# Wavelet-Based Bootstrapping for Non-Gaussian Time Series

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overheads for talk available at

http://faculty.washington.edu/dbp/talks.html

#### **Overview**

- question of interest: how can we assess the sampling variability in statistics computed from a time series  $X_0, X_1, \ldots, X_{N-1}$ ?
- start with some background on bootstrapping
- review parametric and block bootstrapping (two approaching for handling correlated time series)
- review one wavelet-based approach to bootstrapping (Percival, Sardy and Davison, 2001)
- describe a new wavelet-based approach that uses 'trees' for resampling and is potentially useful for non-Gaussian time series
- demonstrate methodology on time series related to BMW stock
- conclude with some remarks

#### **Motivating Question**

• let  $\mathbf{X} = [X_0, ..., X_{N-1}]^T$  be a portion of a stationary process with autocorrelation sequence (ACS)

$$\rho_{\tau} \equiv \frac{s_{\tau}}{s_0}, \text{ where } s_{\tau} \equiv \text{cov} \{X_t, X_{t+\tau}\} \text{ and } s_0 = \text{var} \{X_t\}$$

• given a time series, we can estimate its ACS at  $\tau = 1$  using

$$\hat{\rho}_1 \equiv \frac{\sum_{t=0}^{N-2} (X_t - \overline{X})(X_{t+1} - \overline{X})}{\sum_{t=0}^{N-1} (X_t - \overline{X})^2}, \text{ where } \overline{X} = \frac{1}{N} \sum_{t=0}^{N-1} X_t$$

- Q: given the amount of data N we have, how close can we expect  $\hat{\rho}_1$  to be to the true unknown  $\rho_1$ ?
- i.e., how can we assess the sampling variability in  $\hat{\rho}_1$ ?

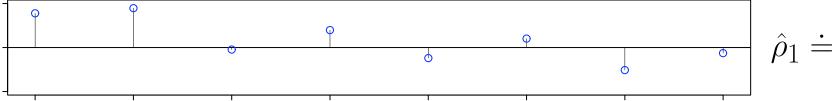
### Classic Approach – Large Sample Theory

- let  $\mathcal{N}(\mu, \sigma^2)$  denote a Gaussian (normal) random variable (RV) with mean  $\mu$  and variance  $\sigma^2$
- under suitable conditions (see, e.g., Fuller, 1996),  $\hat{\rho}_1$  is close to the distribution of  $\mathcal{N}(\rho_1, \sigma_N^2)$  as  $N \to \infty$ , where

$$\sigma_N^2 \equiv \frac{1}{N} \sum_{\tau = -\infty}^{\infty} \left\{ \rho_{\tau}^2 (1 + 2\rho_1^2) + \rho_{\tau+1} \rho_{\tau-1} - 4\rho_1 \rho_{\tau} \rho_{\tau-1} \right\}$$

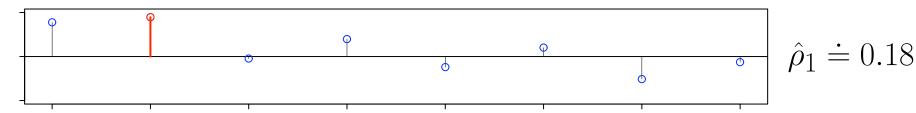
- in practice, this result is unappealing because it requires
  - knowledge of theoretical ACS
  - ACS to damp down fast, ruling out some processes of interest
- while large sample theory has been worked out for  $\hat{\rho}_1$  under certain conditions, similar theory for other statistics can be hard to come by

- if  $X_t$ 's were IID, we could apply 'bootstrapping' to assess the variability in  $\hat{\rho}_1$ , as follows
- consider a time series of length N=8 that is a realization of a Gaussian white noise process ( $\rho_1 = 0$ ):



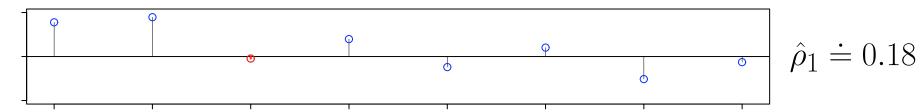
$$\hat{\rho}_1 \doteq 0.18$$

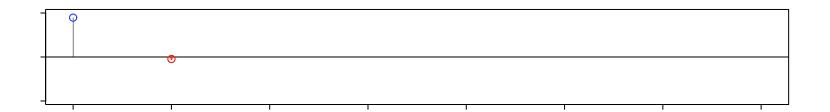
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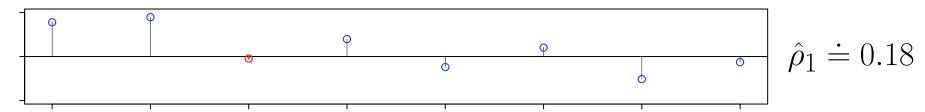


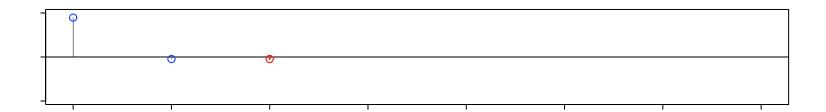
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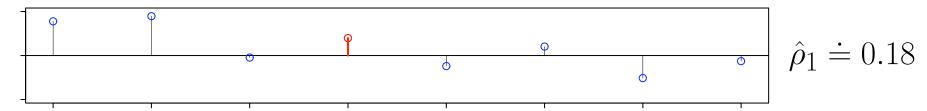


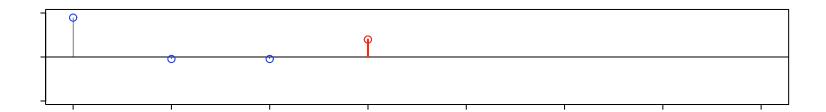
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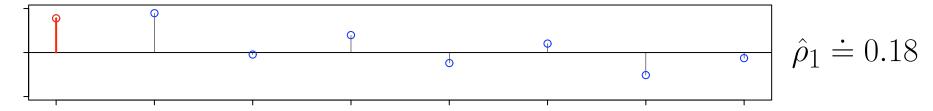


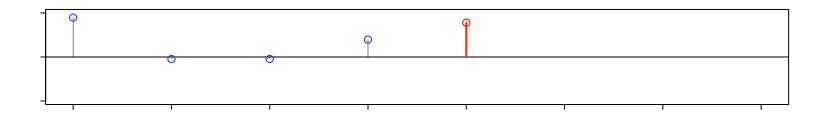
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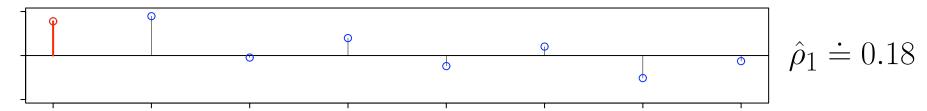


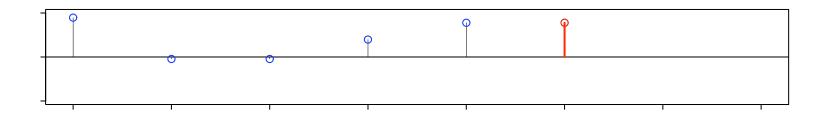
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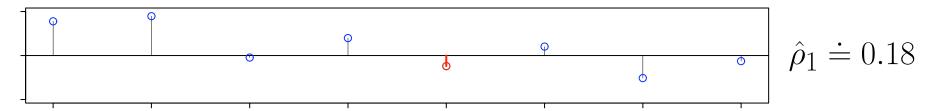


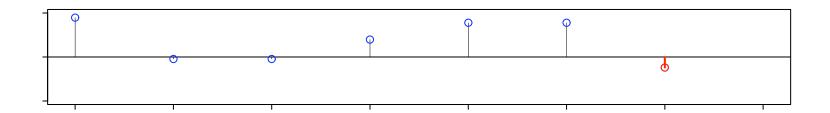
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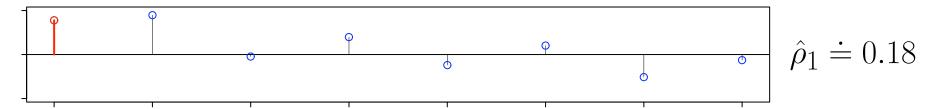


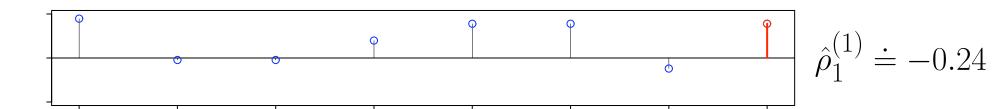
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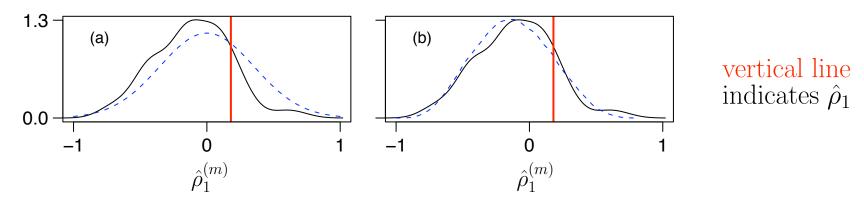


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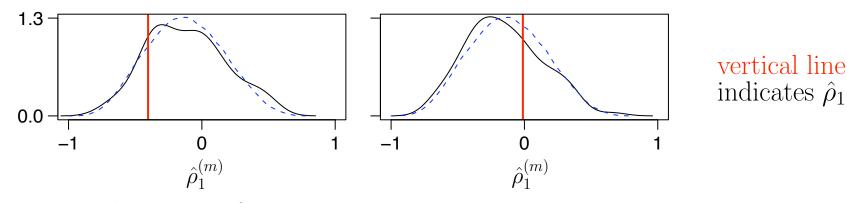


- repeat a large number of times M to get  $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(M)}$
- plots shows estimated probability density function (PDF) for  $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(100)}$ , along with (a) PDF for  $\mathcal{N}(0, \frac{1}{8})$  and (b) approximation to the true PDF for  $\hat{\rho}_1$



• can regard sample distribution of  $\{\hat{\rho}_1^{(m)}\}$  as an approximation to the unknown distribution of  $\hat{\rho}_1$ 

- quality of approximation depends upon particular time series
- here are bootstrap approximations to PDF of  $\hat{\rho}_1$  based upon two other time series of length N=8, along with true PDF



- repeating the above for 50 time series yields 50 bootstrap PDFs
- summarize via sample means and standard deviations (SDs):

average of 50 sample means 
$$\doteq -0.127$$
 (truth  $\doteq -0.124$ )  
average of 50 sample SDs  $\doteq 0.280$  (truth  $\doteq 0.284$ )

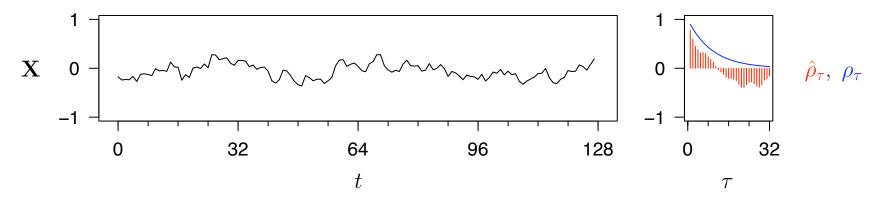
#### Bootstrapping Correlated Time Series: I

- key assumption: **X** contains IID RVs
- if not true (as for most time series!), sample distribution of  $\{\hat{\rho}_1^{(m)}\}\$  can be a poor approximation to distribution of  $\hat{\rho}_1$
- as an example, consider first order autoregressive (AR) process:

$$X_t = \phi X_{t-1} + \epsilon_t,$$

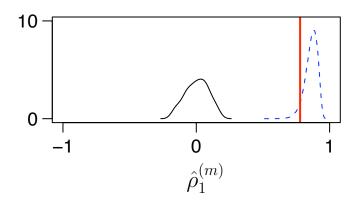
where  $\phi = 0.9$  and  $\{\epsilon_t\}$  is zero mean Gaussian white noise

• AR time series of length N = 128 with sample and true ACSs:



### Bootstrapping Correlated Time Series: II

- use same procedure as before to get  $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(100)}$
- bootstrap approximation to PDF of  $\hat{\rho}_1$  along with true PDF:



vertical line indicates  $\hat{\rho}_1$ 

- bootstrap approximation gets even worse as N increases
- to correct the problem caused by correlation in time series, can use specialized time- or frequency-domain bootstrapping (assuming true ACS damps downs sufficiently fast)

### Parametric Bootstrapping: I

- one well-known time-domain bootstrapping scheme is the parametric (or residual) bootstrap
- suppose **X** is a realization of AR process  $X_t = \phi X_{t-1} + \epsilon_t$
- note that var  $\{X_t\} = \operatorname{var} \{\epsilon_t\}/(1-\phi^2)$  and  $\rho_\tau = \phi^{|\tau|}$
- in particular,  $\rho_1 = \phi$ , so can estimate  $\phi$  using  $\hat{\phi} \equiv \hat{\rho}_1$
- since  $\epsilon_t = X_t \phi X_{t-1}$ , can form residuals

$$r_t = X_t - \hat{\phi} X_{t-1}, \quad t = 1, \dots, N-1,$$

with the idea that  $r_t$  will be a good approximation to  $\epsilon_t$ 

- let  $r_0^{(1)}, r_1^{(1)}, \dots, r_{N-1}^{(1)}$  be a random sample from  $r_1, r_2, \dots, r_{N-1}$
- let  $X_0^{(1)} = r_0^{(1)}/(1-\hat{\phi}^2)^{1/2}$  ('stationary initial condition')

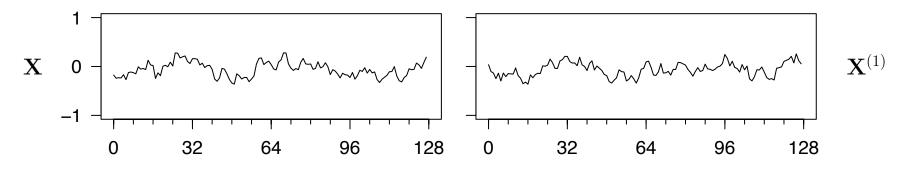
# Parametric Bootstrapping: II

form

$$X_t^{(1)} = \hat{\phi} X_{t-1}^{(1)} + r_t^{(1)}, \quad t = 1, \dots, N-1,$$

yielding the bootstrapped time series  $X_0^{(1)}, X_1^{(1)}, \dots, X_{N-1}^{(1)}$ 

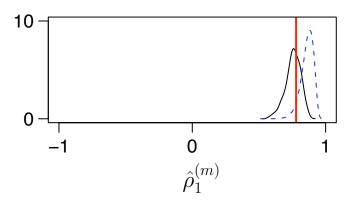
• AR time series (left-hand plot) and bootstrapped series (right):



- use bootstrapped series to compute  $\hat{\rho}_1^{(1)}$
- repeat this procedure M times to get  $\hat{\rho}_1^{(1)}, \hat{\rho}_1^{(2)}, \dots, \hat{\rho}_1^{(M)}$

### Parametric Bootstrapping: III

• bootstrap approximation to PDF of  $\hat{\rho}_1$  along with true PDF:



vertical line indicates  $\hat{\rho}_1$ 

• repeating the above for 50 AR time series yields:

average of 50 sample means 
$$\doteq 0.83$$
 (truth  $\doteq 0.86$ )  
average of 50 sample SDs  $\doteq 0.053$  (truth  $\doteq 0.048$ )

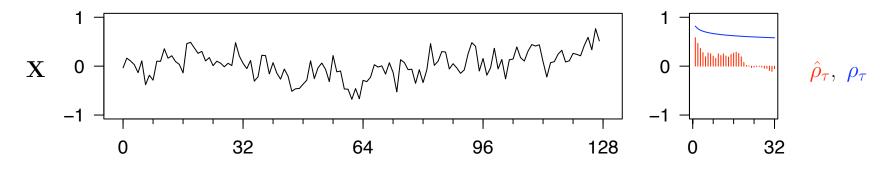
### Parametric Bootstrapping: IV

- important assumption: **X** generated by AR process
- to see what happens if assumption fails, consider a fractionally differenced (FD) process

$$X_{t} = \sum_{k=0}^{\infty} \frac{\Gamma(1-\delta)}{\Gamma(k+1)\Gamma(1-\delta-k)} \epsilon_{t-k},$$

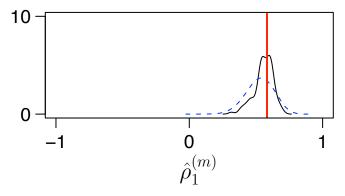
where  $\delta = 0.45$  and  $\{\epsilon_t\}$  is zero mean Gaussian white noise

• FD time series of length N = 128 with sample and true ACSs:



### Parametric Bootstrapping: V

- AR process has 'short-range' dependence, whereas FD process exhibits 'long-range' (or 'long-memory') dependence
- bootstrap approximation to PDF of  $\hat{\rho}_1$  along with true PDF:



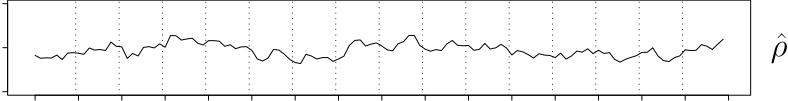
vertical line indicates  $\hat{\rho}_1$ 

• repeating the above for 50 FD time series yields:

average of 50 sample means  $\doteq 0.49$  (truth  $\doteq 0.53$ ) average of 50 sample SDs  $\doteq 0.078$  (truth  $\doteq 0.107$ )

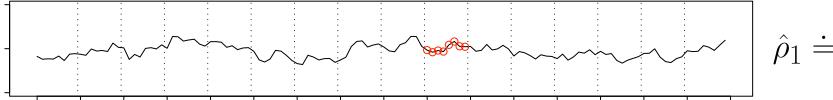
note:  $\rho_1 \doteq 0.82$  for this FD process; agreement in SD gets worse (better) as N increases (decreases)

- another time-domain approach is block bootstrapping, which has many variations, of which the following is the simplest
- break time series up into B blocks (subseries) of equal length:

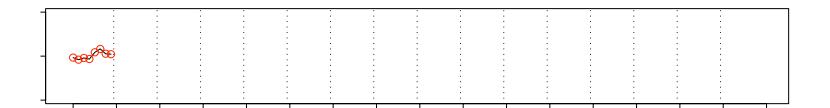


$$\hat{\rho}_1 \doteq 0.78$$

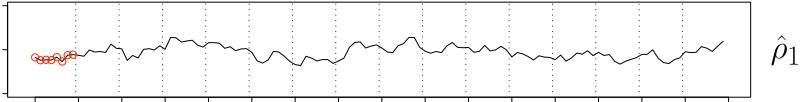
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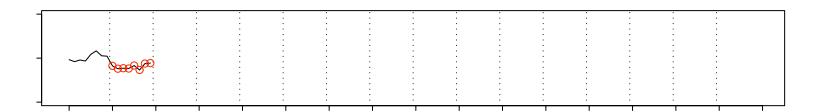
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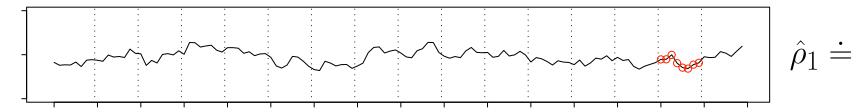
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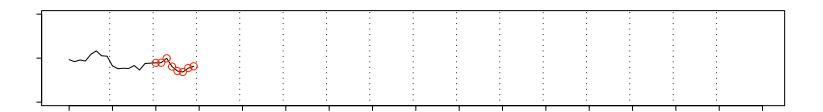


