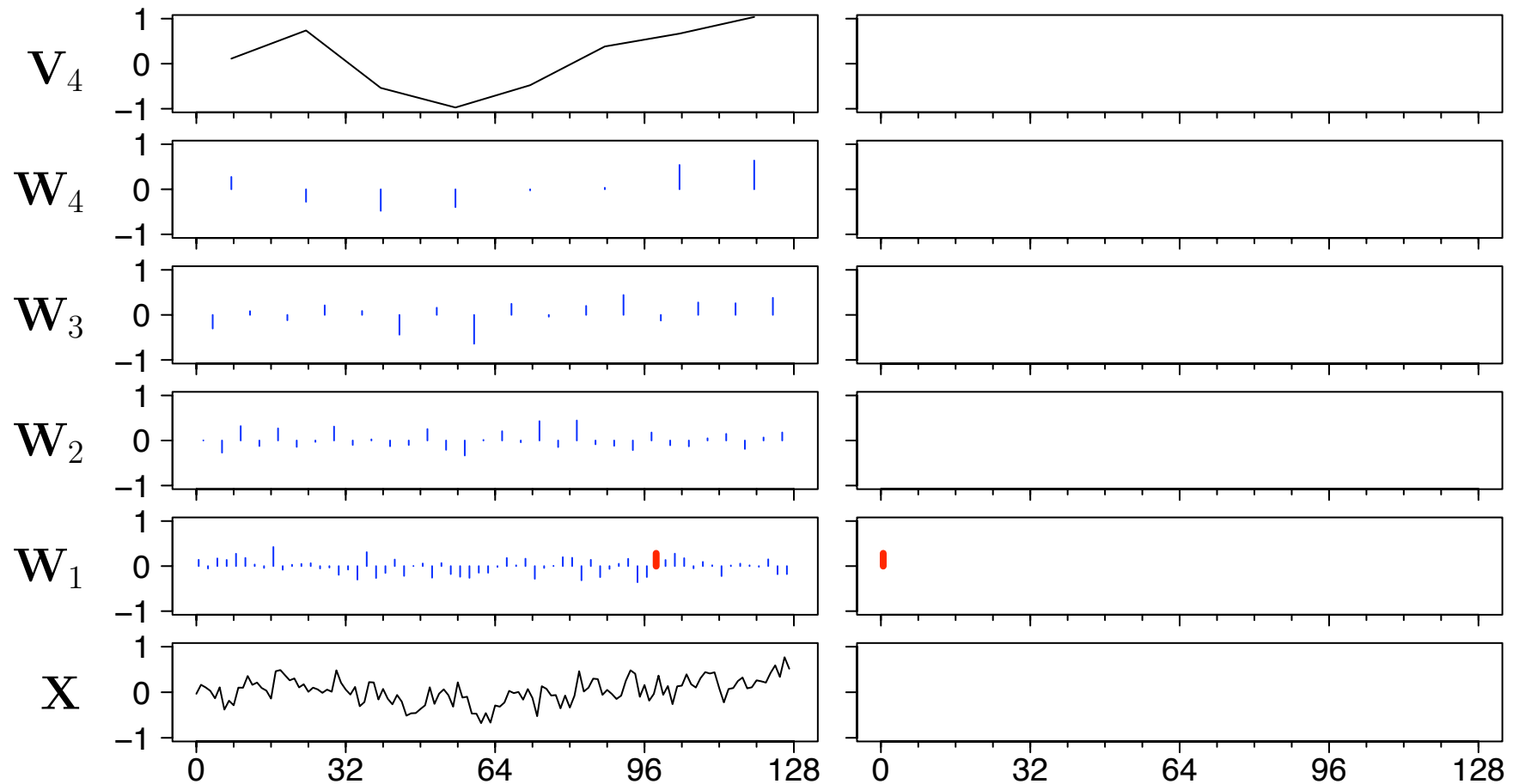
1. given \mathbf{X} of length $N = 2^J$, compute level J_0 DWT (the choice $J_0 = J - 3$ yields 8 coefficients in \mathbf{W}_{J_0} and \mathbf{V}_{J_0})
 2. randomly sample with replacement from \mathbf{W}_j to create bootstrapped vector $\mathbf{W}_j^{(b)}$, $j = 1, \dots, J_0$
 3. create $\mathbf{V}_{J_0}^{(b)}$ using a parametric bootstrap
 4. apply \mathcal{W}^T to $\mathbf{W}_1^{(b)}, \dots, \mathbf{W}_{J_0}^{(b)}$ and $\mathbf{V}_{J_0}^{(b)}$ to obtain bootstrapped time series $\mathbf{X}^{(b)}$ and then form corresponding $\hat{\rho}_1^{(b)}$
- repeat above many times to build up sample distribution of bootstrapped autocorrelations

Illustration of Wavelet-Domain Bootstrapping



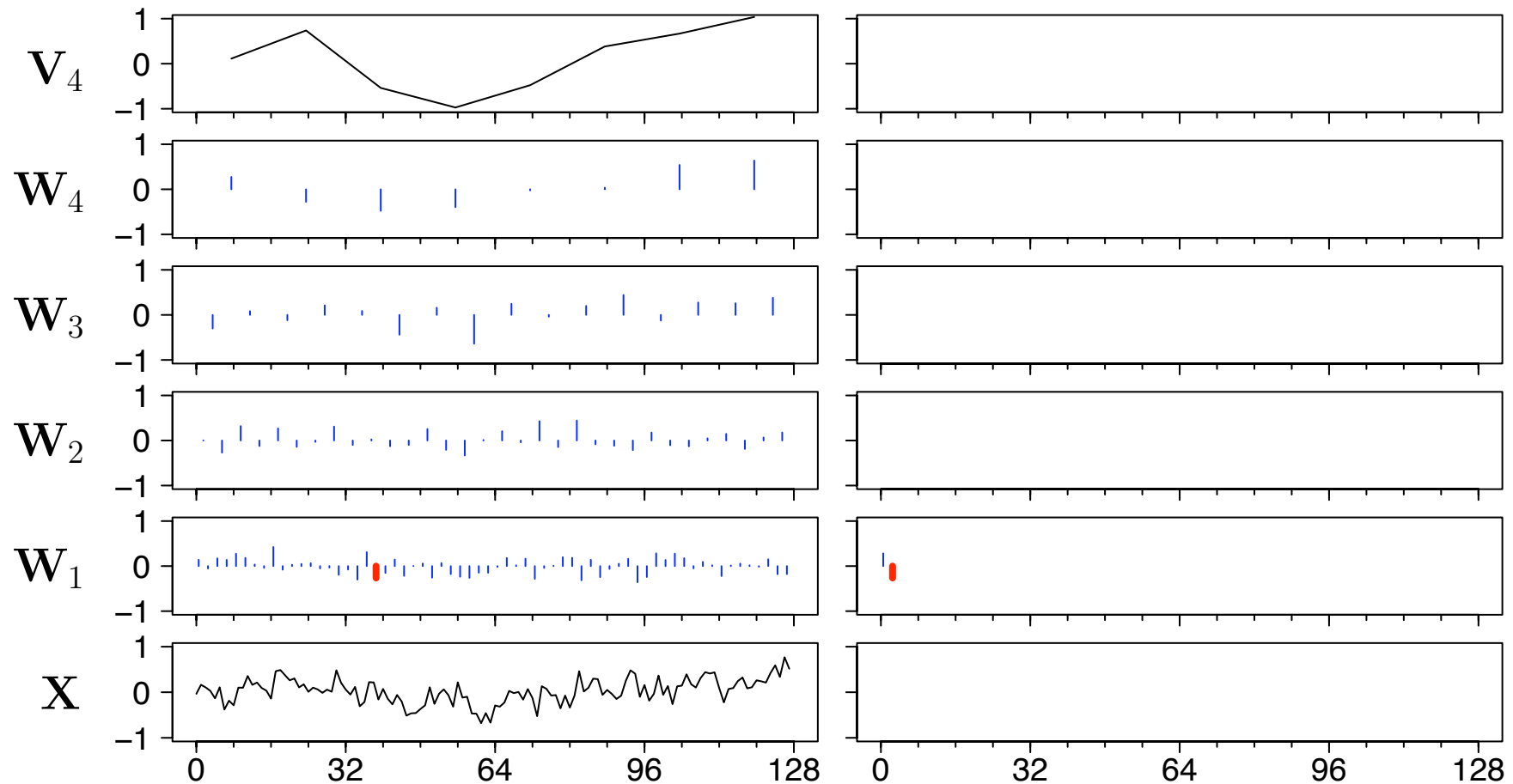
- Haar DWT of FD(0.45) series \mathbf{X} (left-hand column) and wavelet-domain bootstrap thereof (right-hand)

Illustration of Wavelet-Domain Bootstrapping



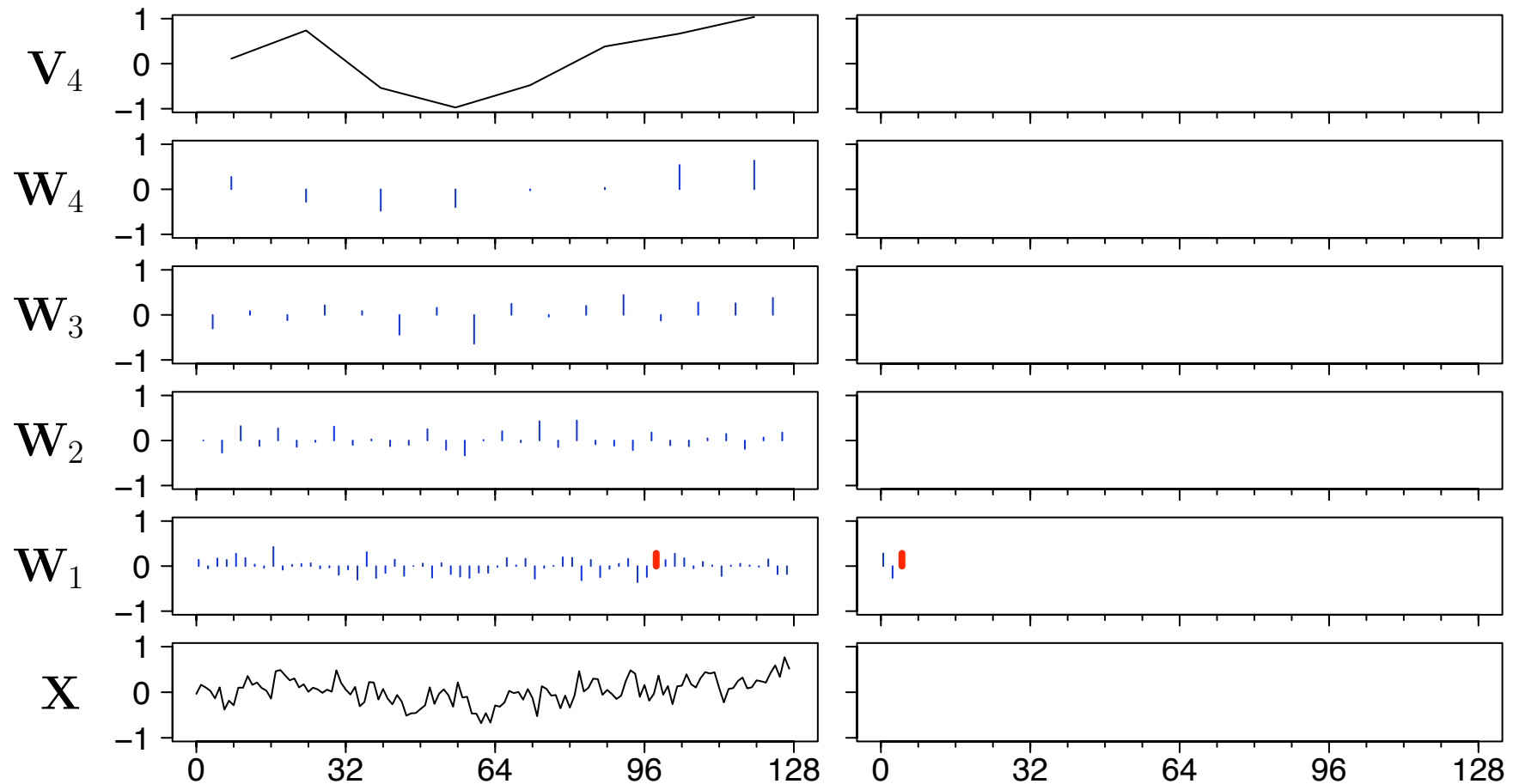
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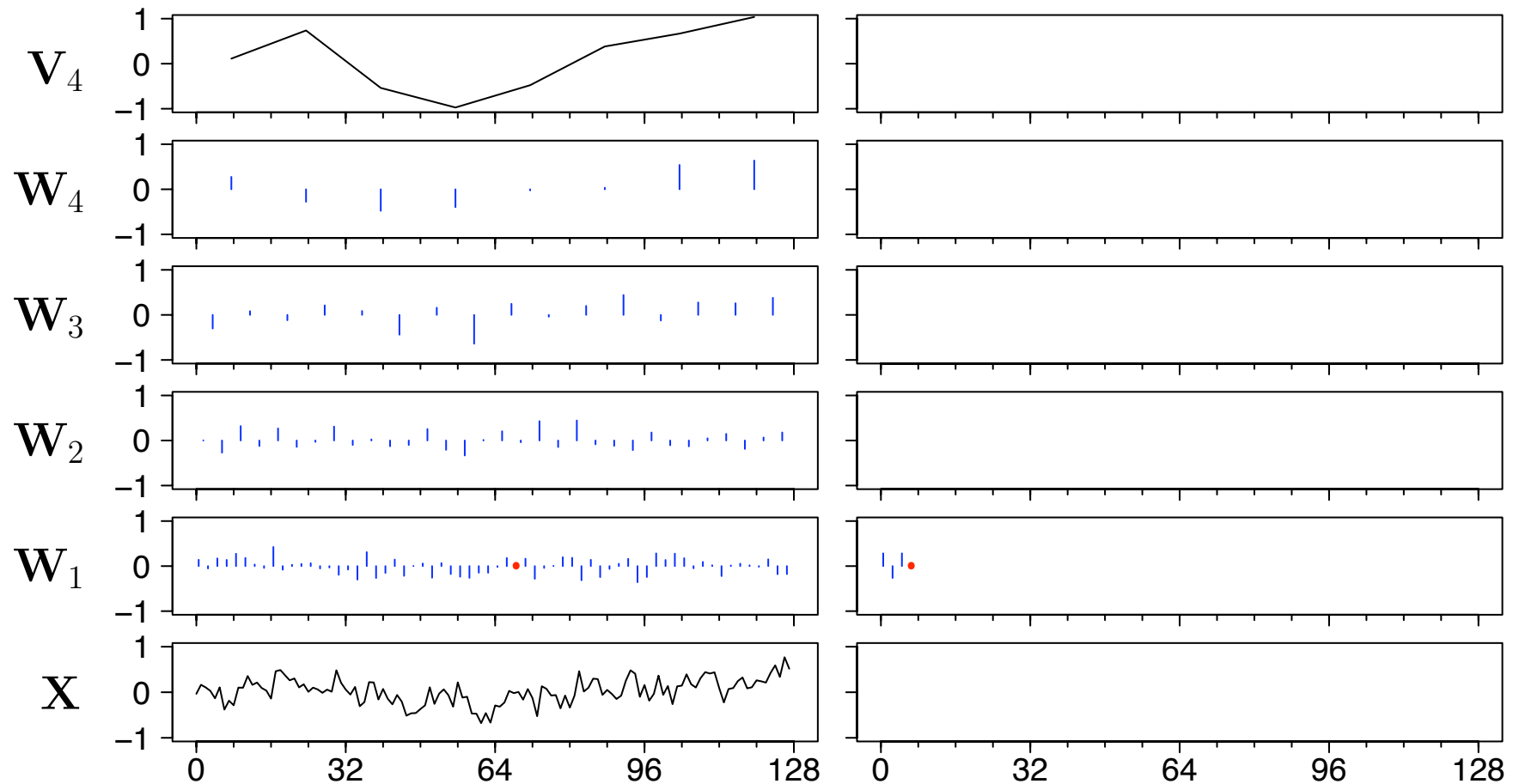
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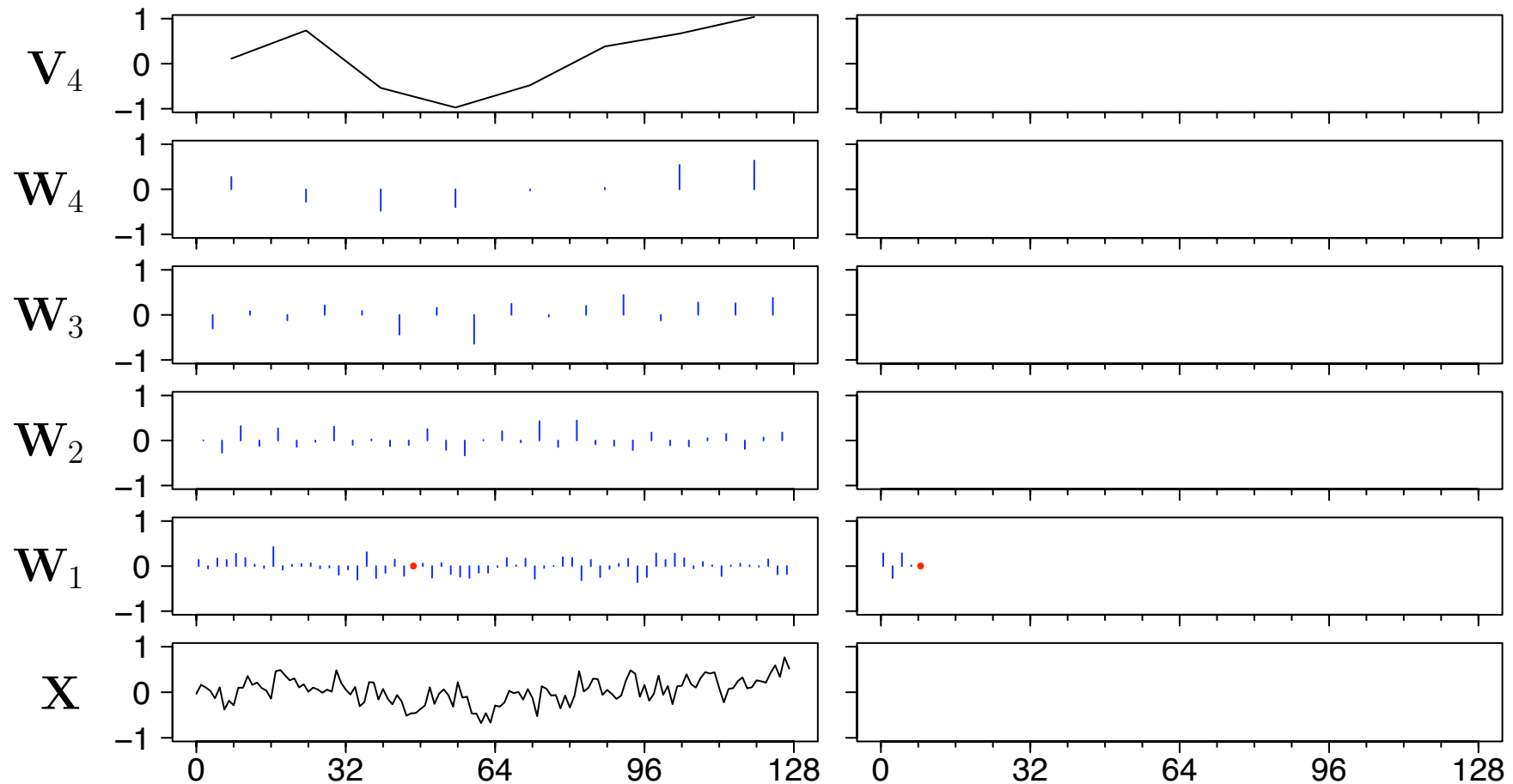
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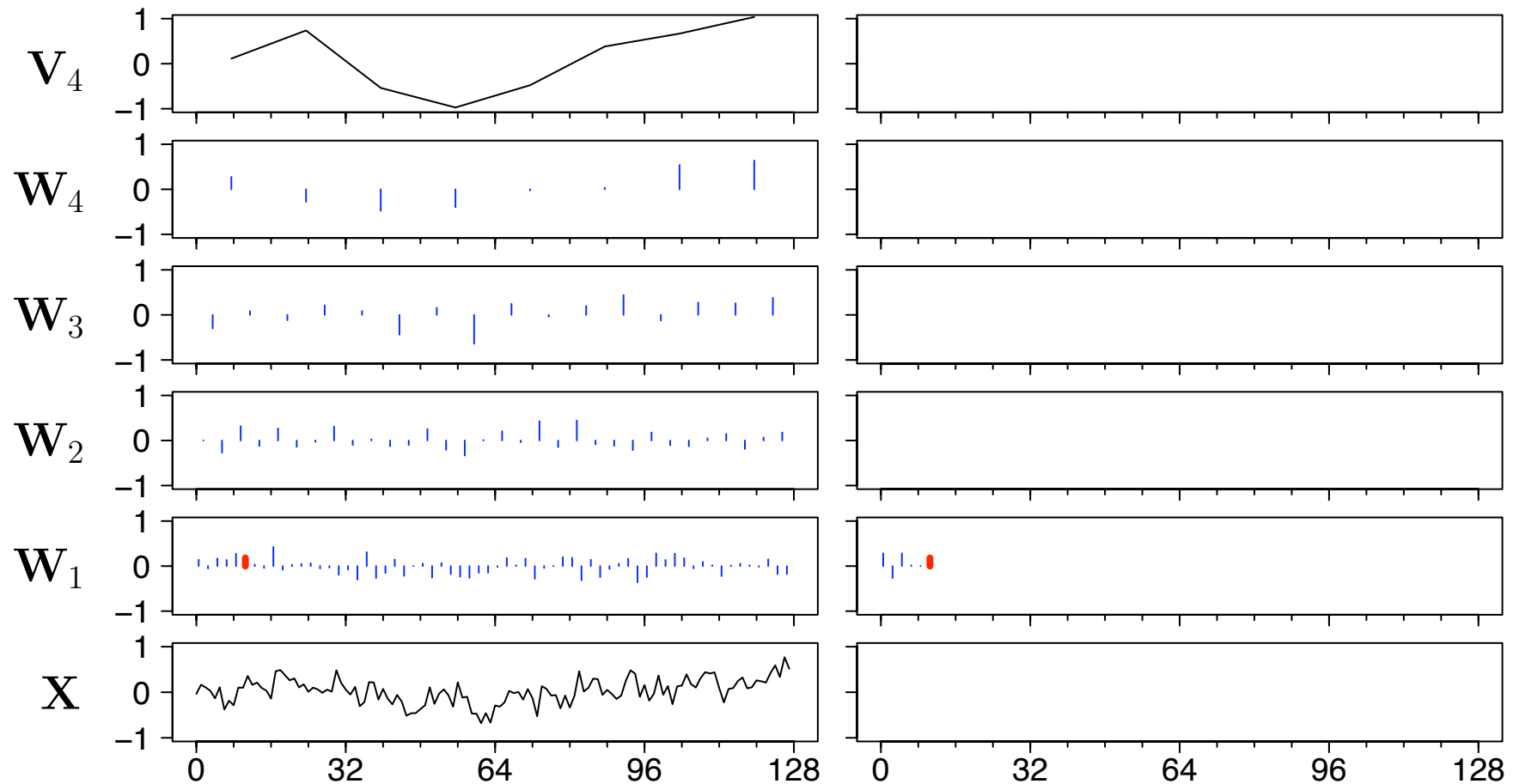
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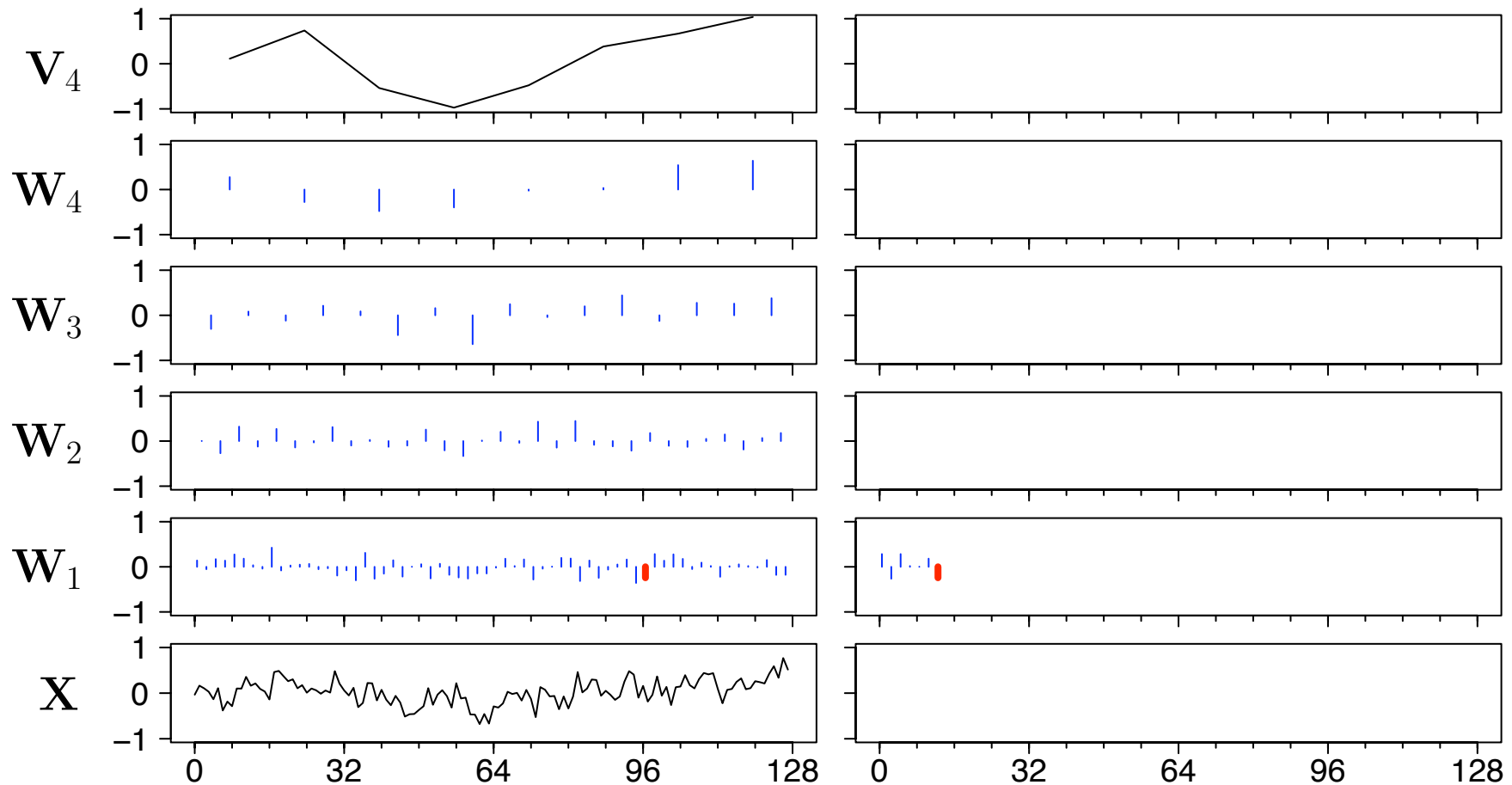
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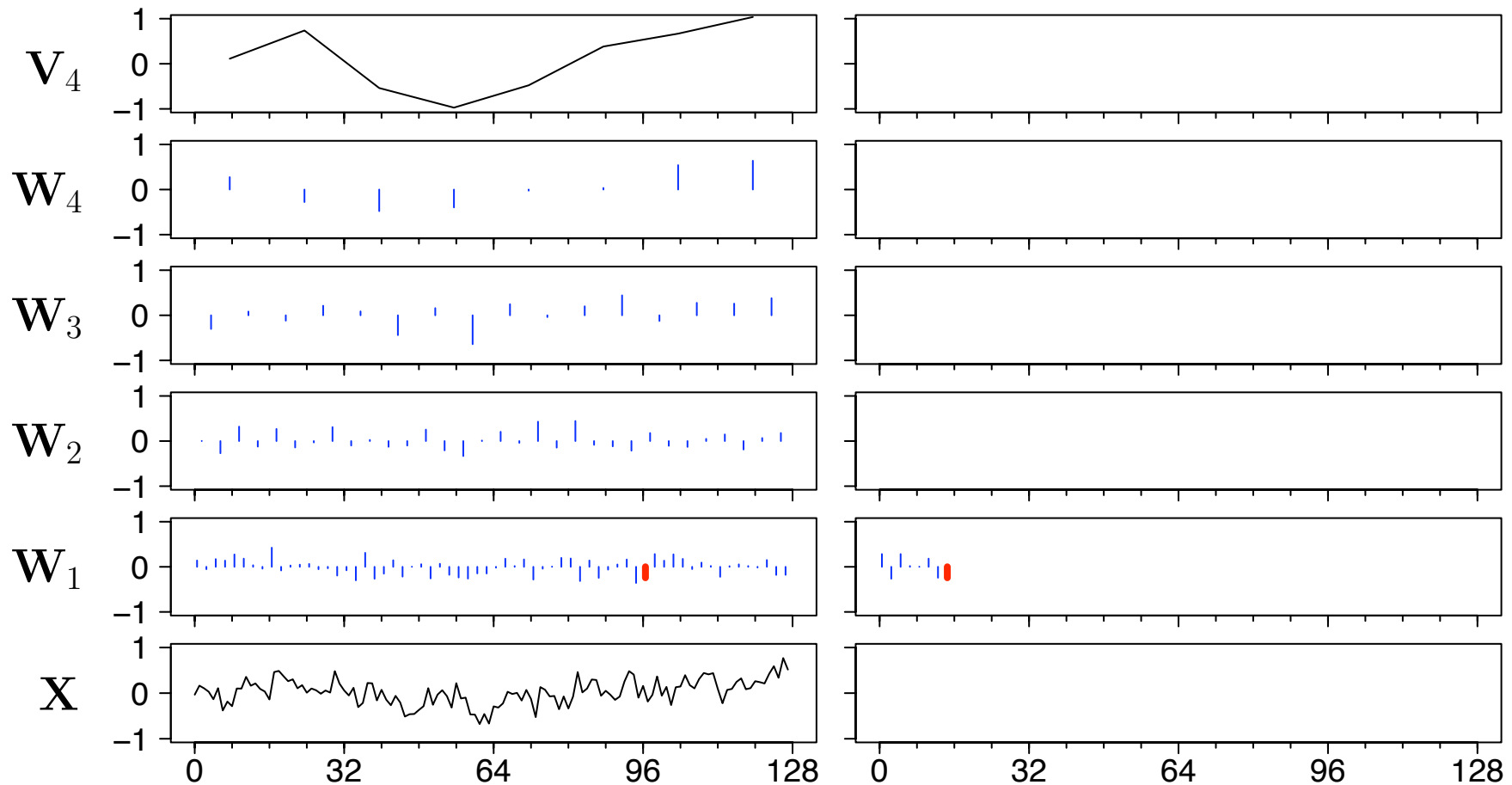
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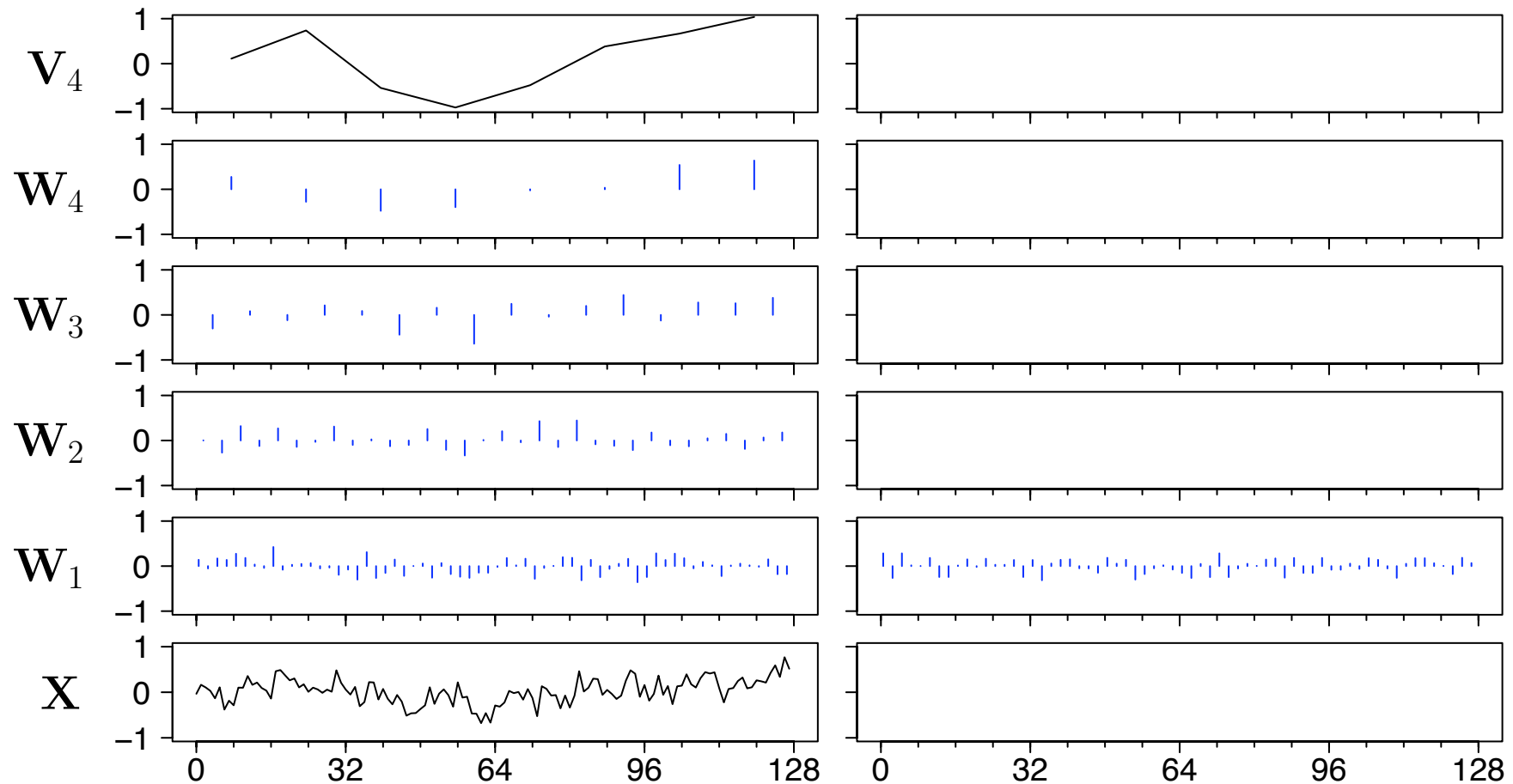
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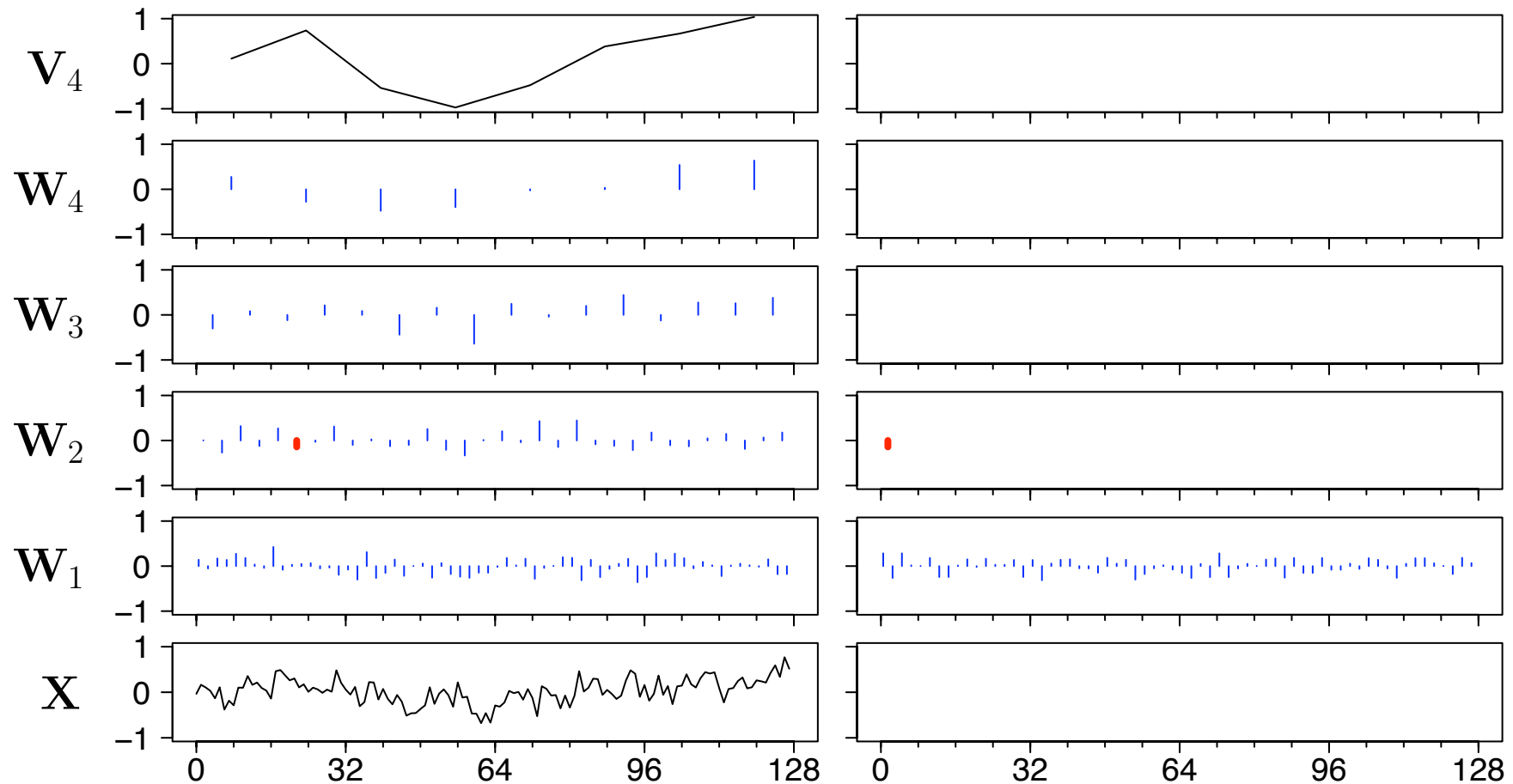
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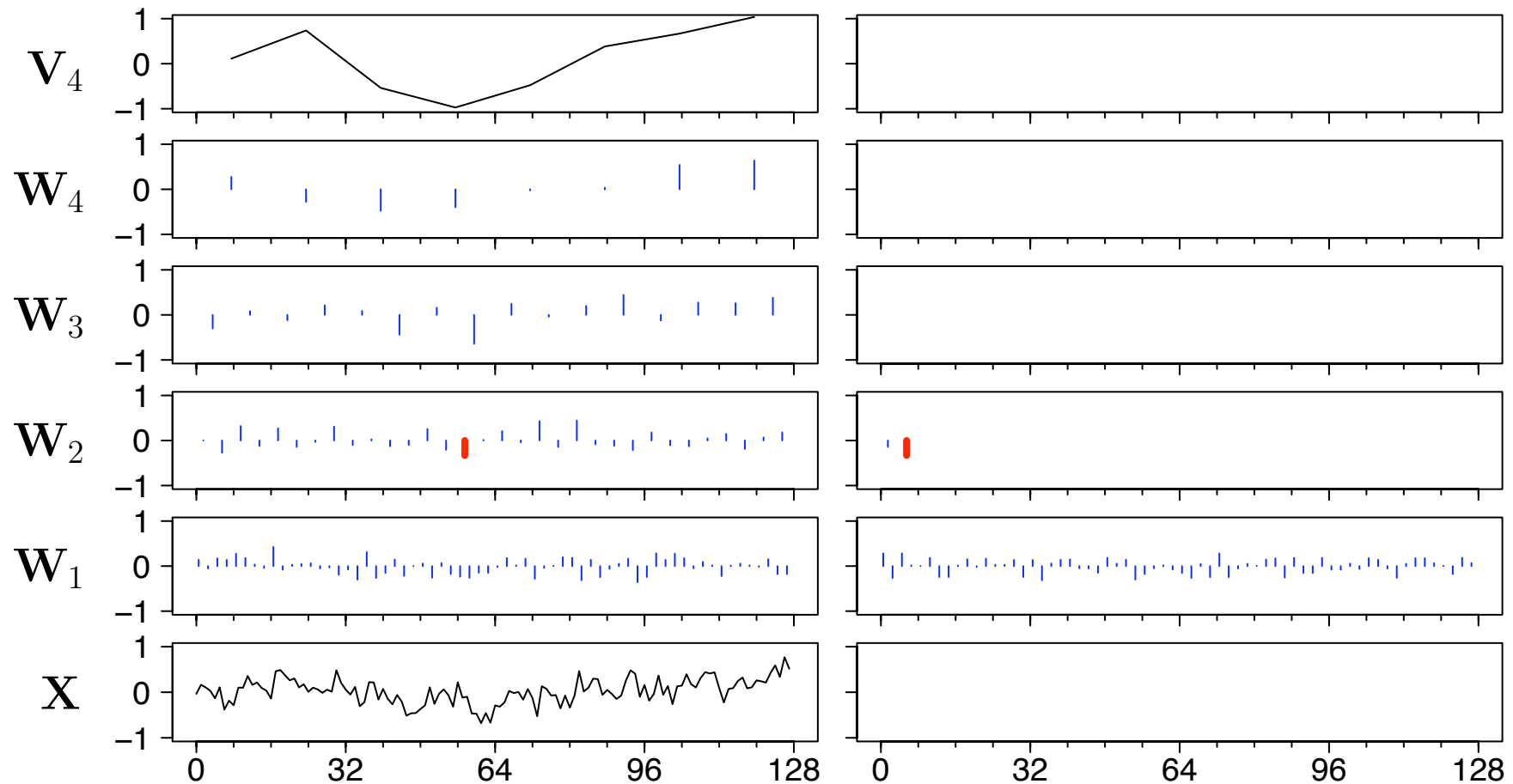
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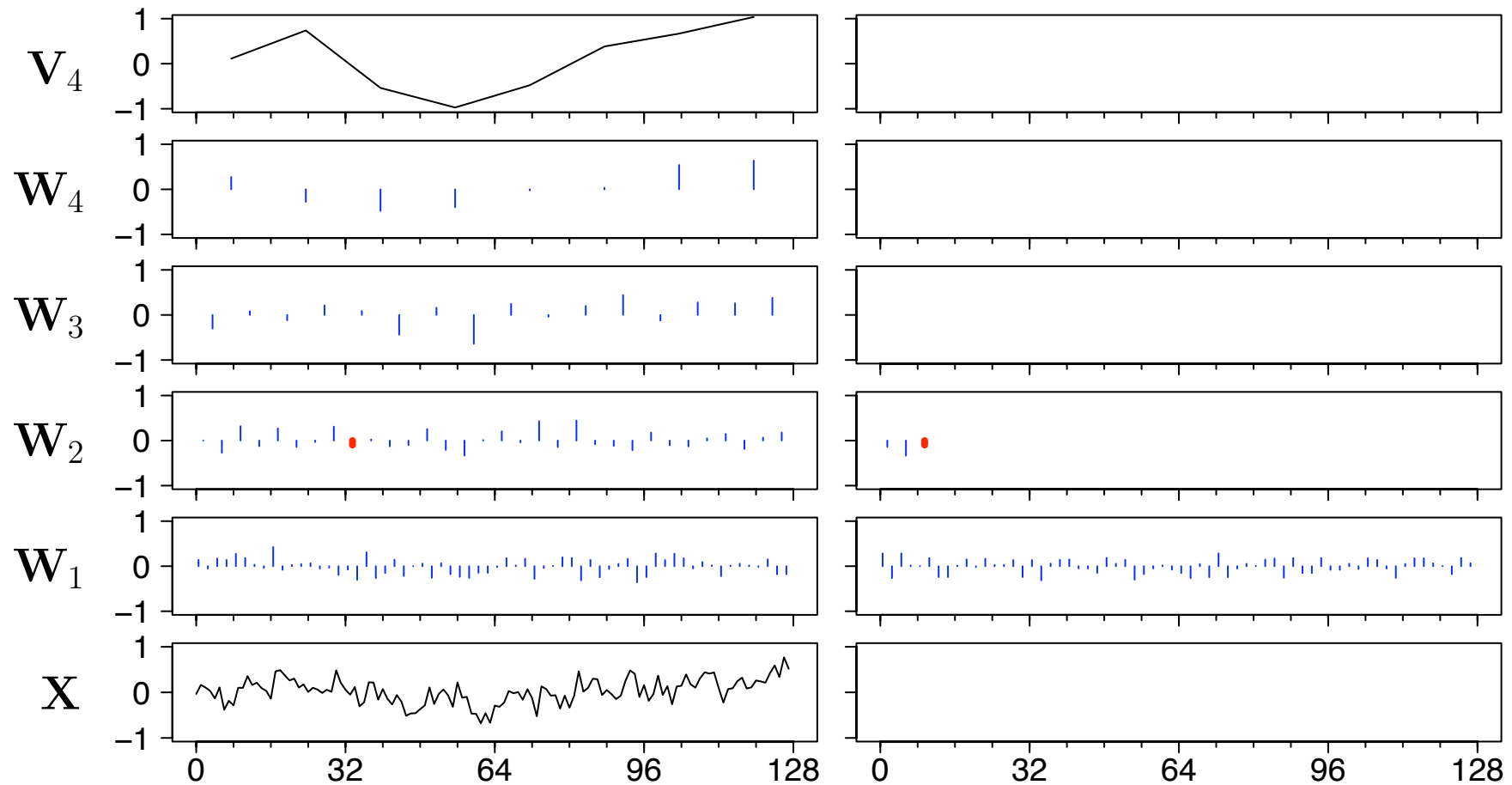
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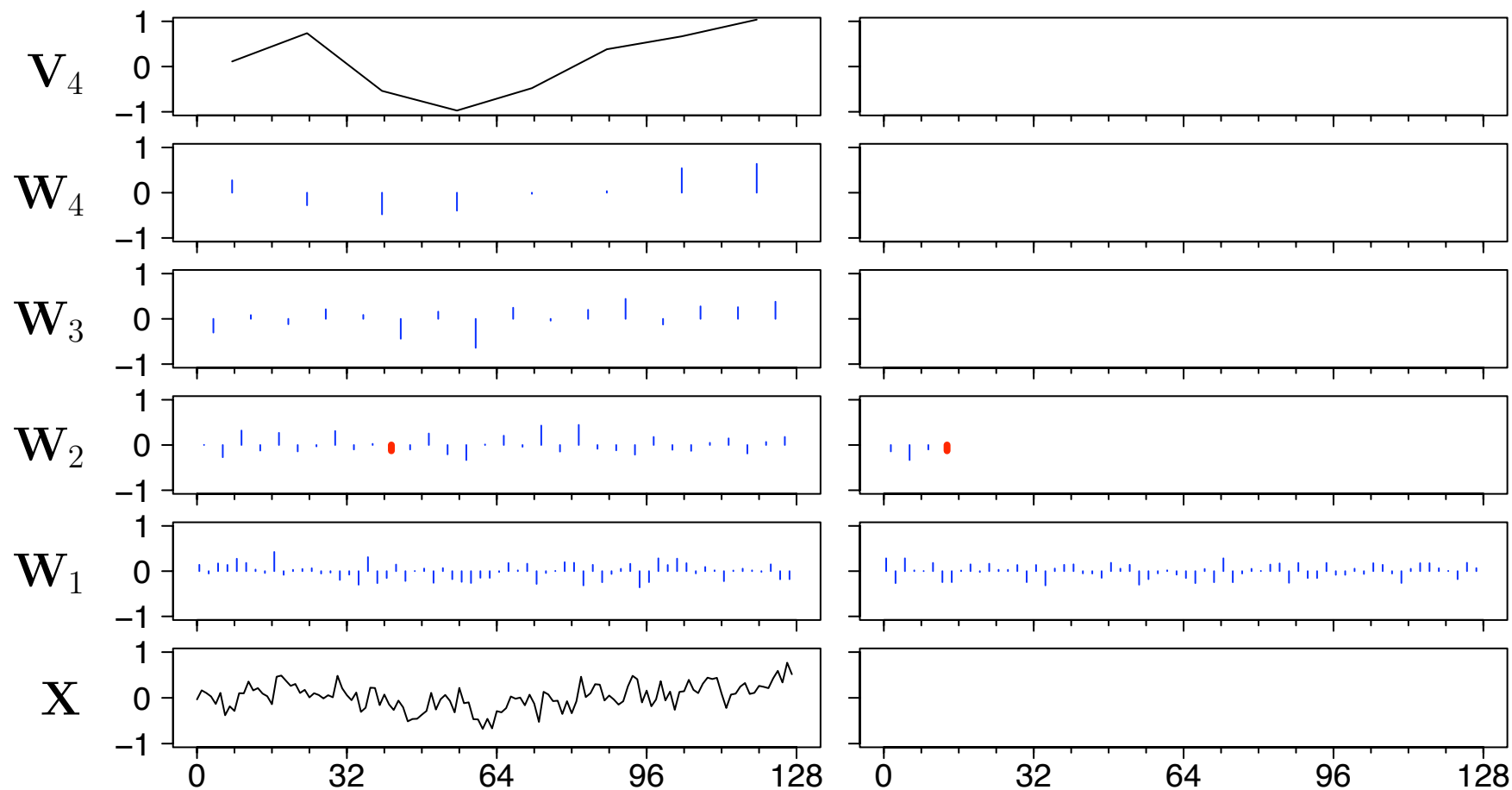
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Illustration of Wavelet-Domain Bootstrapping