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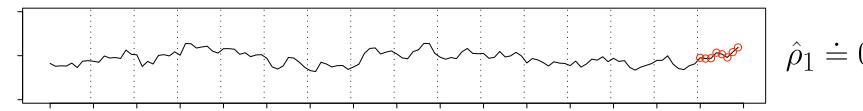


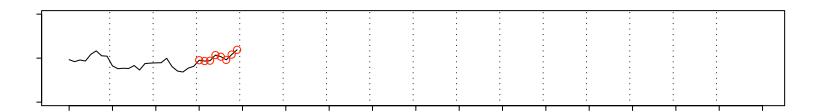
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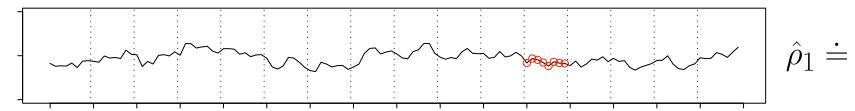


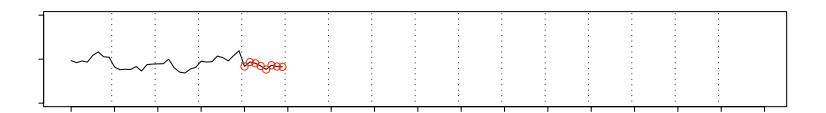
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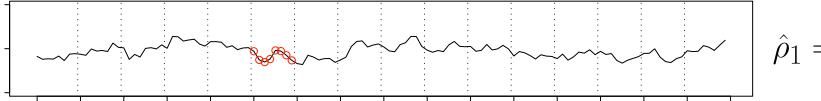


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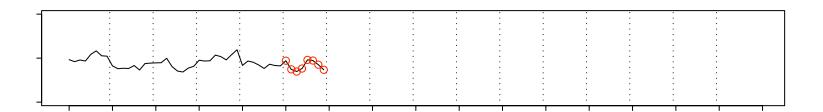




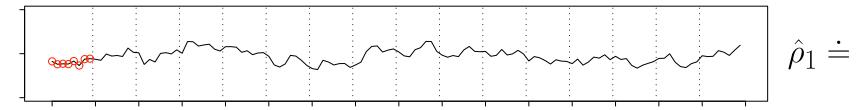
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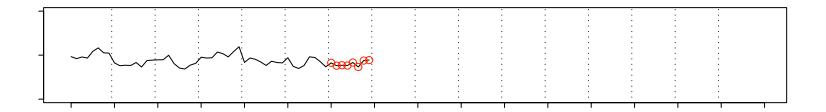


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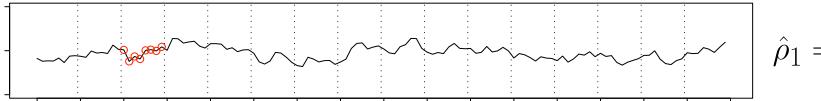


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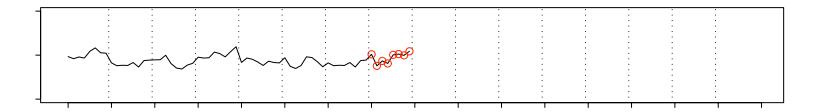




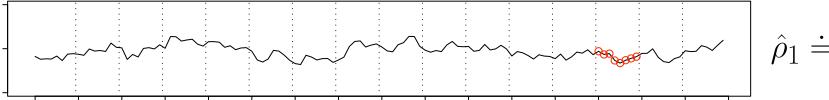
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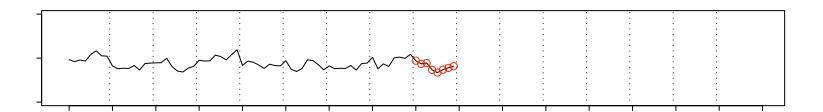
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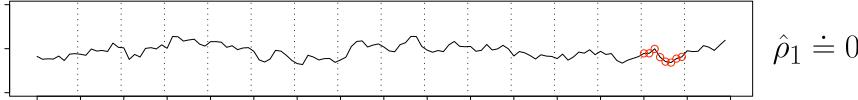
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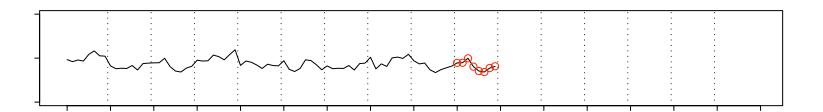


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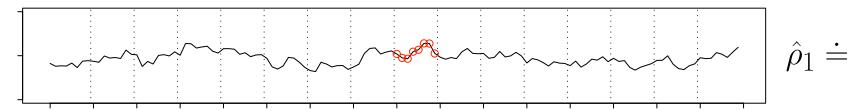


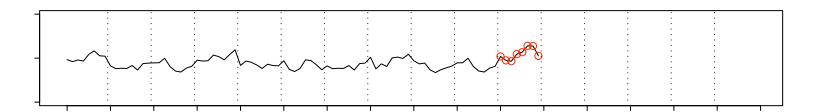
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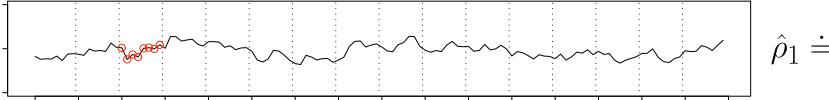


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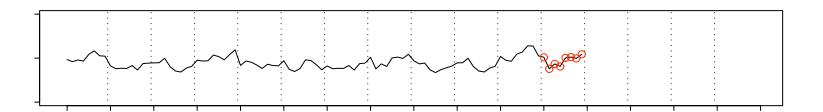




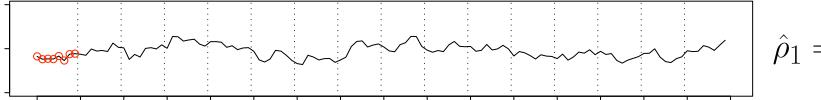
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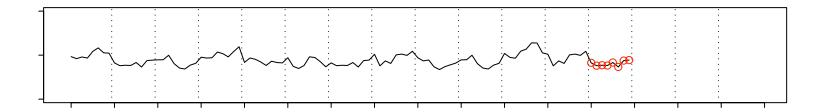
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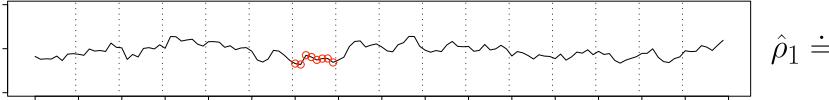


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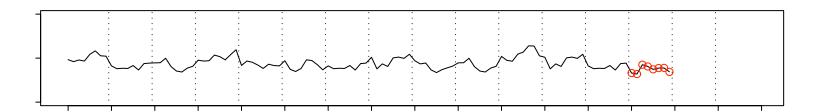
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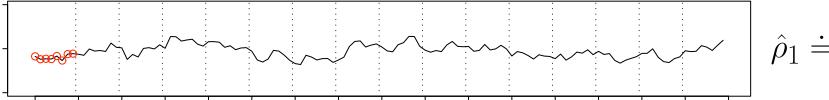
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• generate bootstrapped AR series by randomly sampling blocks:



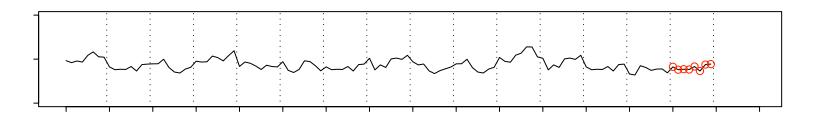
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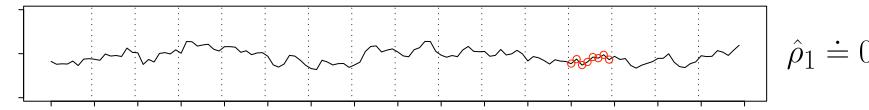
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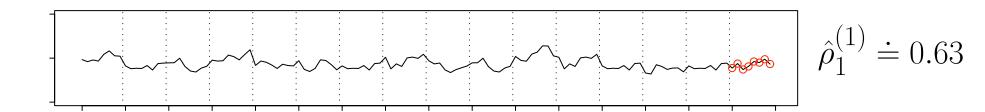


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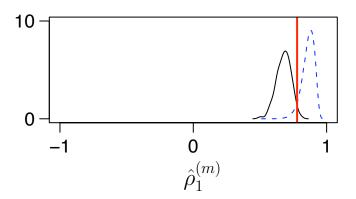


• generate bootstrapped AR series by randomly sampling blocks:



# Block Bootstrapping: II

• bootstrap approximation to PDF of  $\hat{\rho}_1$  along with true PDF:



vertical line indicates  $\hat{\rho}_1$ 

• repeating the above for 50 AR time series yields:

average of 50 sample means  $\doteq 0.75$  (truth  $\doteq 0.86$ ) average of 50 sample SDs  $\doteq 0.049$  (truth  $\doteq 0.048$ )

• repeating the above for 50 FD time series yields:

average of 50 sample means  $\doteq 0.46$  (truth  $\doteq 0.53$ ) average of 50 sample SDs  $\doteq 0.082$  (truth  $\doteq 0.107$ )

### Frequency-Domain Bootstrapping

- again, many variations, including the following three
- 'phase scramble' discrete Fourier transform (DFT)

$$\mathcal{X}_{k} = \sum_{t=0}^{N-1} X_{t} e^{-i2\pi kt/N} = A_{k} e^{i\theta_{k}}$$

of X and apply inverse DFT to create new series

- periodogram-based bootstrapping: in addition to phase scrambling, evoke large sample result that  $|A_k|$ 's are approximately uncorrelated with distribution related to a chi-square RV with 2 degrees of freedom
- circulant embedding bootstrapping: form nonparametric estimate of spectral density function and generate realizations using circulant embedding

# Critique of Time/Frequency-Domain Bootstrapping

- time- and frequency-domain approaches are mainly designed for series with short-range dependence (e.g., AR) and are problematic for those exhibiting long-range dependence (e.g., FD)
- parametric and frequency-domain bootstraps work best for series that obey a Gaussian distribution, but can be problematic for non-Gaussian series
- non-Gaussian series better handled by block bootstrapping, but quality of this approach depends critically on chosen size for blocks (ad hoc rule is to set size close to  $\sqrt{N}$ )
- room for improvement: will consider wavelet-based approaches

# Overview of Discrete Wavelet Transform (DWT): I

• DWT is an orthonormal transform  $\mathcal{W}$  that reexpresses a time series  $\mathbf{X}$  of length N as a vector of DWT coefficients  $\mathbf{W}$ :

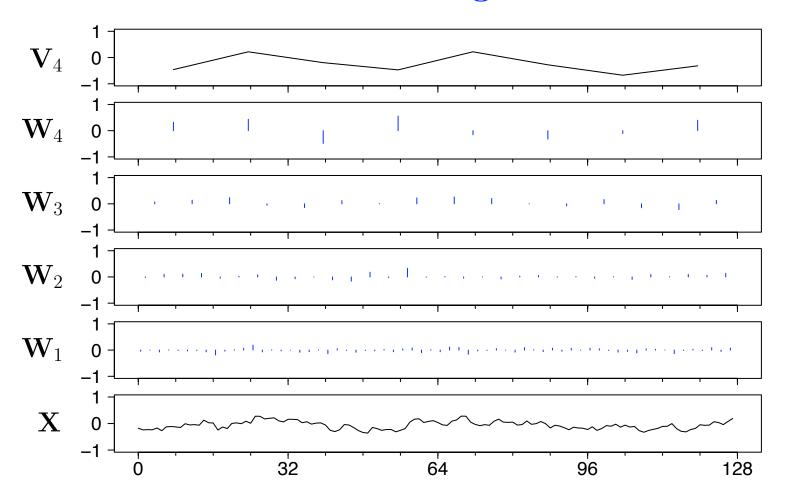
$$\mathbf{W} = \mathcal{W}\mathbf{X},$$

where W is an  $N \times N$  matrix such that  $\mathbf{X} = \mathcal{W}^T \mathbf{W}$ 

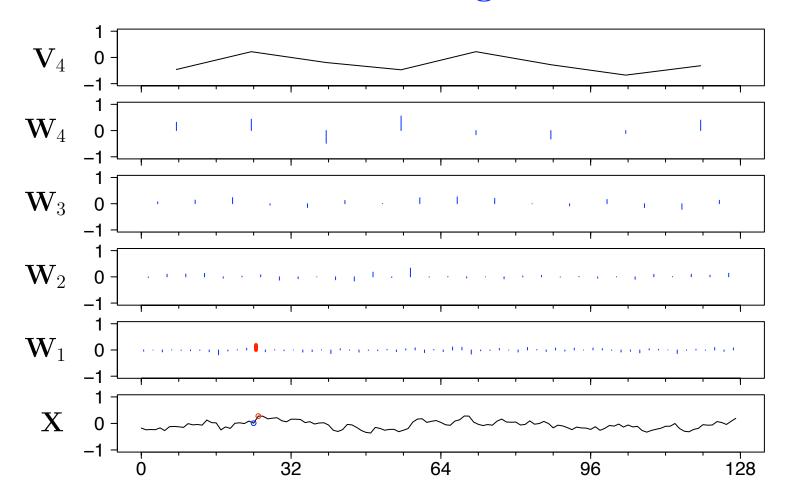
- ullet particular  ${\mathcal W}$  depends on the choice of
  - wavelet filter, the most basic of which is the Haar filter (fancier filters include the Daubechies family of 'least asymmetric' filters of width L denoted by LA(L), with L=8 being a popular choice)
  - level  $J_0$ , which determines the number of dyadic scales  $\tau_j = 2^{j-1}$ ,  $j = 1, 2, \ldots, J_0$ , involved in the transform

# Overview of Discrete Wavelet Transform (DWT): II

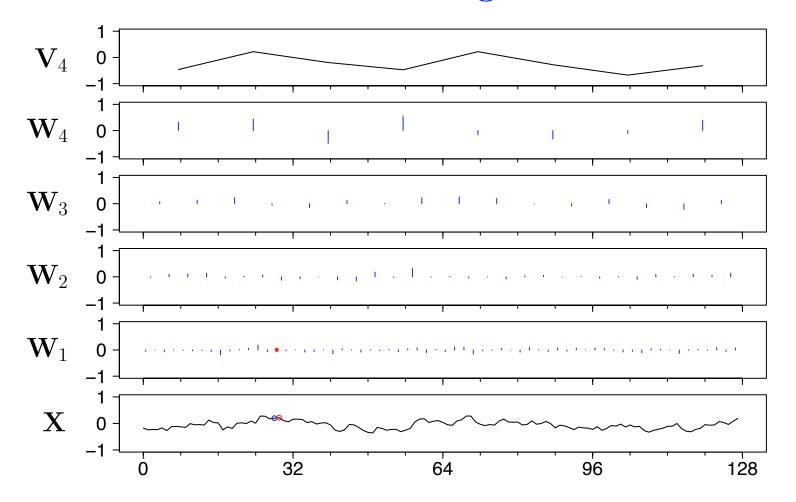
- DWT coefficient vector  $\mathbf{W}$  can be partitioned into  $J_0$  subvectors of wavelet coefficients  $\mathbf{W}_j$ ,  $j=1,2,\ldots,J_0$ , along with one sub-vector of scaling coefficients  $\mathbf{V}_{J_0}$
- wavelet coefficients in  $\mathbf{W}_j$  are associated with changes in averages over a scale of  $\tau_j$ , whereas the scaling coefficients in  $\mathbf{V}_{J_0}$  are associated with averages over a scale of  $2\tau_{J_0}$
- as a concrete example, let's look at a level  $J_0 = 4$  Haar DWT of the AR time series



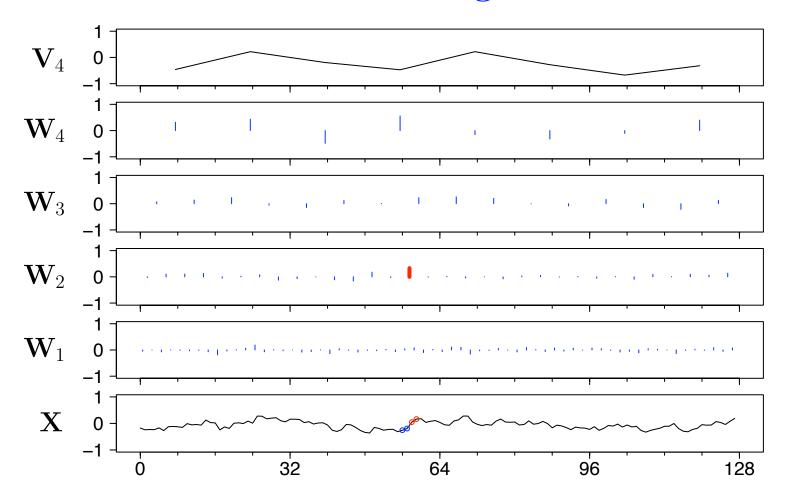
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ 



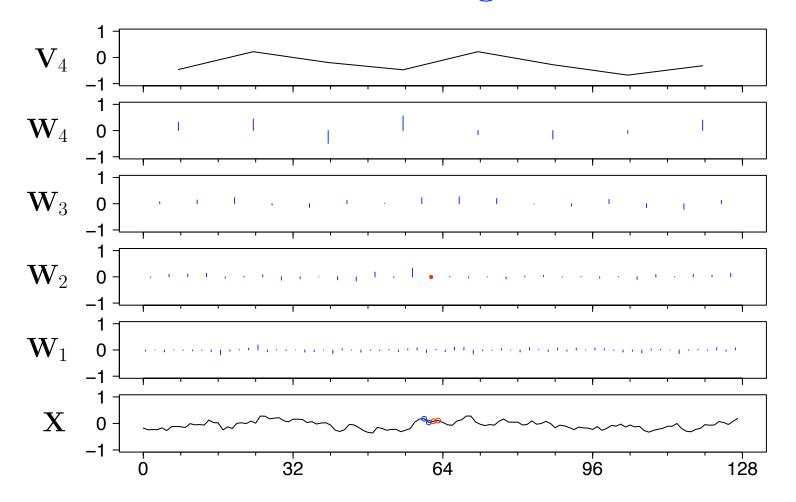
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_1 = 1$  wavelet coefficient highlighted



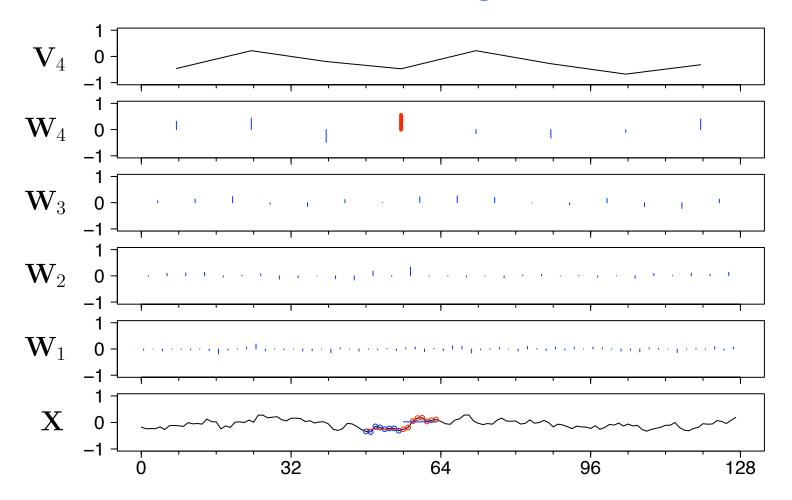
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_1 = 1$  wavelet coefficient highlighted