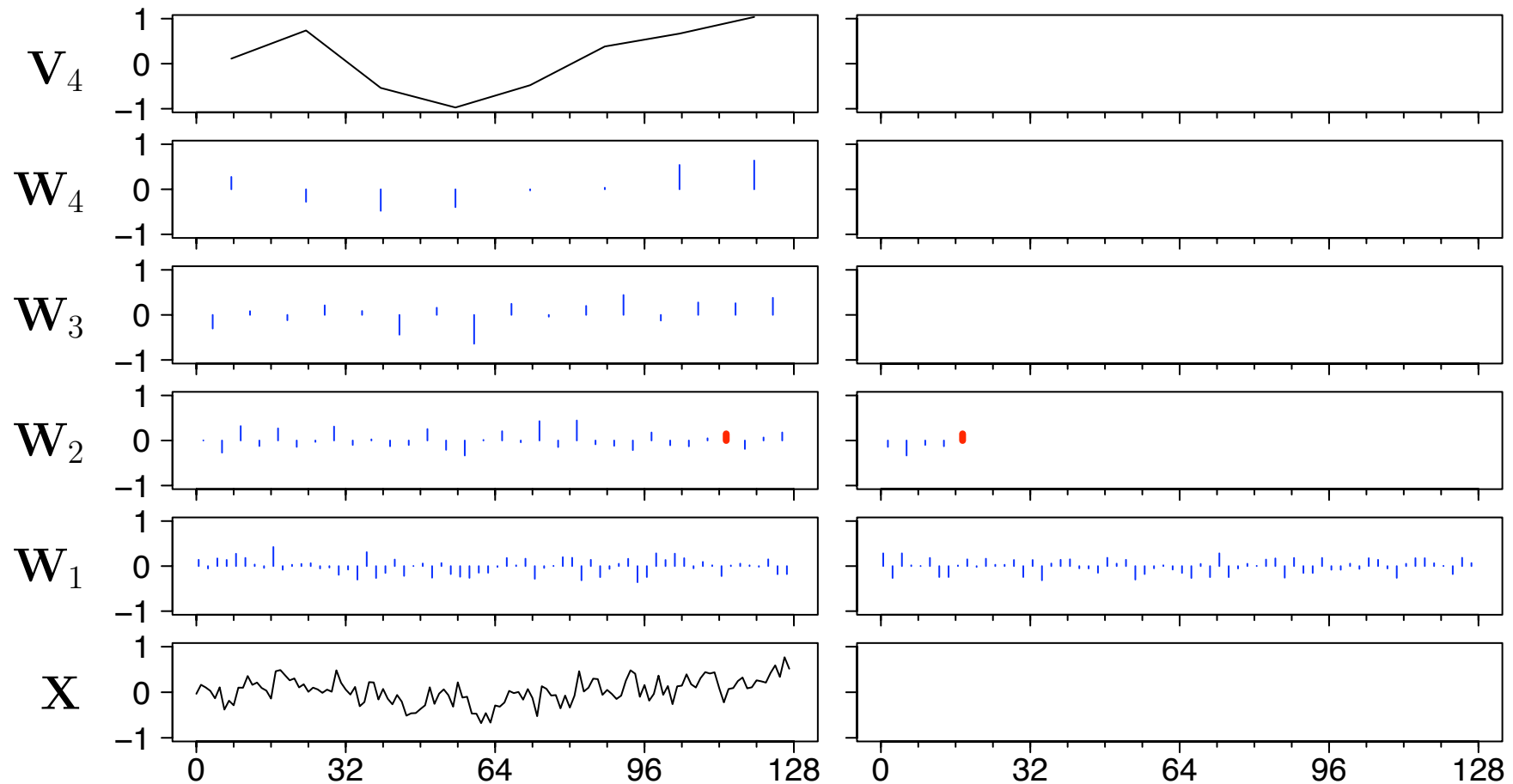
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Illustration of Wavelet-Domain Bootstrapping



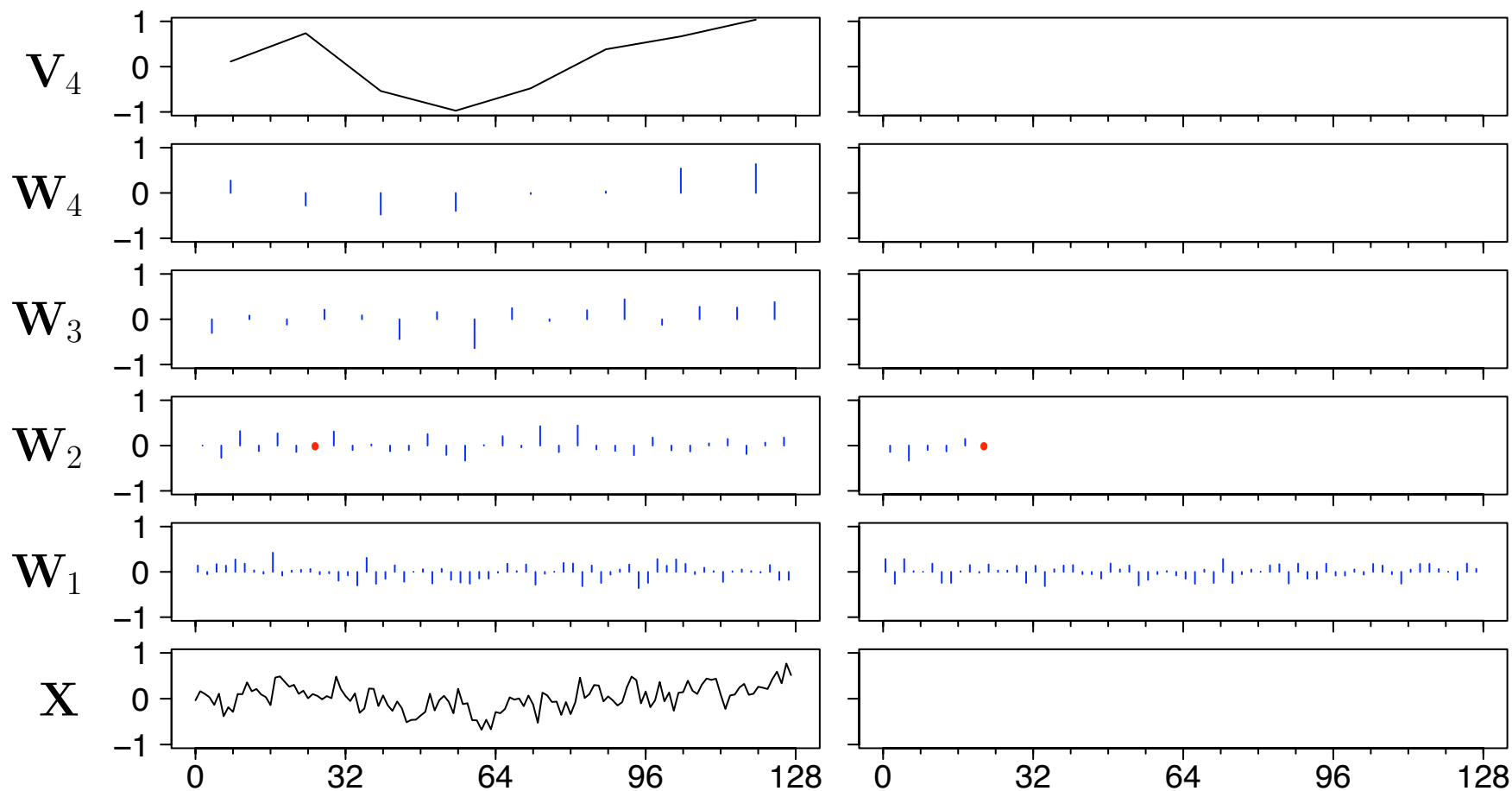
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Illustration of Wavelet-Domain Bootstrapping



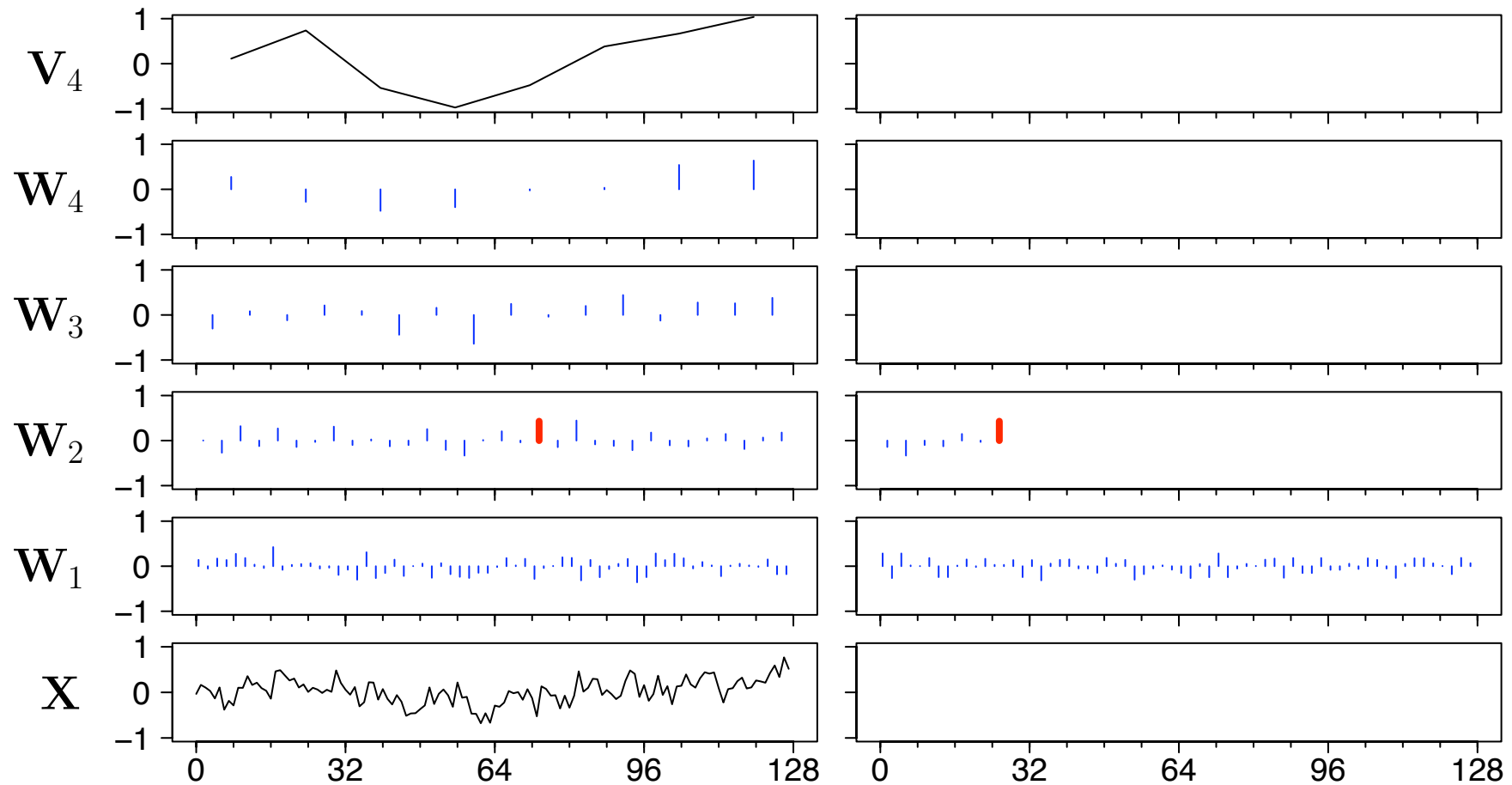
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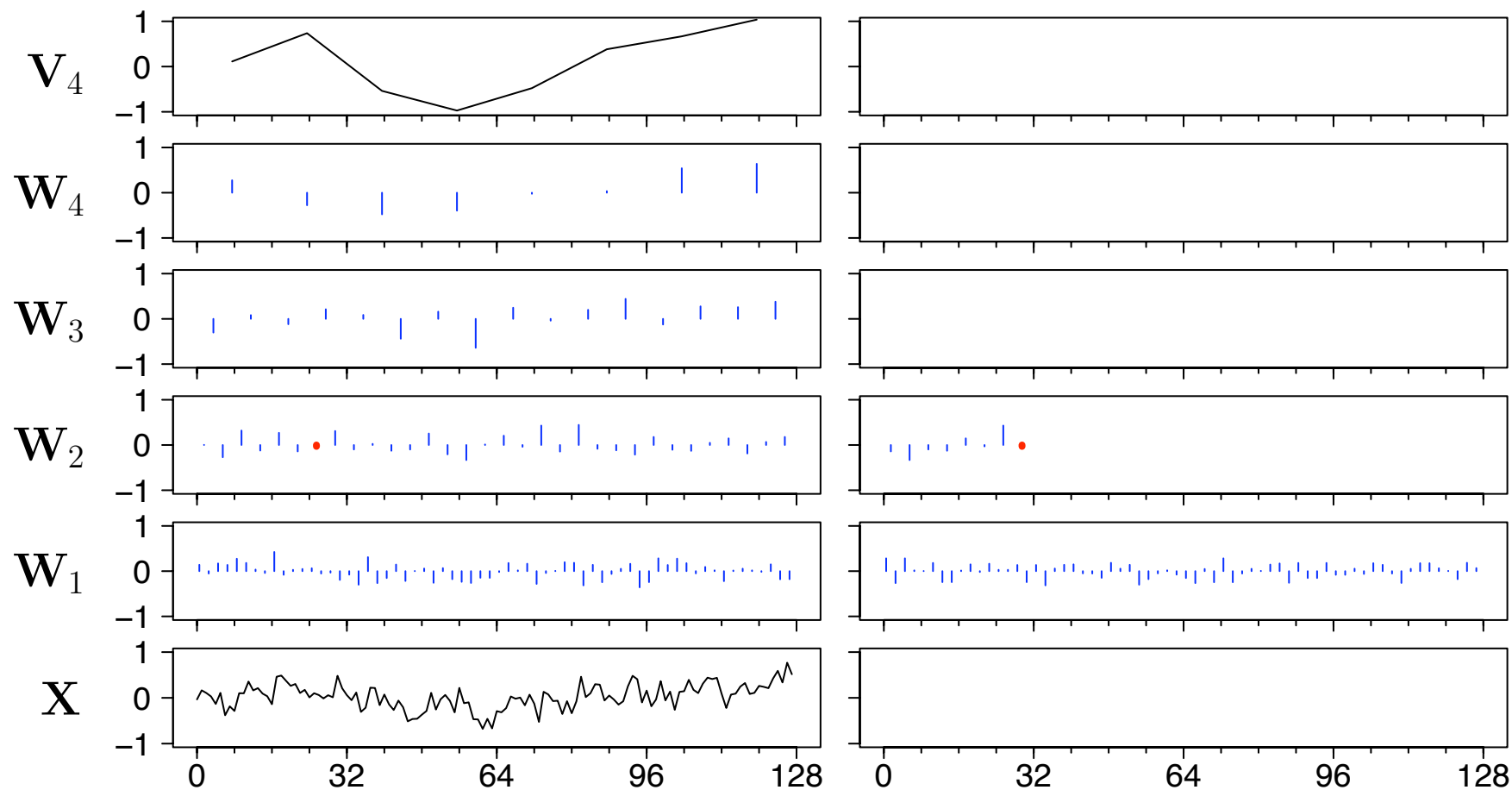
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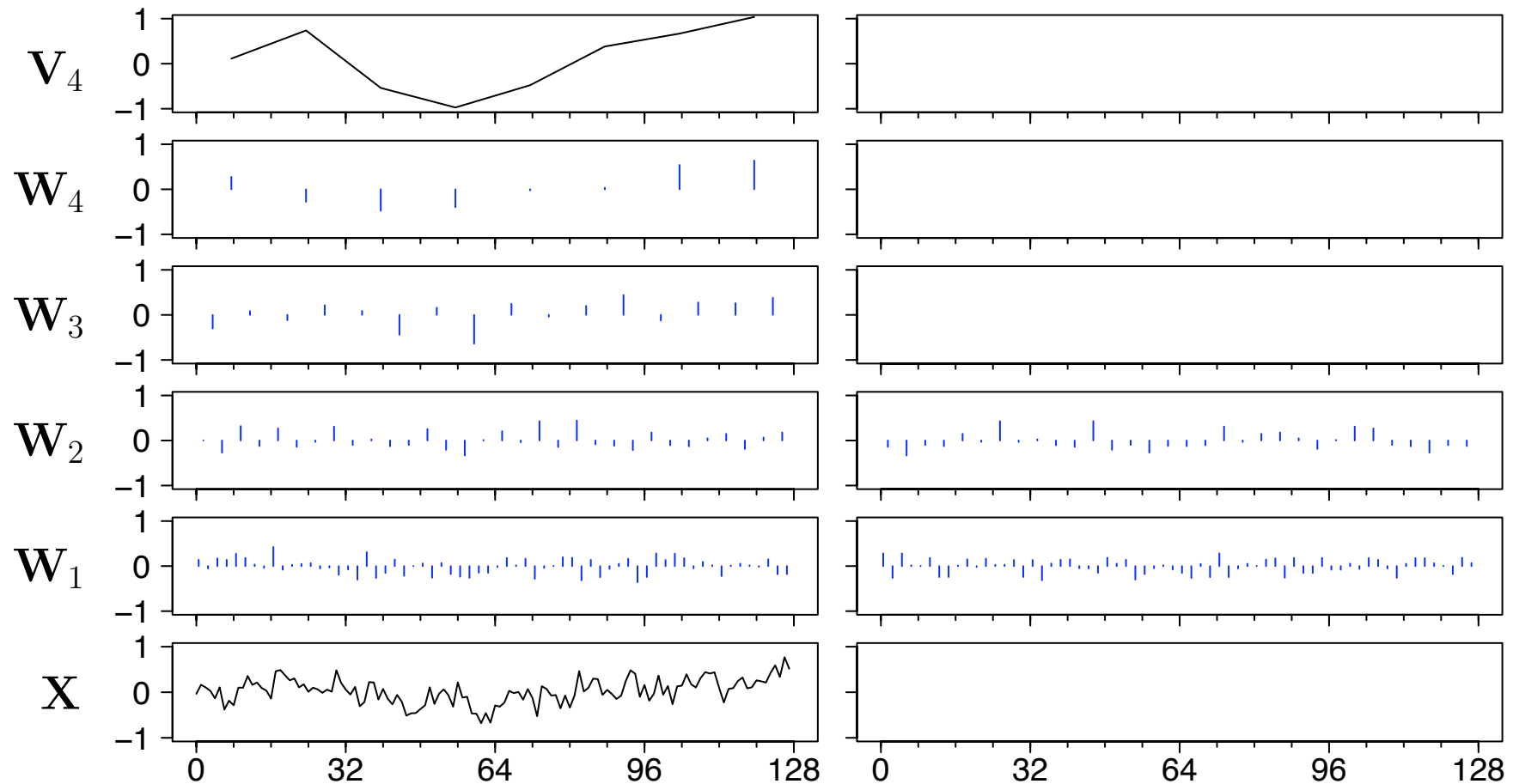
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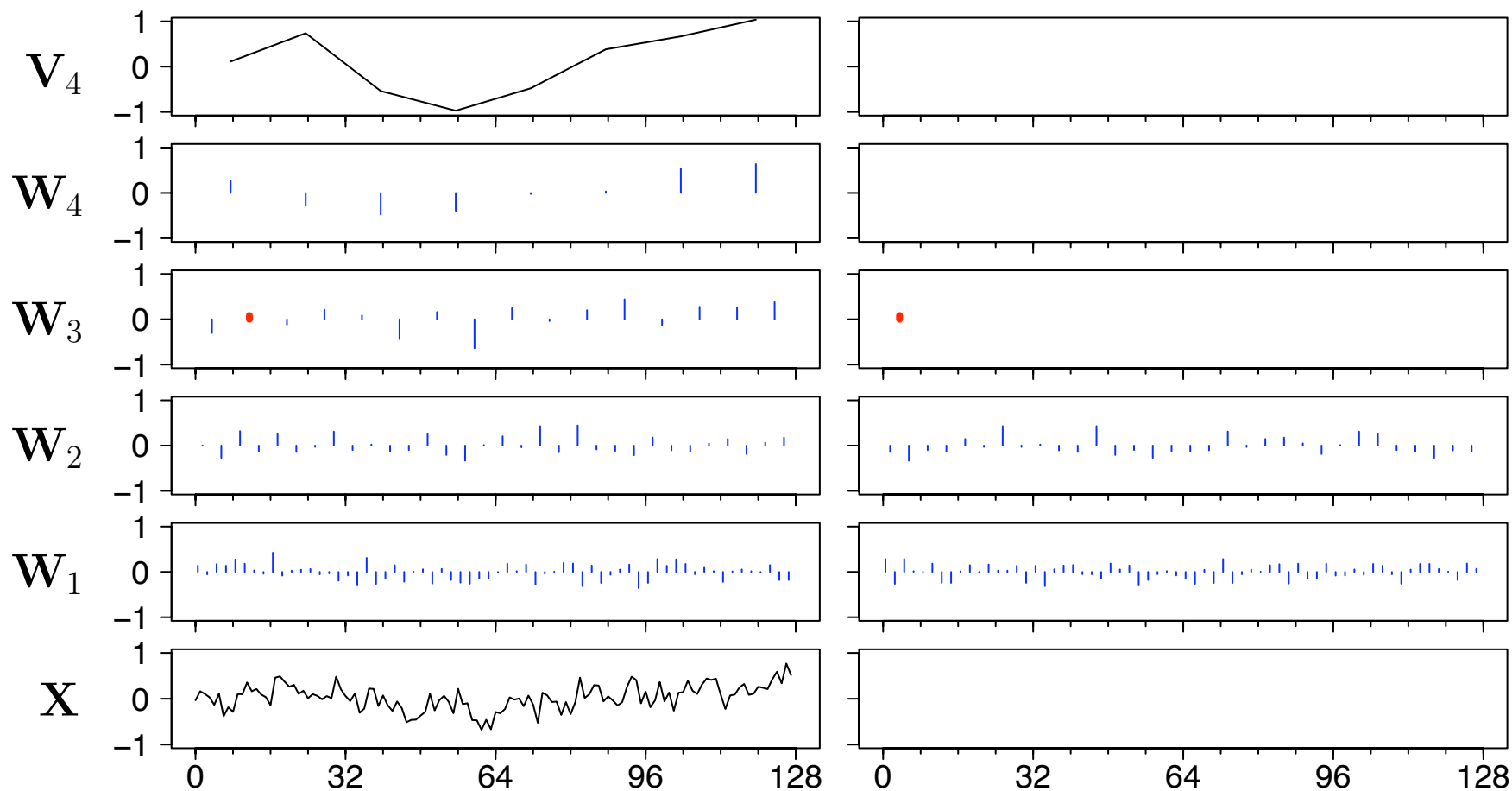
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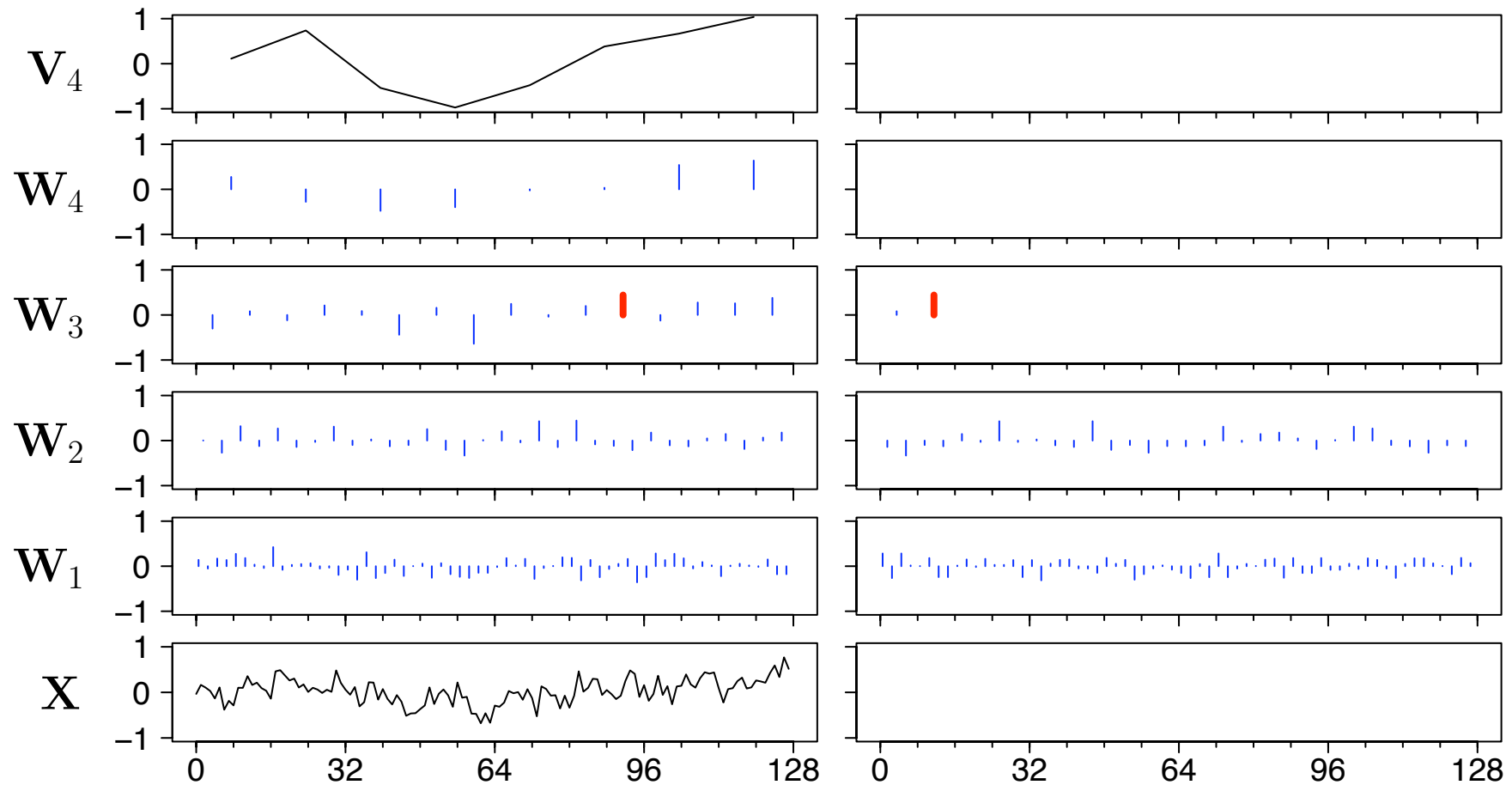
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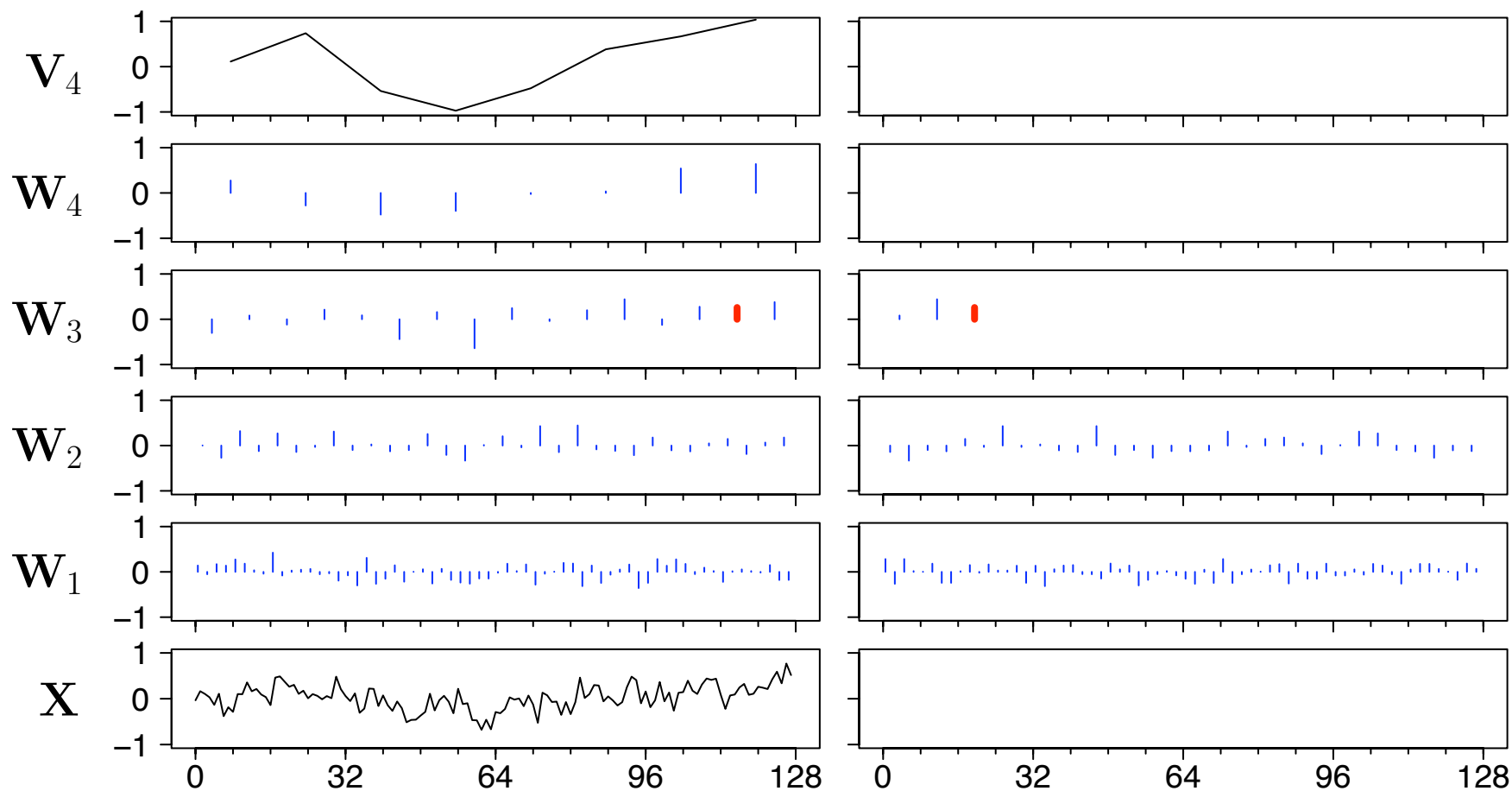
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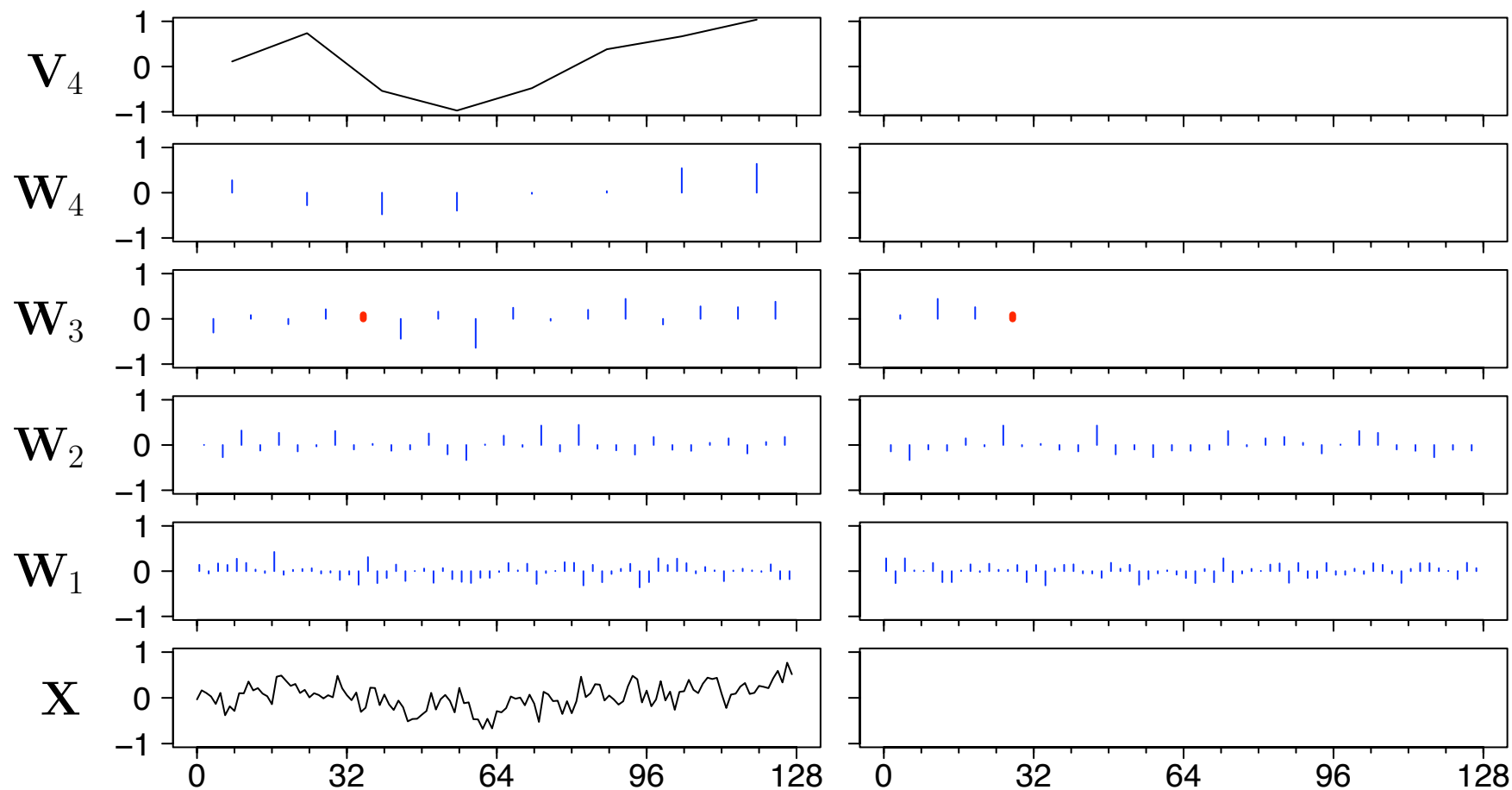
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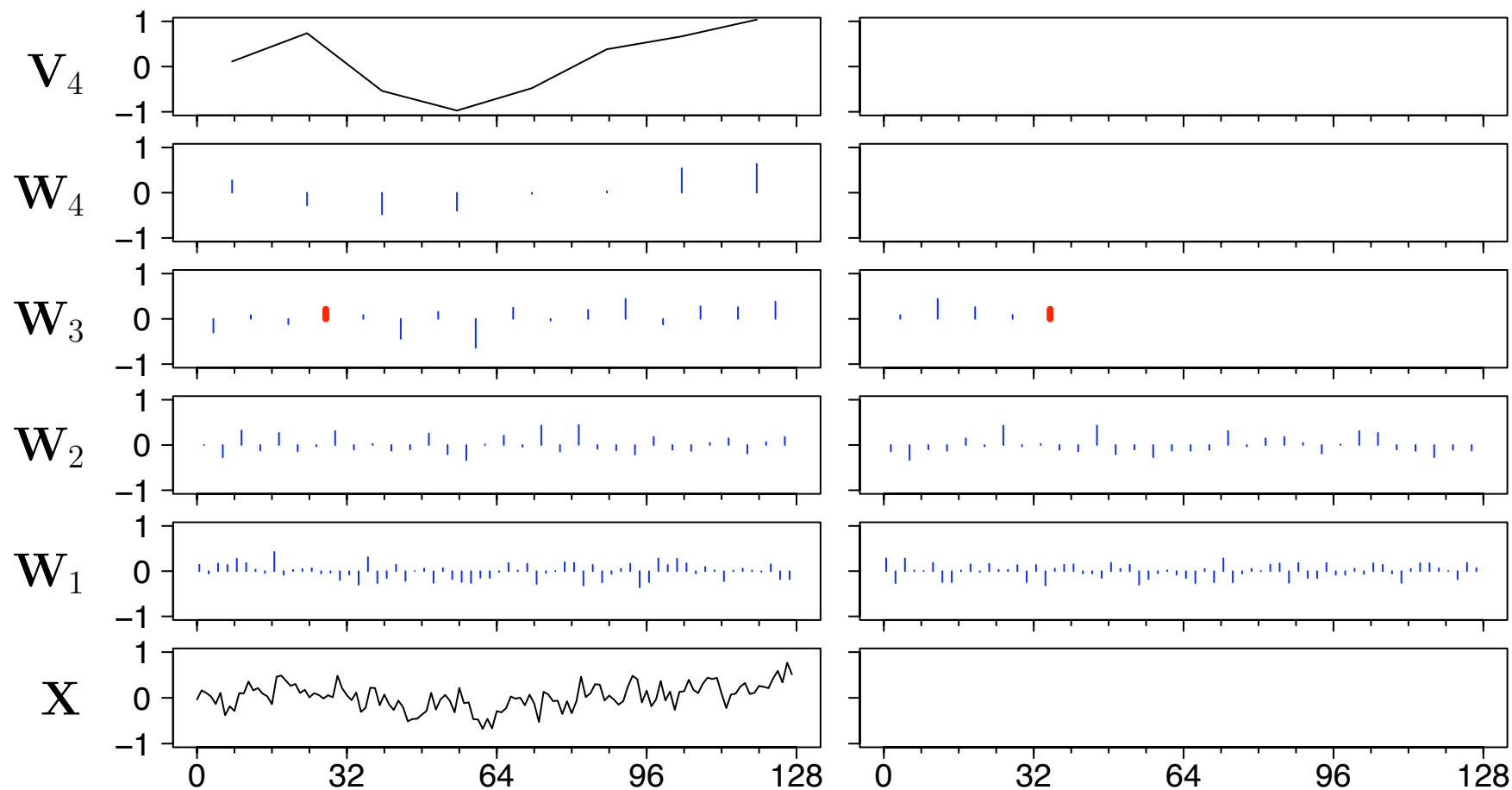
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Illustration of Wavelet-Domain Bootstrapping



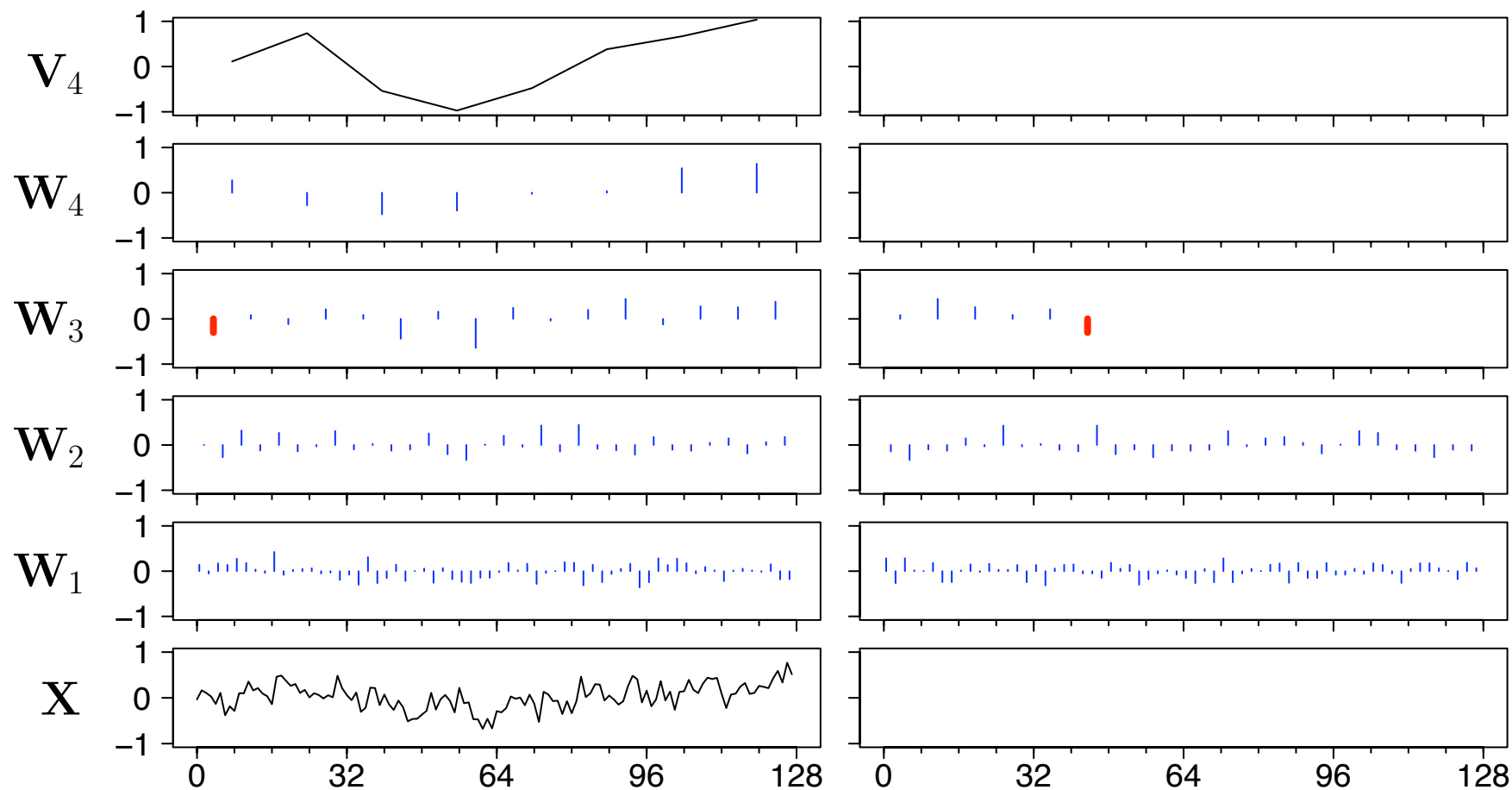
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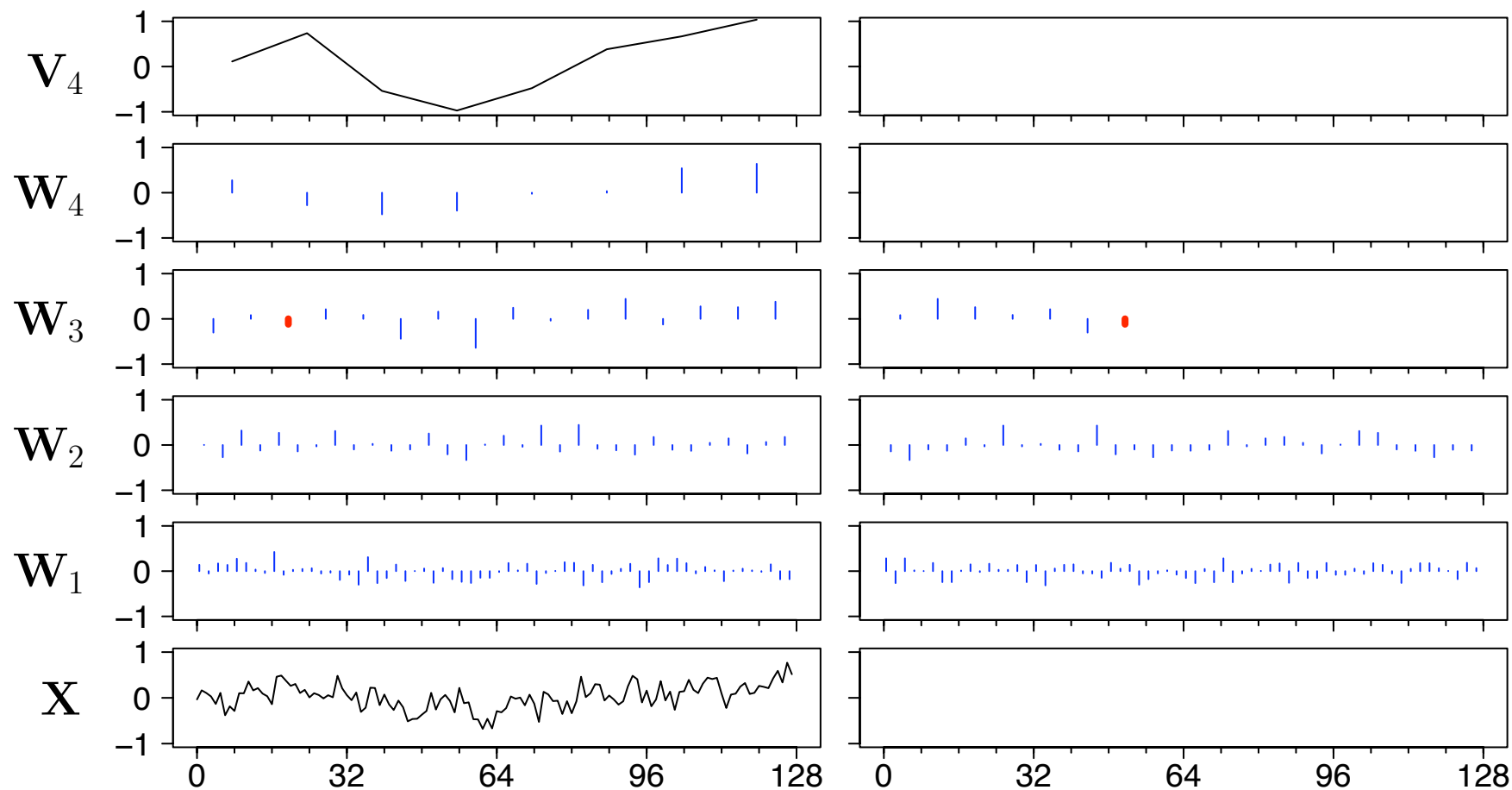
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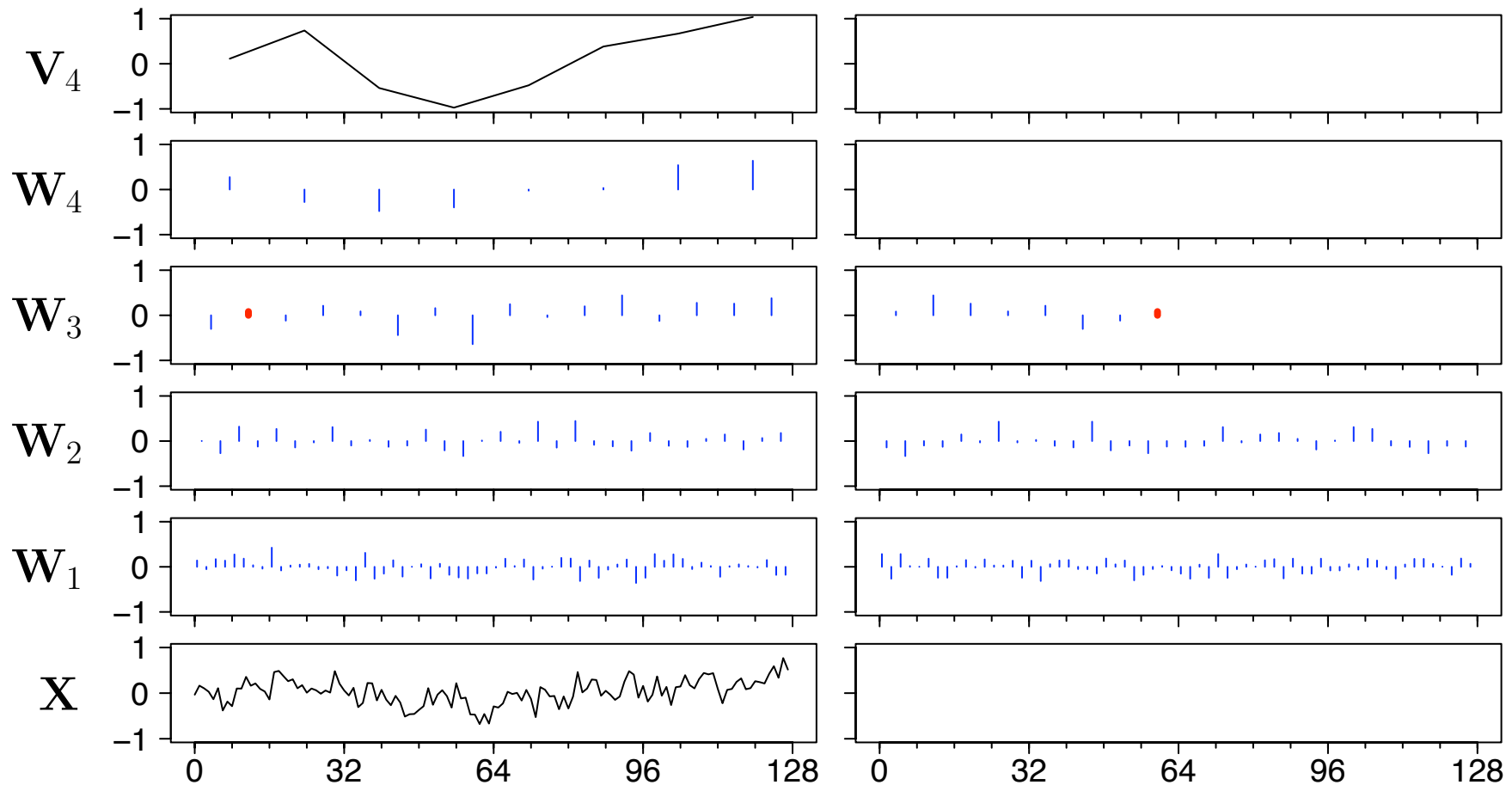
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Illustration of Wavelet-Domain Bootstrapping



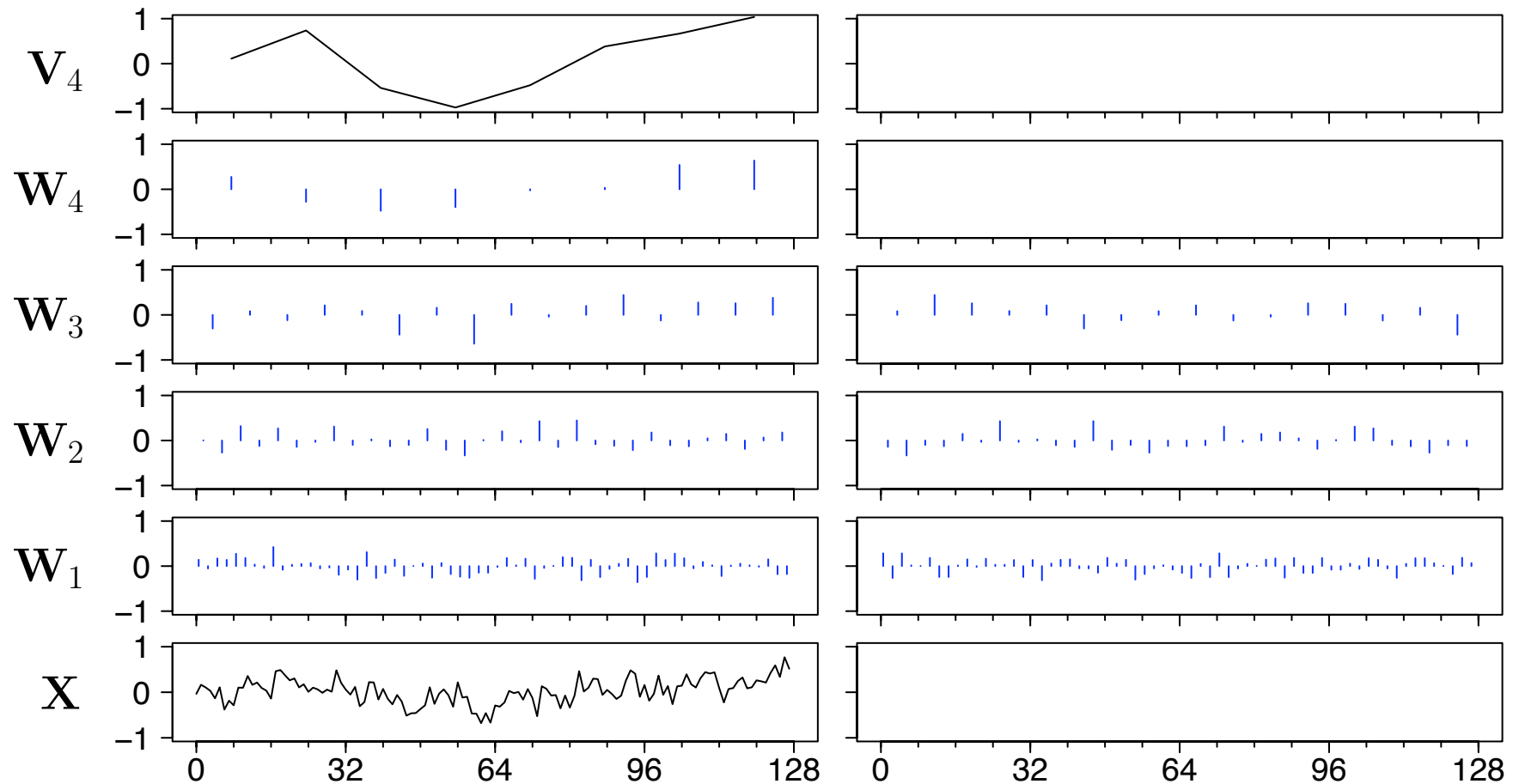
- Haar DWT of FD(0.45) series \mathbf{X} (left-hand column) and wavelet-domain bootstrap thereof (right-hand)