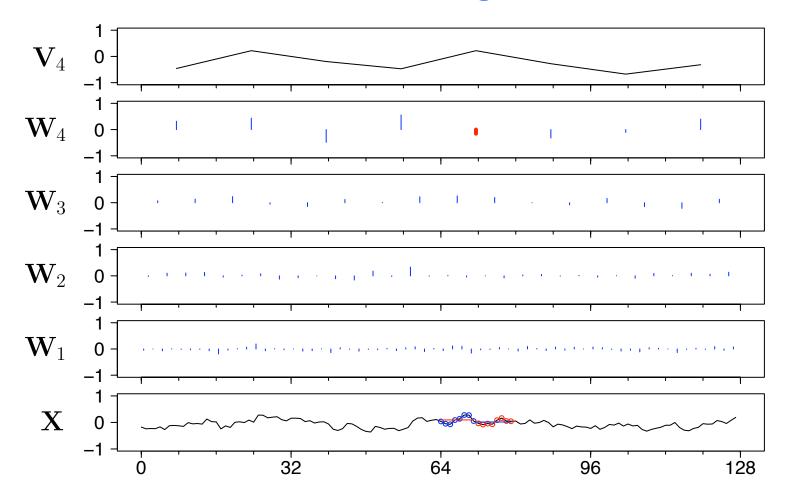
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_2 = 2$  wavelet coefficient highlighted



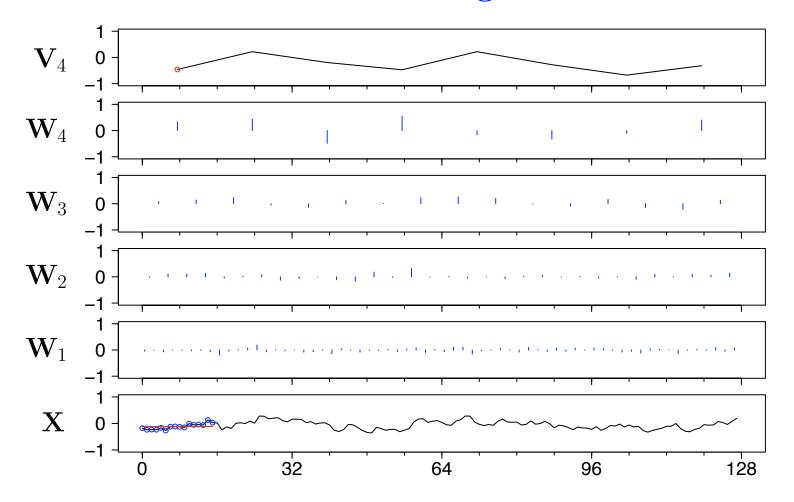
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_2 = 2$  wavelet coefficient highlighted

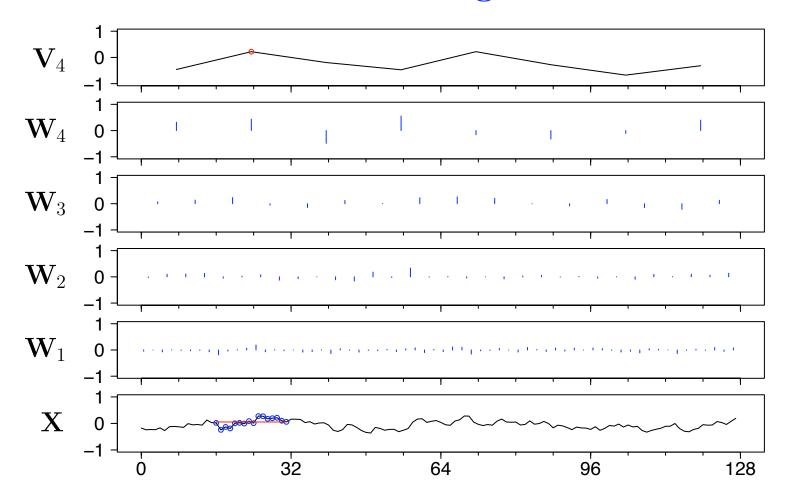


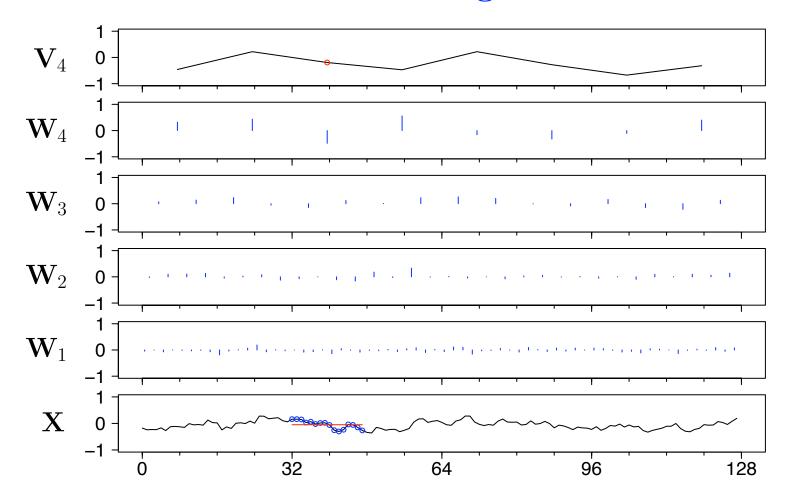
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_4 = 8$  wavelet coefficient highlighted

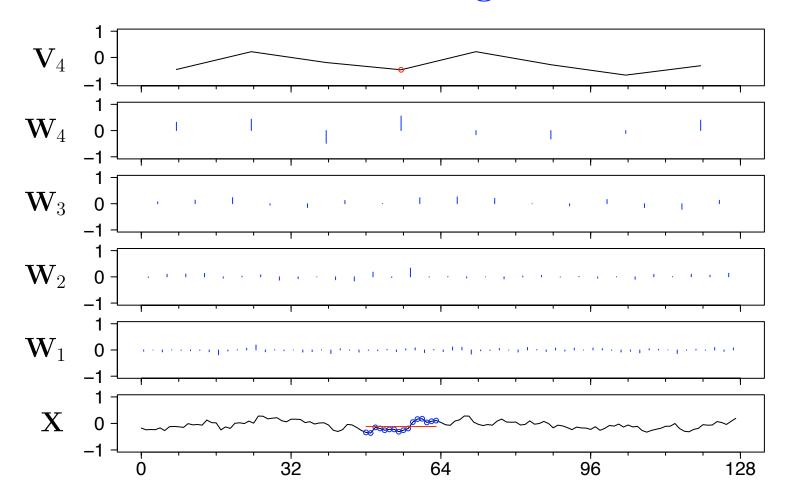


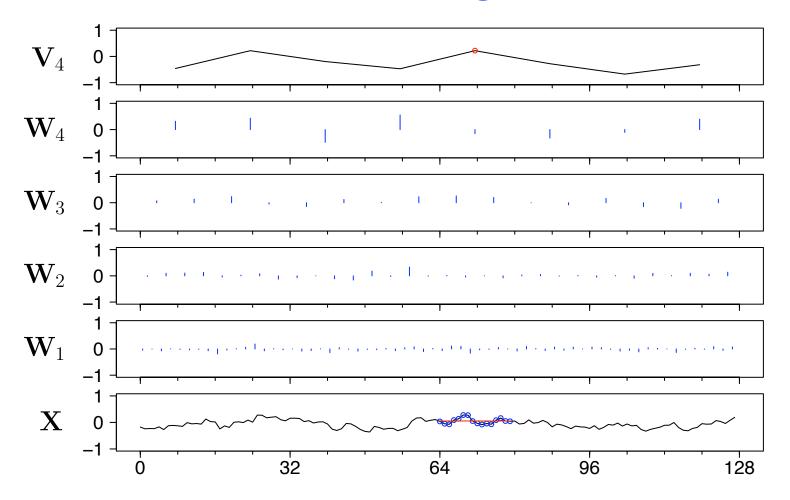
• level  $J_0 = 4$  Haar DWT of AR series  $\mathbf{X}$ , with scale  $\tau_4 = 8$  wavelet coefficient highlighted

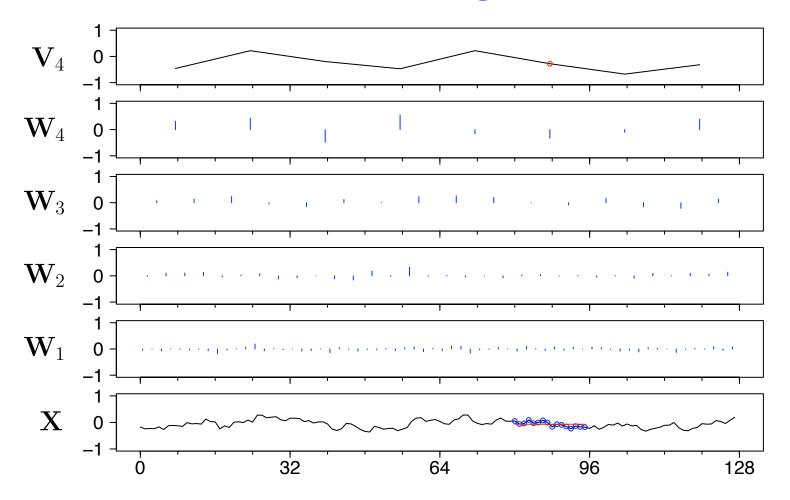


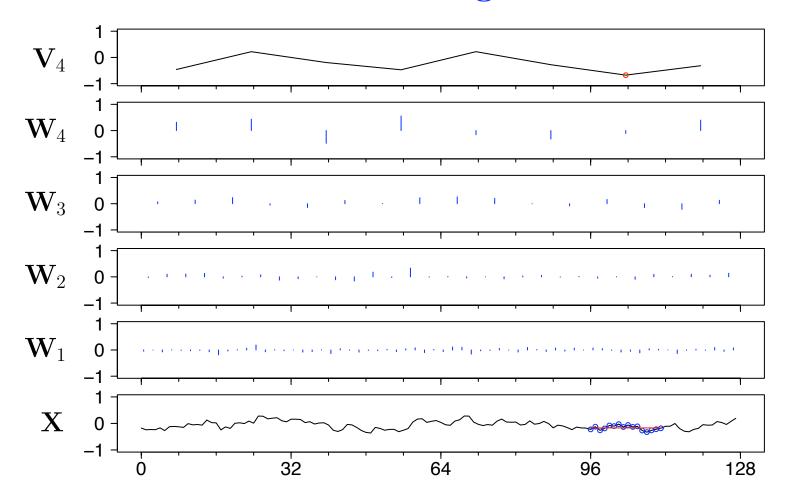


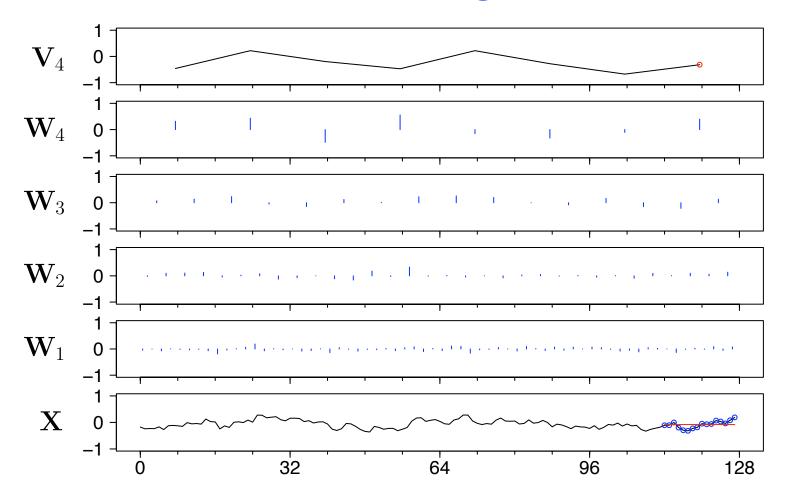


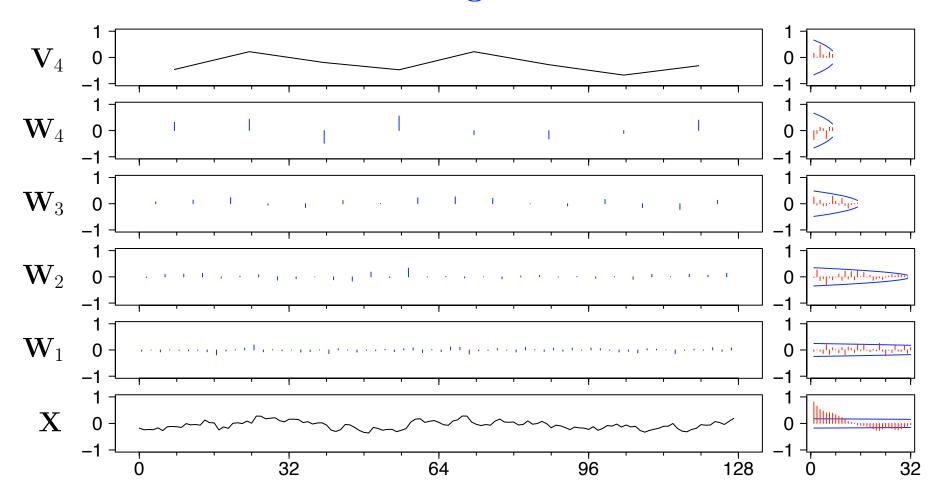






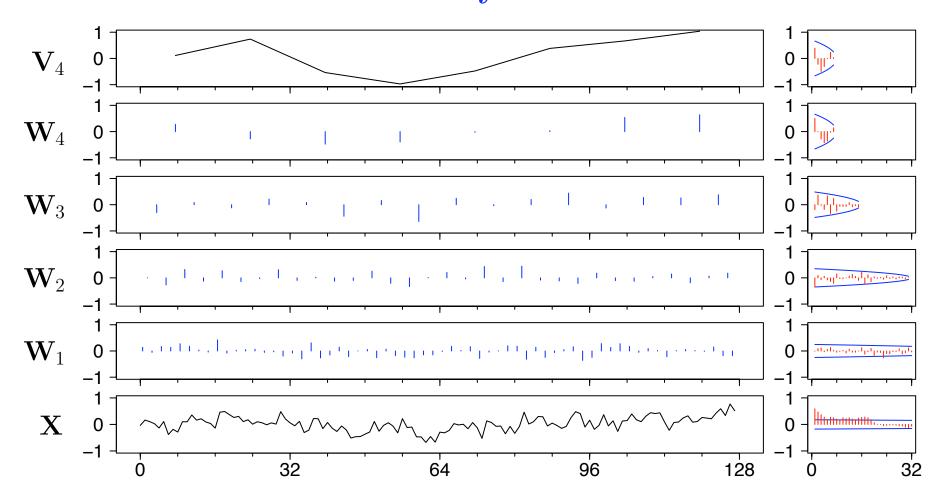






• Haar DWT of AR series  $\mathbf{X}$  and sample ACSs for each  $\mathbf{W}_j$  &  $\mathbf{V}_4$ , along with 95% confidence intervals for white noise

### DWT of Fractionally Differenced Process



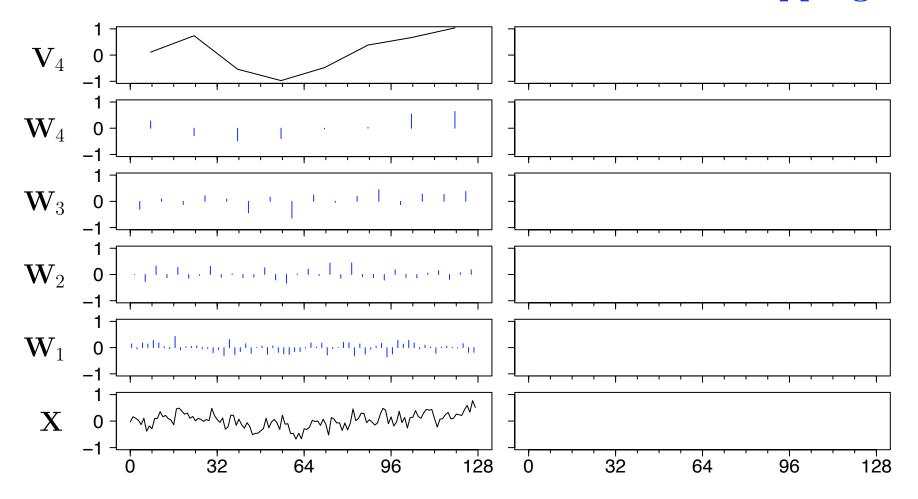
• Haar DWT of FD series  $\mathbf{X}$  and sample ACSs for each  $\mathbf{W}_j$  &  $\mathbf{V}_4$ , along with 95% confidence intervals for white noise

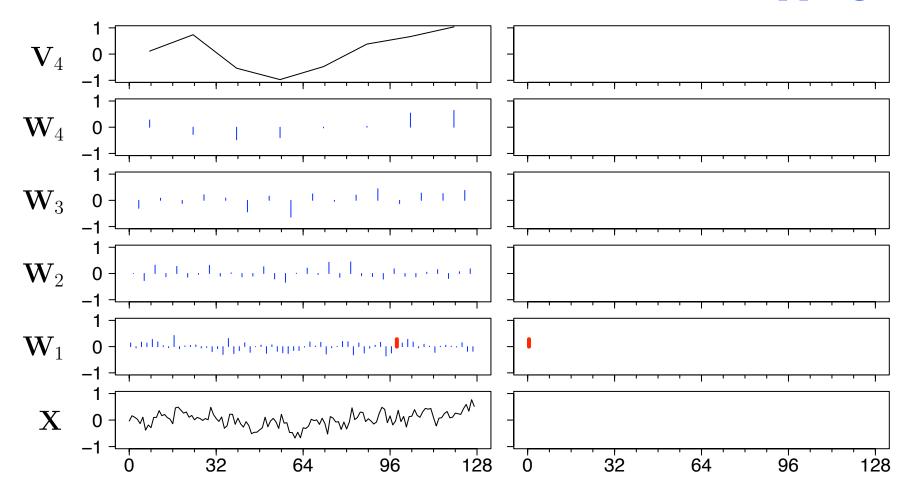
## DWT as a Decorrelating Transform

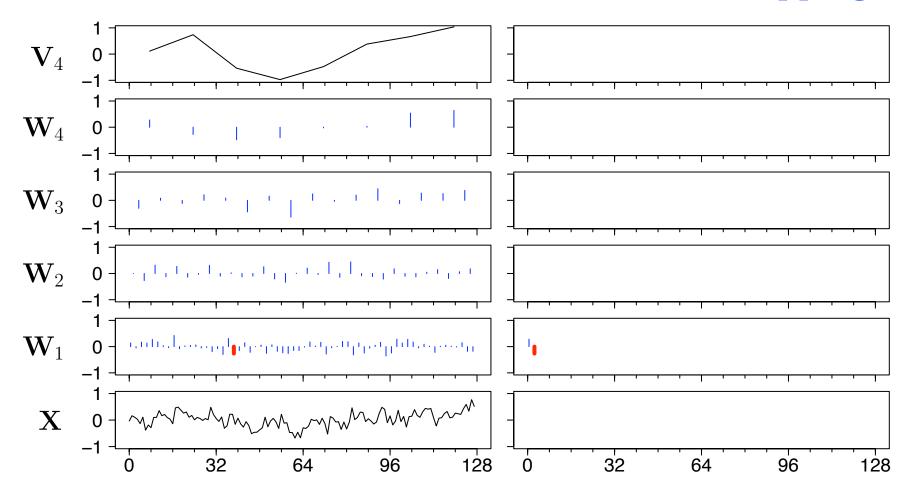
- for many (but not all!) time series, DWT acts as a decorrelating transform: to a good approximation, each  $\mathbf{W}_j$  is a sample of a white noise process, and coefficients from different sub-vectors  $\mathbf{W}_j$  and  $\mathbf{W}_{j'}$  are also pairwise uncorrelated
- variance of coefficients in  $\mathbf{W}_j$  depends on j
- scaling coefficients  $V_{J_0}$  are still autocorrelated, but there will be just a few of them if  $J_0$  is selected to be large
- decorrelating property holds particularly well for FD and other processes with long-range dependence
- above suggests the following recipe for wavelet-domain bootstrapping

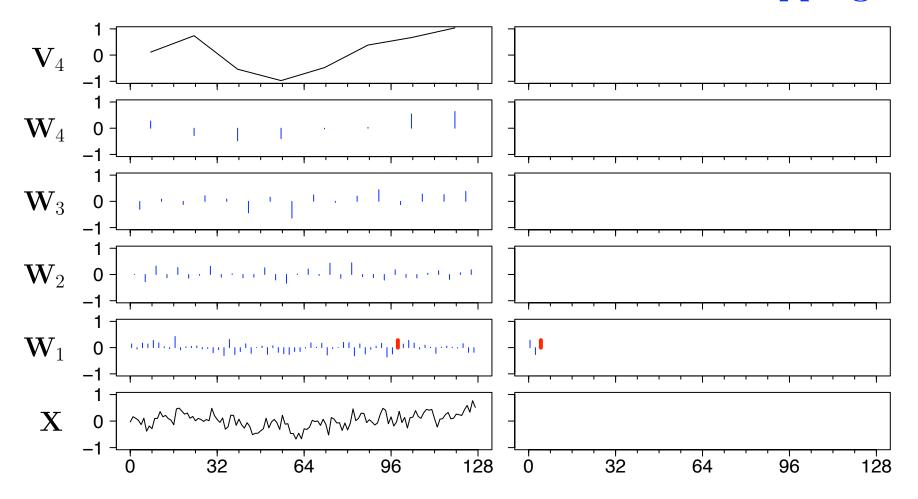
## Recipe for Wavelet-Domain Bootstrapping

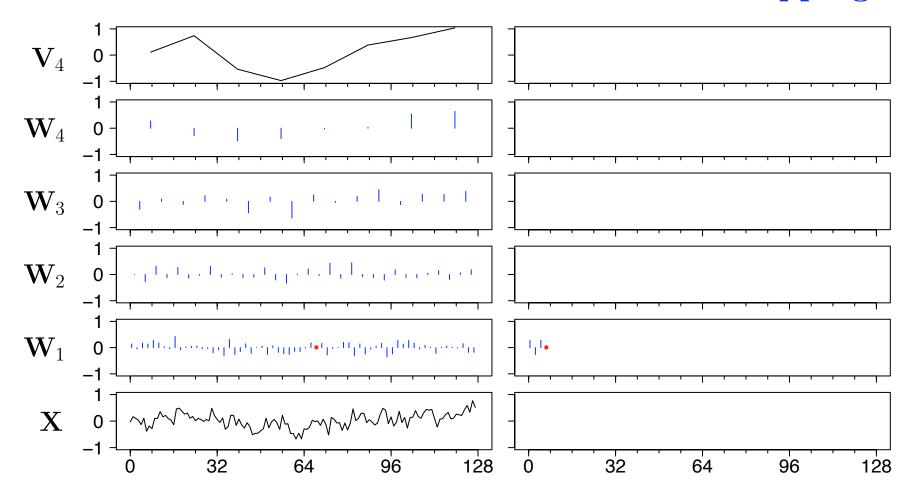
- 1. given **X** of length  $N = 2^J$ , compute level  $J_0$  DWT (the choice  $J_0 = J 3$  yields 8 coefficients in  $\mathbf{W}_{J_0}$  and  $\mathbf{V}_{J_0}$ )
- 2. randomly sample with replacement from  $\mathbf{W}_j$  to create bootstrapped vector  $\mathbf{W}_j^{(b)}$ ,  $j=1,\ldots,J_0$
- 3. create  $\mathbf{V}_{J_0}^{(b)}$  using a parametric bootstrap
- 4. apply  $\mathcal{W}^T$  to  $\mathbf{W}_1^{(b)}, \dots, \mathbf{W}_{J_0}^{(b)}$  and  $\mathbf{V}_{J_0}^{(b)}$  to obtain bootstrapped time series  $\mathbf{X}^{(b)}$  and then form corresponding  $\hat{\rho}_1^{(b)}$
- repeat above many times to build up sample distribution of bootstrapped autocorrelations