Illustration of Wavelet-Domain Bootstrapping



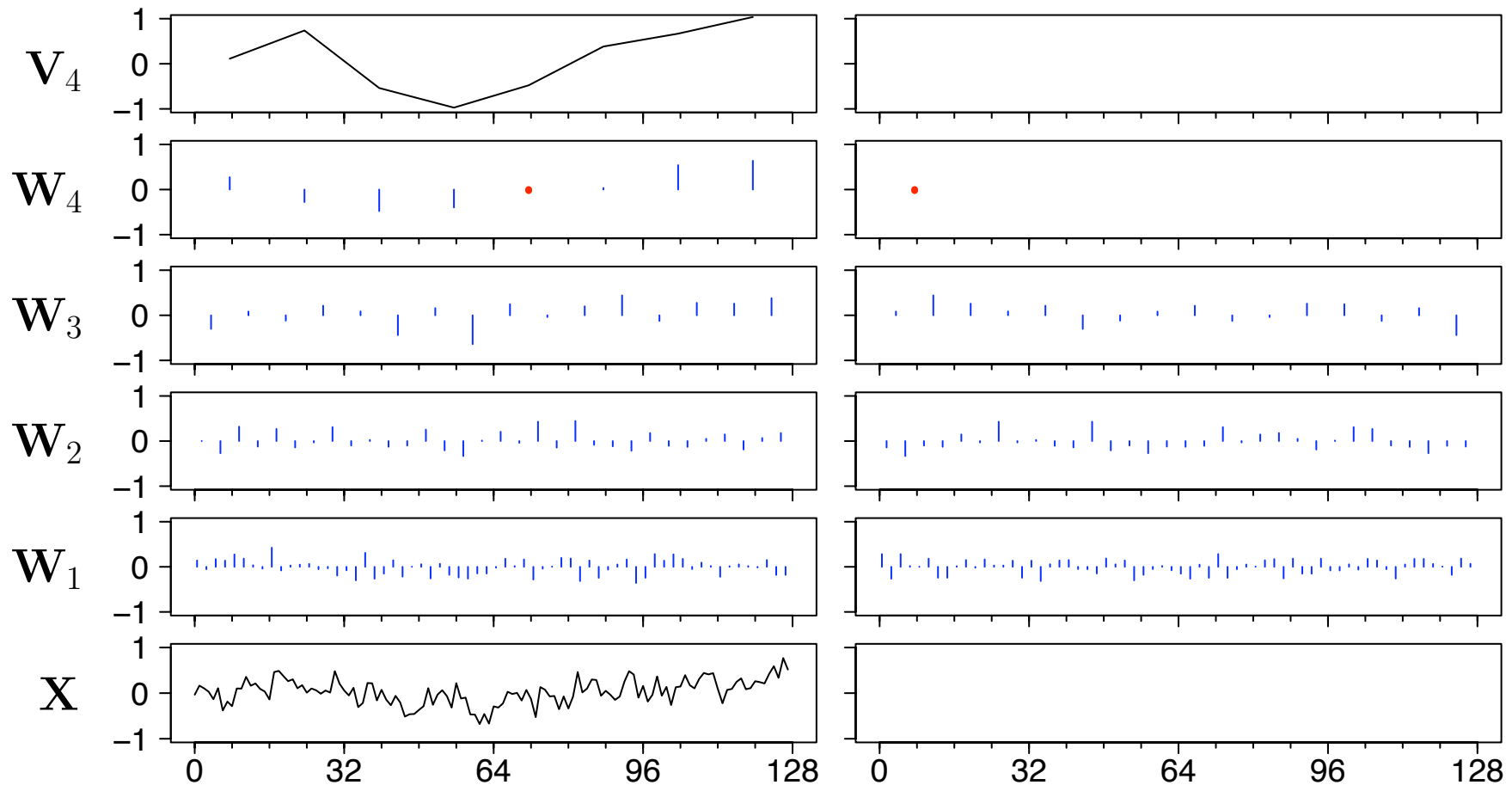
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Illustration of Wavelet-Domain Bootstrapping



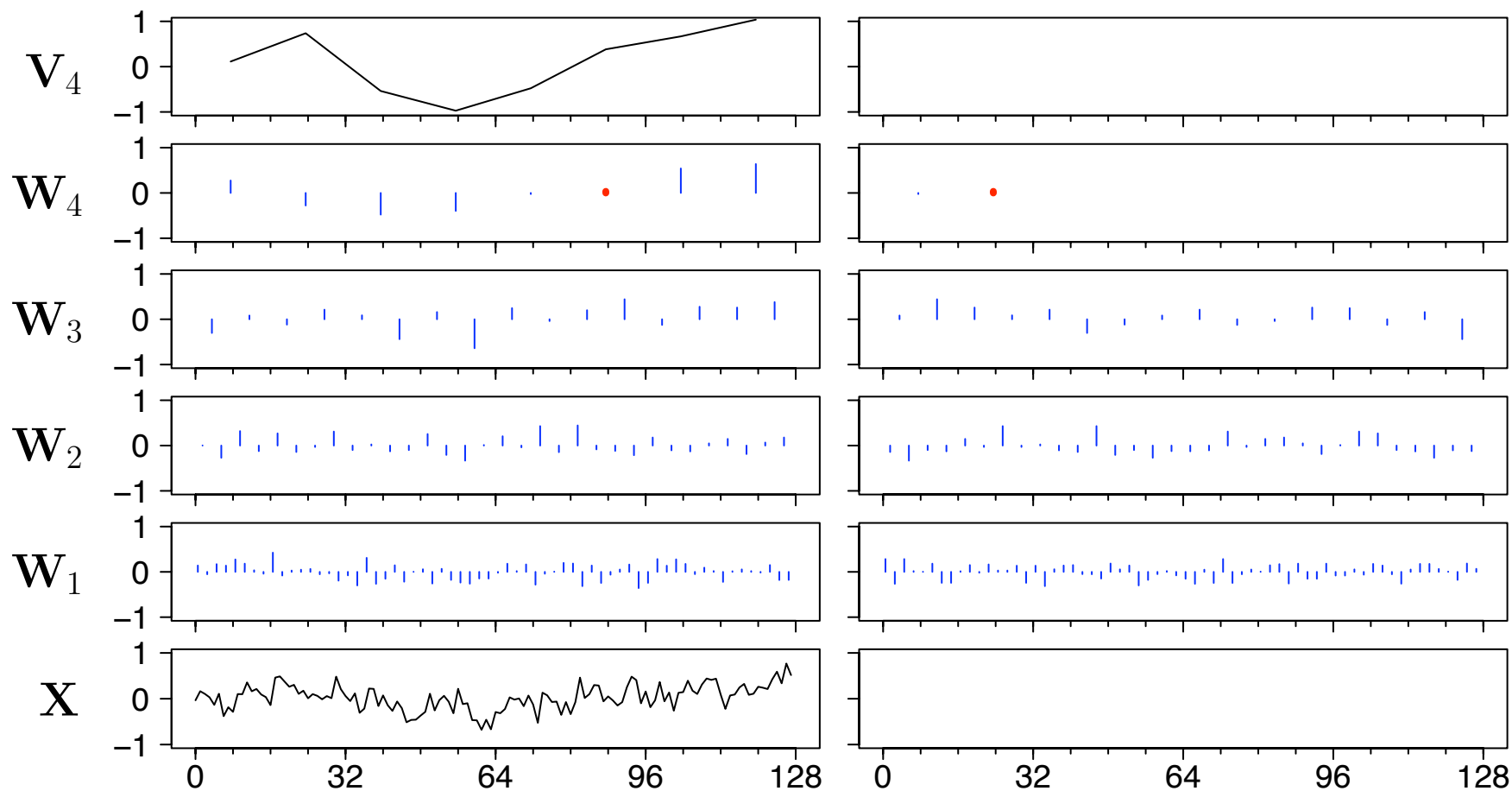
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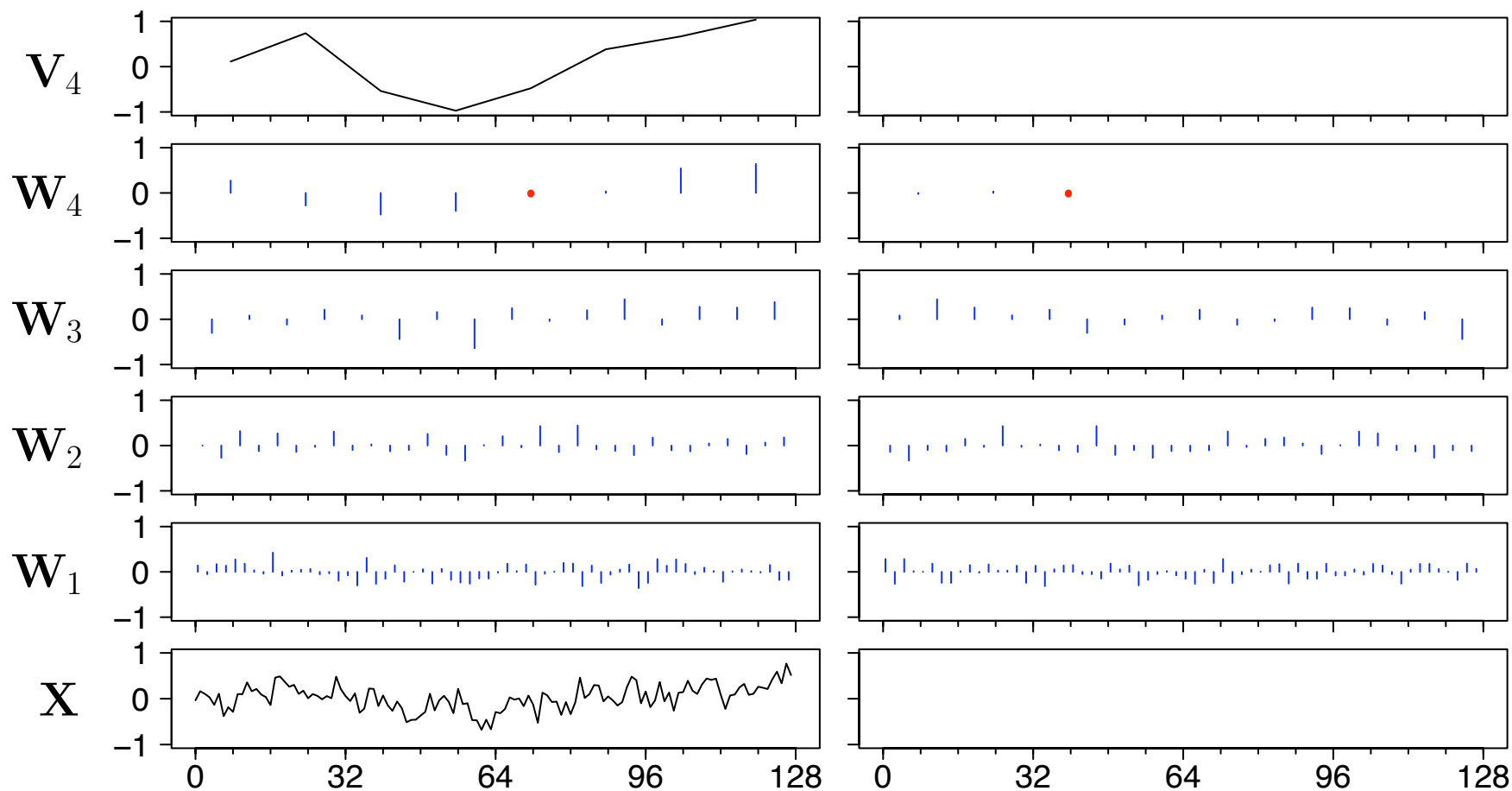
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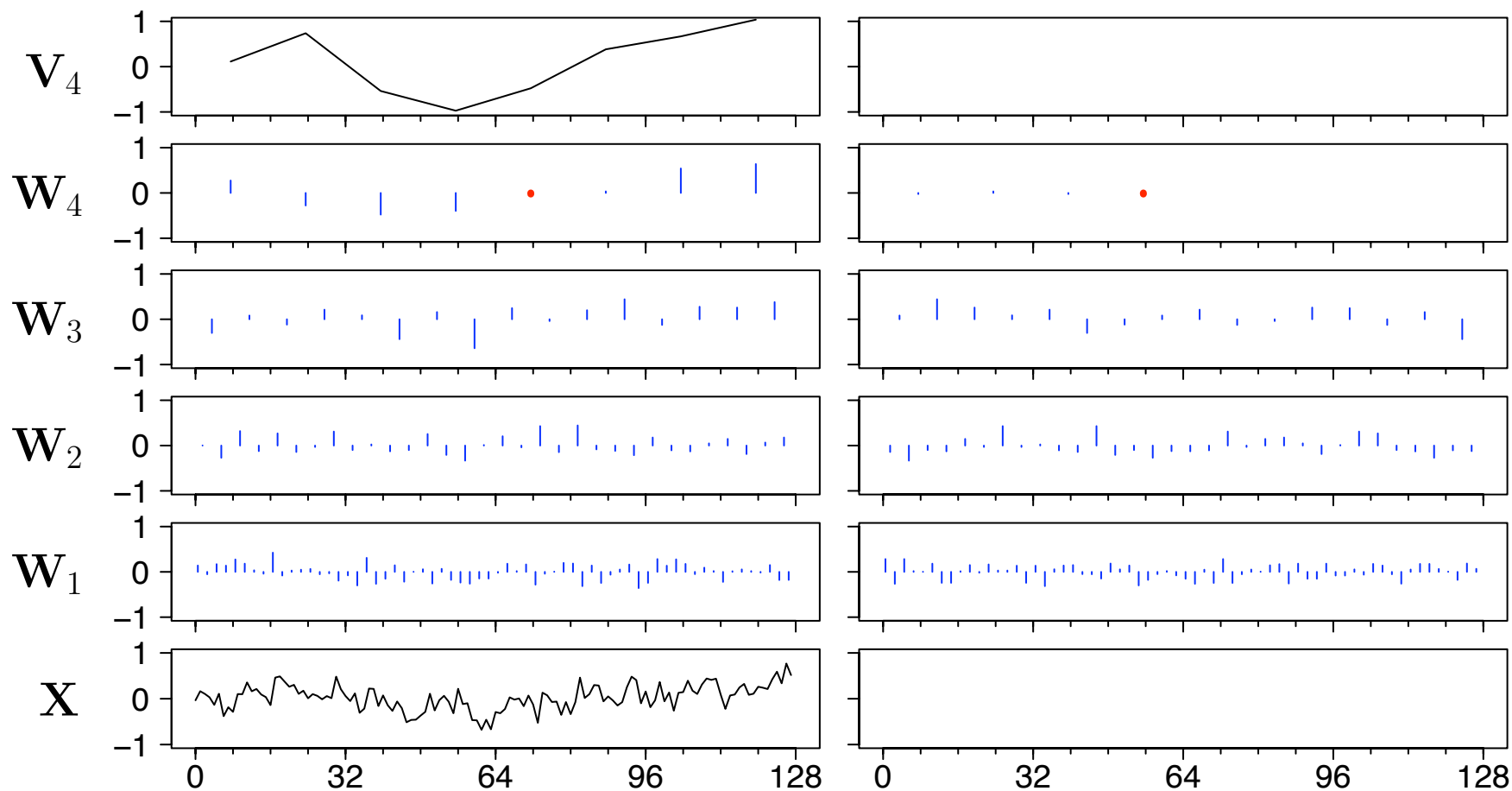
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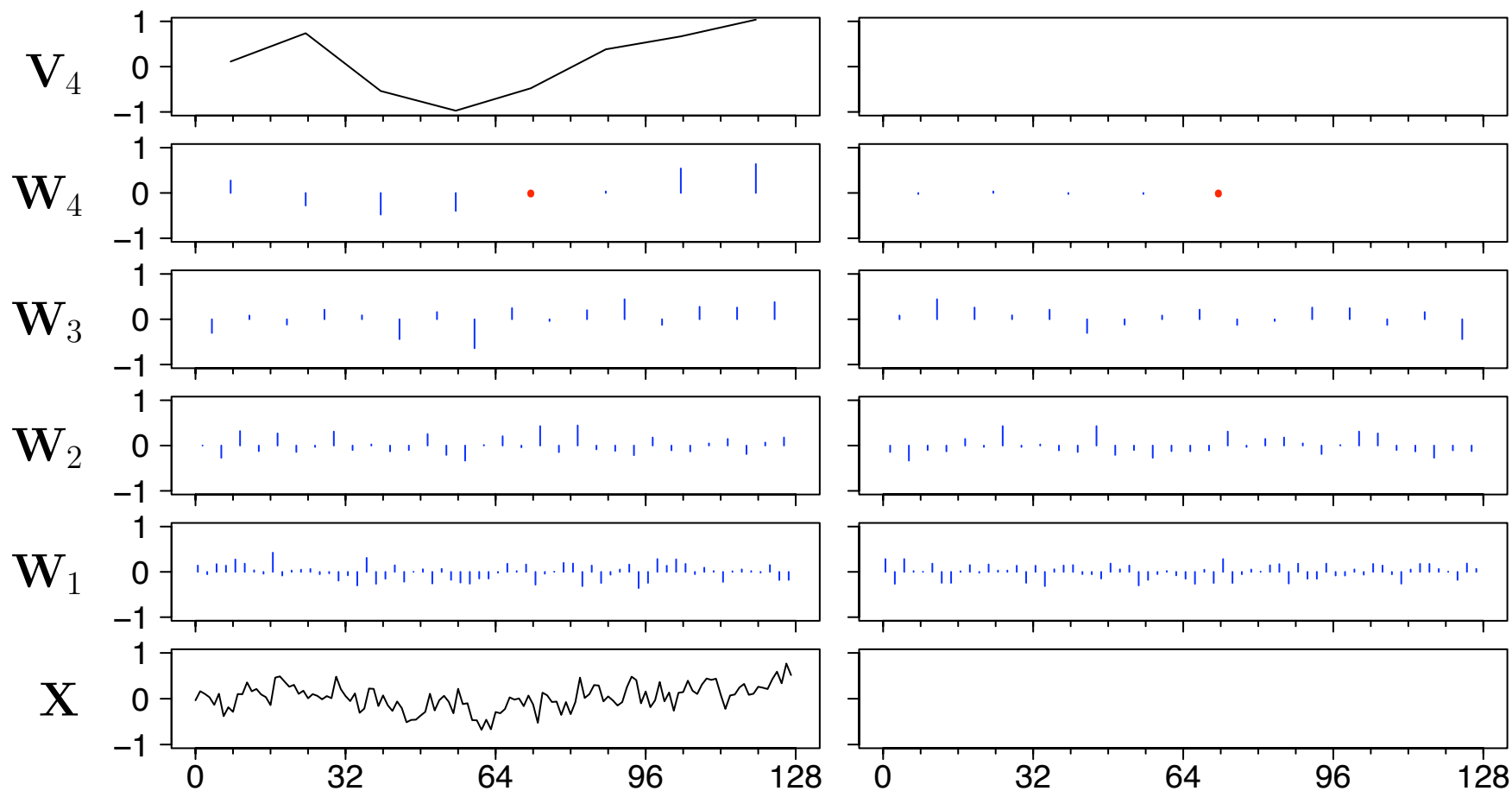
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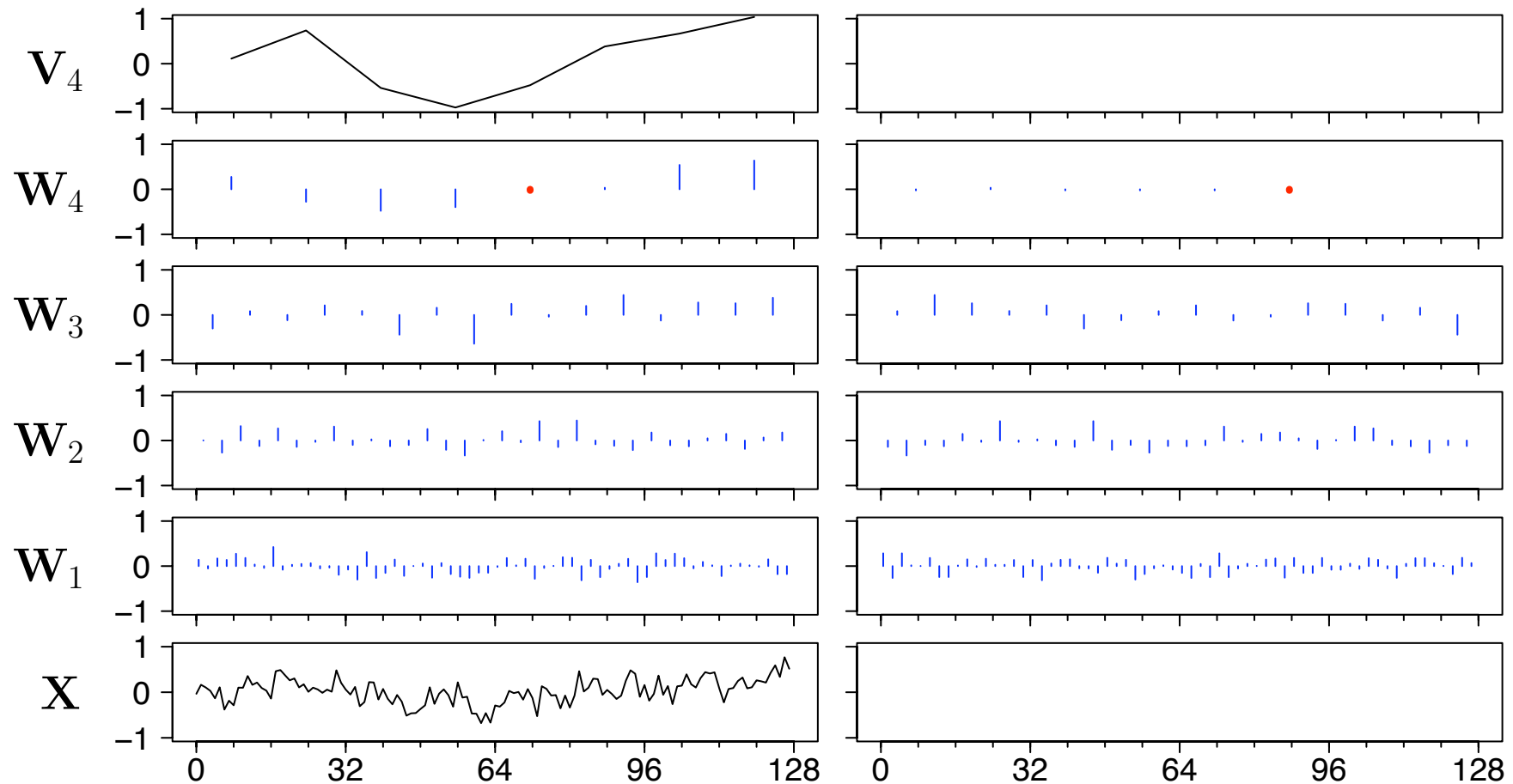
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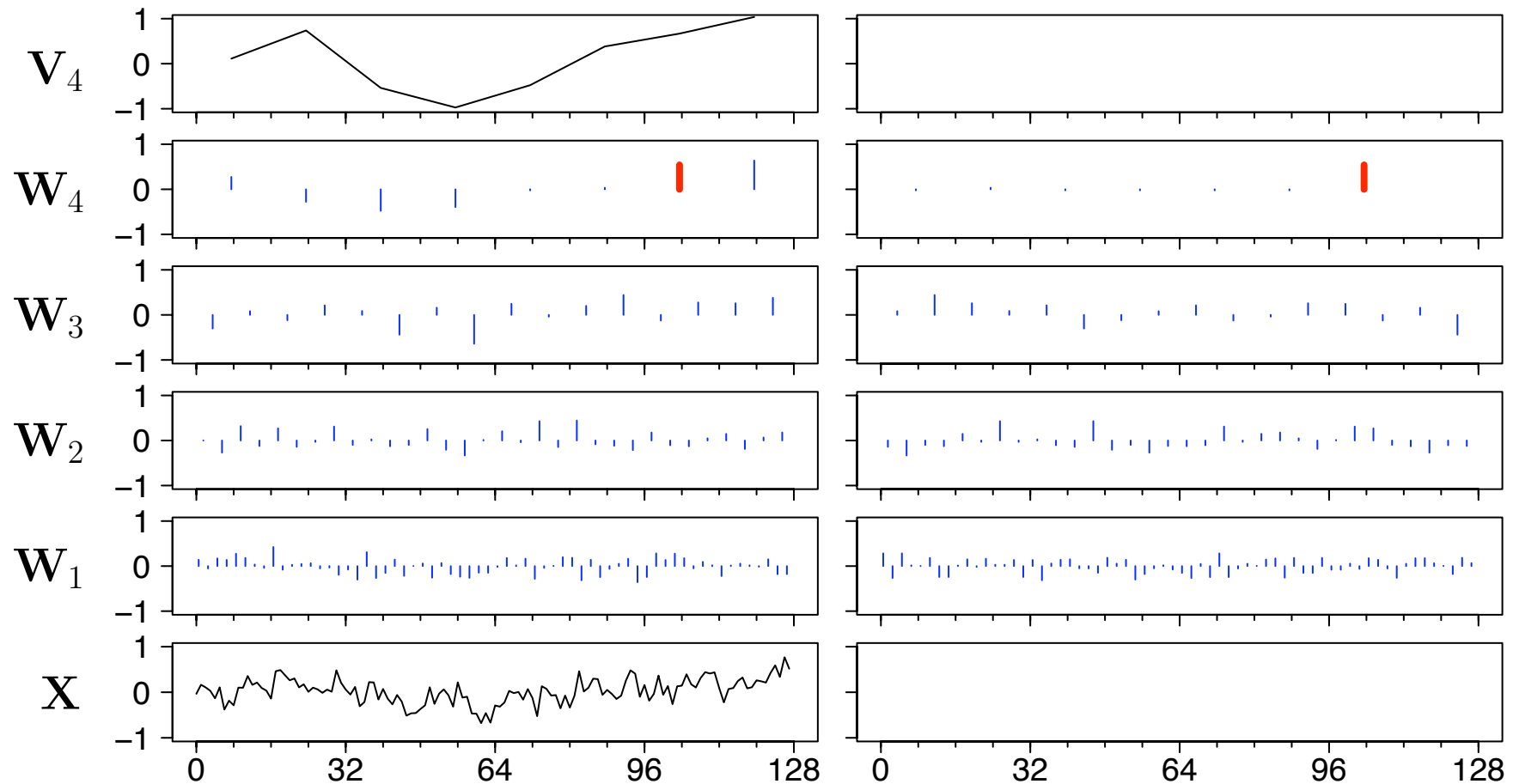
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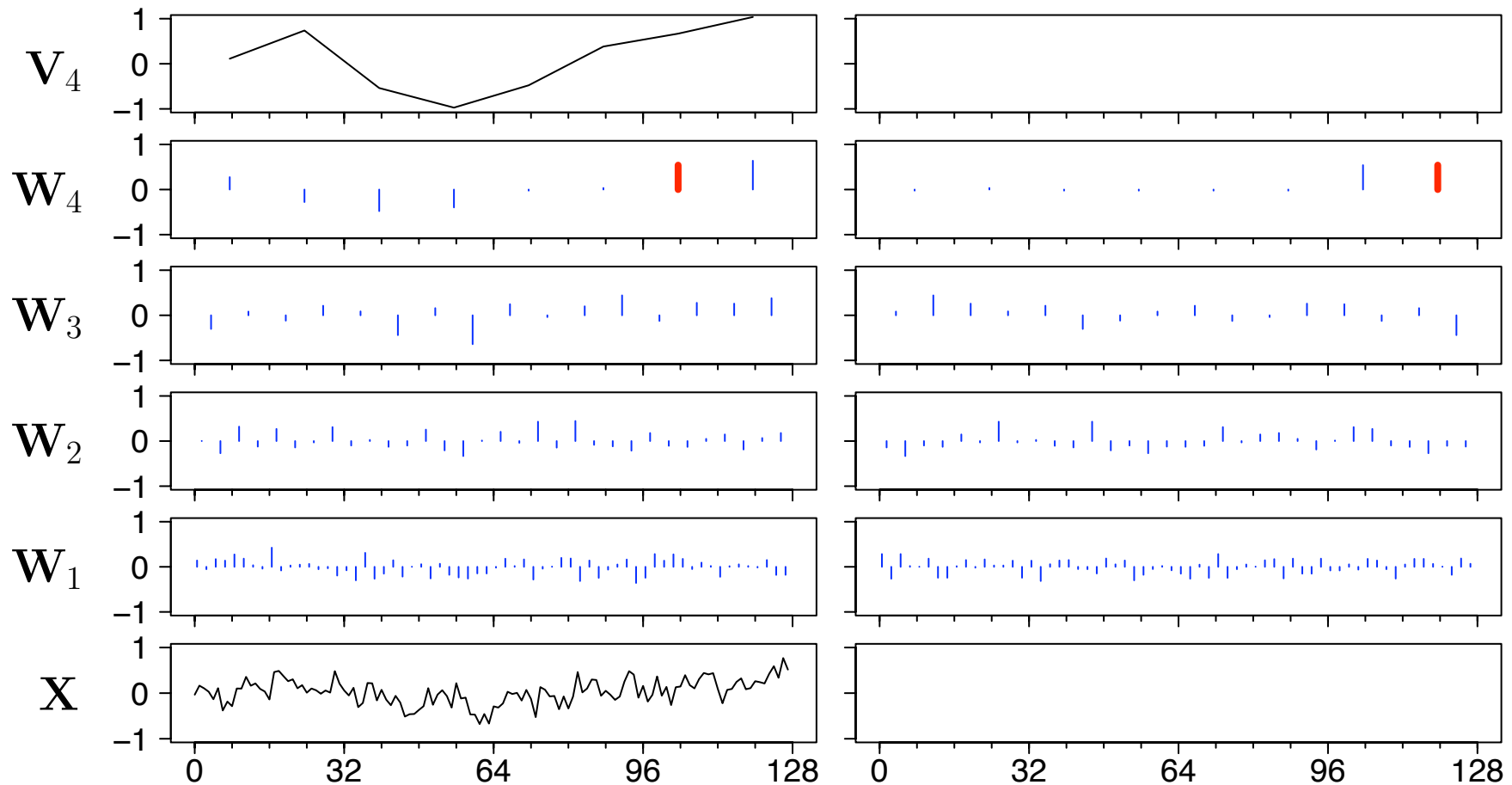
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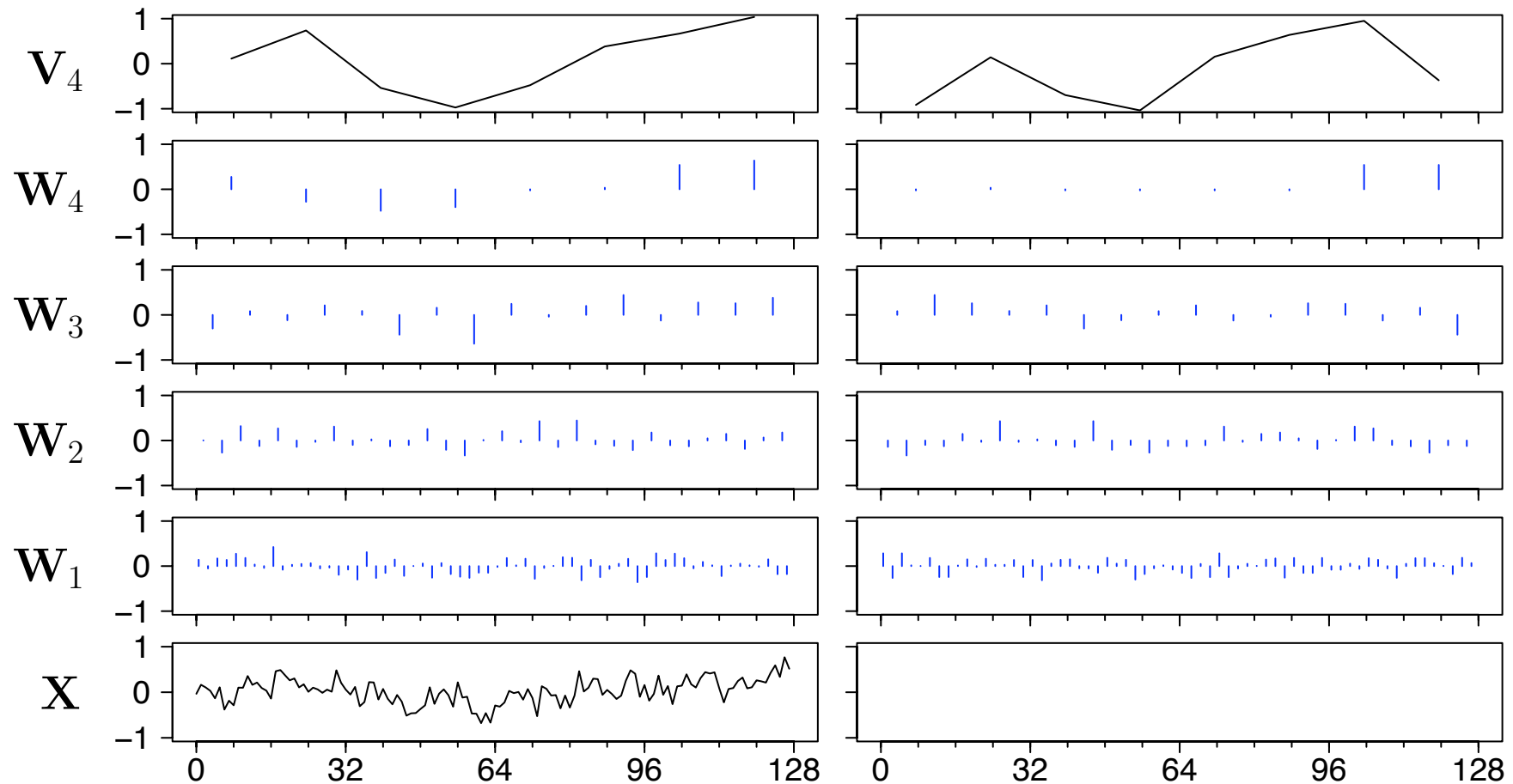
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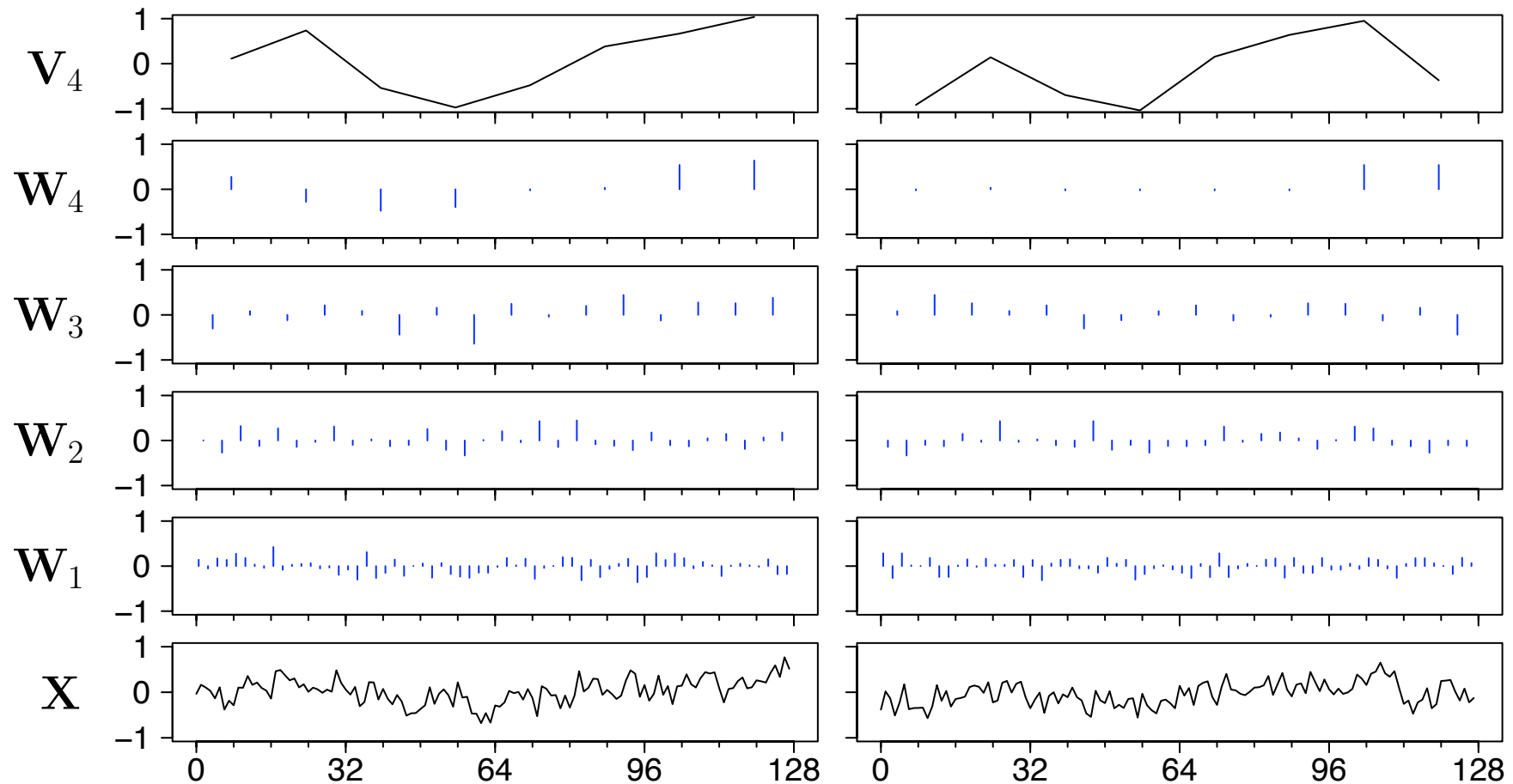
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Illustration of Wavelet-Domain Bootstrapping