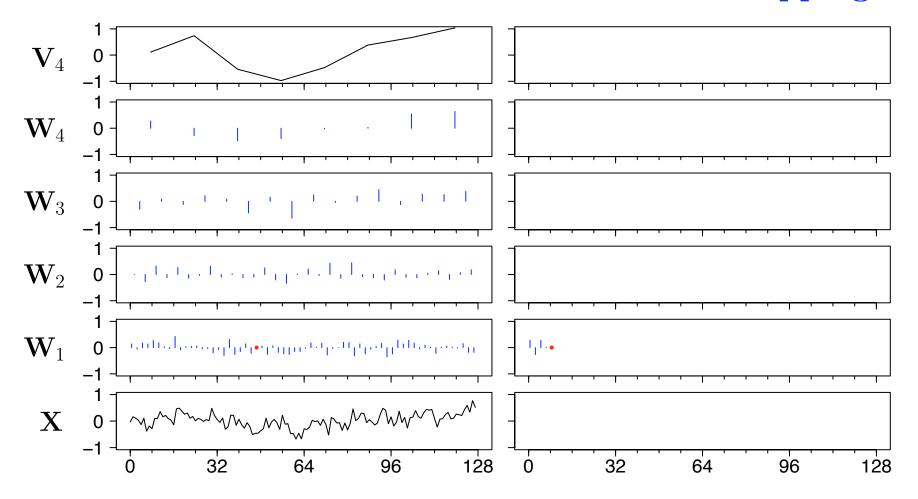


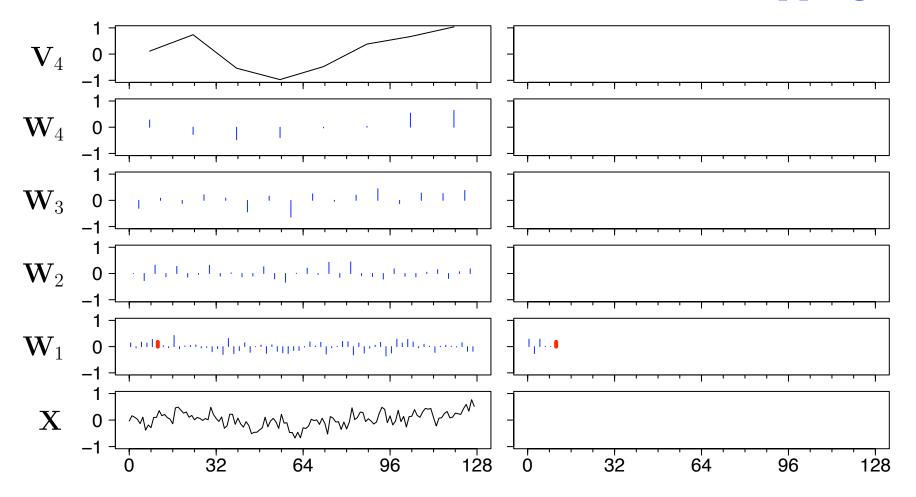


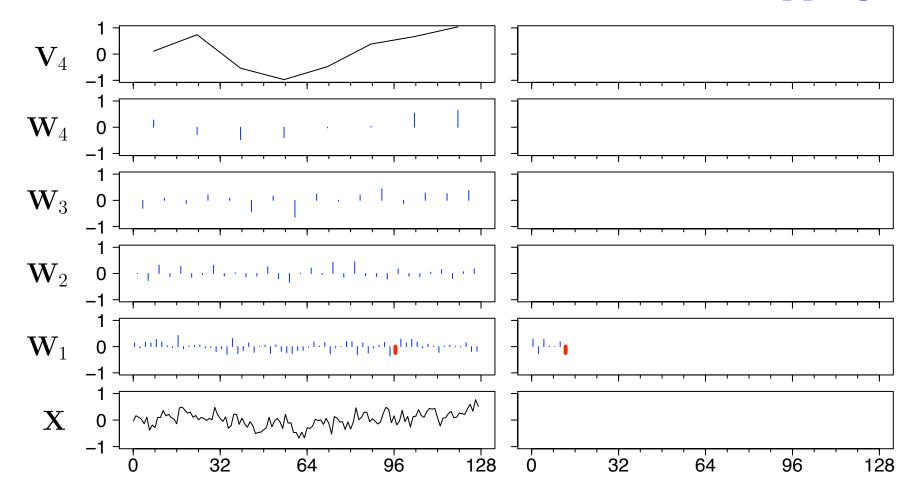


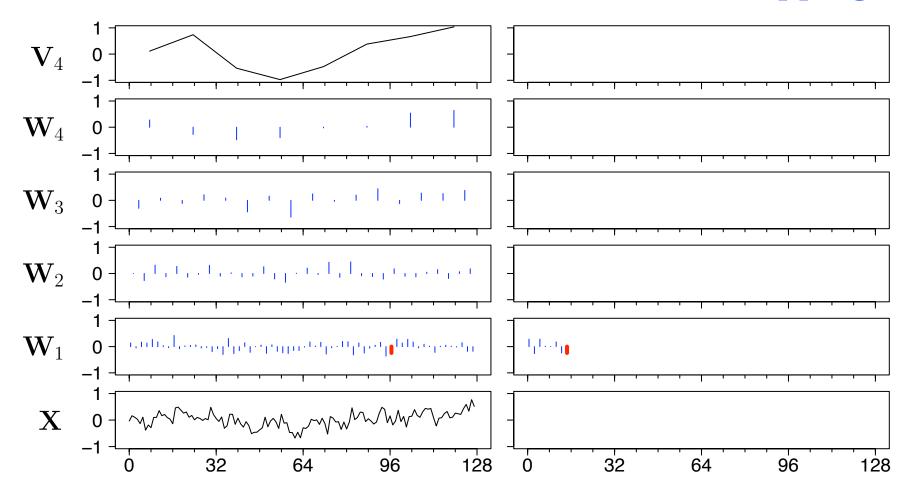


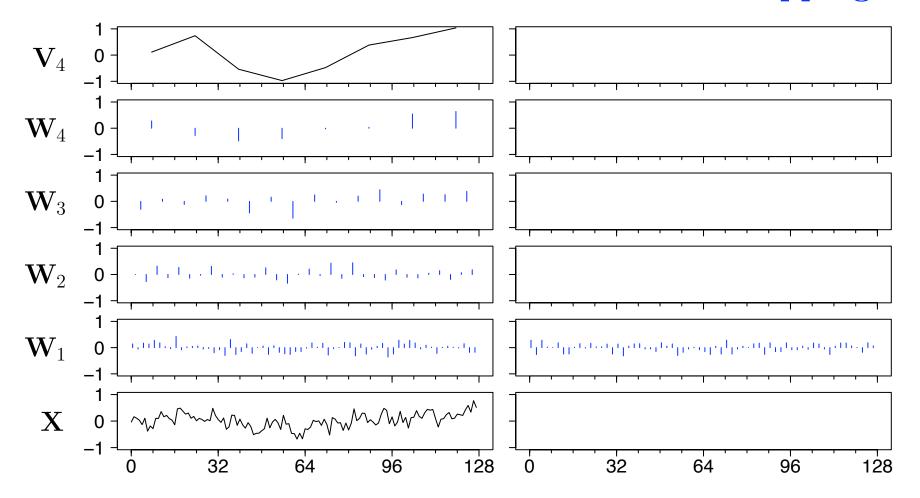


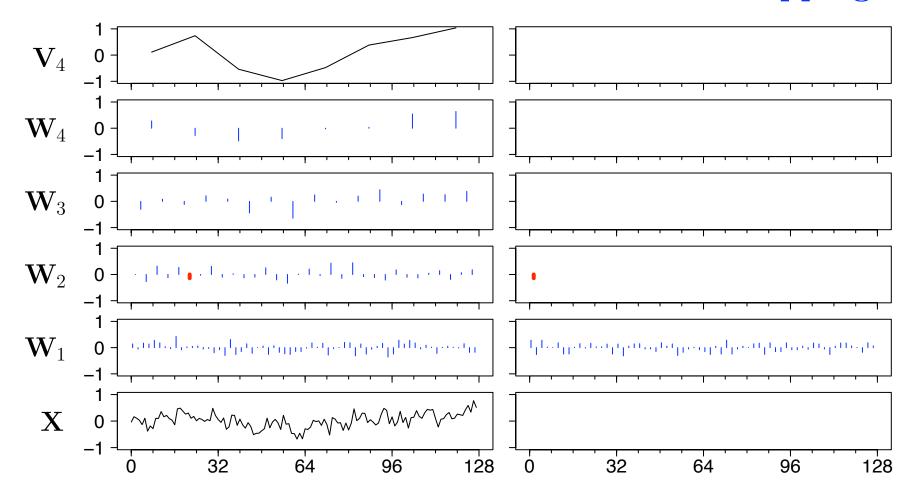


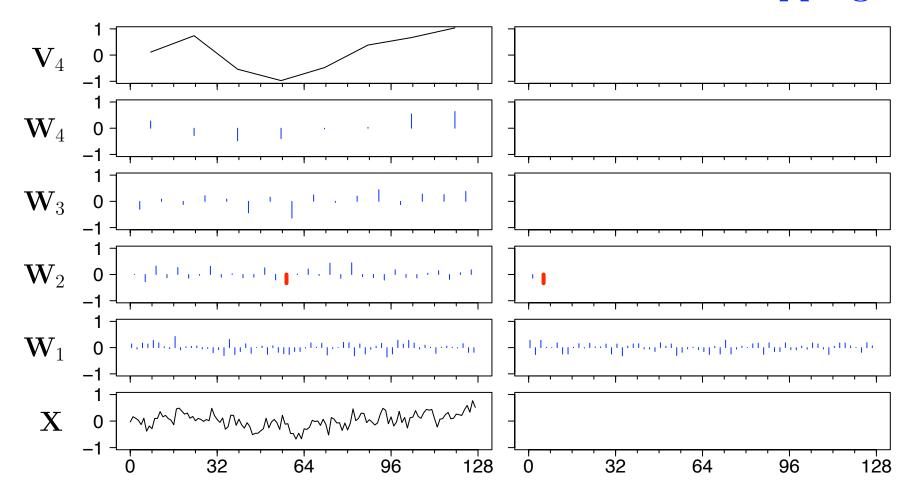


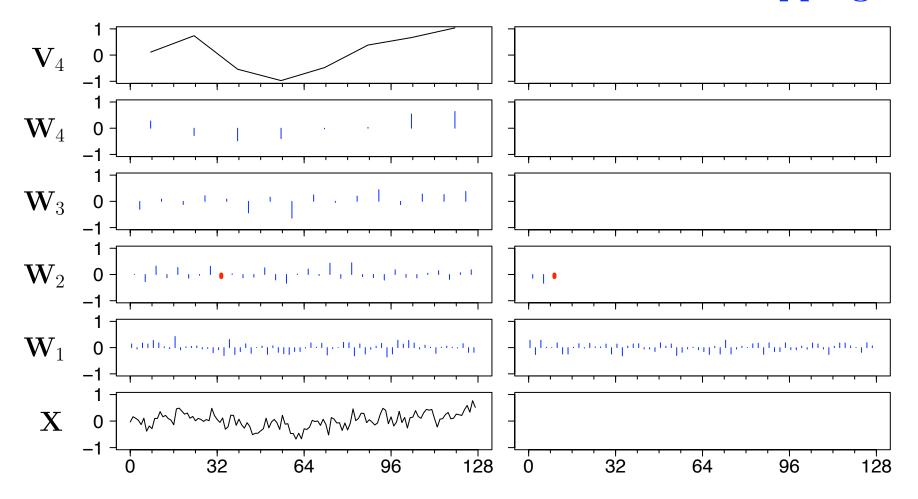


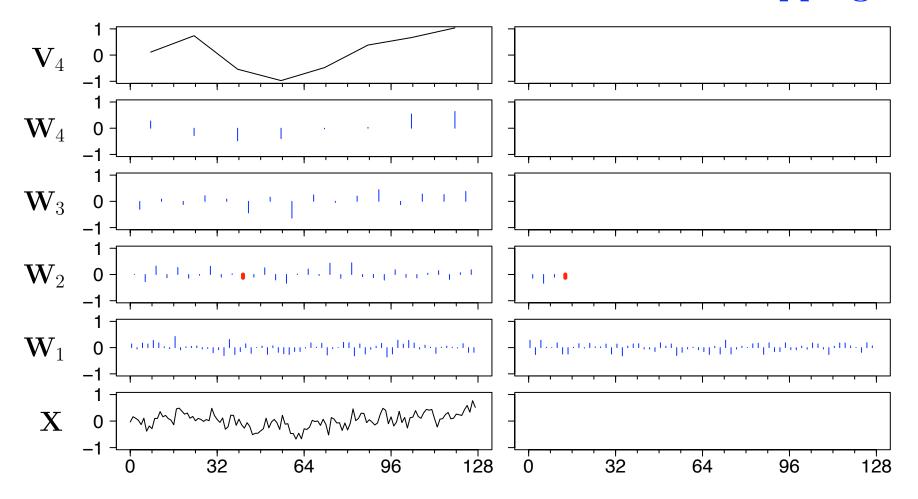


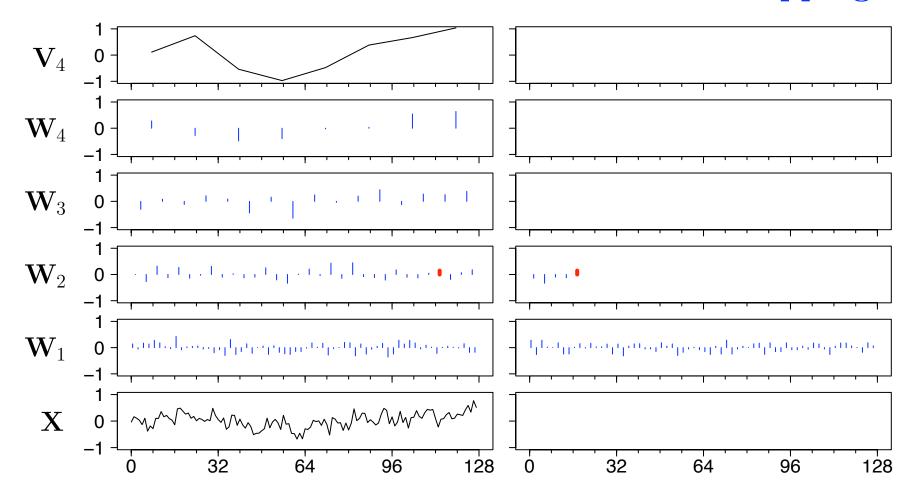


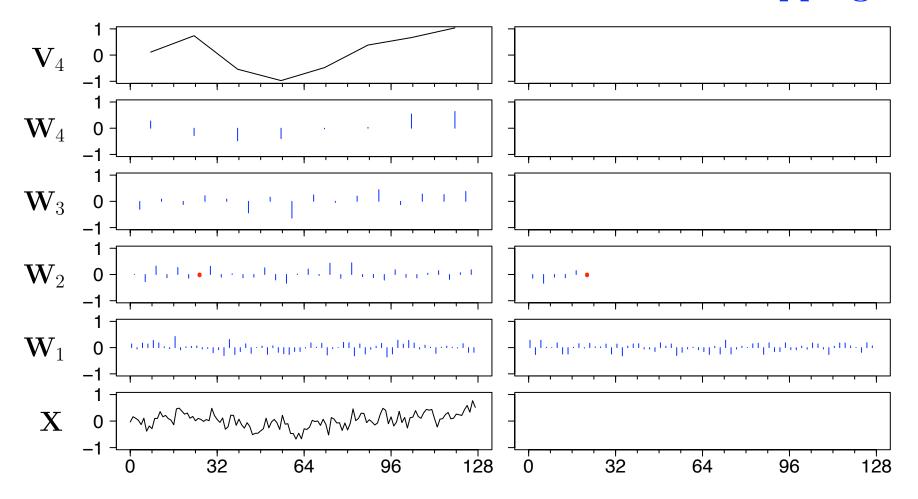


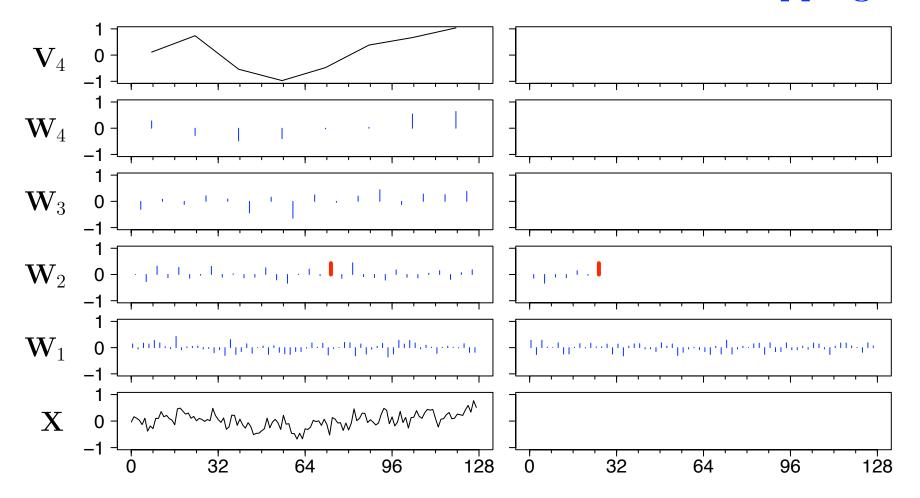


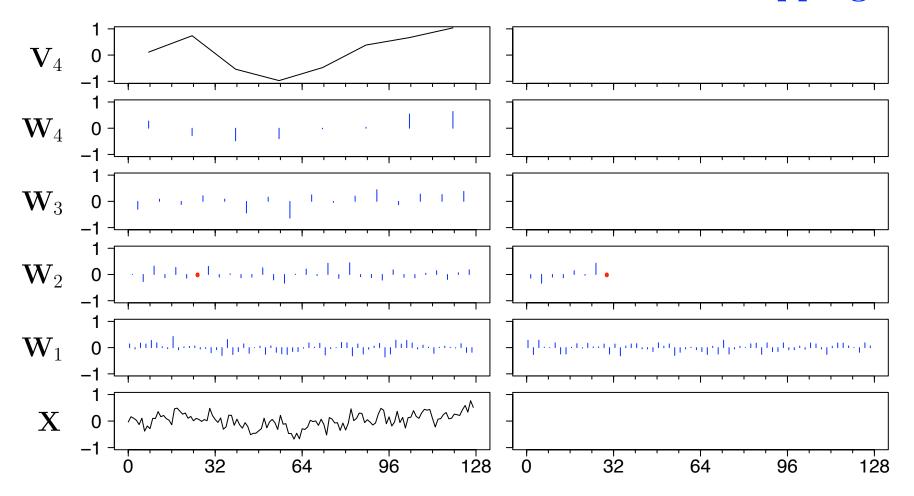


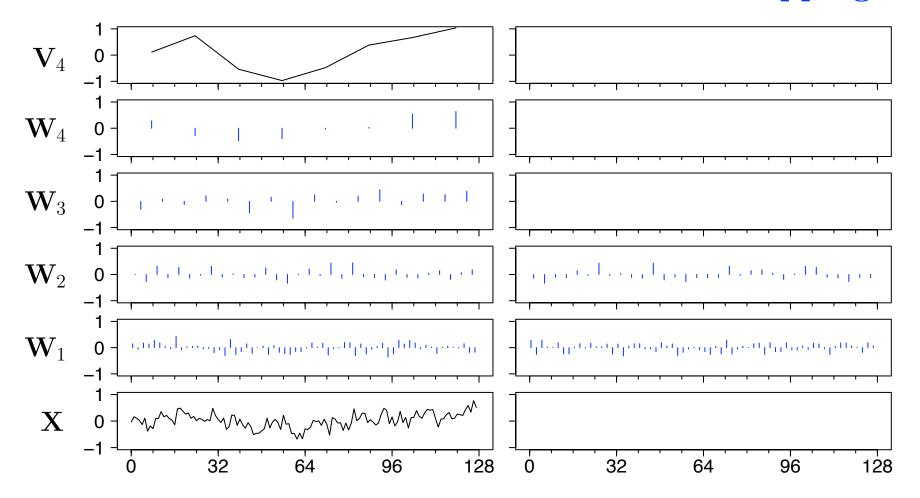


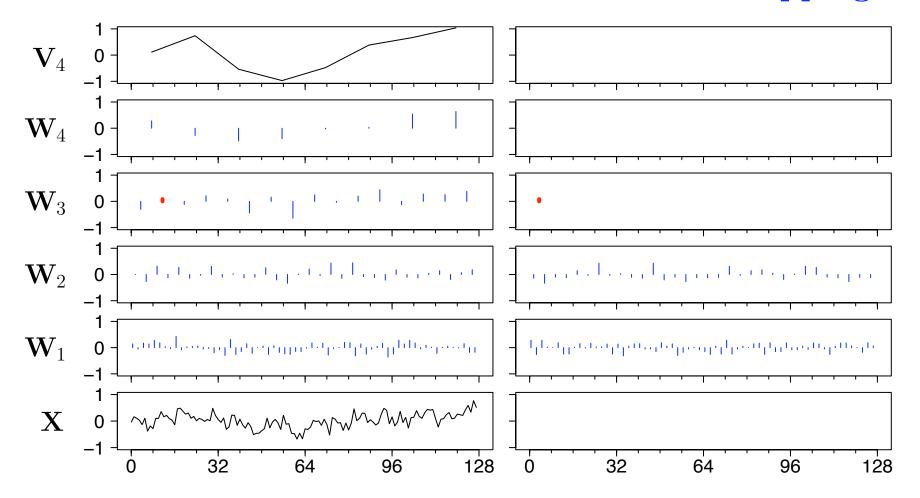


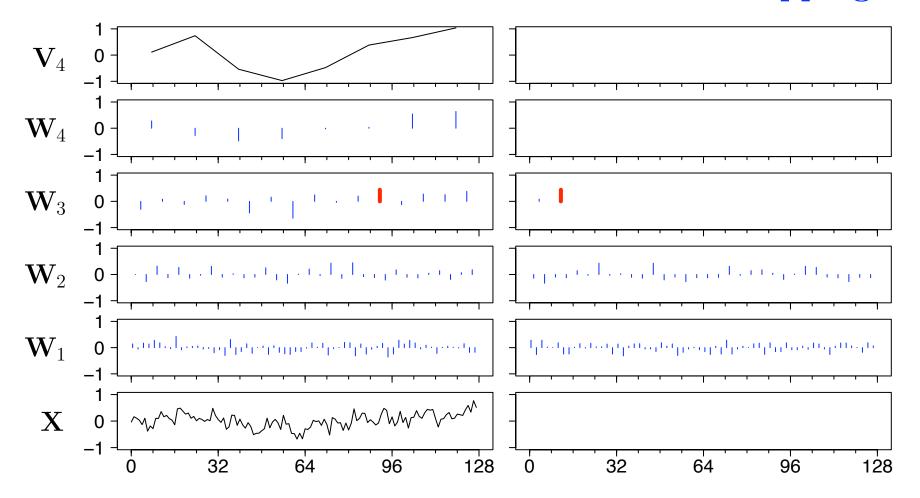


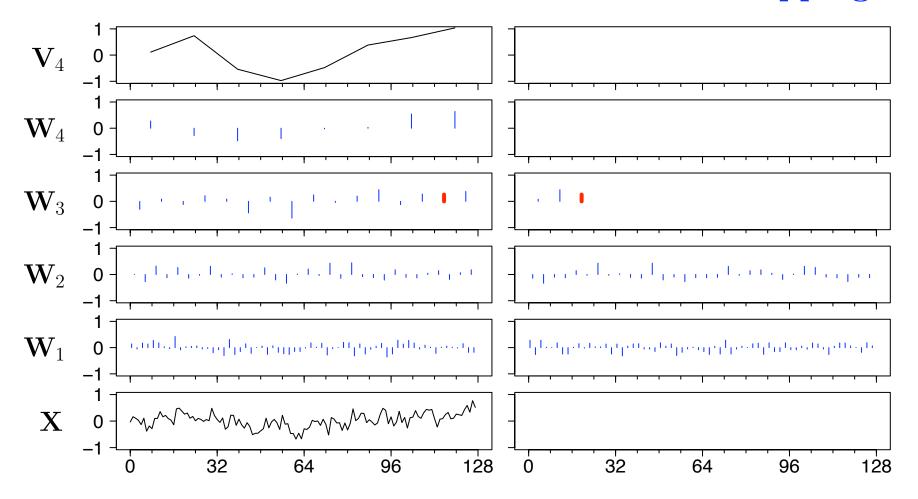


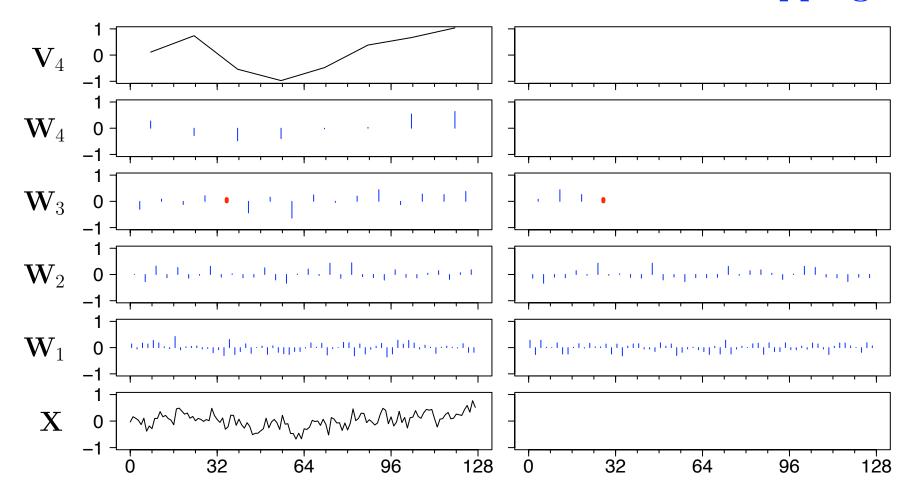


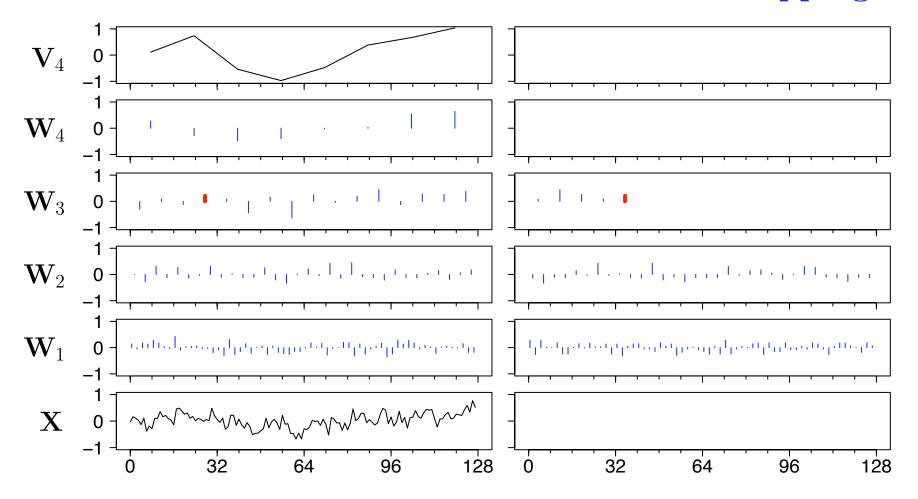


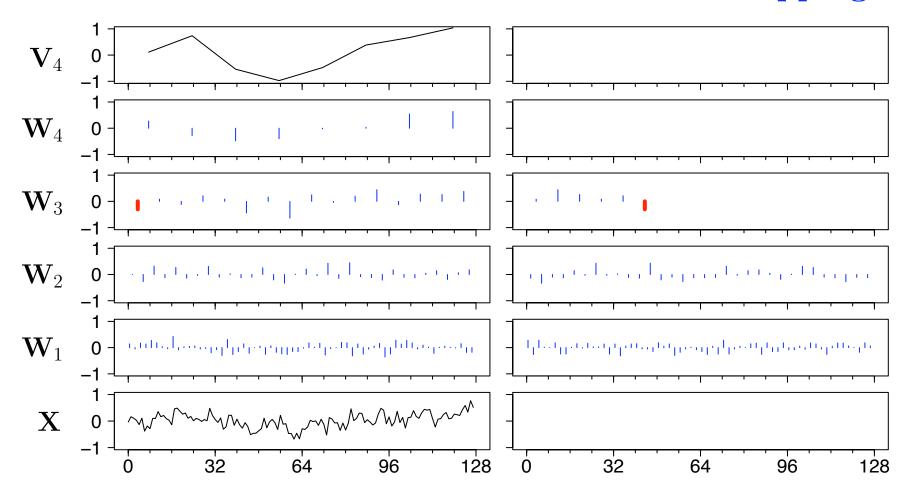


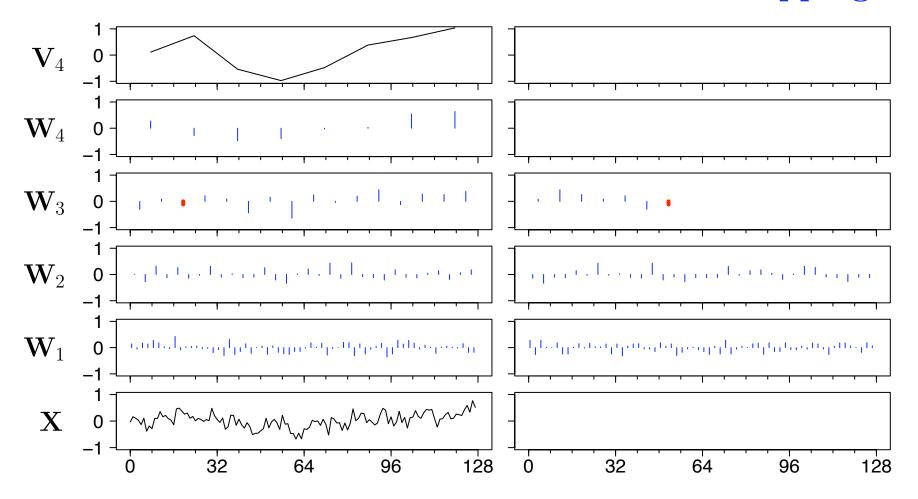


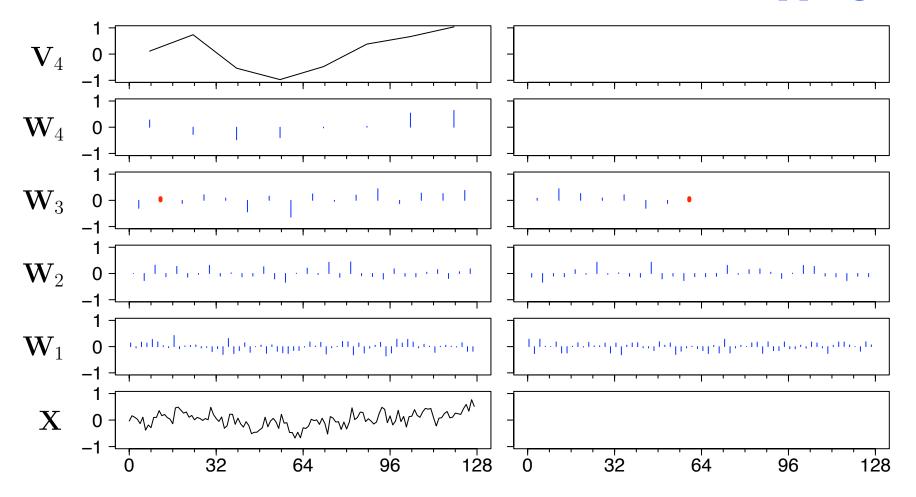


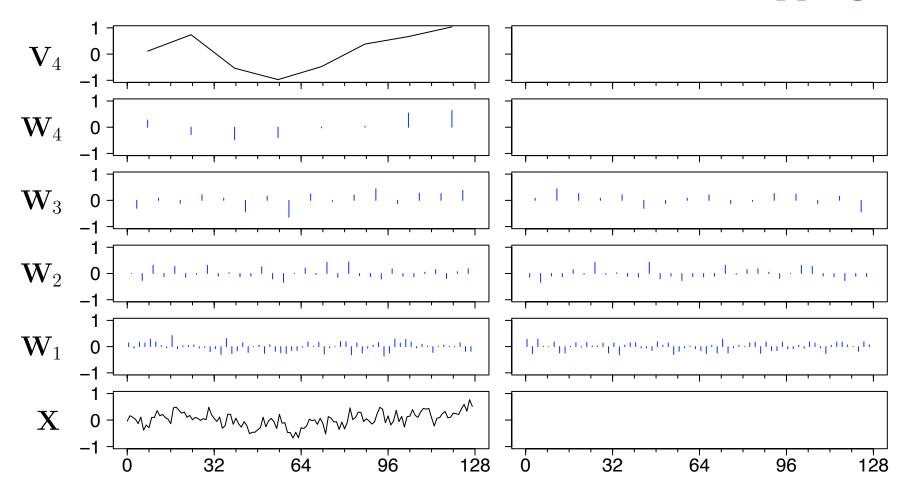


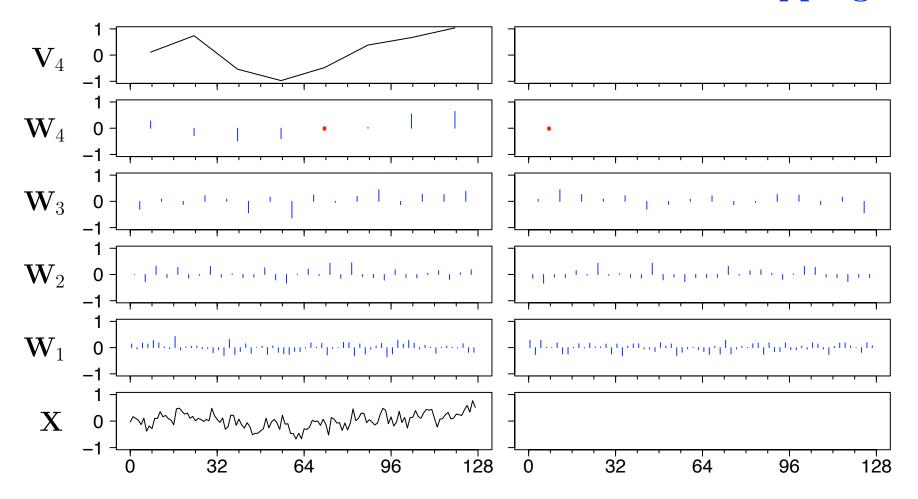


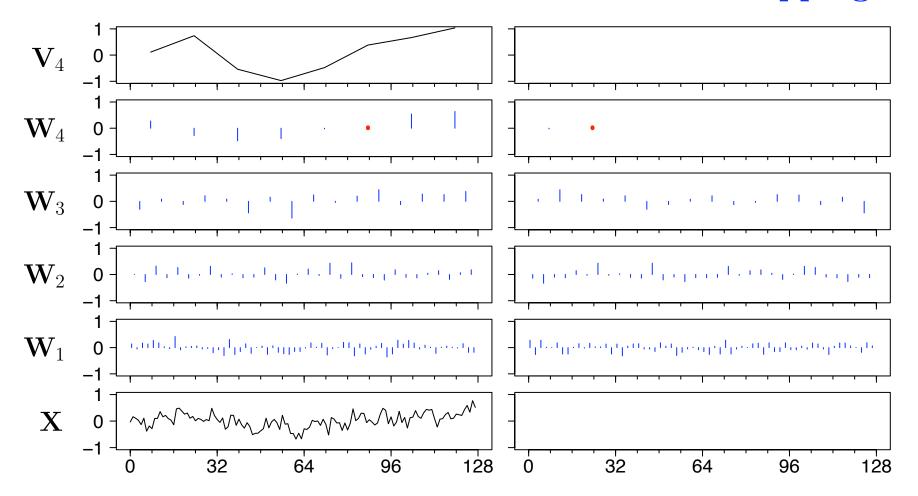


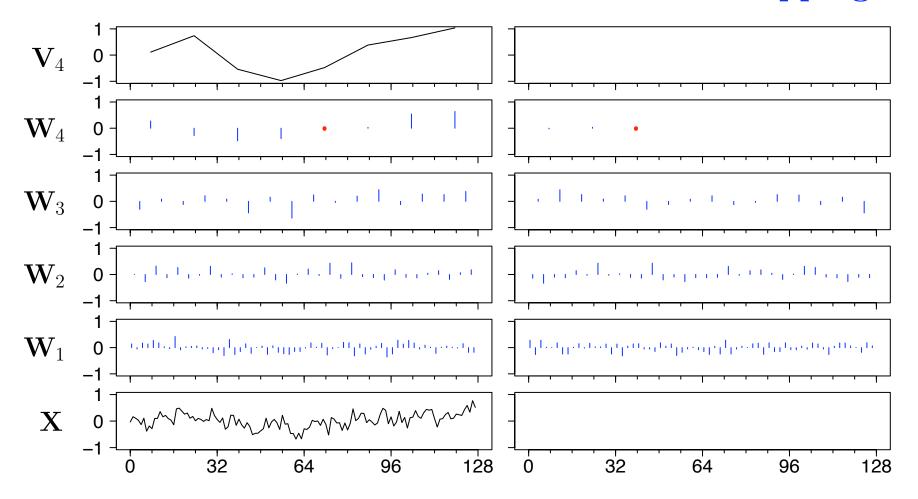


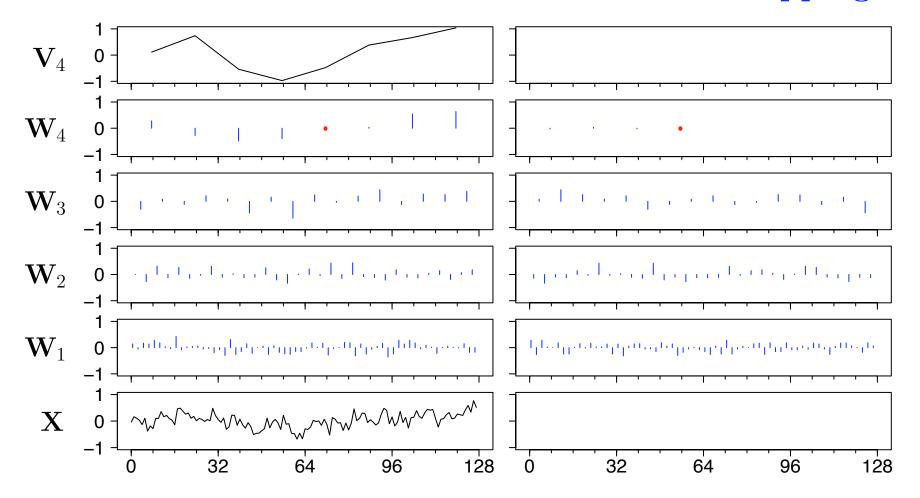


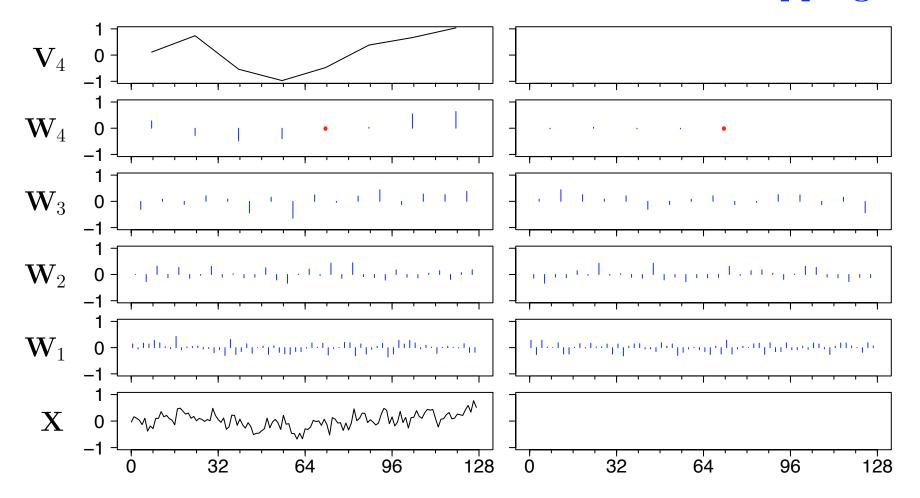


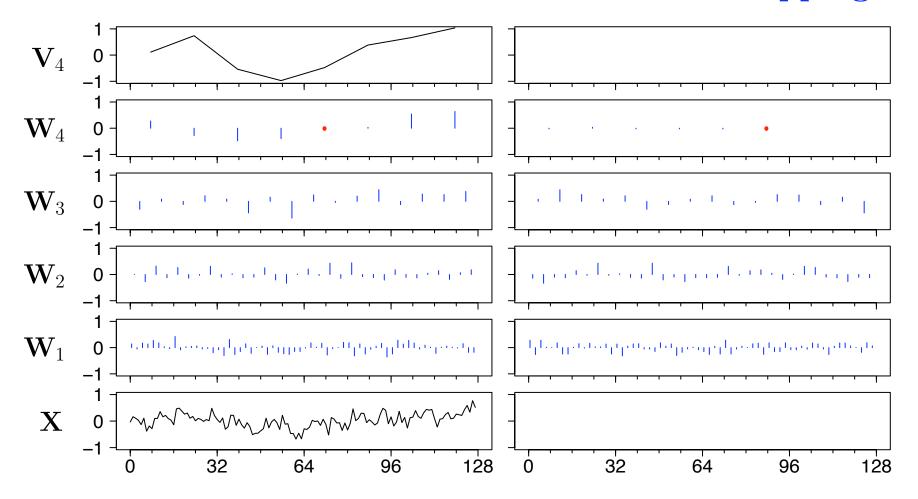


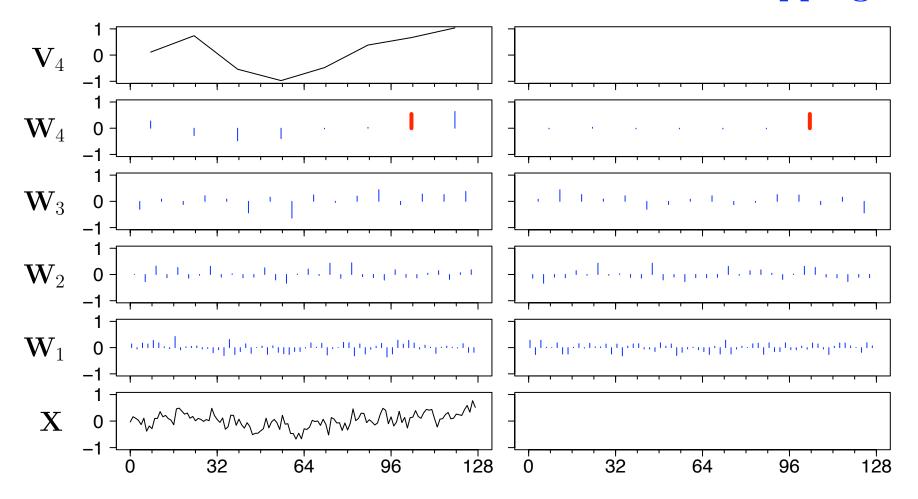


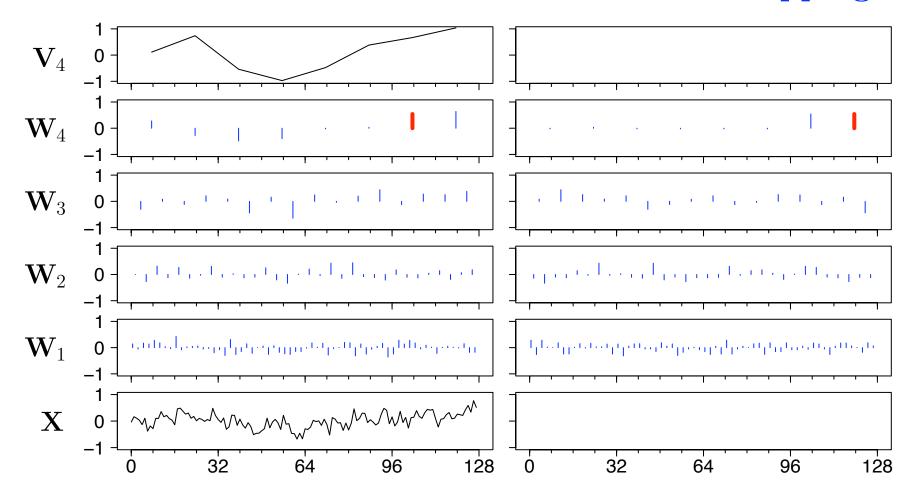


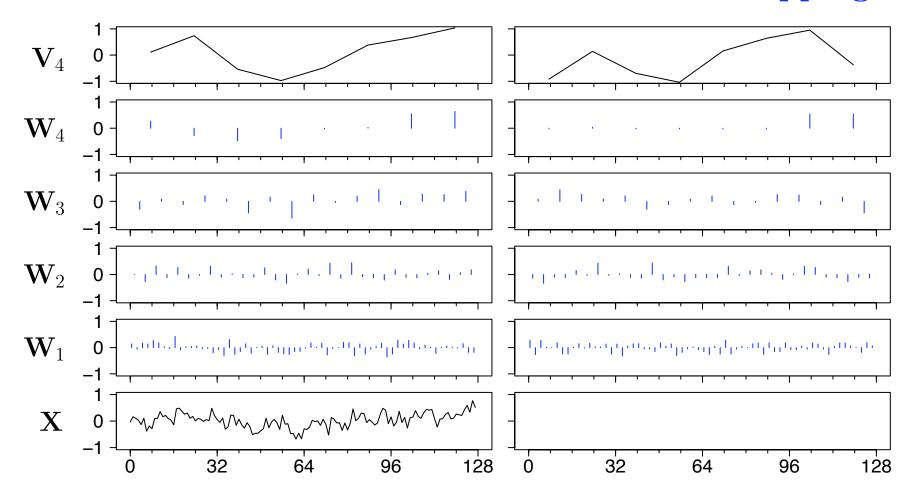


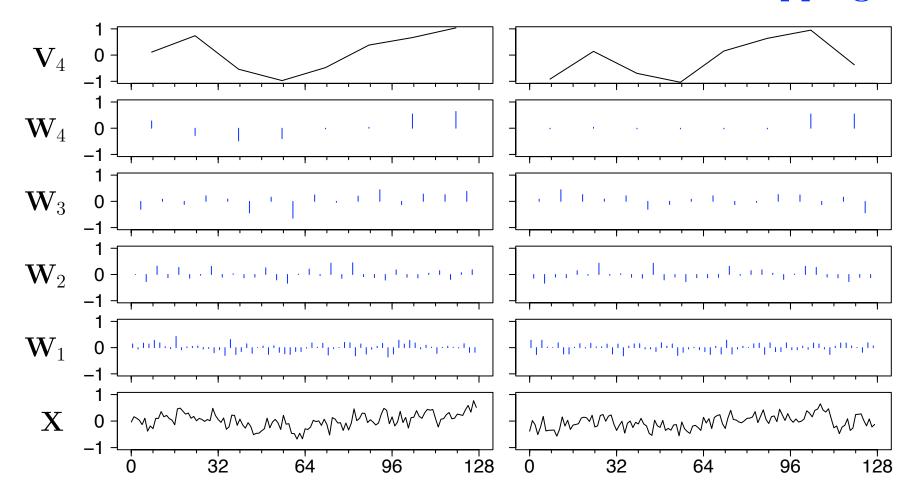






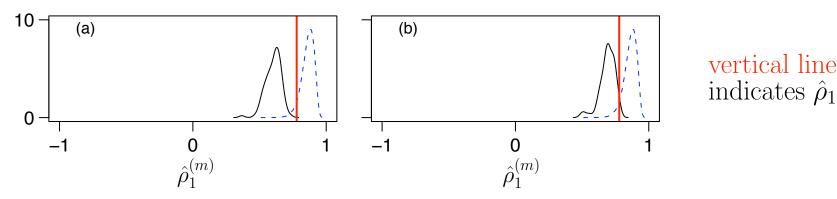






#### Wavelet-Domain Bootstrapping of AR Series

• approximations to true PDF using (a) Haar & (b) LA(8) wavelets



• using 50 AR time series and the Haar DWT yields:

average of 50 sample means 
$$\doteq 0.67$$
 (truth  $\doteq 0.86$ )  
average of 50 sample SDs  $\doteq 0.071$  (truth  $\doteq 0.048$ )

• using 50 AR time series and the LA(8) DWT yields:

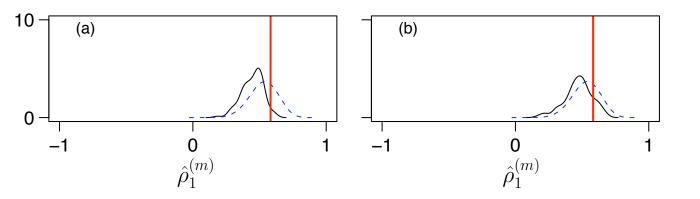
average of 50 sample means 
$$\doteq 0.80$$
 (truth  $\doteq 0.86$ )  
average of 50 sample SDs  $\doteq 0.055$  (truth  $\doteq 0.048$ )

## Wavelet-Domain Bootstrapping of FD Series

• approximations to true PDF using (a) Haar & (b) LA(8) wavelets

vertical line

indicates  $\hat{\rho}_1$ 



• using 50 FD time series and the Haar DWT yields:

average of 50 sample means 
$$\doteq 0.35$$
 (truth  $\doteq 0.53$ )  
average of 50 sample SDs  $\doteq 0.096$  (truth  $\doteq 0.107$ )

• using 50 FD time series and the LA(8) DWT yields:

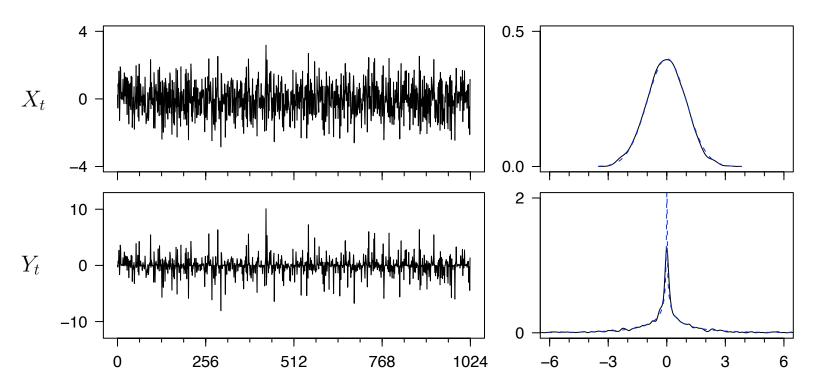
average of 50 sample means 
$$\doteq 0.43$$
 (truth  $\doteq 0.53$ )  
average of 50 sample SDs  $\doteq 0.098$  (truth  $\doteq 0.107$ )

# Effect of Non-Gaussianity: I

- wavelet-domain bootstrapping works well if we can assume Gaussianity, but can be problematic if this assumption fails
- for non-Gaussian series, wavelet-domain bootstraps are typically closer to Gaussianity than original series, which poses a problem for assessing variability in certain statistics

# Effect of Non-Gaussianity: II

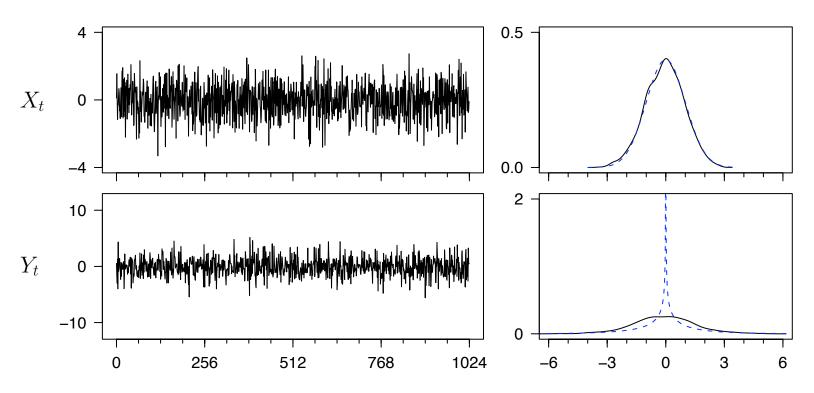
• consider Gaussian white noise  $X_t$  and  $Y_t = \text{sign}\{X_t\} \times X_t^2$ :



• right-hand plots show estimated PDFs and true PDFs

#### Effect of Non-Gaussianity: III

• wavelet-domain bootstraps of  $X_t$  and  $Y_t = \text{sign}\{X_t\} \times X_t^2$ :