- Haar DWT of FD(0.45) series \mathbf{X} (left-hand column) and wavelet-domain bootstrap thereof (right-hand)

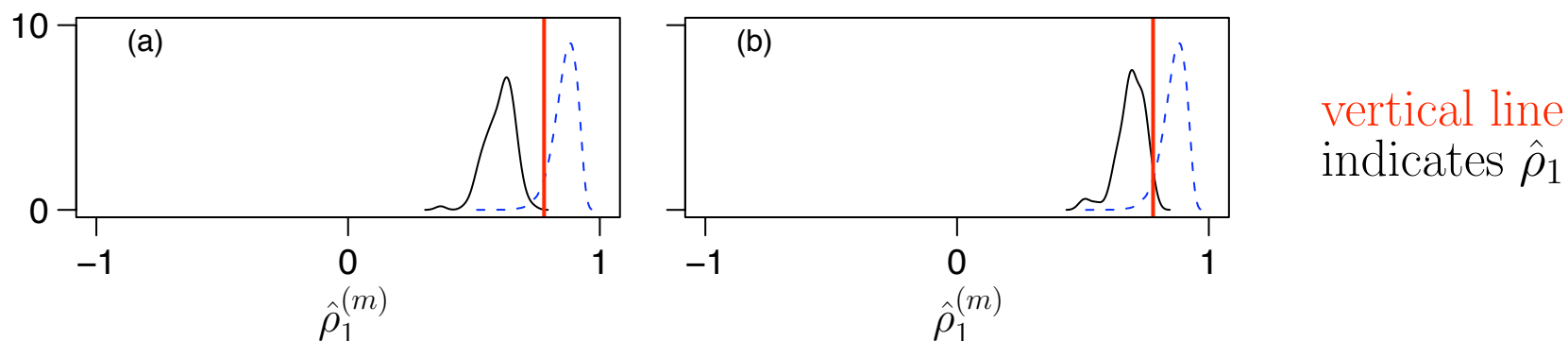
Illustration of Wavelet-Domain Bootstrapping



- Haar DWT of FD(0.45) series X (left-hand column) and wavelet-domain bootstrap thereof (right-hand)

Wavelet-Domain Bootstrapping of AR Series

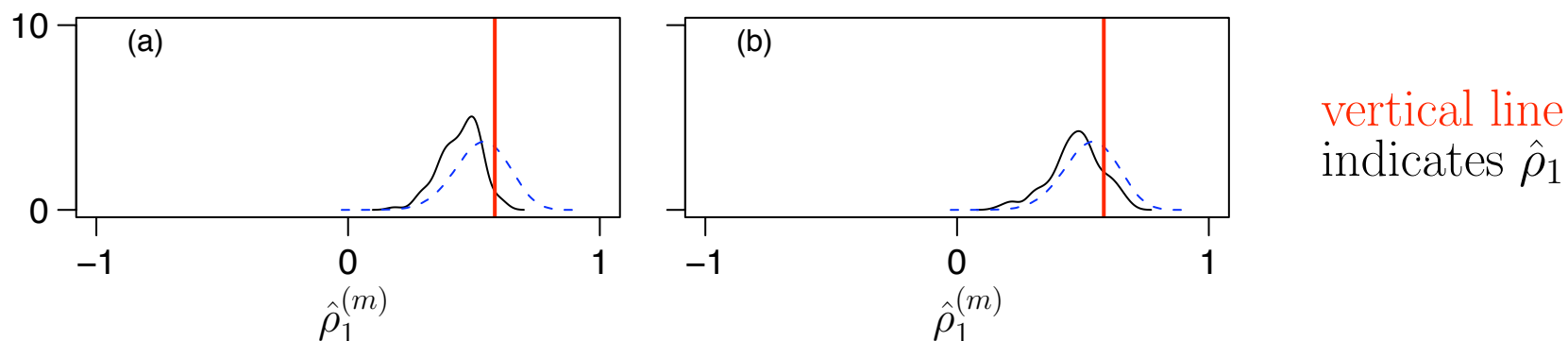
- approximations to true PDF using (a) Haar & (b) LA(8) wavelets



- using 50 AR time series and the Haar DWT yields:
 - average of 50 sample means $\doteq 0.67$ (truth $\doteq 0.86$)
 - average of 50 sample SDs $\doteq 0.071$ (truth $\doteq 0.048$)
- using 50 AR time series and the LA(8) DWT yields:
 - average of 50 sample means $\doteq 0.80$ (truth $\doteq 0.86$)
 - average of 50 sample SDs $\doteq 0.055$ (truth $\doteq 0.048$)

Wavelet-Domain Bootstrapping of FD Series

- approximations to true PDF using (a) Haar & (b) LA(8) wavelets



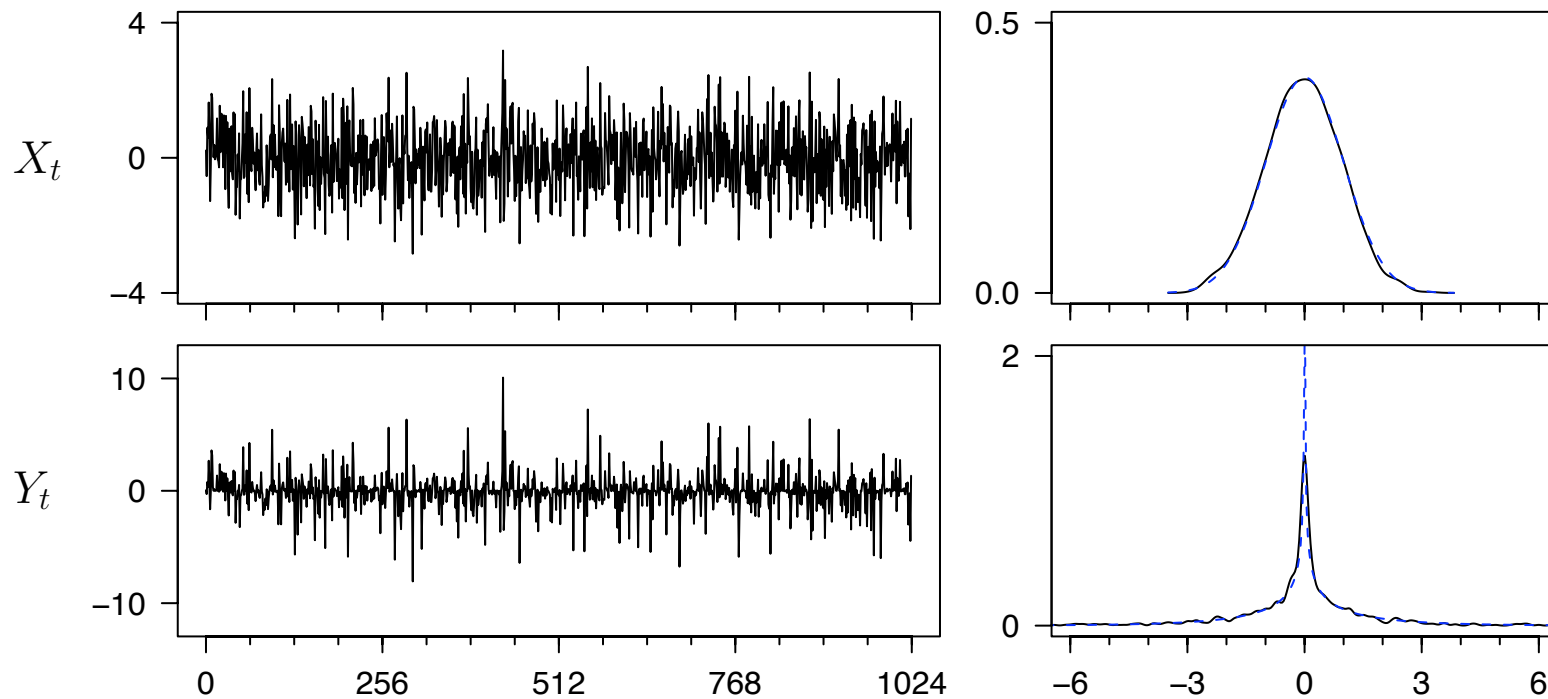
- using 50 FD time series and the Haar DWT yields:
 - average of 50 sample means $\doteq 0.35$ (truth $\doteq 0.53$)
 - average of 50 sample SDs $\doteq 0.096$ (truth $\doteq 0.107$)
- using 50 FD time series and the LA(8) DWT yields:
 - average of 50 sample means $\doteq 0.43$ (truth $\doteq 0.53$)
 - average of 50 sample SDs $\doteq 0.098$ (truth $\doteq 0.107$)

Effect of Non-Gaussianity: I

- wavelet-domain bootstrapping works well if we can assume Gaussianity, but can be problematic if this assumption fails
- for non-Gaussian series, wavelet-domain bootstraps are typically closer to Gaussianity than original series, which poses a problem for assessing variability in certain statistics

Effect of Non-Gaussianity: II

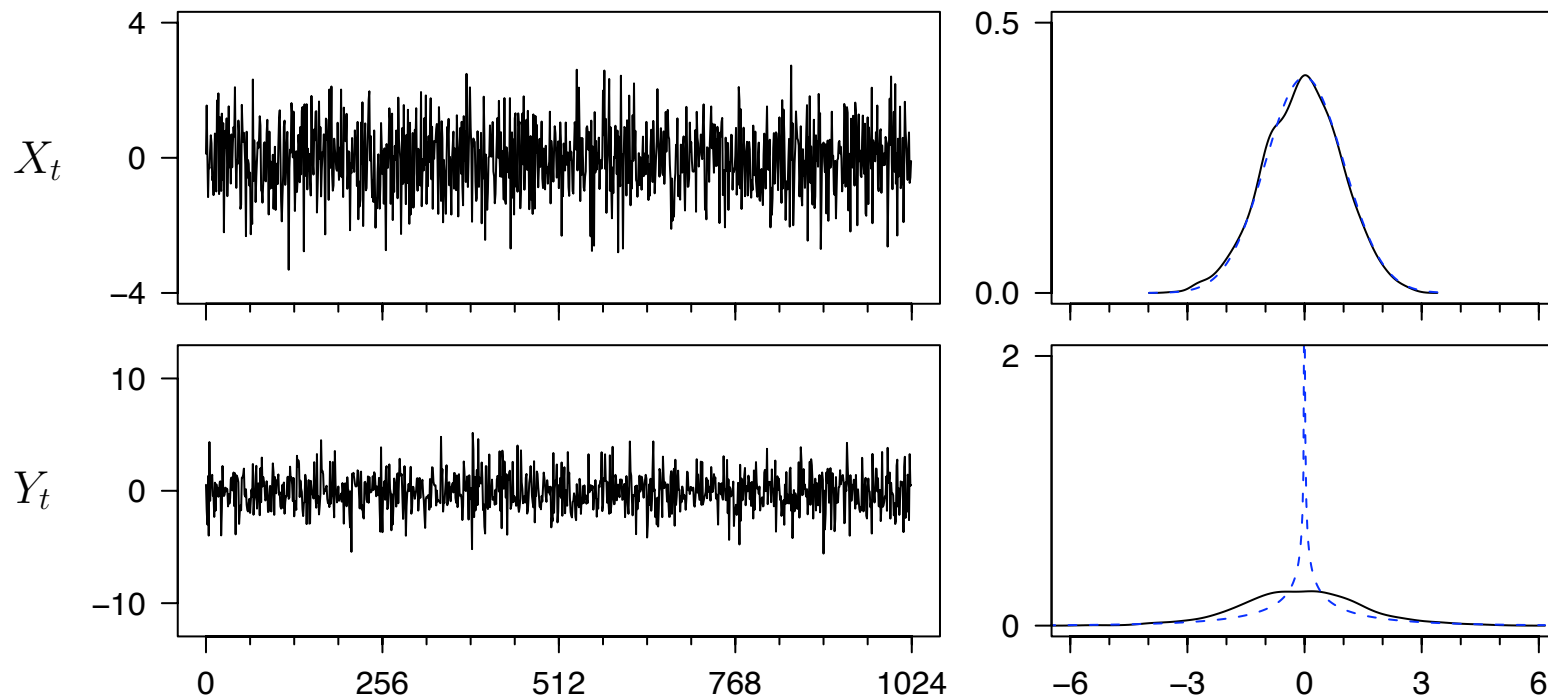
- consider Gaussian white noise X_t and $Y_t = \text{sign}\{X_t\} \times X_t^2$:



- right-hand plots show estimated PDFs and true PDFs

Effect of Non-Gaussianity: III

- wavelet-domain bootstraps of X_t and $Y_t = \text{sign}\{X_t\} \times X_t^2$:

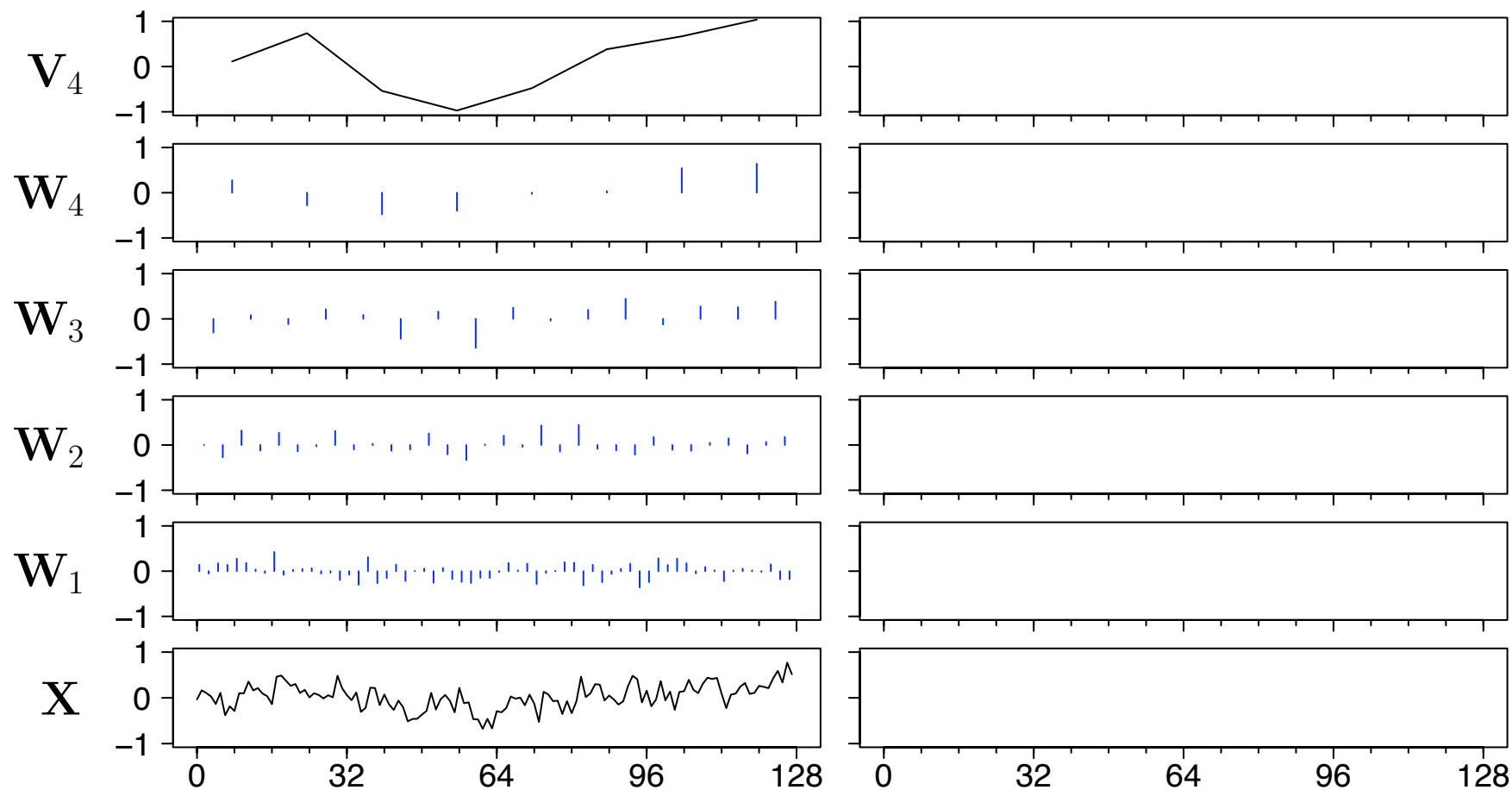


- right-hand plots show estimated PDFs and true original PDFs

Tree-Based Bootstrapping

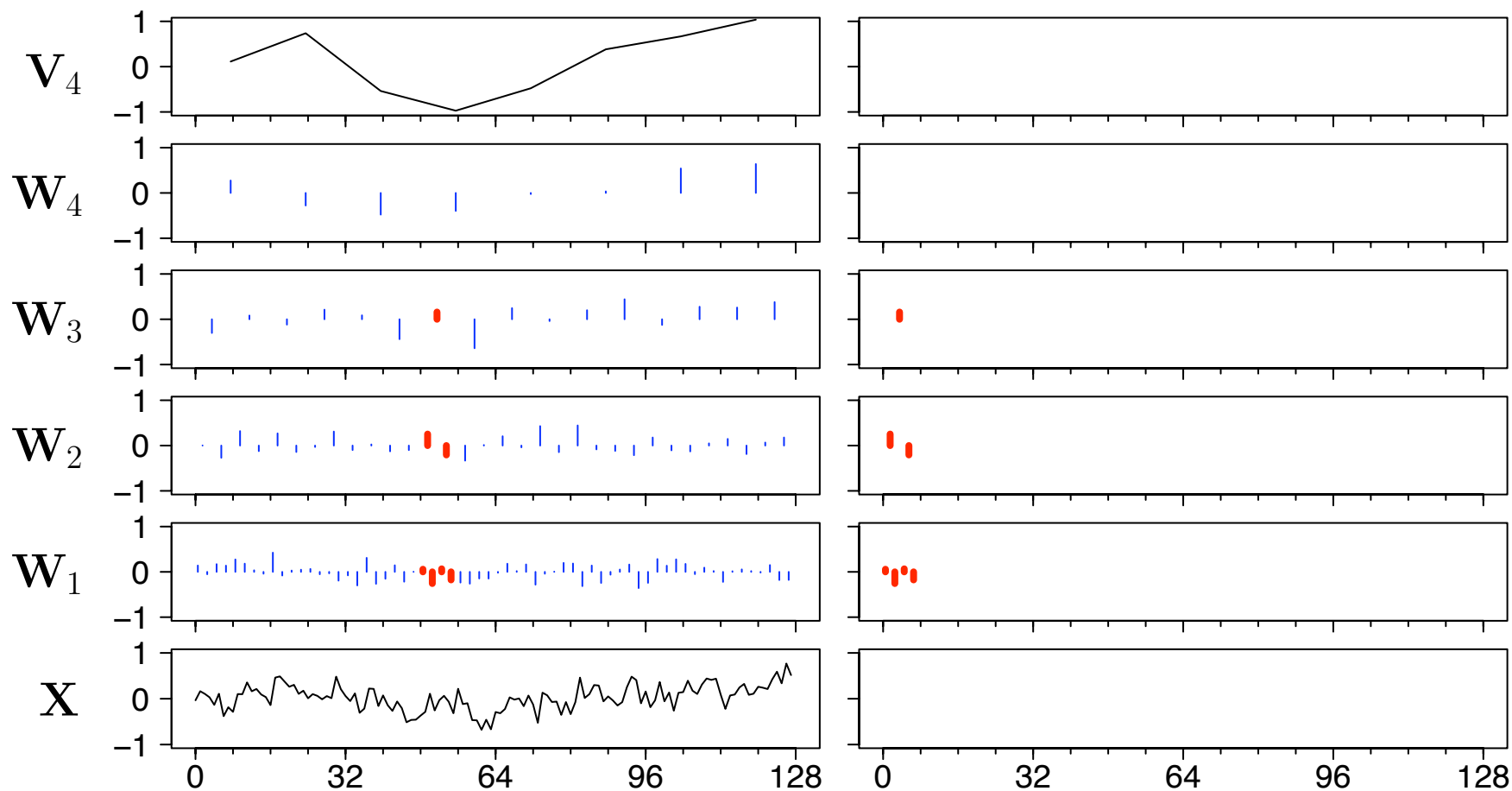
- to preserve non-Gaussianity, consider using groups (‘trees’) of wavelet coefficients co-located across small scales as basic sampling unit for bootstrapping at those scales
- wavelet coefficients at large scales treated in same way as in usual wavelet-domain bootstrap
- scaling coefficients handled using parametric bootstrap
- certain wavelet-based signal denoising schemes for non-Gaussian noise treat small scales in a special way and large scales in the same way as in the Gaussian case (see, e.g., Gao, 1997)
- tree-based structuring of wavelet coefficients is key idea behind denoising using Markov models (Crouse *et al.*, 1998) and notion of wavelet ‘footprints’ (Dragotti and Vetterli, 2003)

Illustration of Tree-Based Bootstrapping



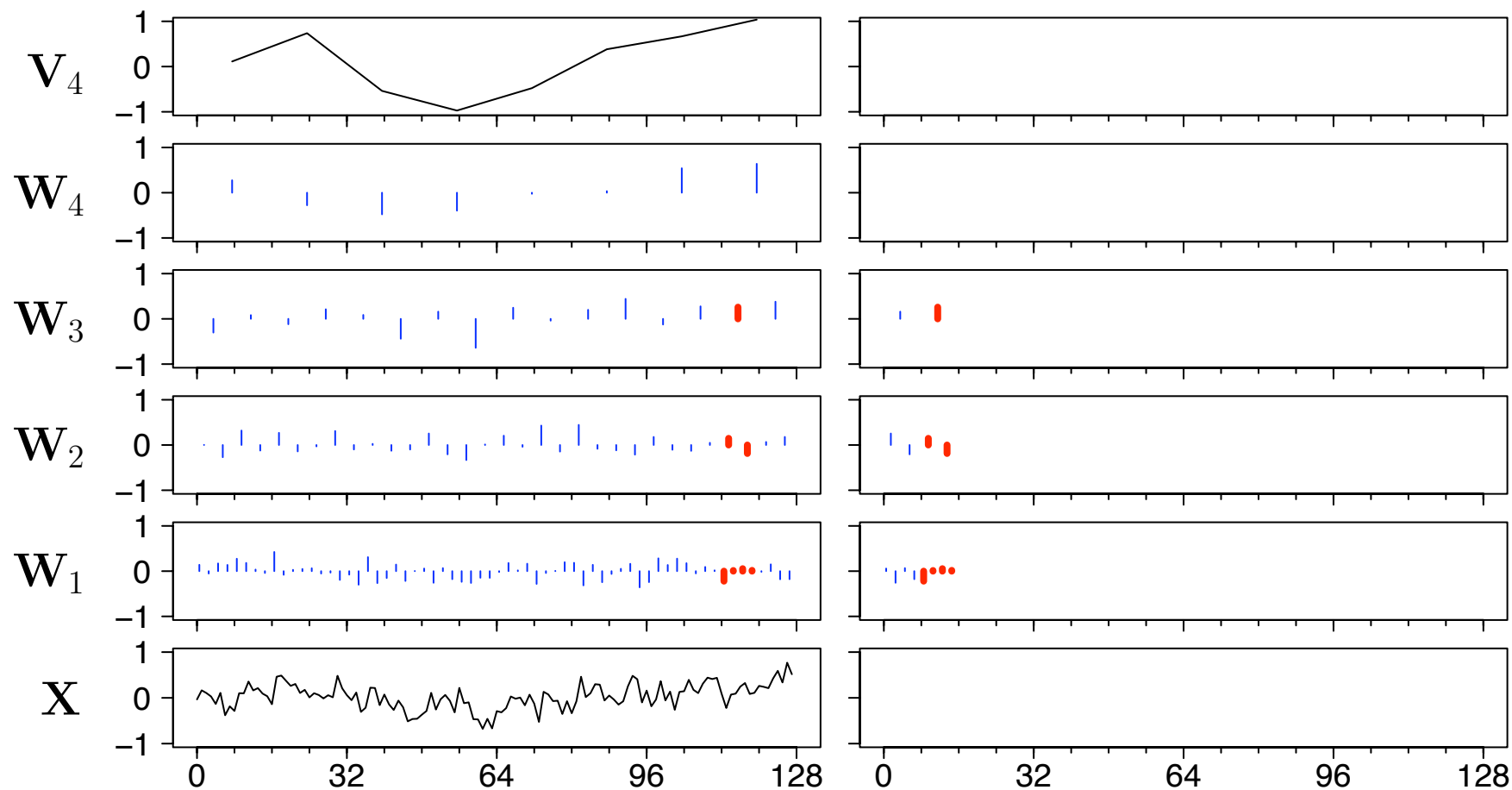
- Haar DWT of FD(0.45) series \mathbf{X} (left-hand column) and level $j = 3$ tree-based bootstrap thereof (right-hand)

Illustration of Tree-Based Bootstrapping



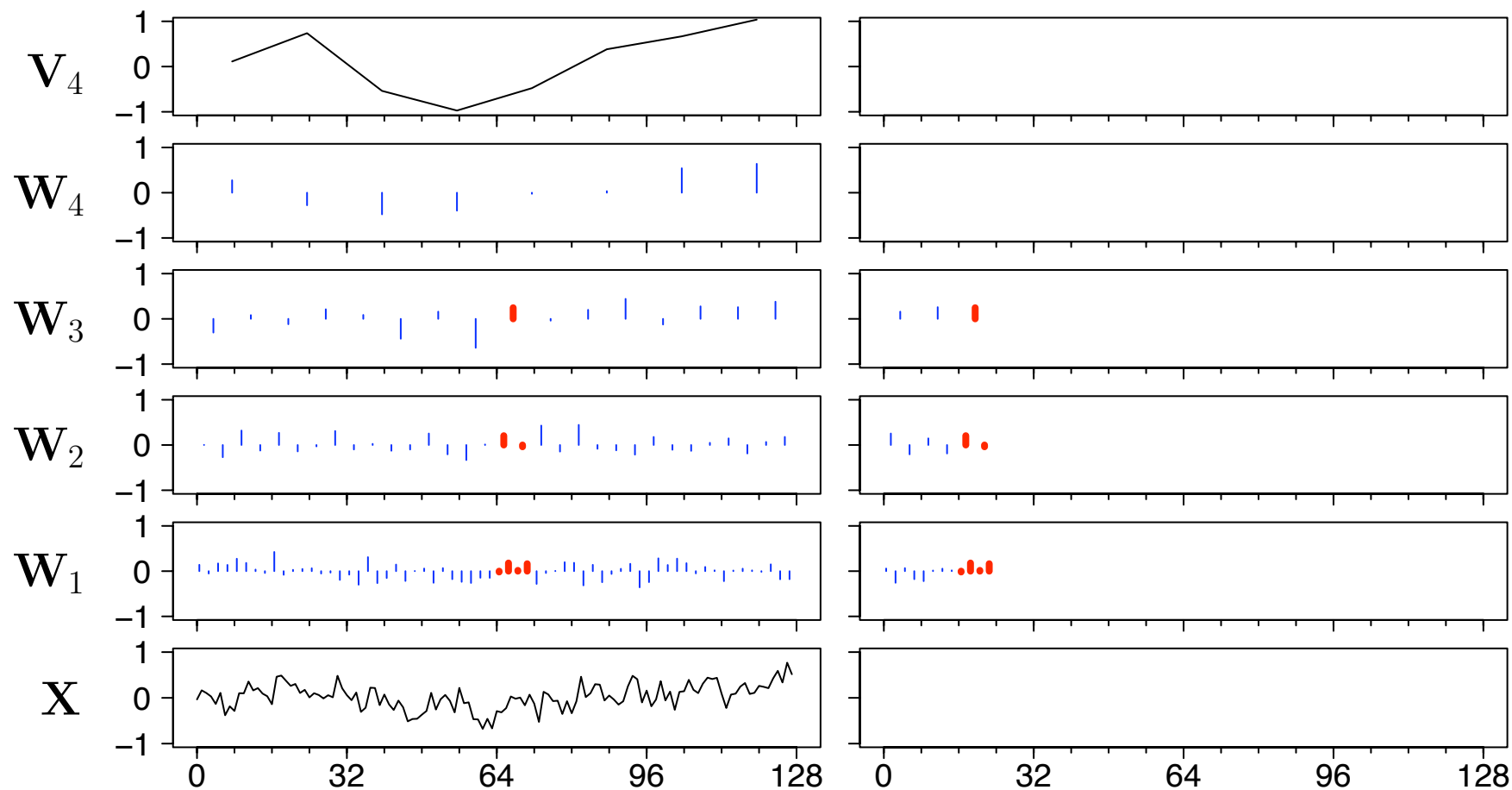
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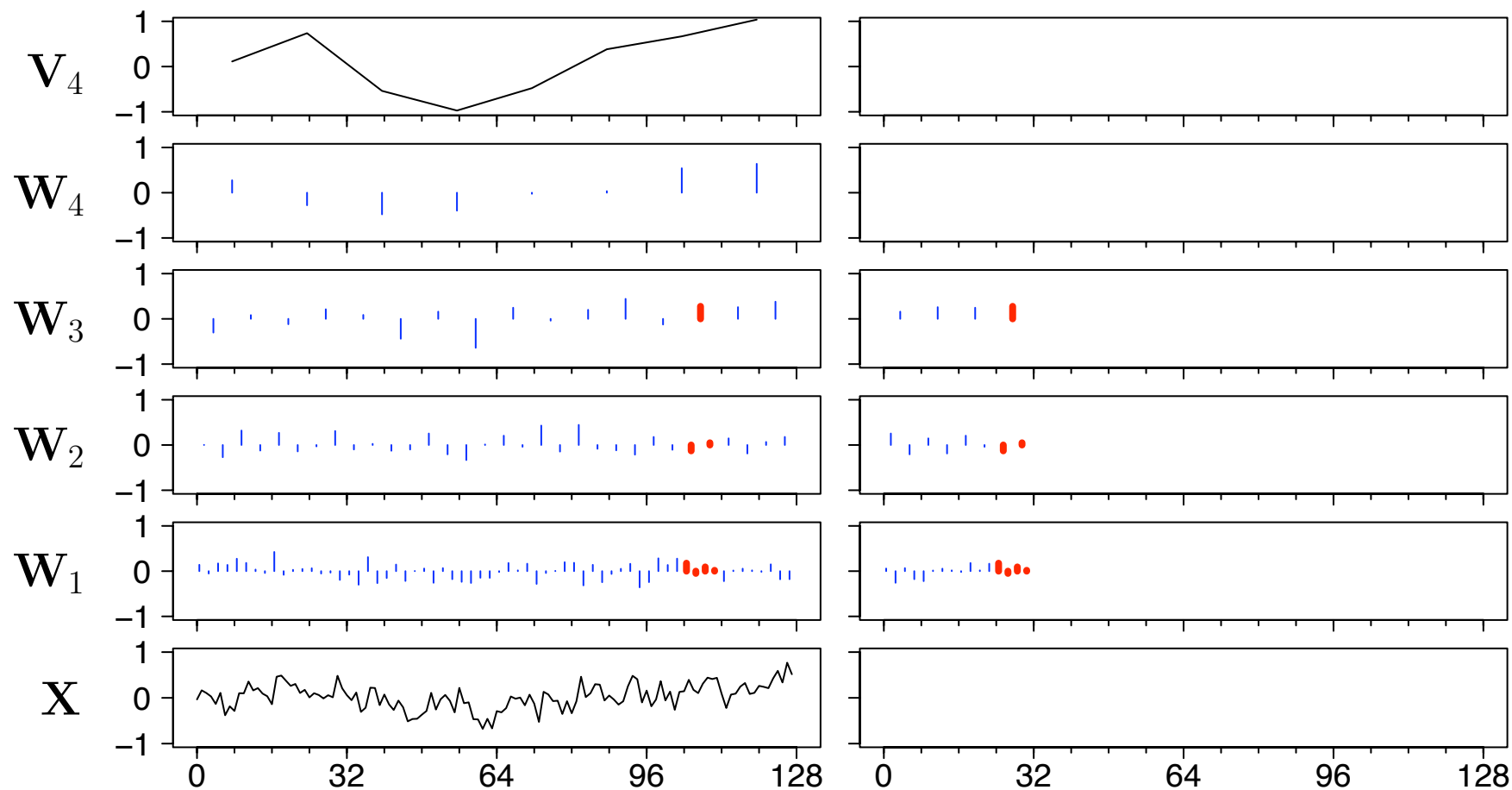
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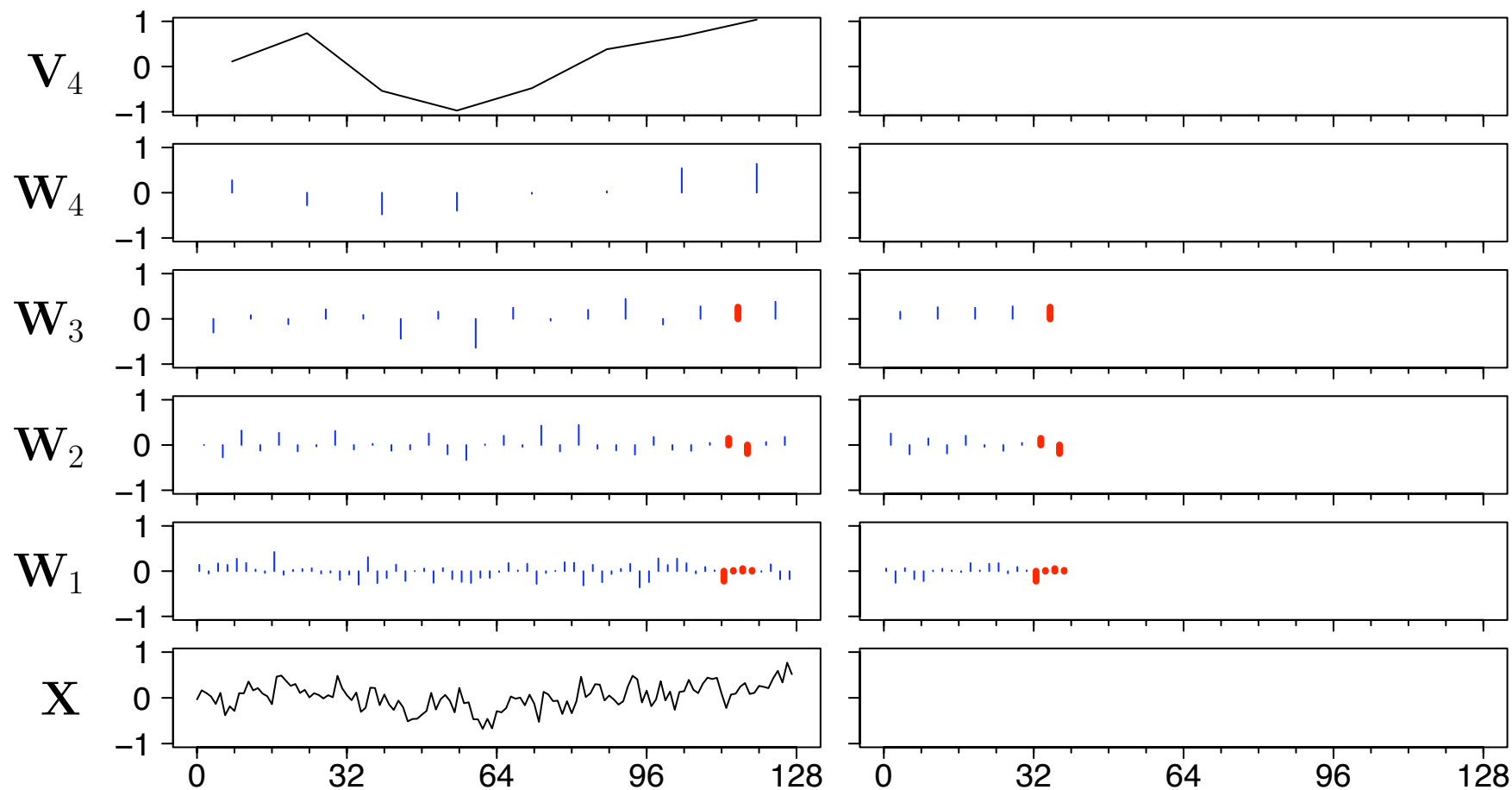
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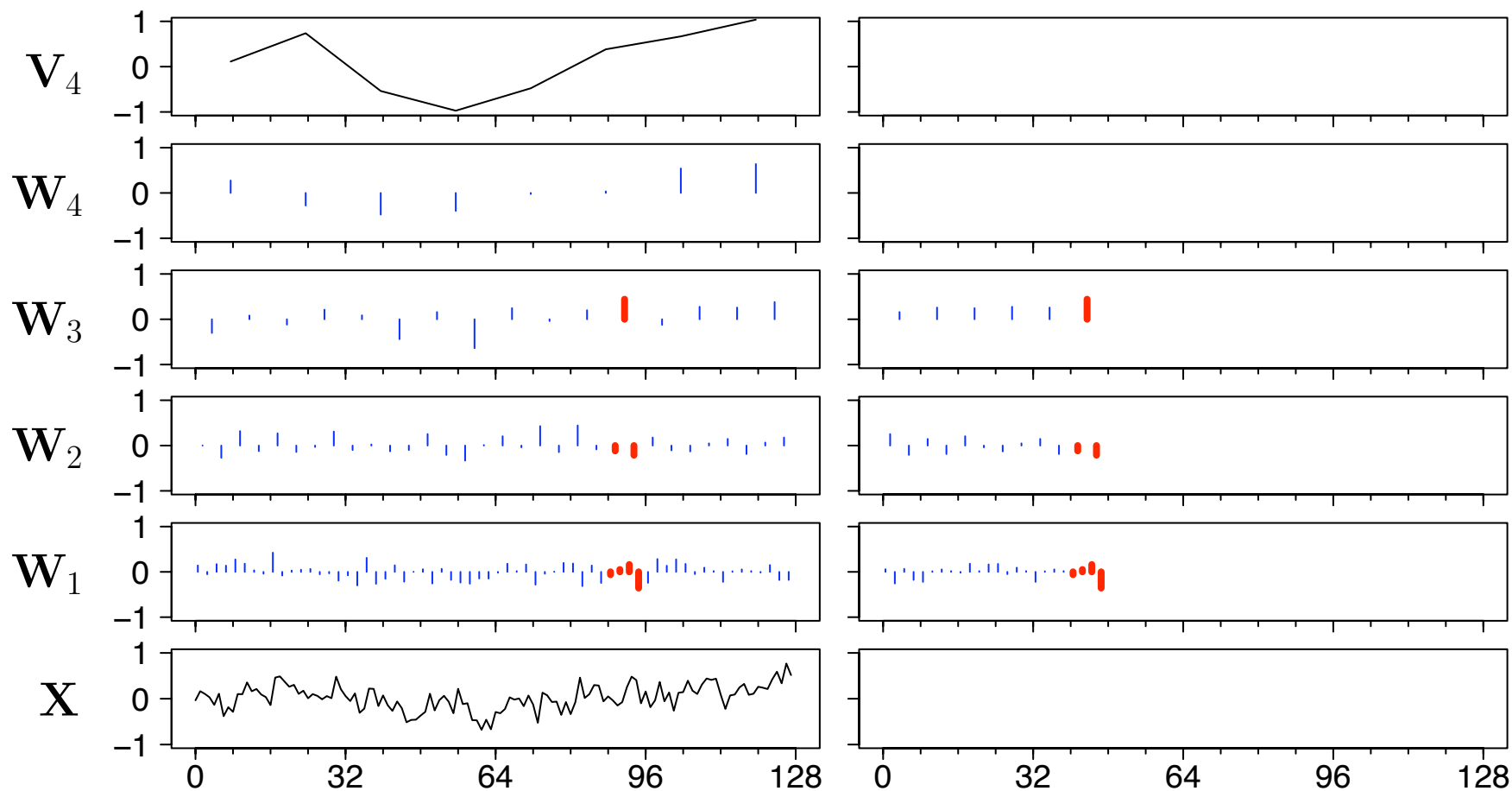
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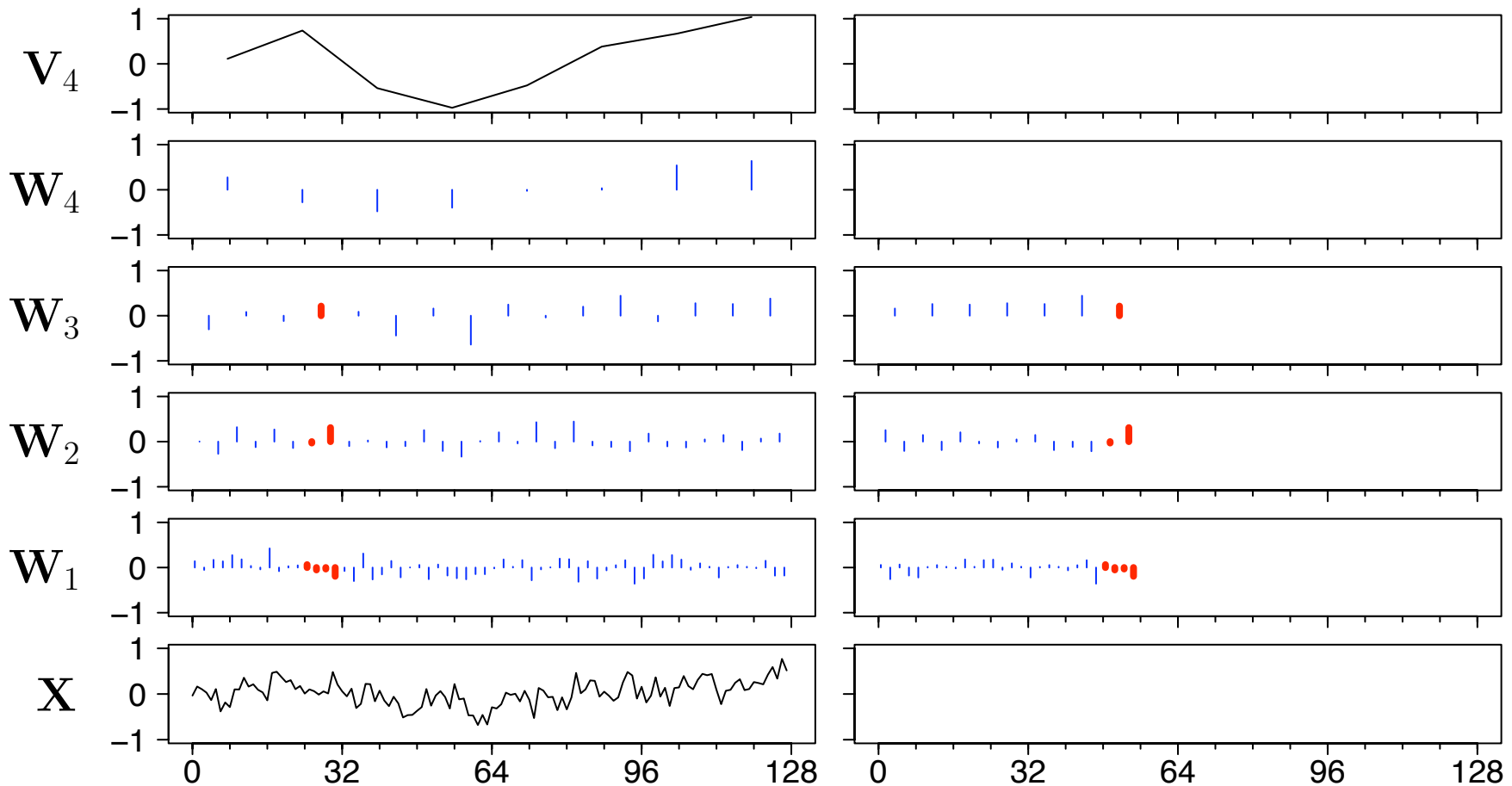
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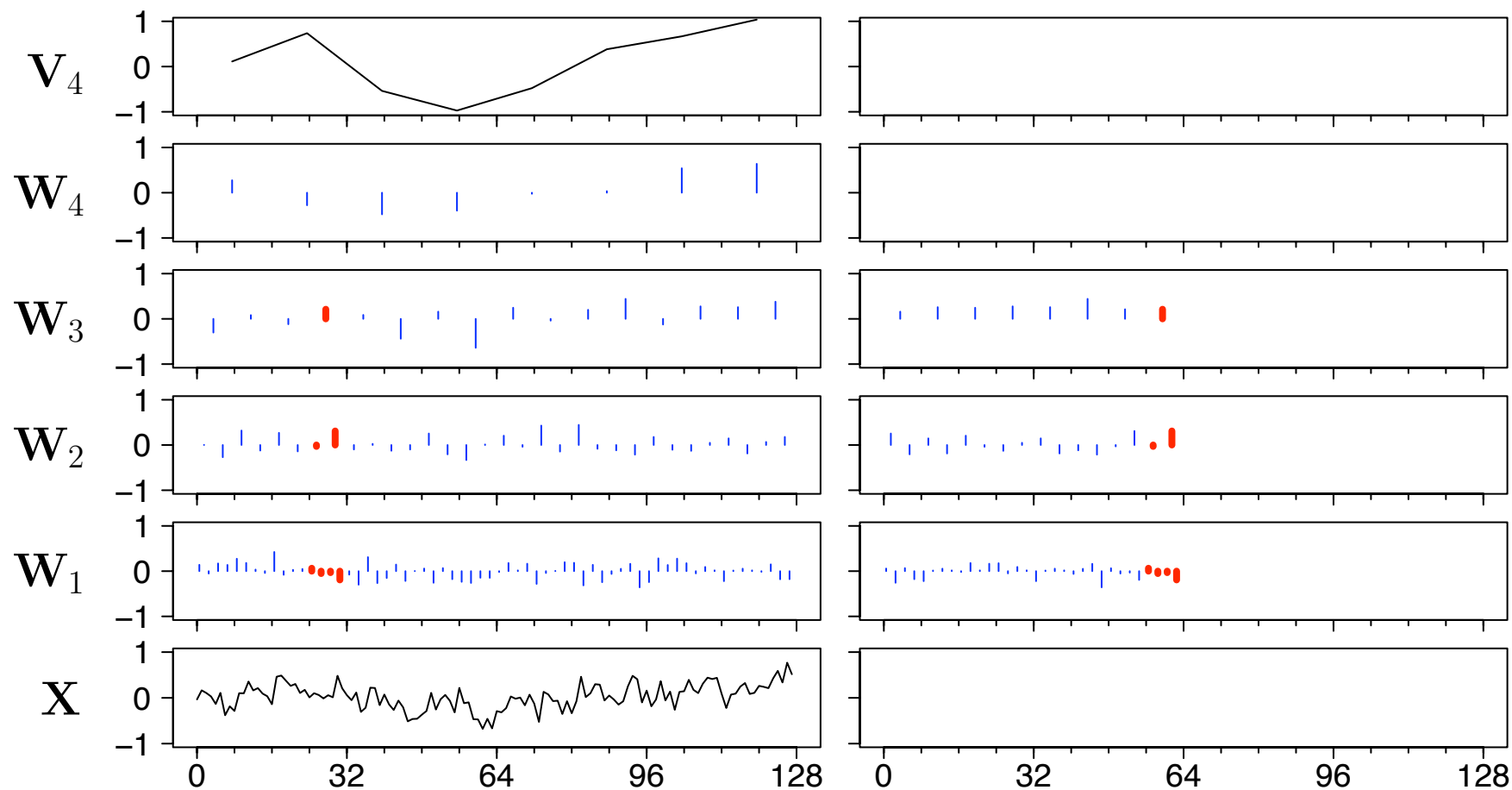
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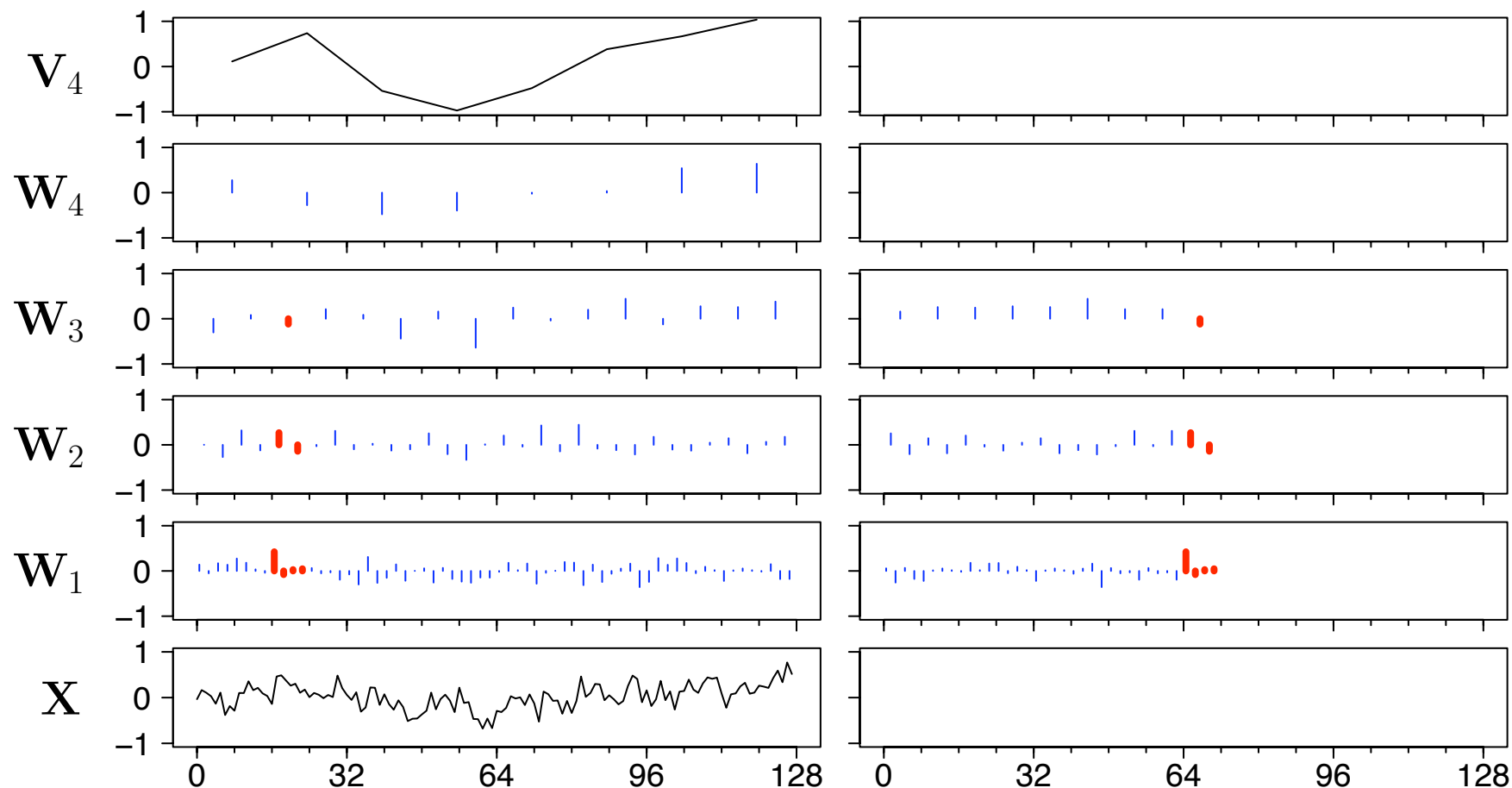
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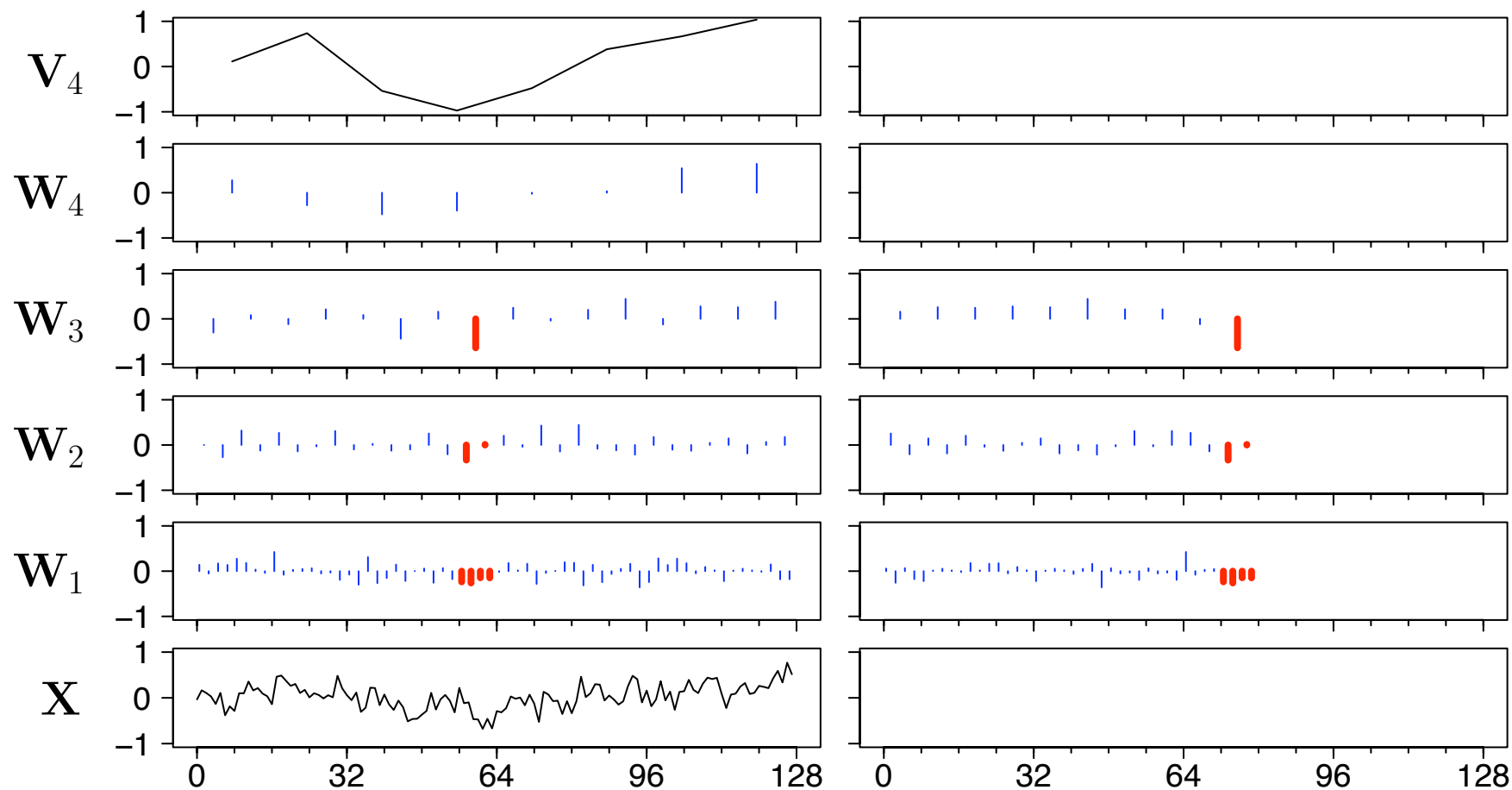
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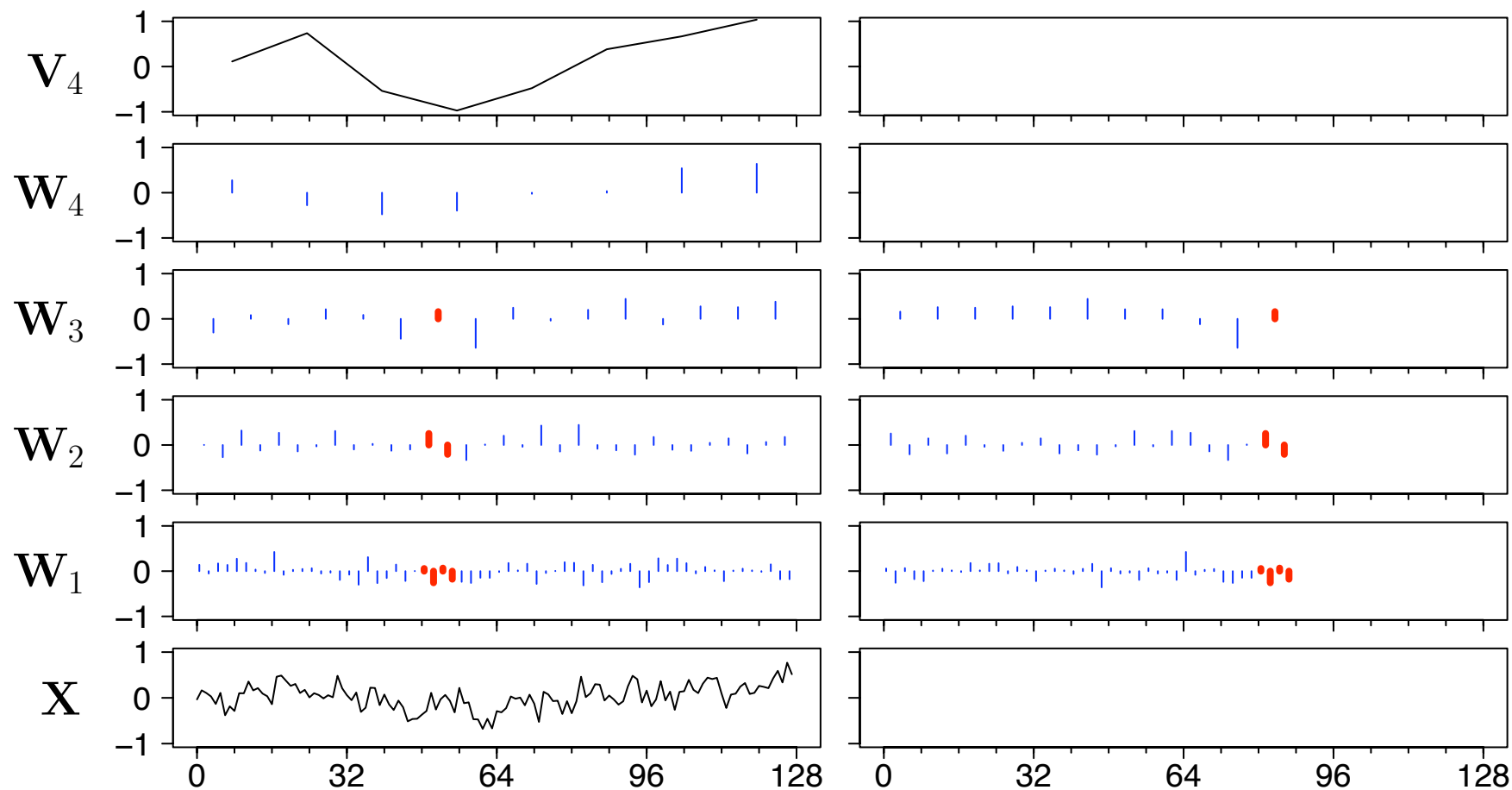
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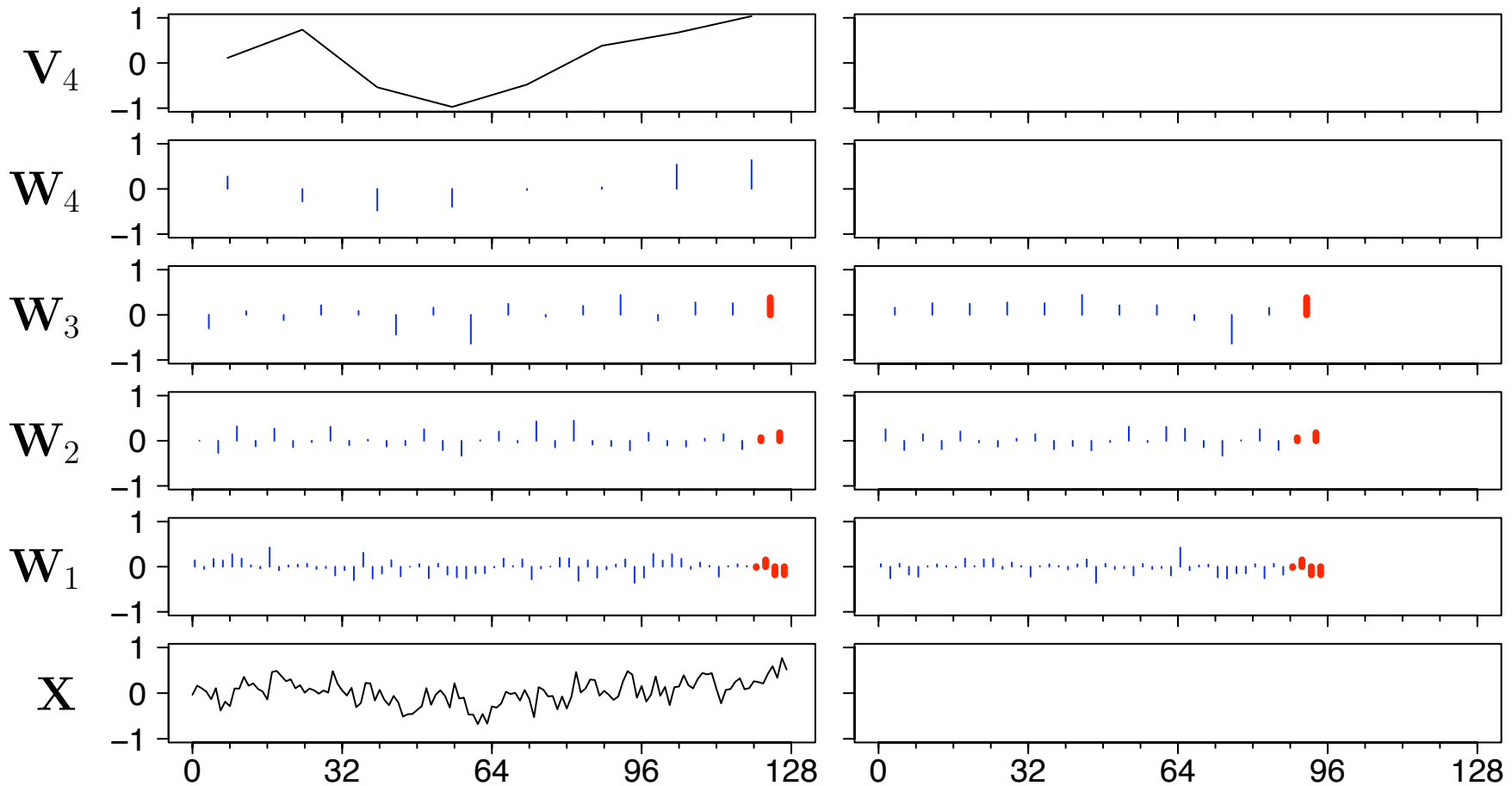
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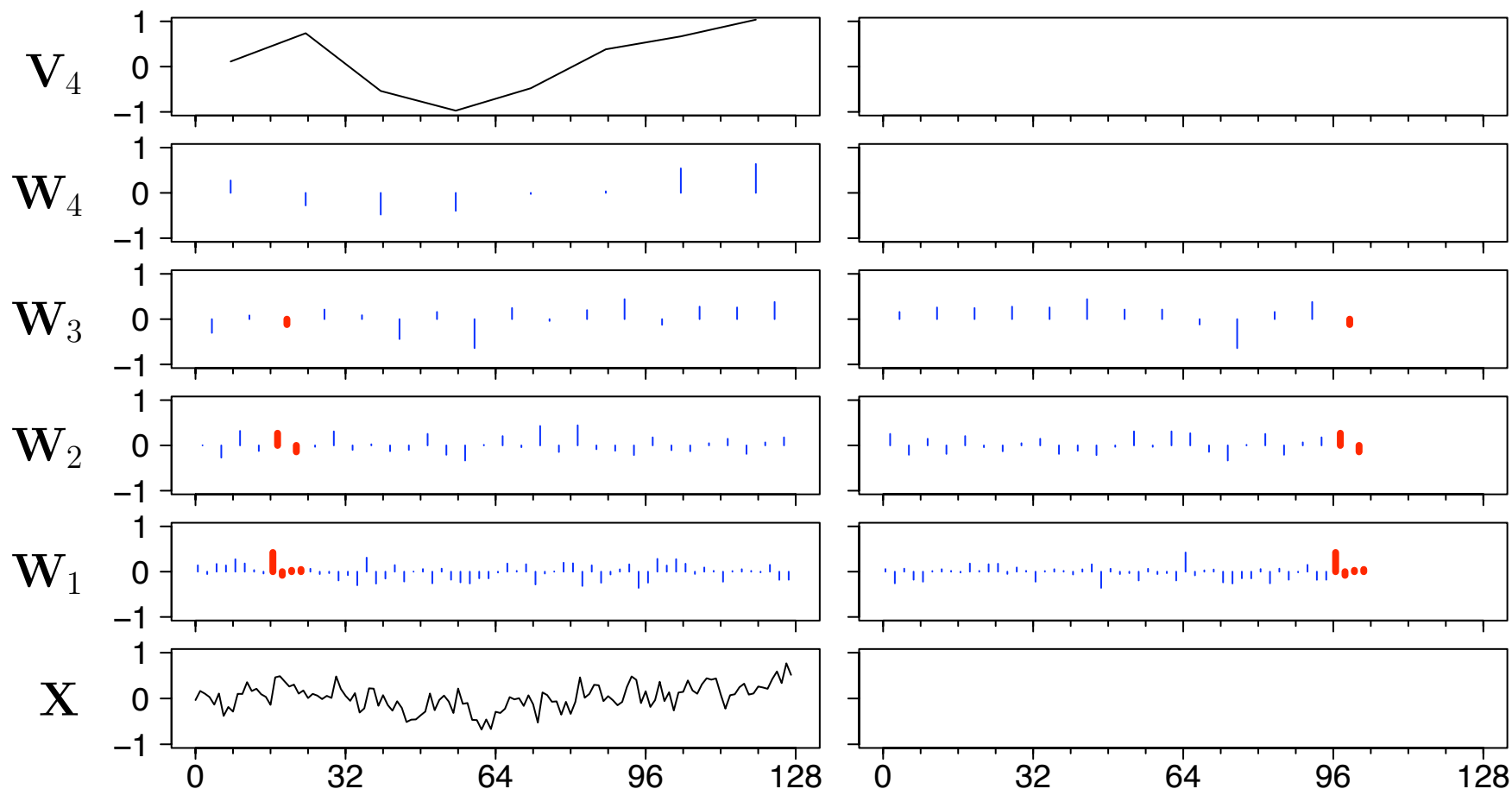
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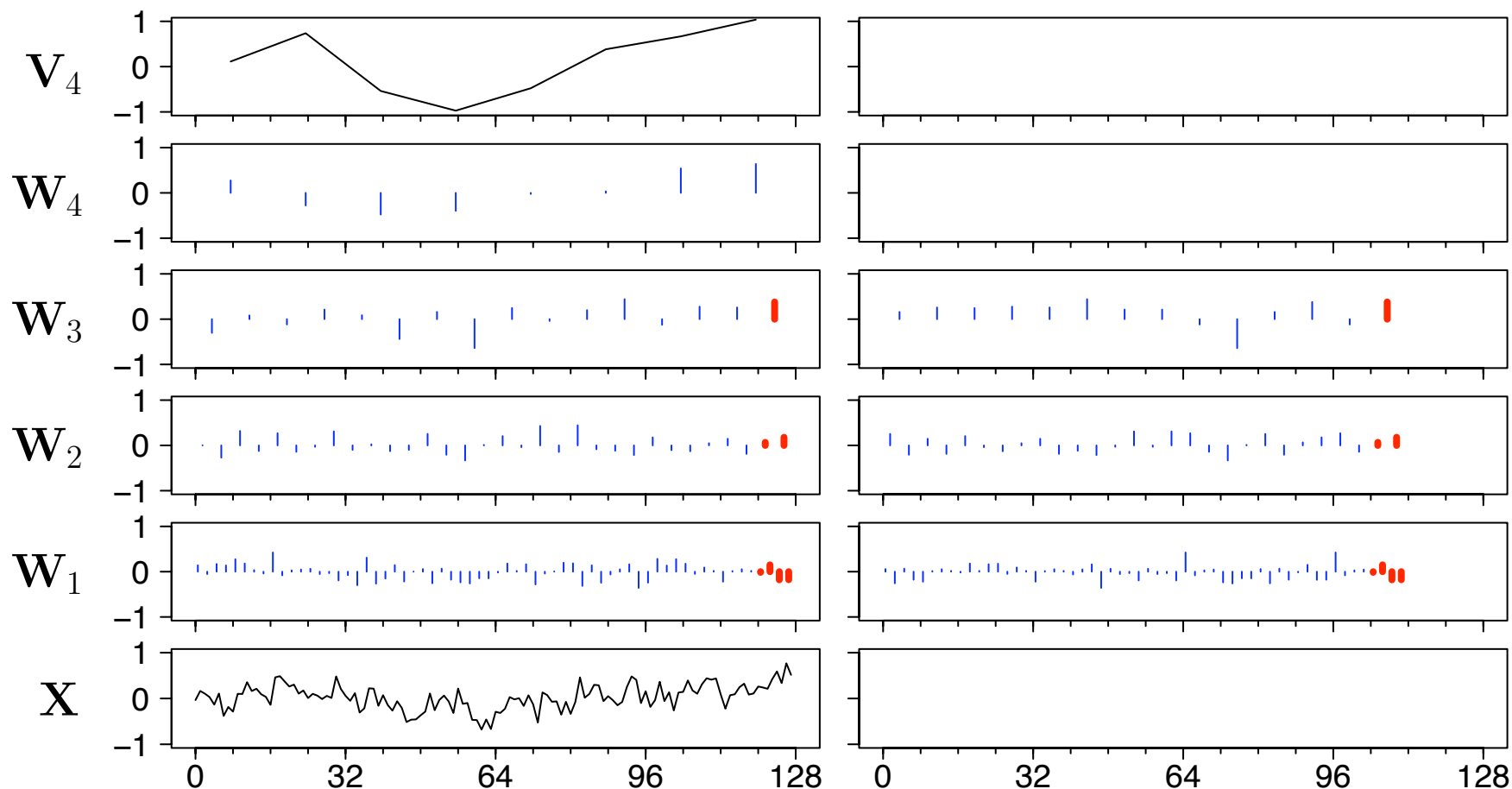
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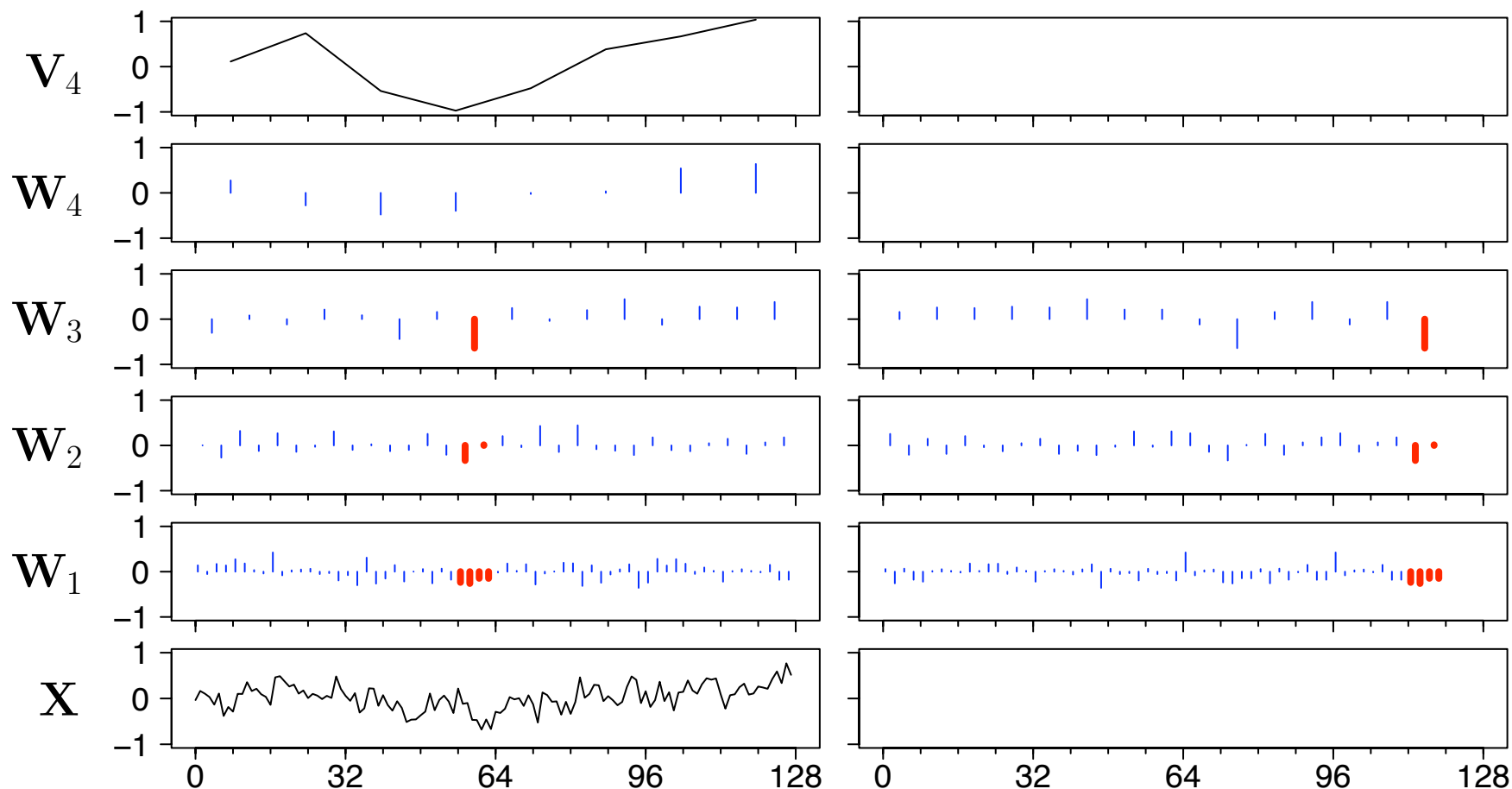