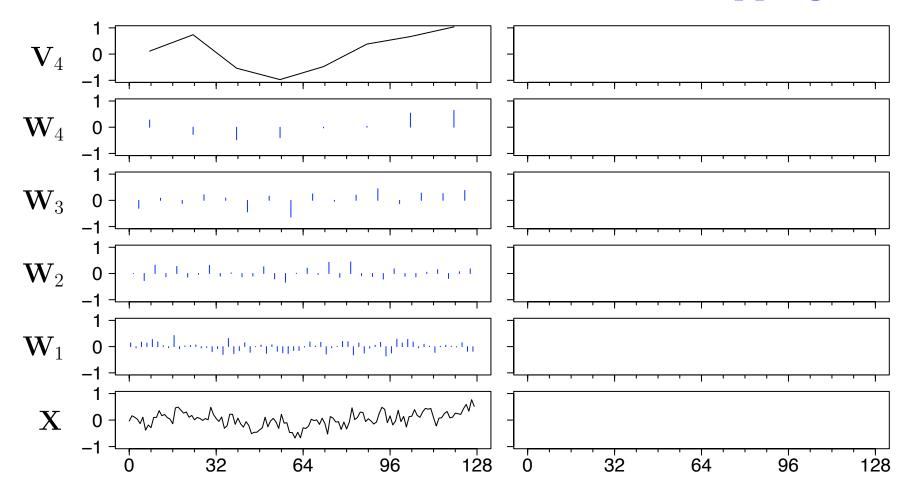


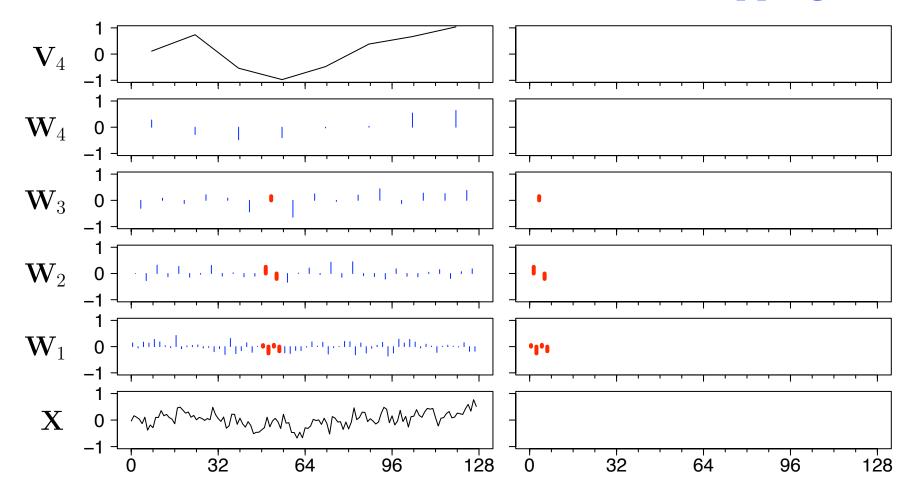
• right-hand plots show estimated PDFs and true original PDFs

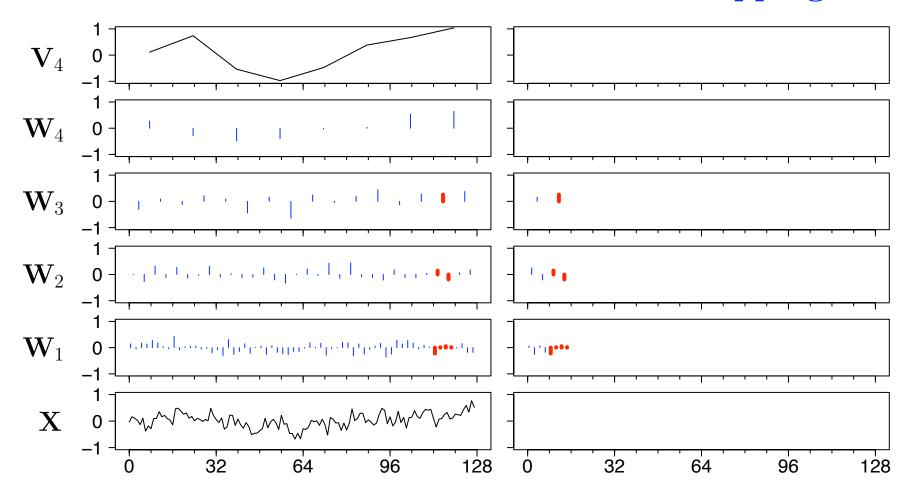
## Tree-Based Bootstrapping

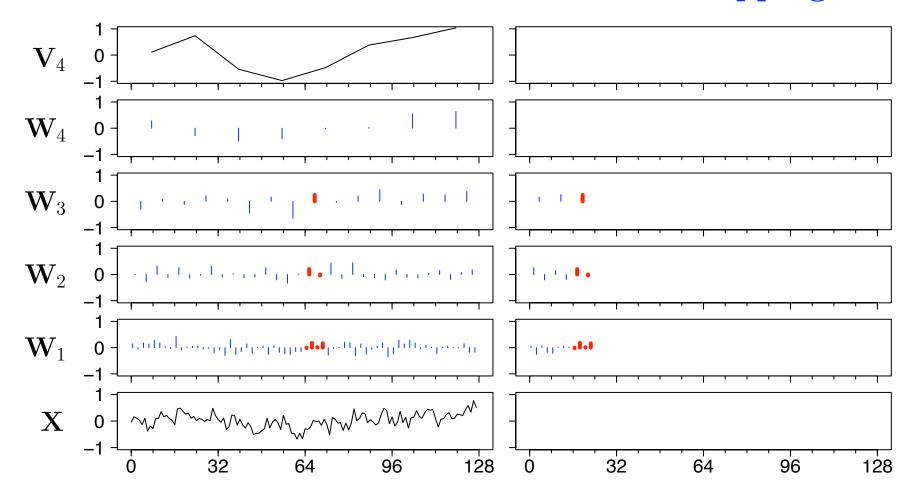
- to preserve non-Gaussianity, consider using groups ('trees') of wavelet coefficients co-located across small scales as basic sampling unit for bootstrapping at those scales
- wavelet coefficients at large scales treated in same way as in usual wavelet-domain bootstrap
- scaling coefficients handled using parametric bootstrap
- certain wavelet-based signal denoising schemes for non-Gaussian noise treat small scales in a special way and large scales in the same way as in the Gaussian case (see, e.g., Gao, 1997)
- tree-based structuring of wavelet coefficients is key idea behind denoising using Markov models (Crouse *et al.*, 1998) and notion of wavelet 'footprints' (Dragotti and Vetterli, 2003)

#### Illustration of Tree-Based Bootstrapping

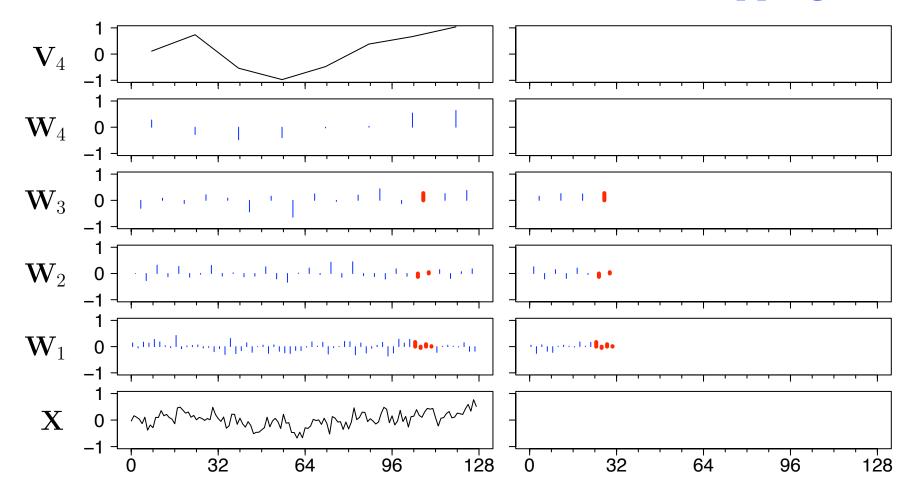


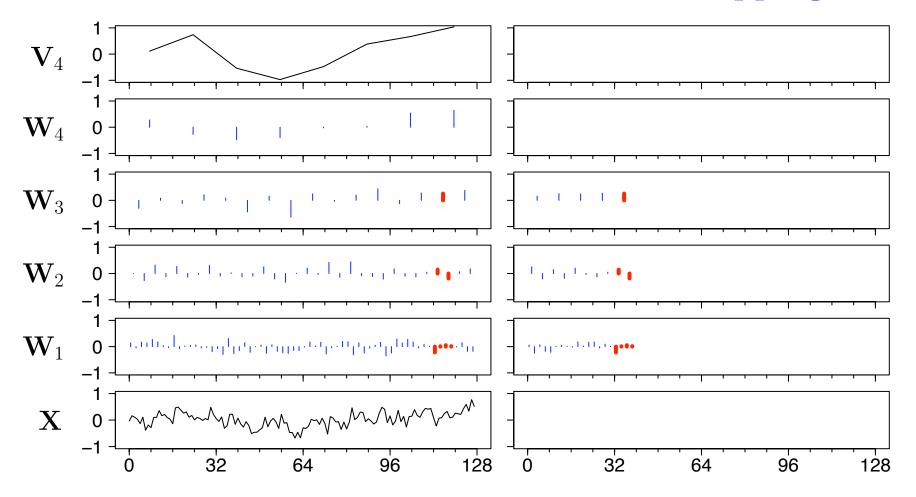


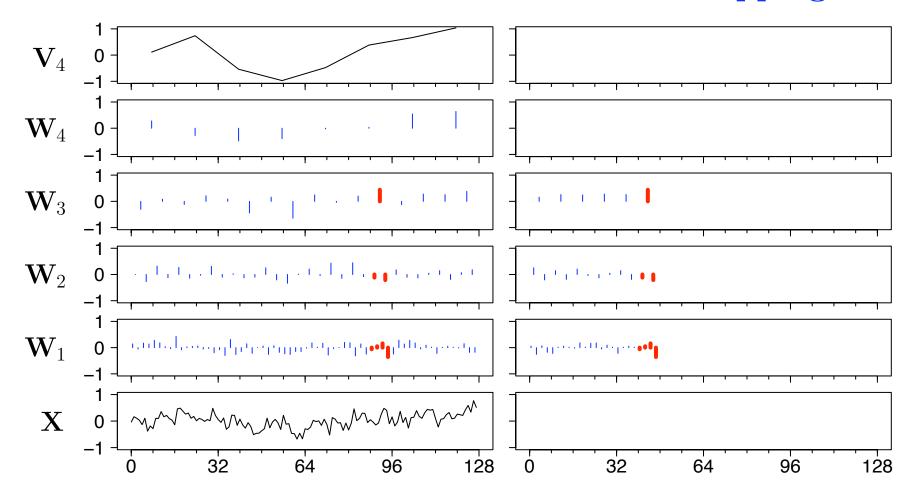


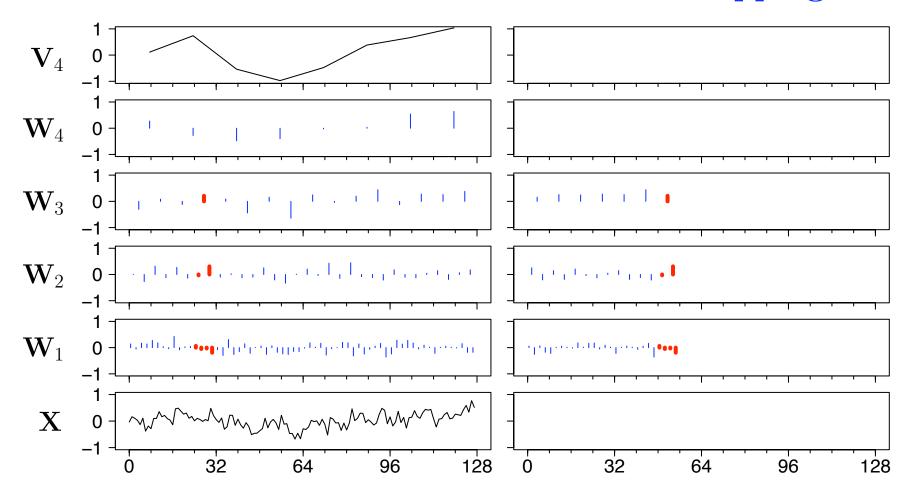


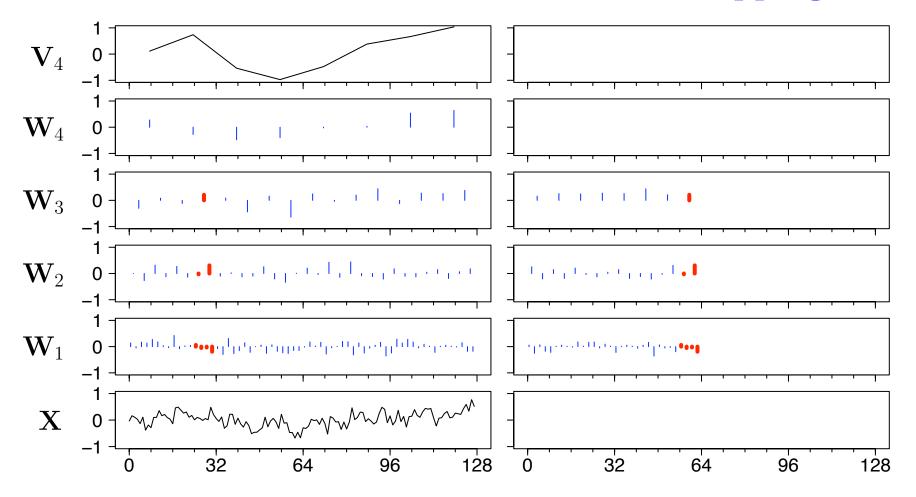
• Haar DWT of FD(0.45) series  $\mathbf{X}$  (left-hand column) and level j=3 tree-based bootstrap thereof (right-hand)