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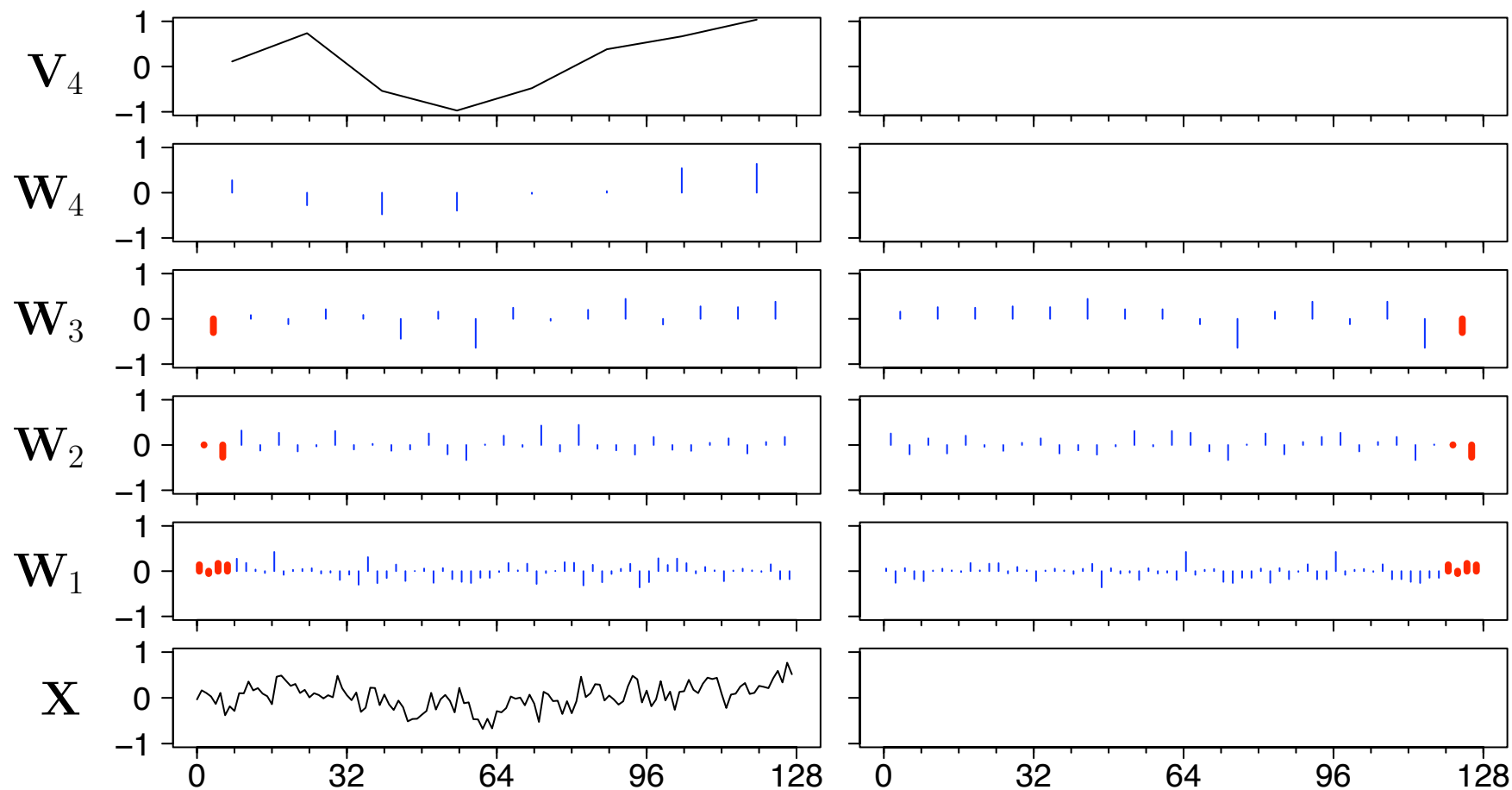
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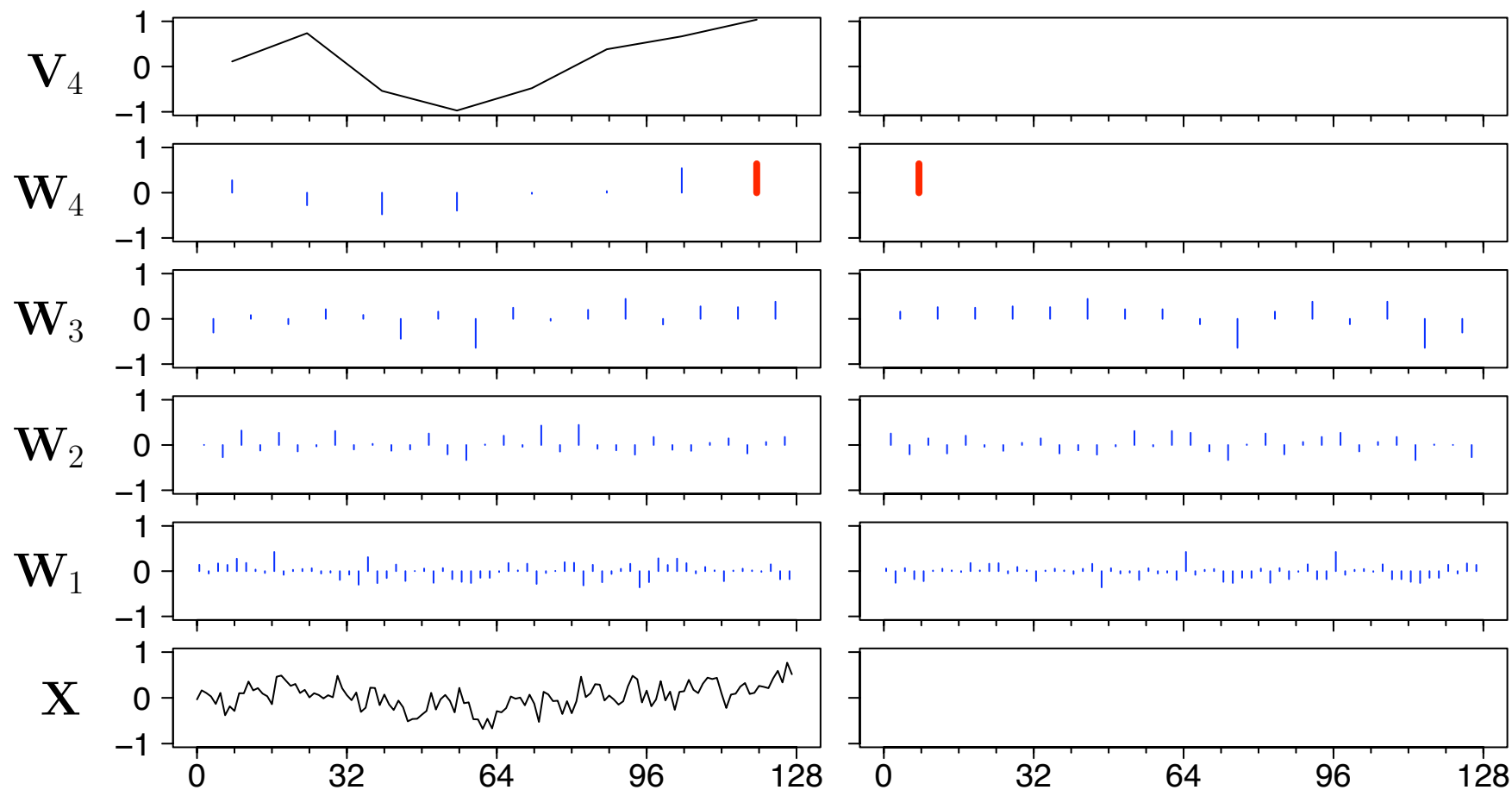
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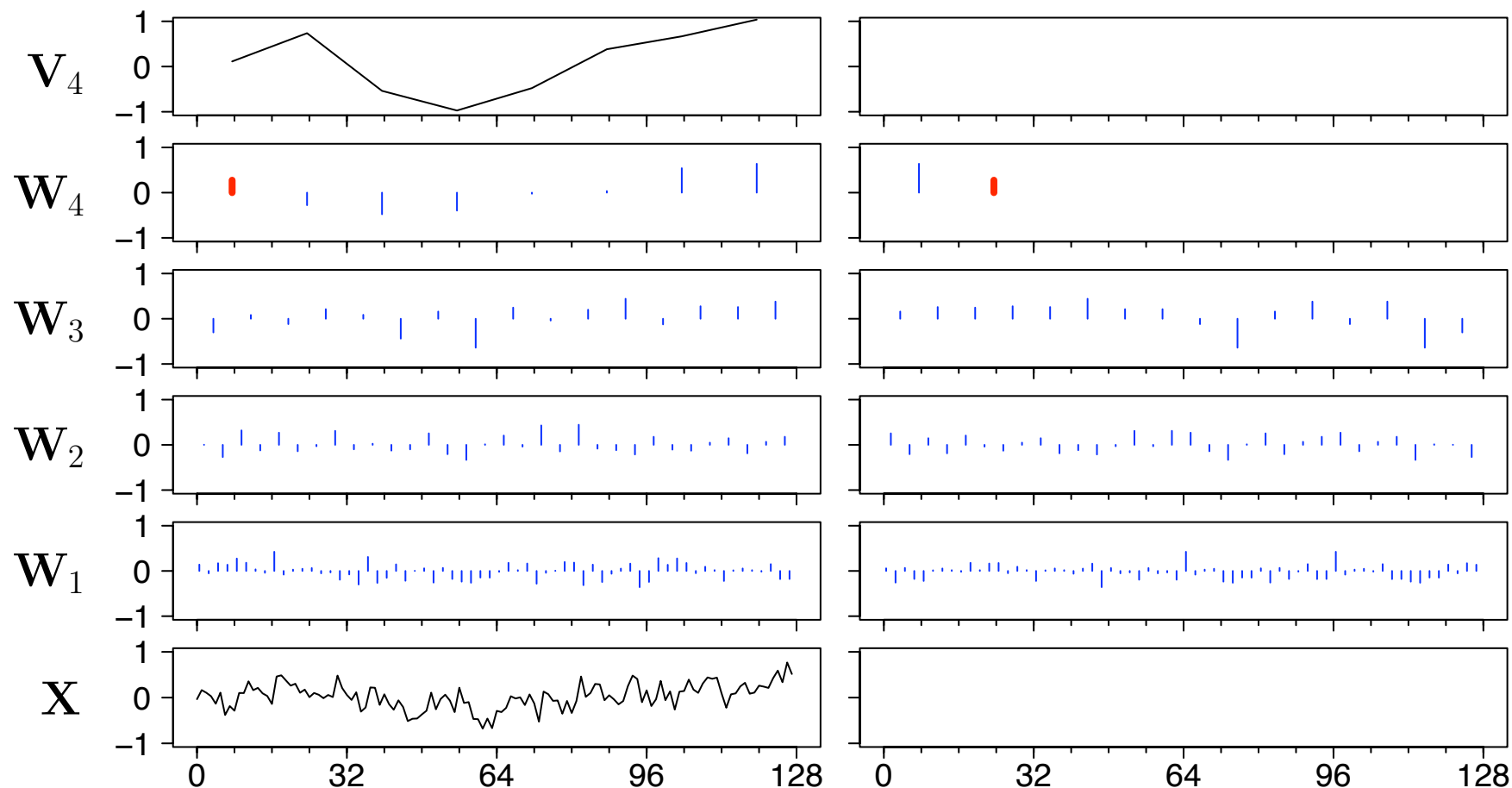
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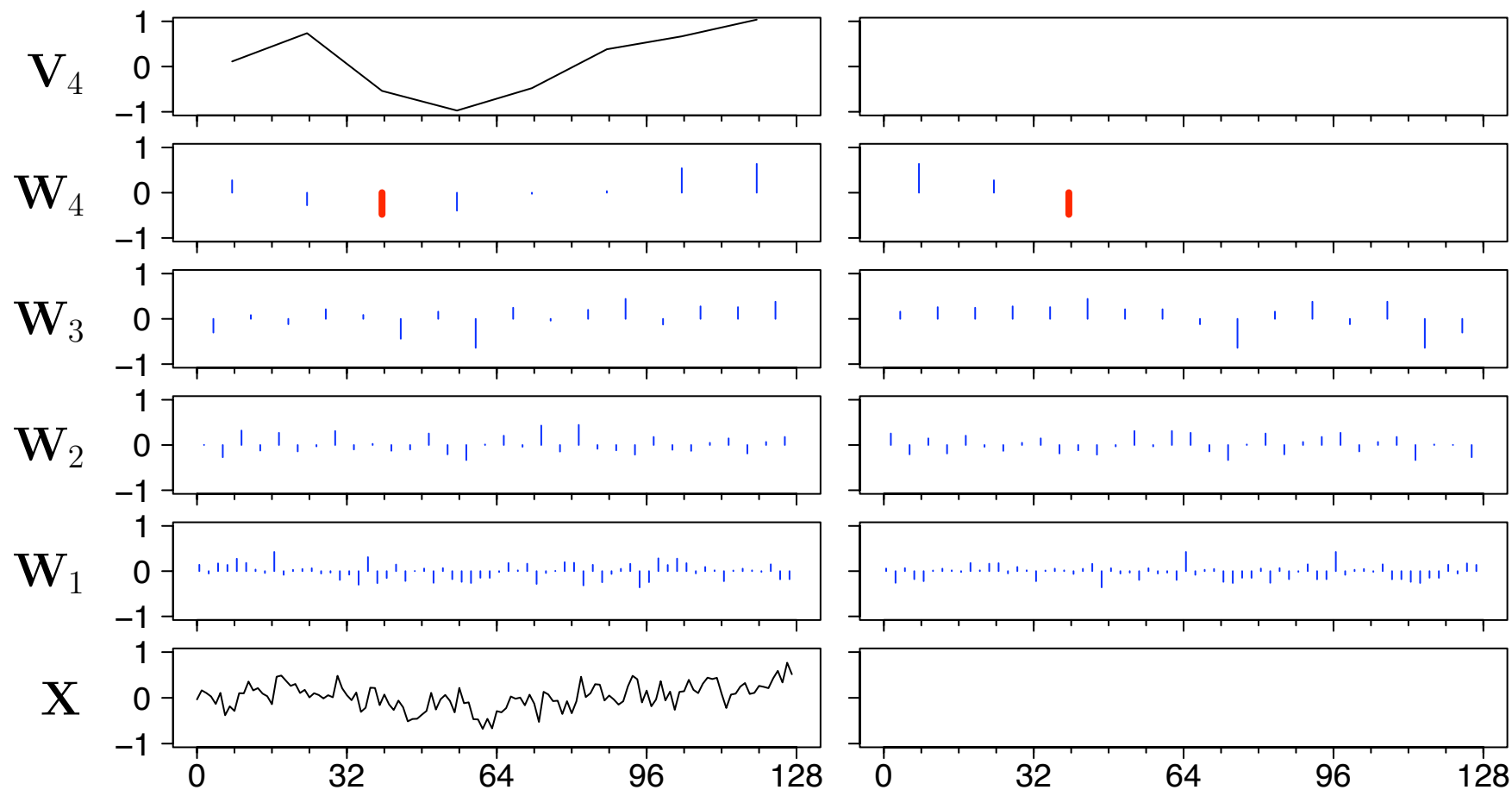
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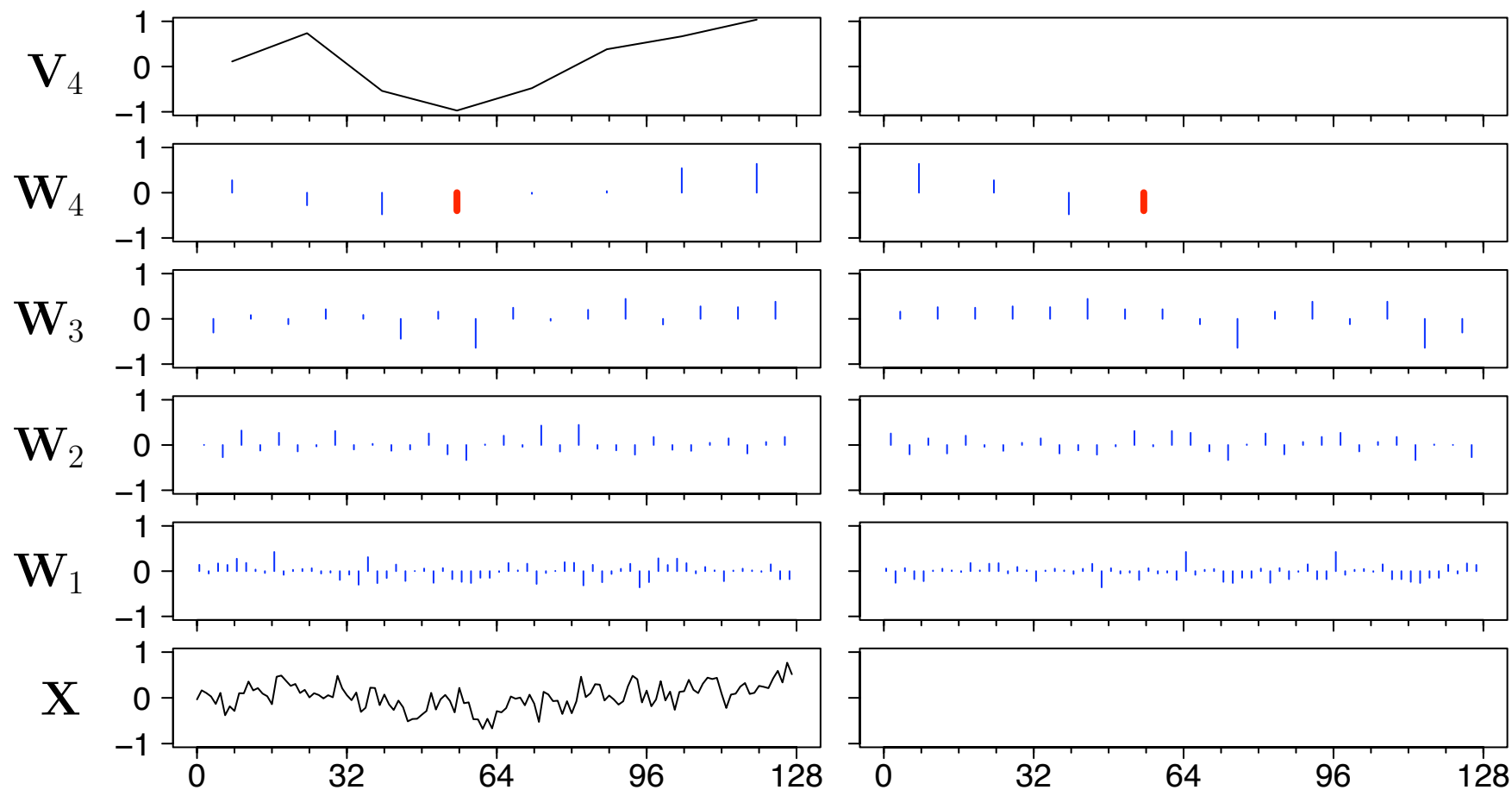
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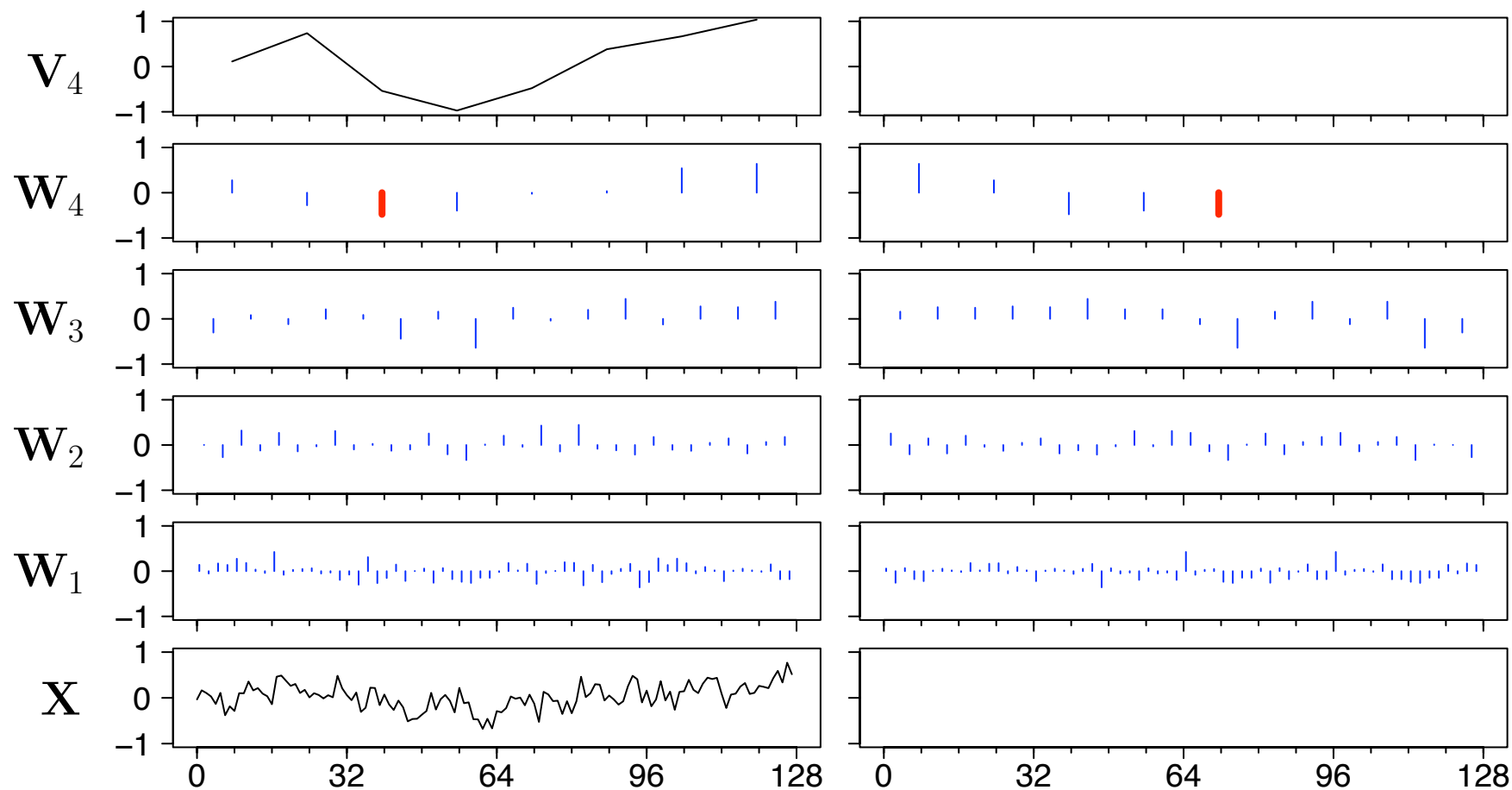
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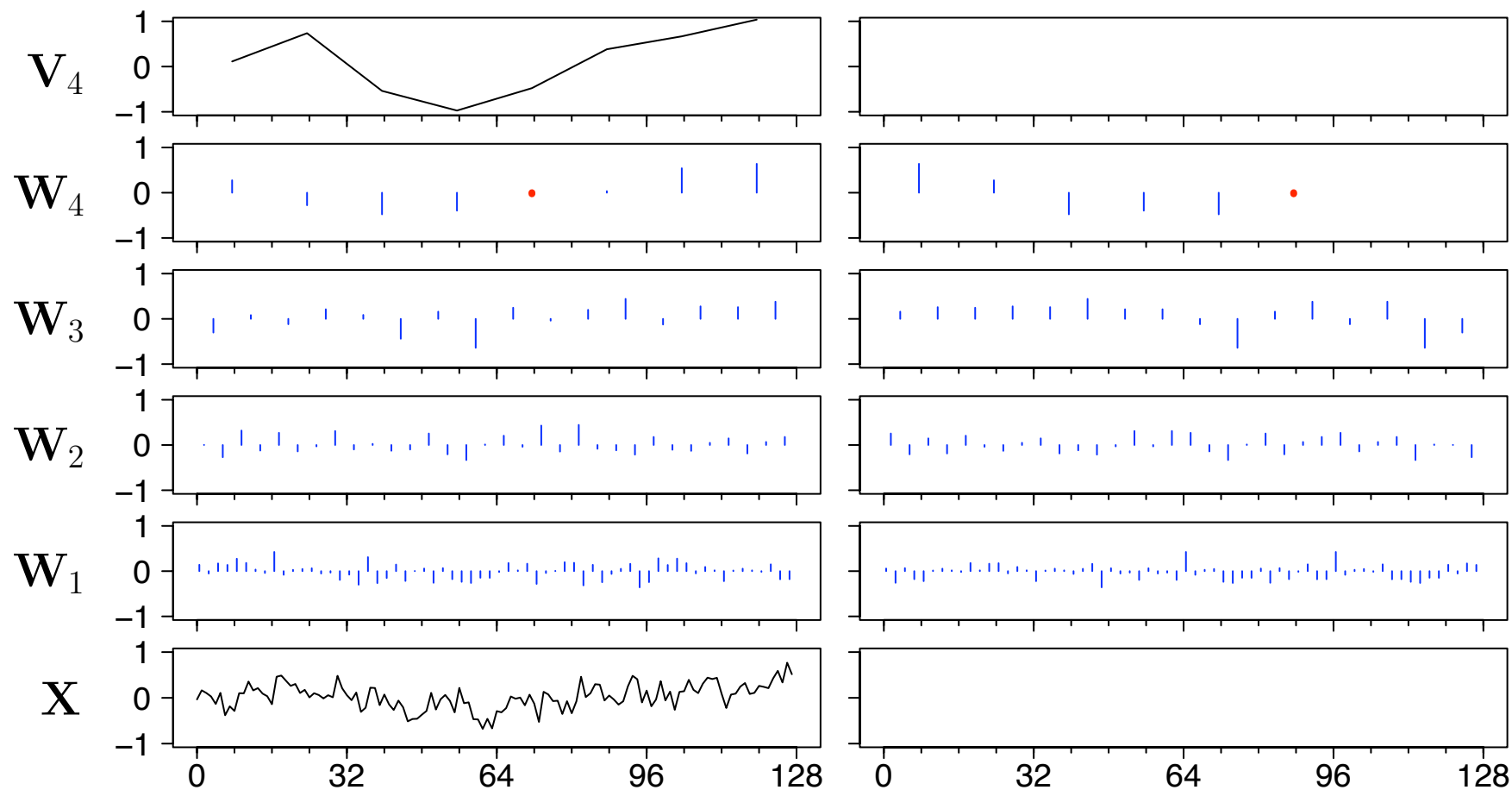
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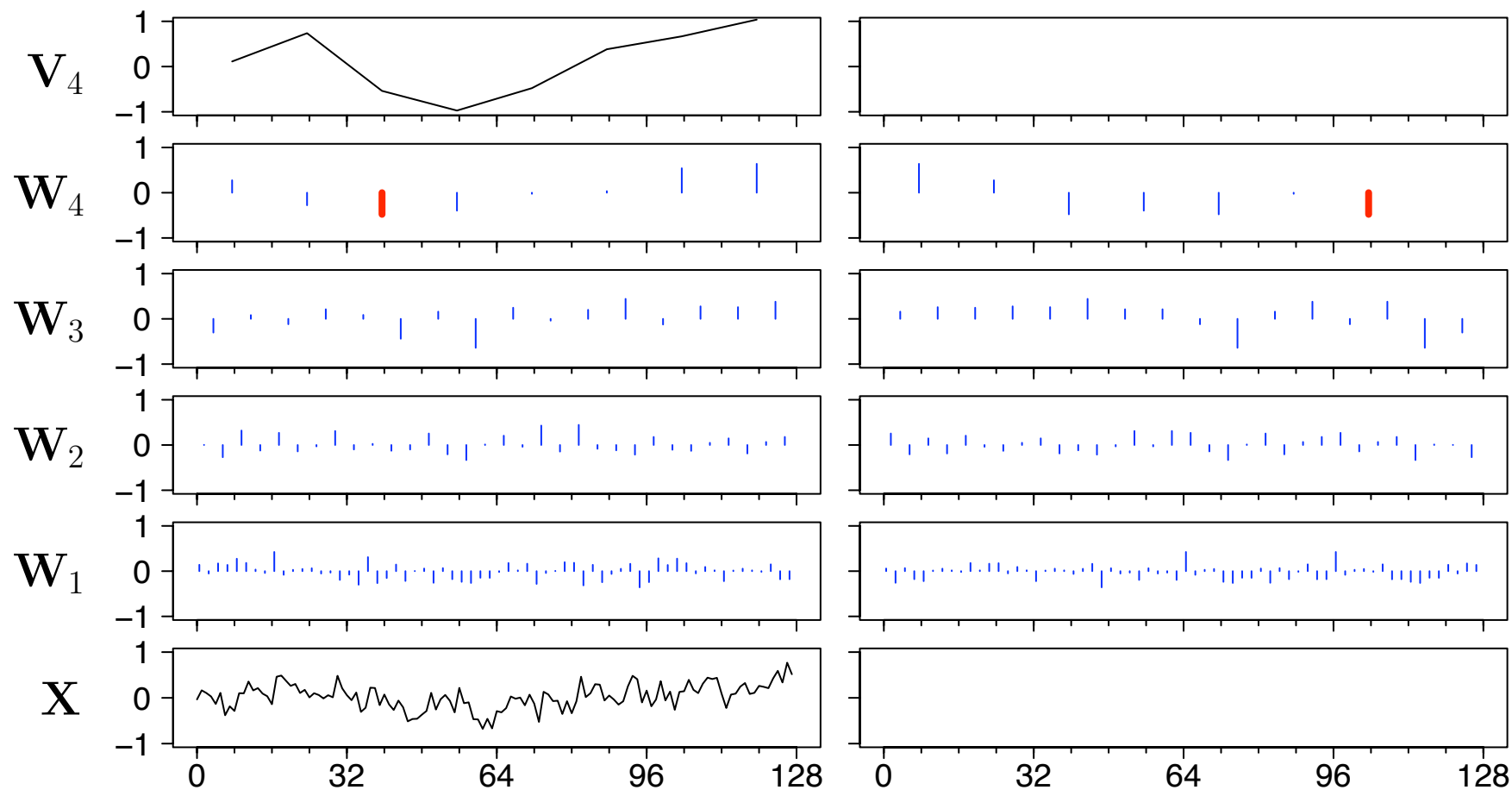
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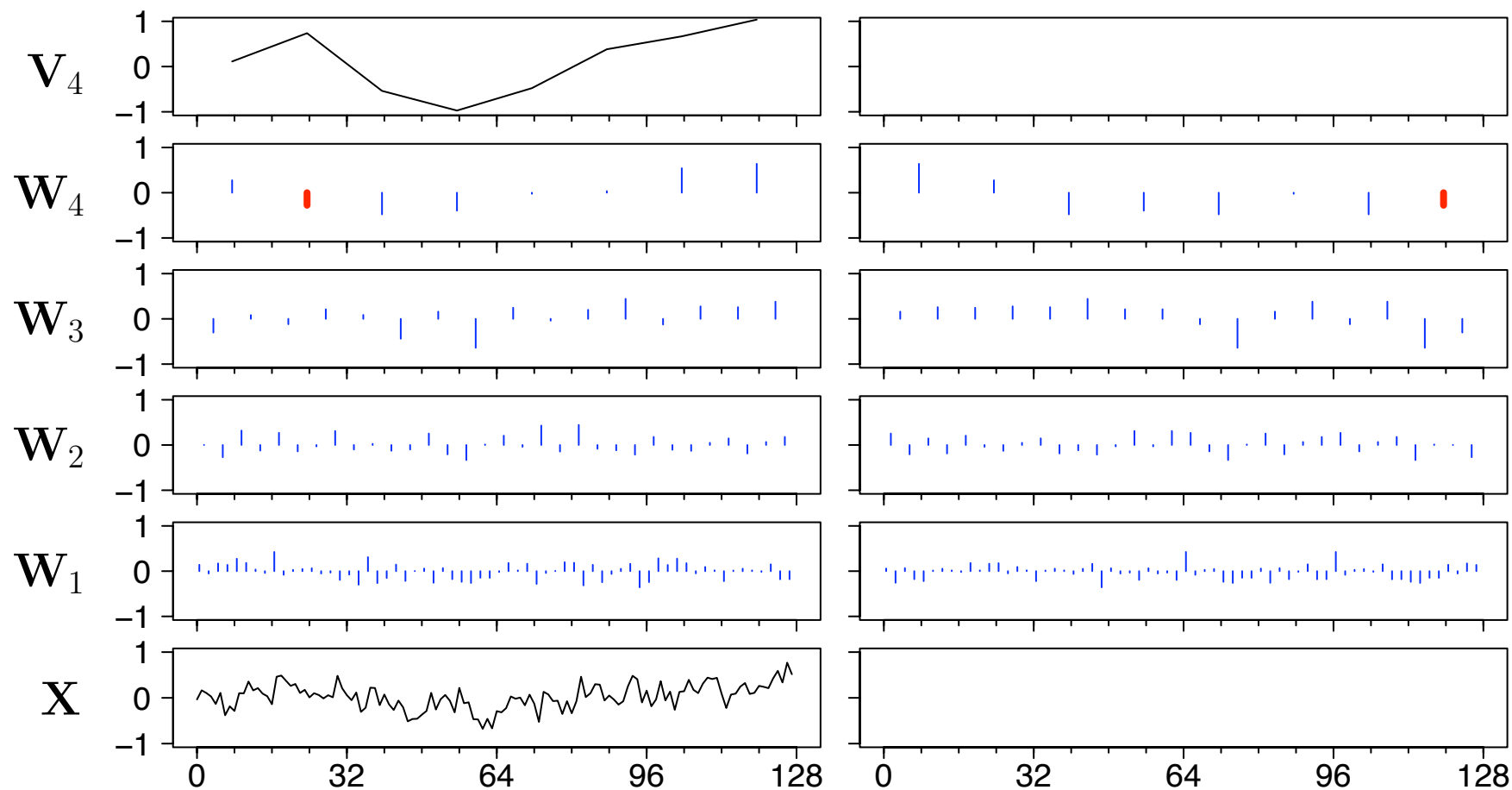
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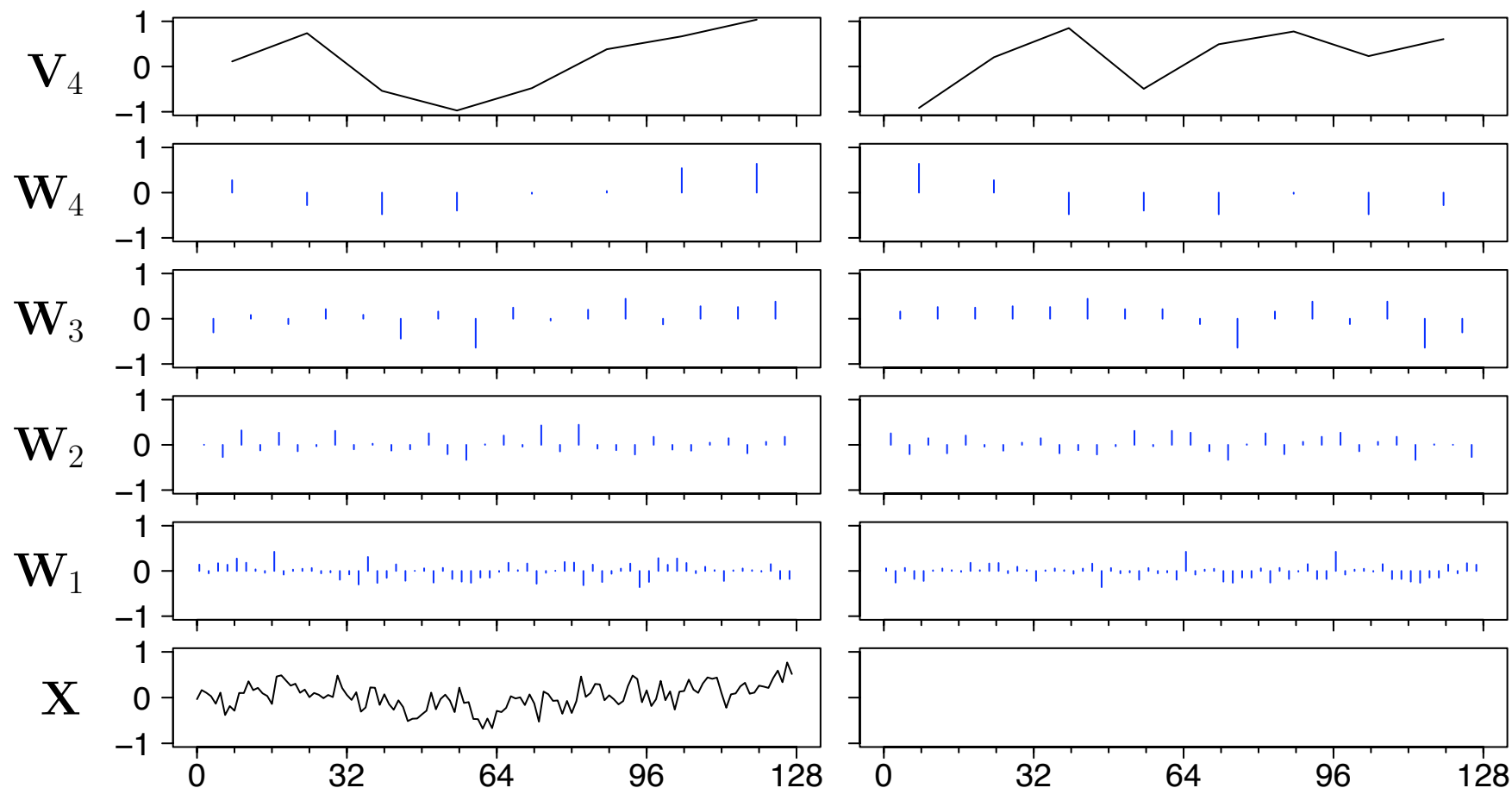
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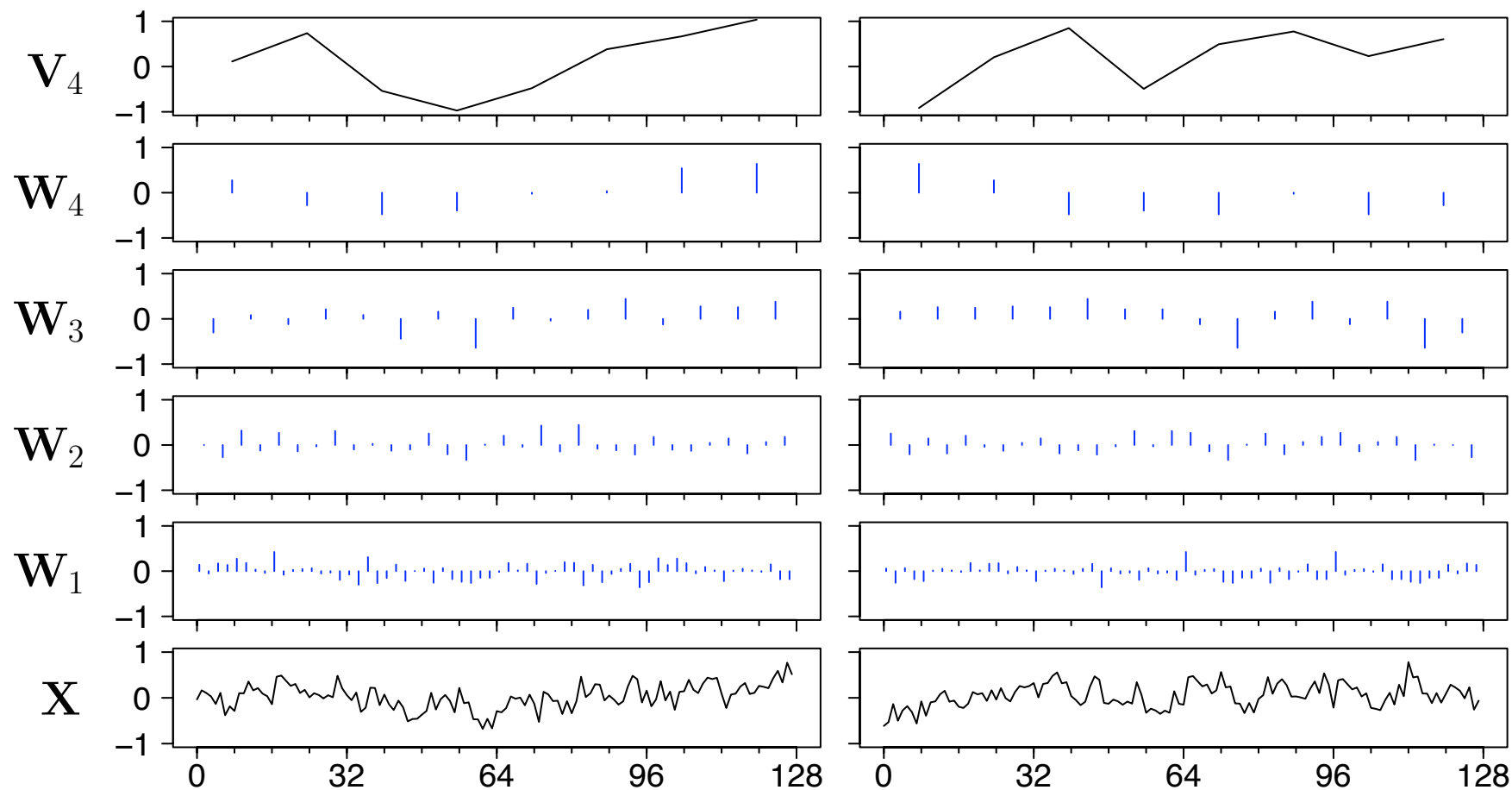
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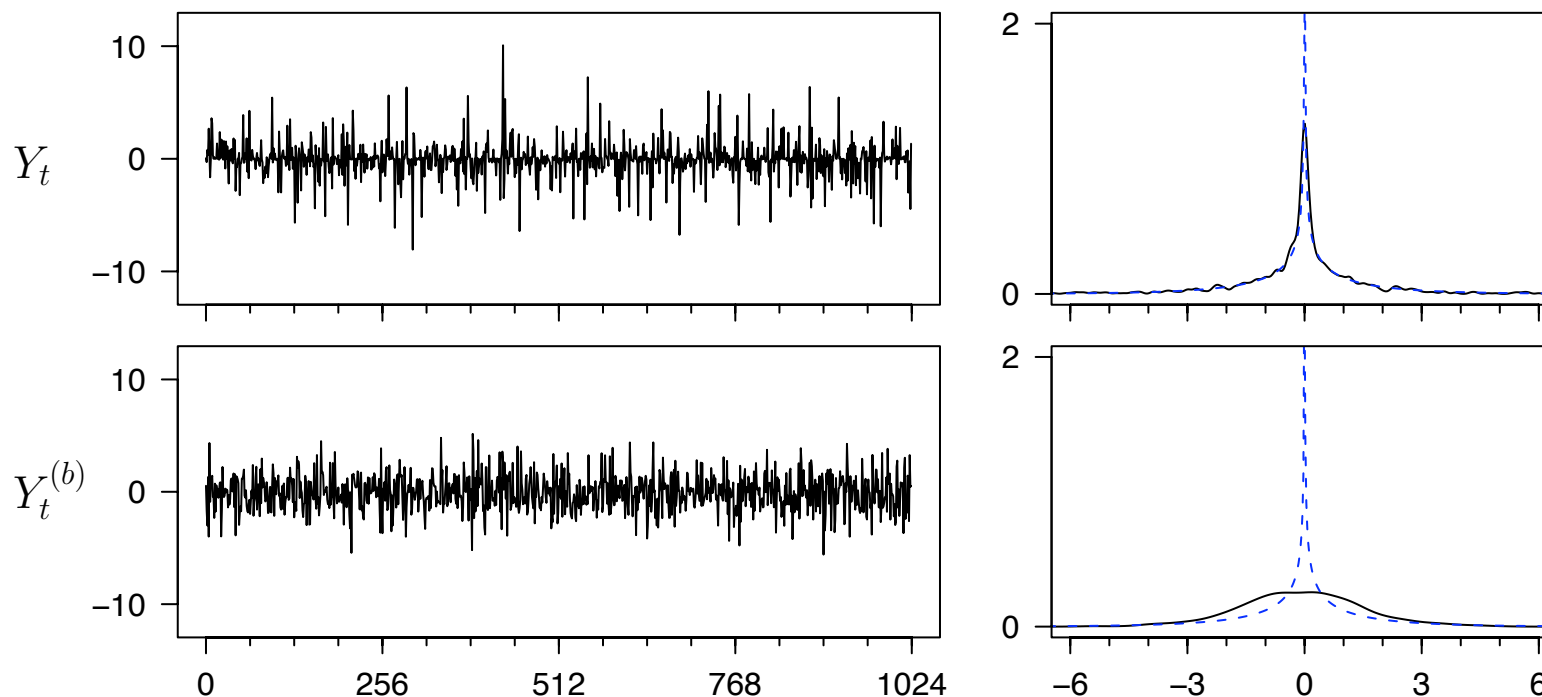
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Tree-Based Bootstraps of Non-Gaussian White Noise

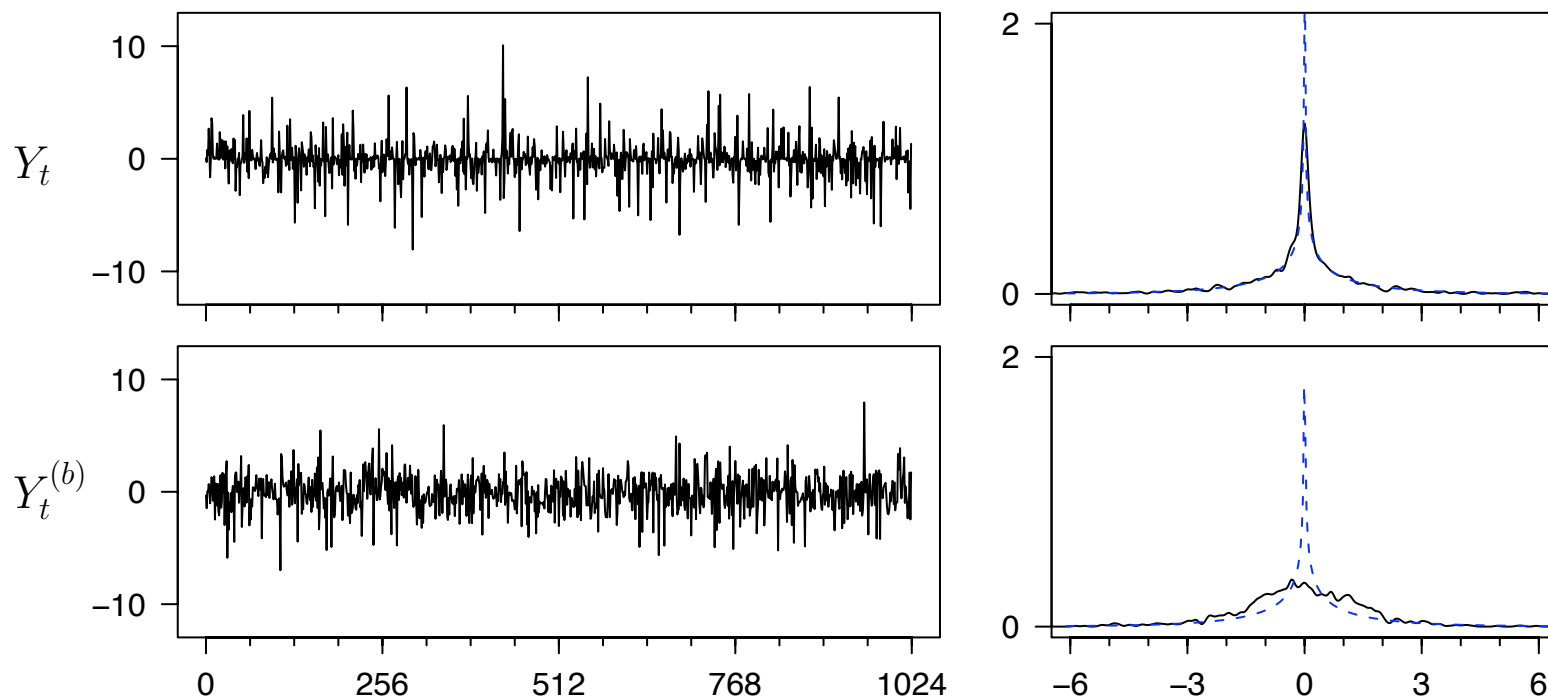
- Y_t (top row) and $j = 1$ Haar tree-based bootstrap (bottom)



- right-hand plots show estimated PDFs and true original PDF

Tree-Based Bootstraps of Non-Gaussian White Noise

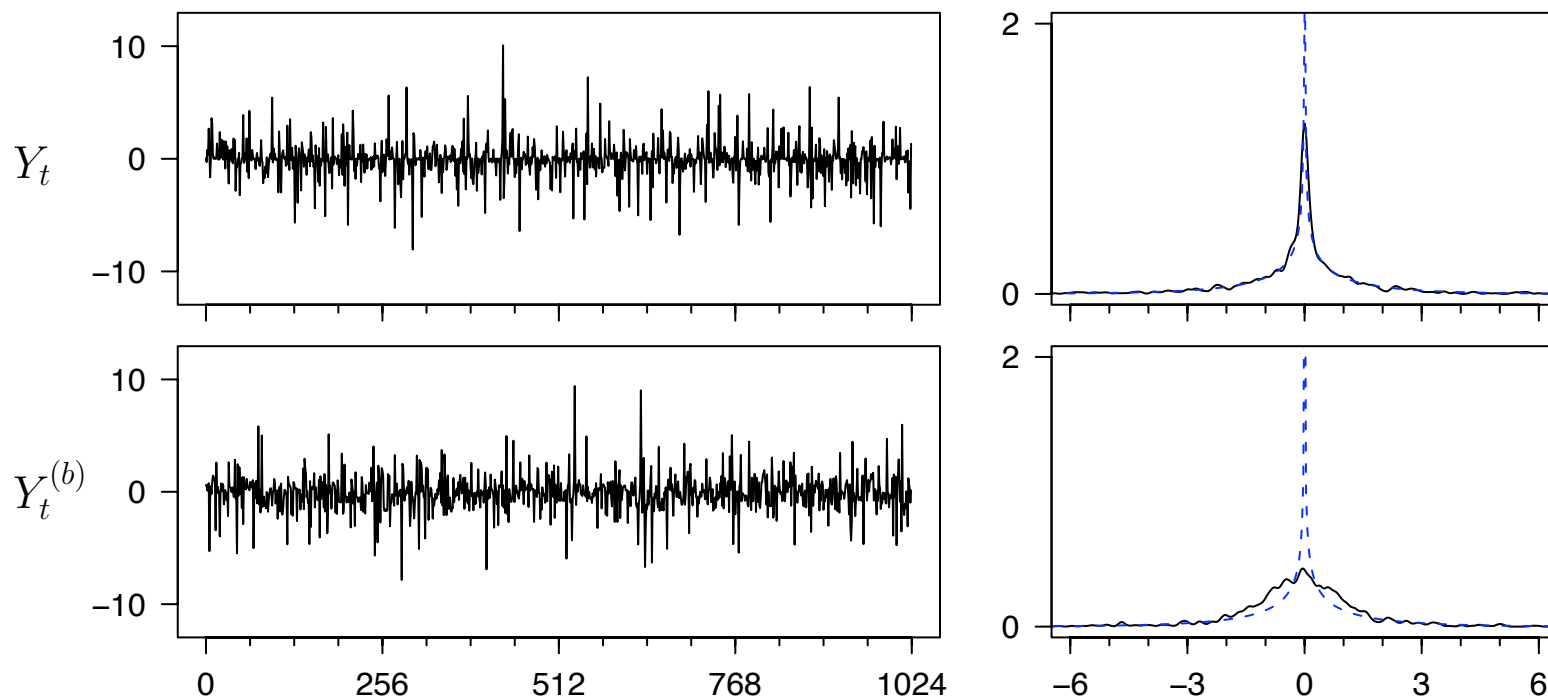
- Y_t (top row) and $j = 2$ Haar tree-based bootstrap (bottom)



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Tree-Based Bootstraps of Non-Gaussian White Noise

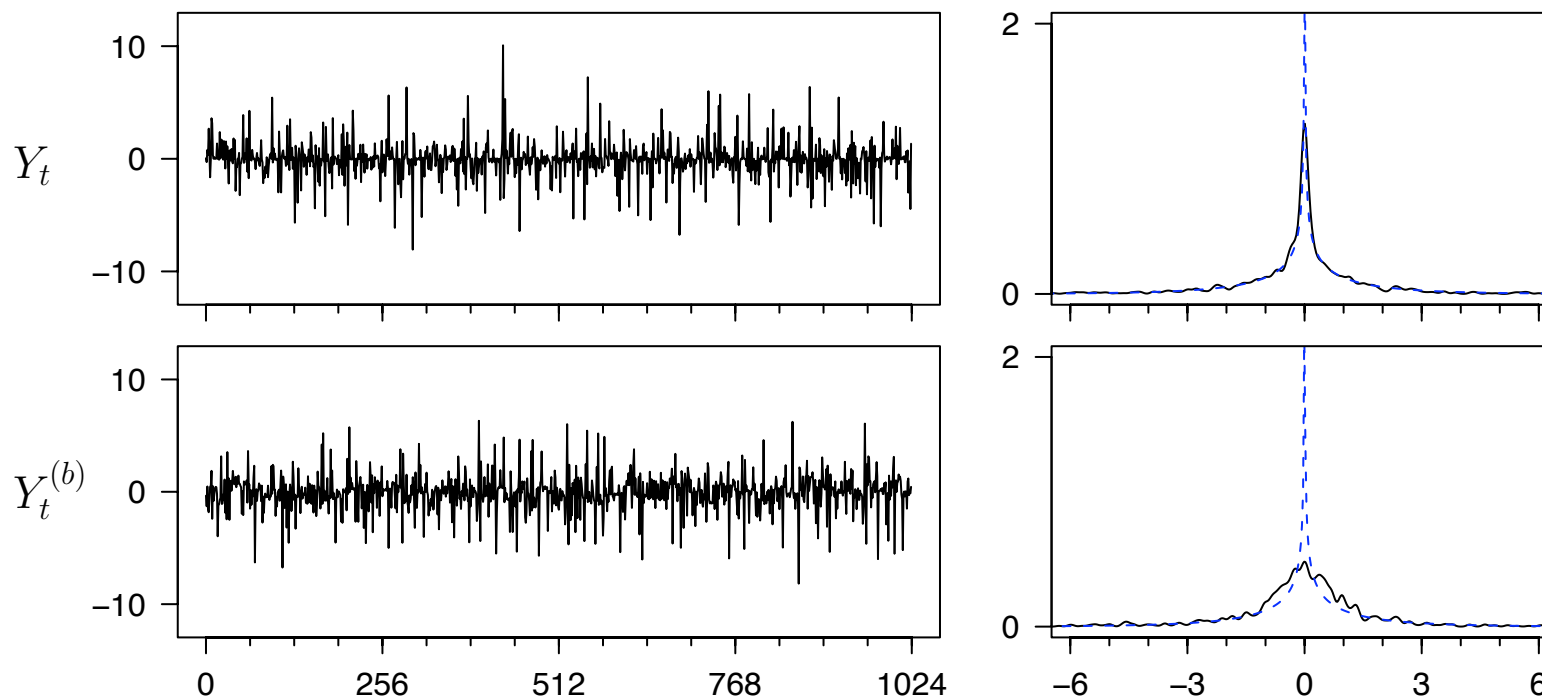
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- right-hand plots show estimated PDFs and true original PDF

Tree-Based Bootstraps of Non-Gaussian White Noise

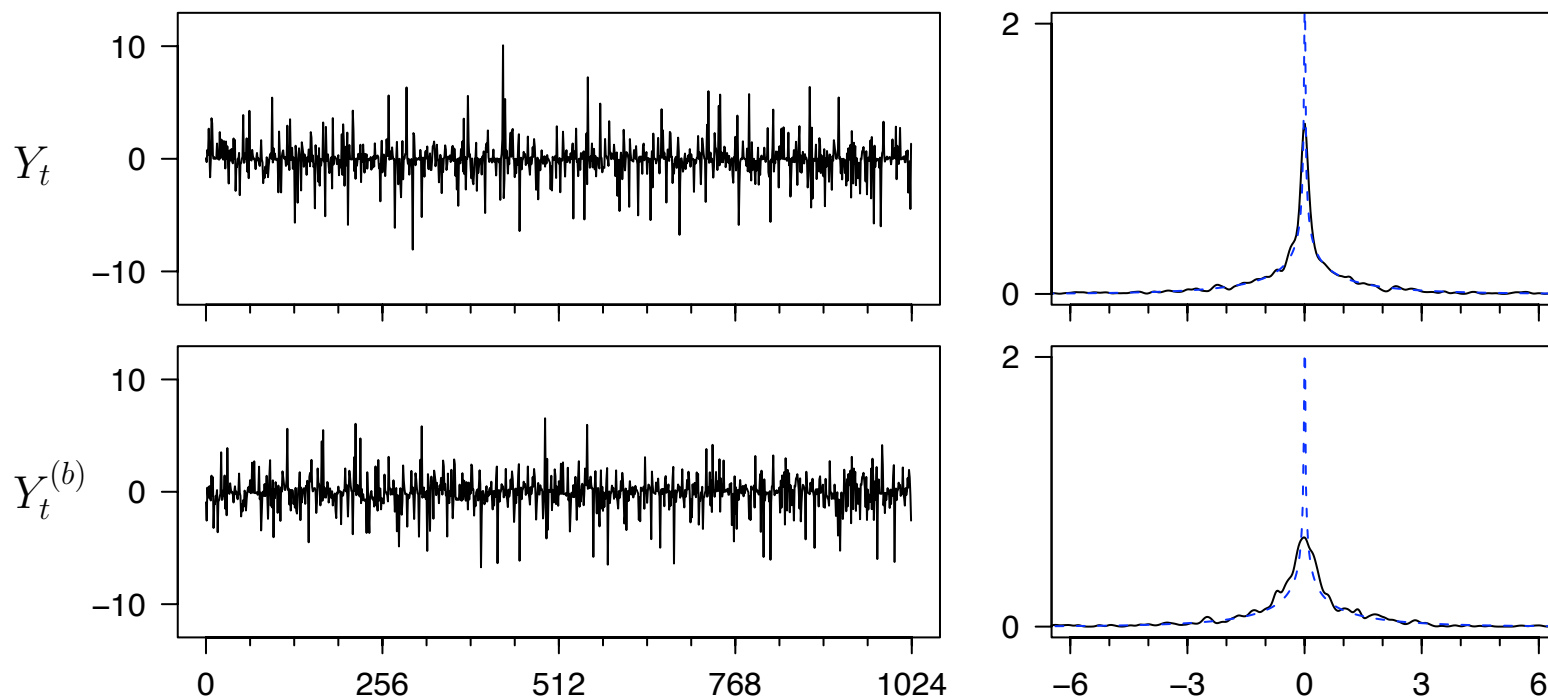
- Y_t (top row) and $j = 4$ Haar tree-based bootstrap (bottom)



- right-hand plots show estimated PDFs and true original PDF

Tree-Based Bootstraps of Non-Gaussian White Noise

- Y_t (top row) and $j = 5$ Haar tree-based bootstrap (bottom)



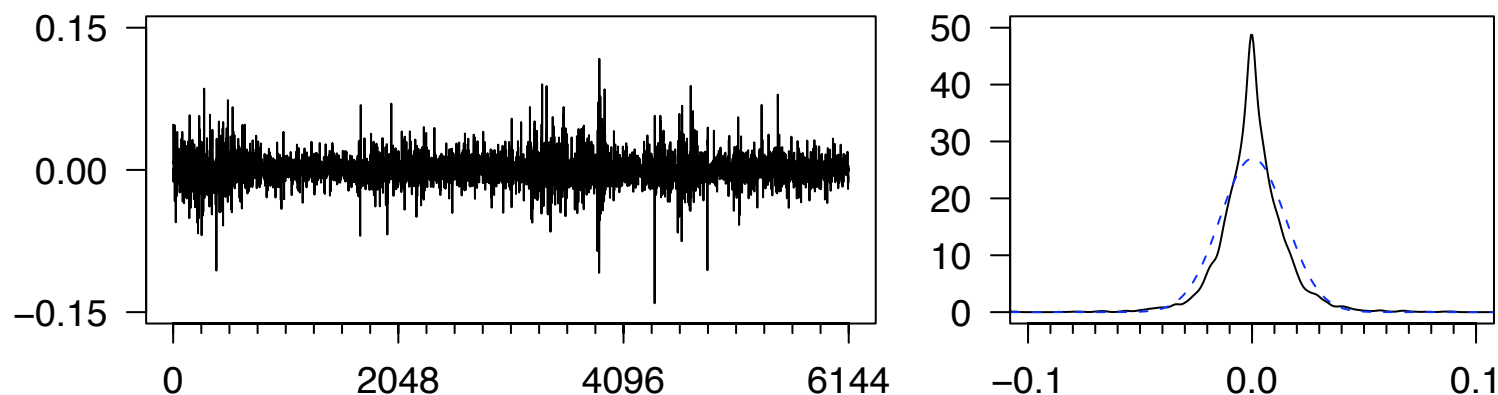
- right-hand plots show estimated PDFs and true original PDF

Summary of Computer Experiments

| Statistic | Process | LA(8) | | | | | True |
|-----------|---------|-------|-------|---------|---------|-------|-------|
| | | Parm | Block | $j = 2$ | $j = 4$ | DWT | |
| mean | AR | 0.86 | 0.83 | 0.83 | 0.84 | 0.85 | 0.86 |
| | FD | 0.58 | 0.57 | 0.54 | 0.55 | 0.57 | 0.59 |
| SD | AR | 0.016 | 0.021 | 0.025 | 0.025 | 0.024 | 0.021 |
| | FD | 0.025 | 0.042 | 0.054 | 0.051 | 0.055 | 0.059 |

- 50 time series of length $N = 1024$ for each $Y_t = \text{sign}\{X_t\} \times X_t^2$
- 100 bootstrap samples from each series, yielding 100 unit lag sample autocorrelations $\hat{\rho}_1^{(m)}$
- mean and SD of 100 sample autocorrelations recorded
- table reports averages of these two statistics over 50 time series
- true values based on 100,000 generated series for each process

Application to BMW Stock Prices - I



- right-hand plot: log of daily returns on BMW share prices
- left-hand: nonparametric and Gaussian PDF estimates
- series has small unit lag sample autocorrelation: $\hat{\rho}_1 \doteq 0.081$.
- large sample theory appropriate for Gaussian white noise gives standard deviation of $1/\sqrt{N} \doteq 0.013$

Application to BMW Stock Prices - II

- bootstrap estimates of standard deviations:

| | LA(8) $j = 2$ $j = 4$ | | | | | Gaussian |
|---------|-----------------------|-------|-------|-------|-------|----------|
| | Parm | Block | DWT | Tree | Tree | |
| SD est. | 0.012 | 0.016 | 0.021 | 0.019 | 0.019 | 0.013 |

- since $\hat{\rho}_1 \doteq 0.081$, bootstrap methods all confirm presence of autocorrelation (small, but presumably exploitable by traders)

Concluding Remarks

- wavelet-domain & tree-based bootstraps competitive with parametric & block bootstraps for series with short-range dependence and offer improvement in case of long-range dependence
- results to date for tree-based bootstrapping encouraging, but many questions need to be answered, including:
 - are there statistics & non-Gaussian series for which tree-based approach offers more than just a marginal improvement over wavelet-domain approach?
 - what are asymptotic properties of tree-based approach?
 - how can the tree-based approach be adjusted to handle stationary processes that are not well decorrelated by the DWT?

Thanks to . . .

- Ann Maharaj and Giovanni Forchini for opportunity to speak
- CSIRO Mathematics, Informatics and Statistics (CMIS) for visiting scientist position allowing for extended Australian visit
- Crime Scene for 2nd place finish in Melbourne Cup (got \$13 in \$2 sweep – first winnings ever from a horse race!!!)

References: I

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