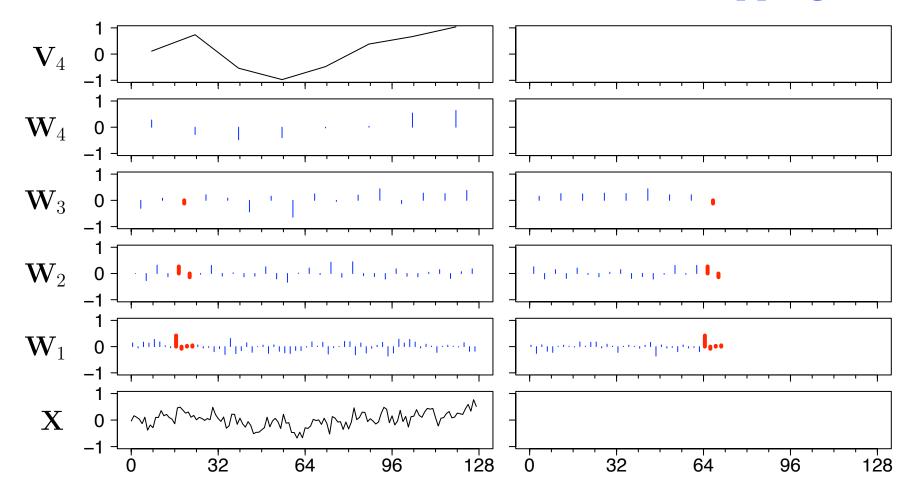


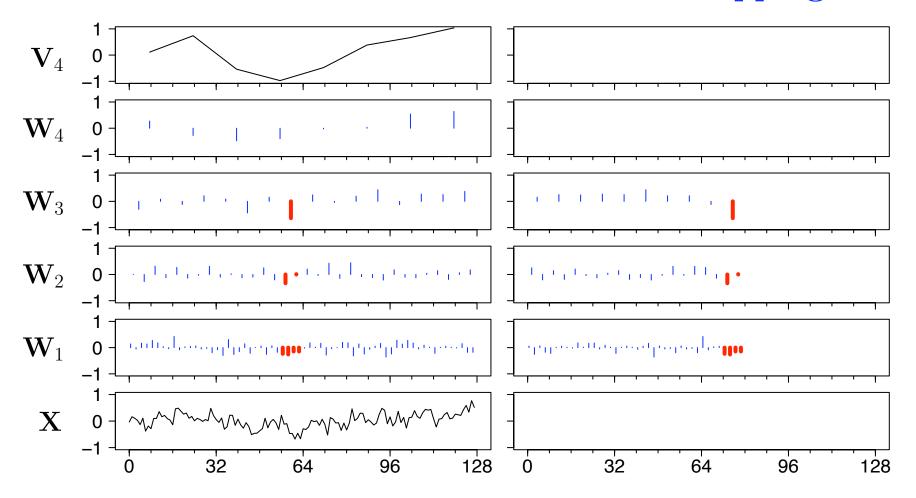


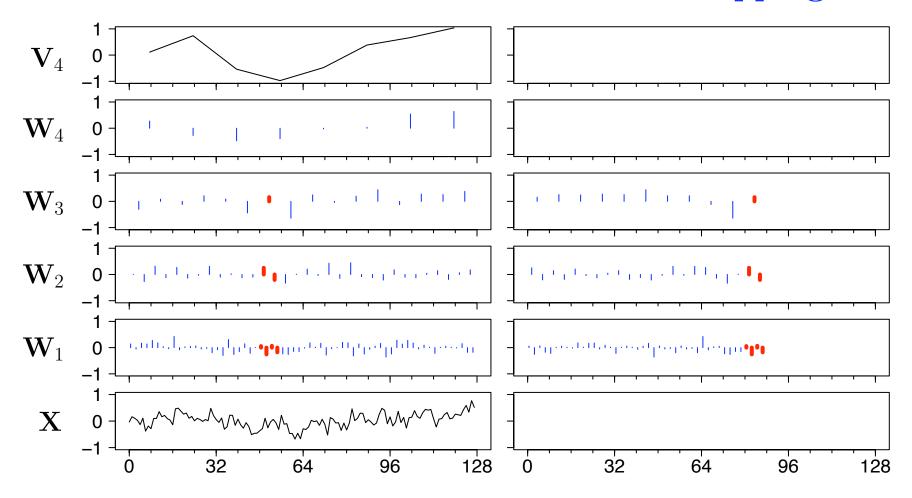


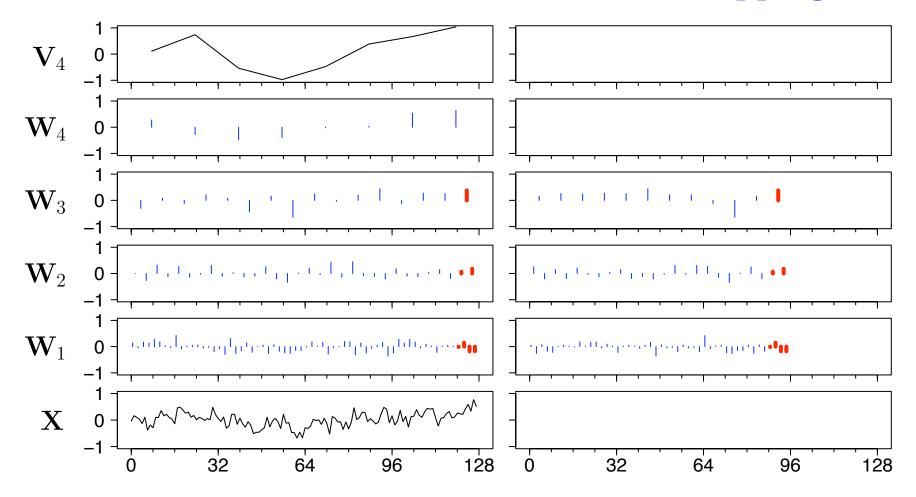


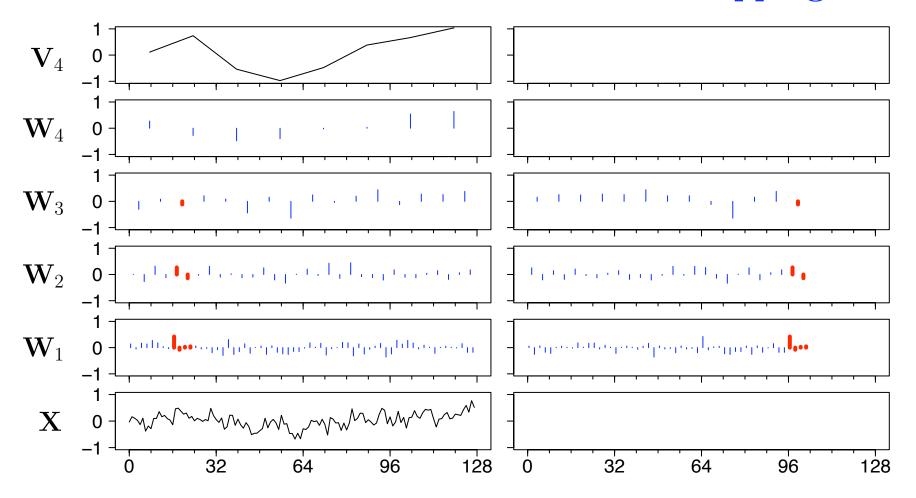


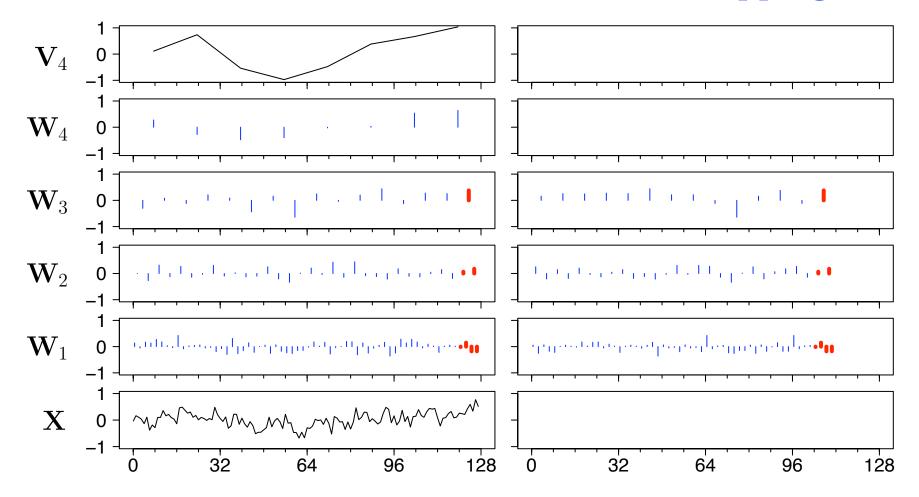


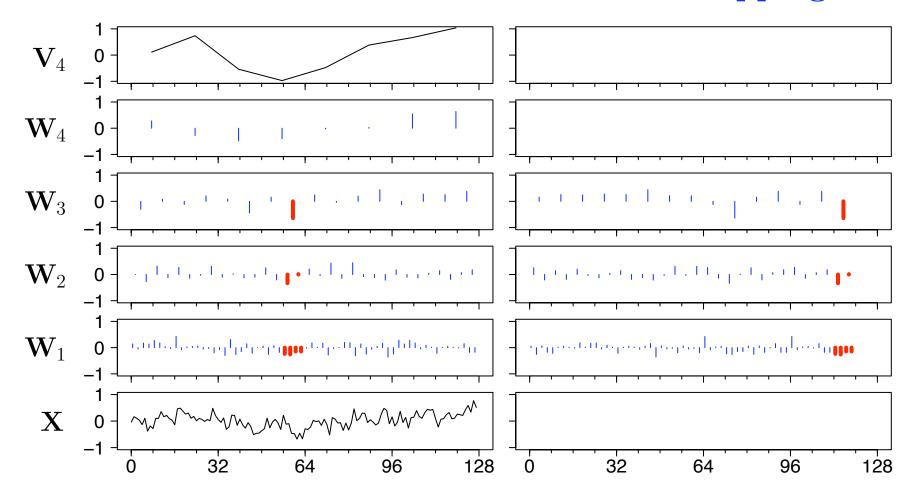


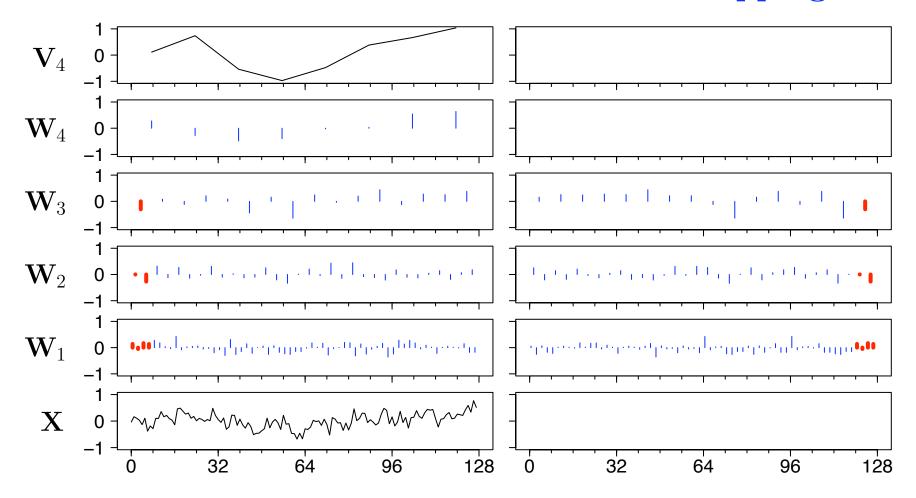




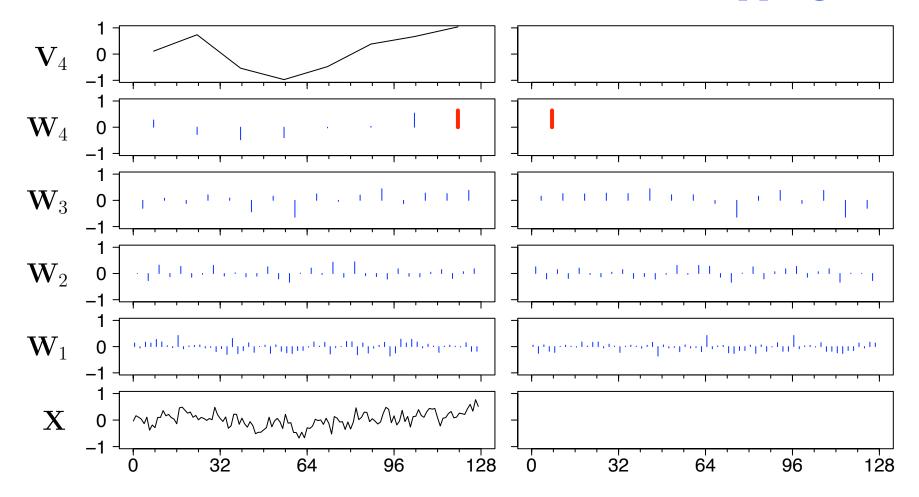


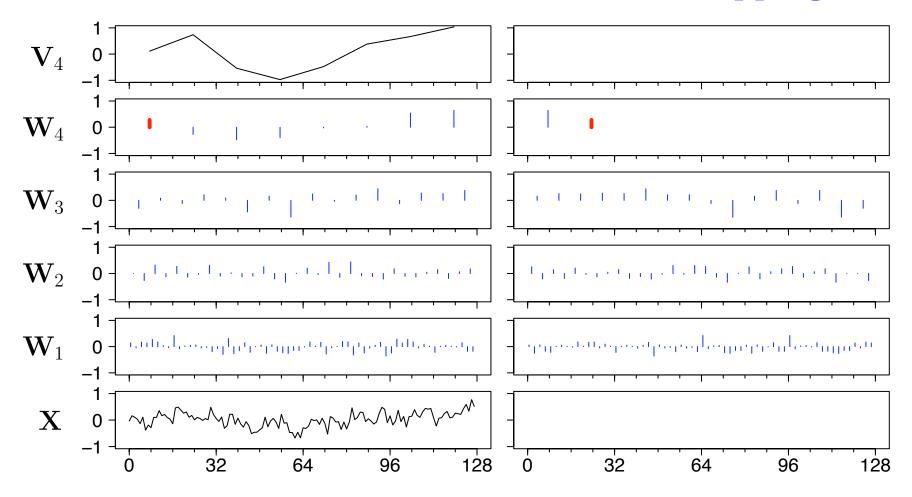


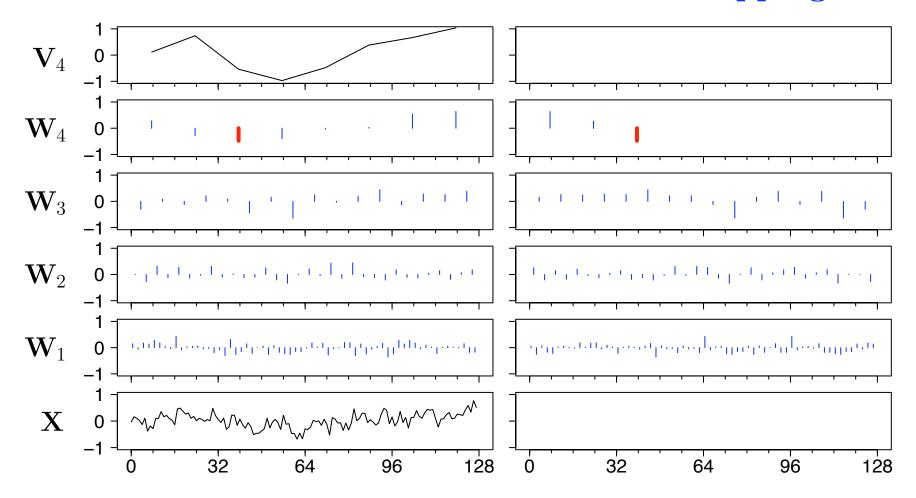


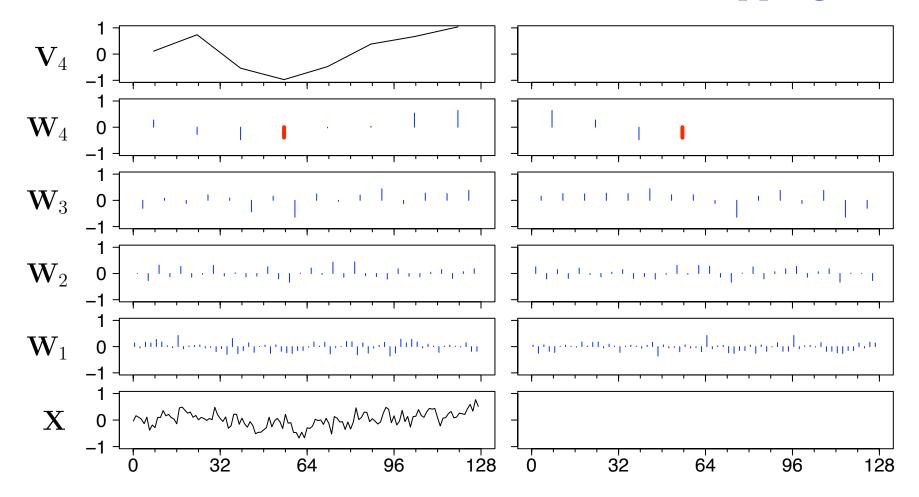


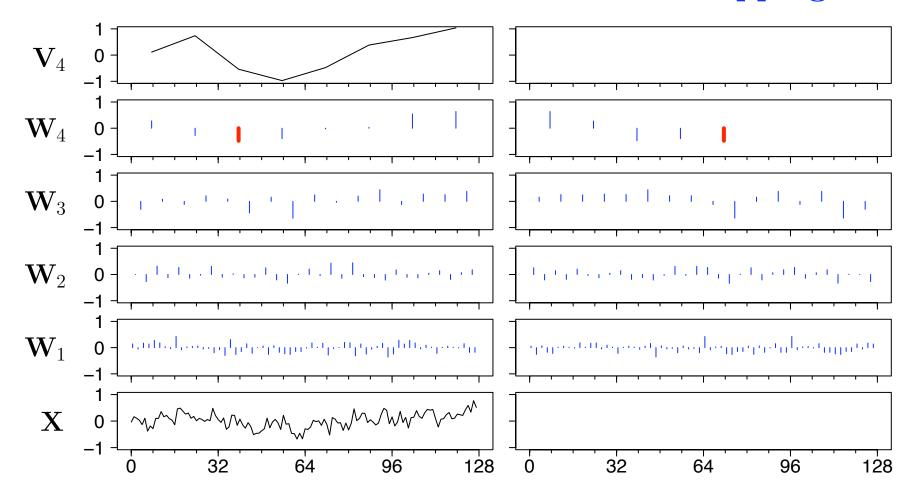
• Haar DWT of FD(0.45) series  $\mathbf{X}$  (left-hand column) and level j=3 tree-based bootstrap thereof (right-hand)

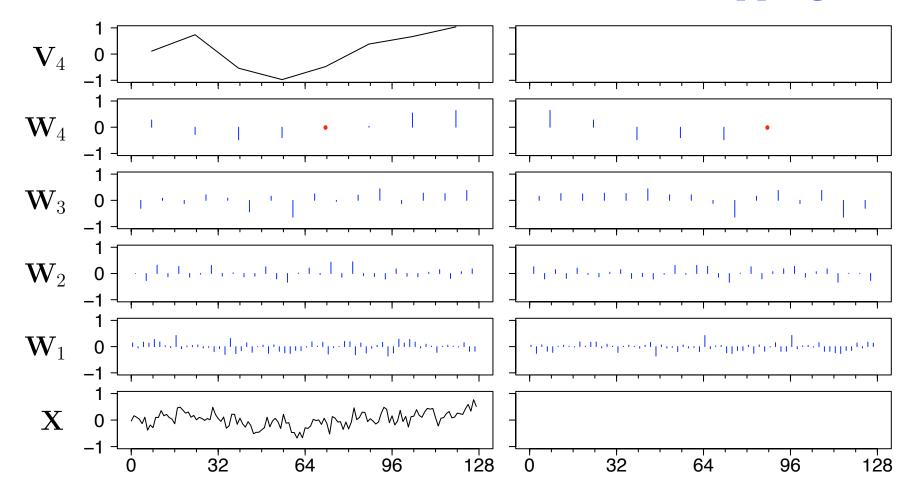


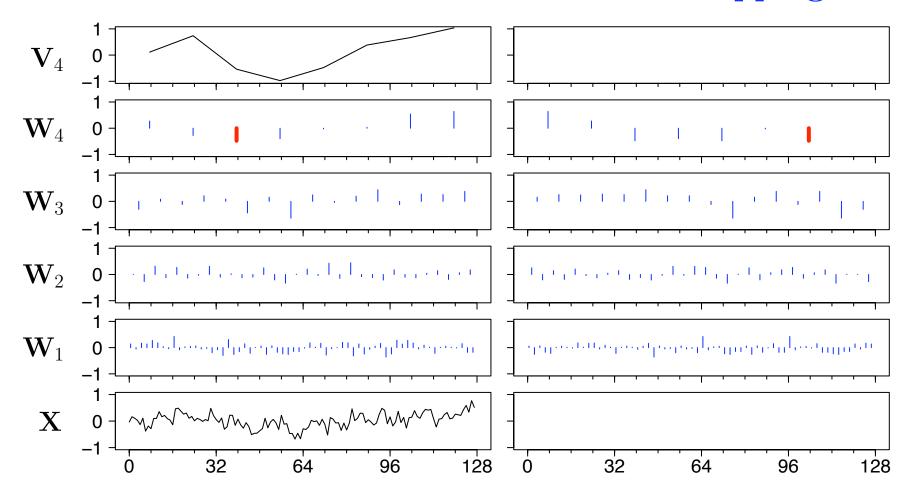


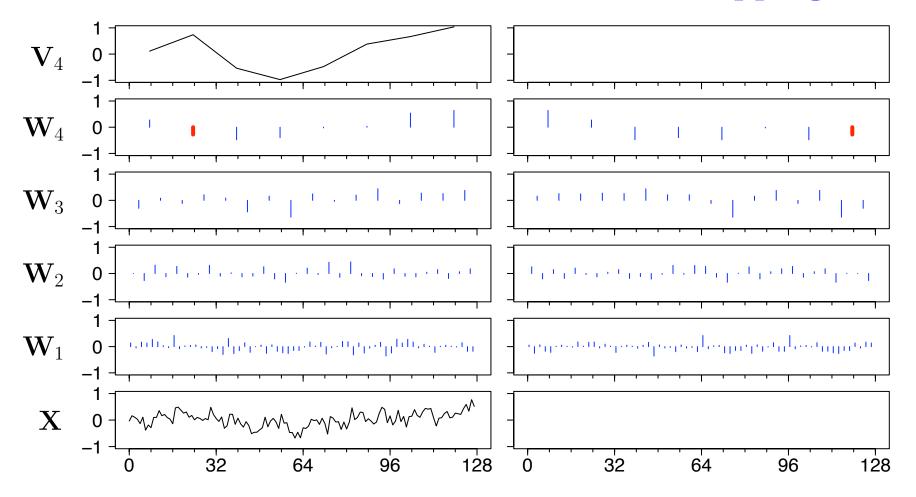


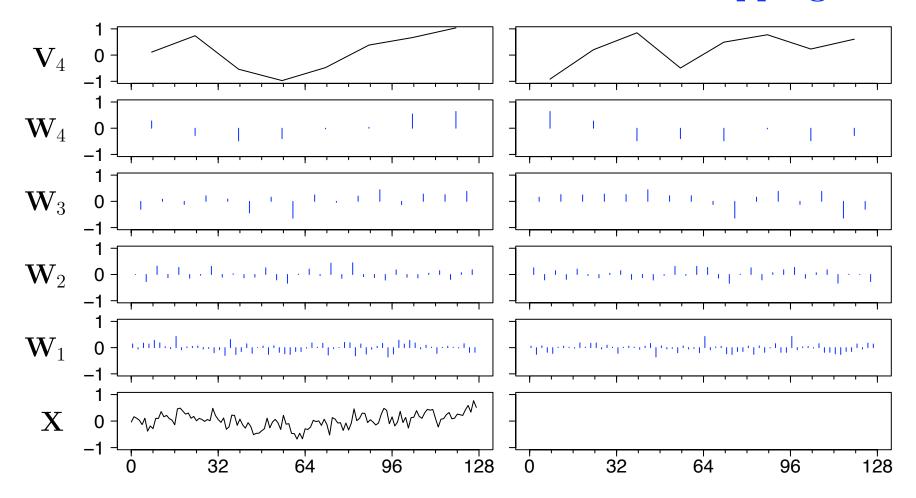


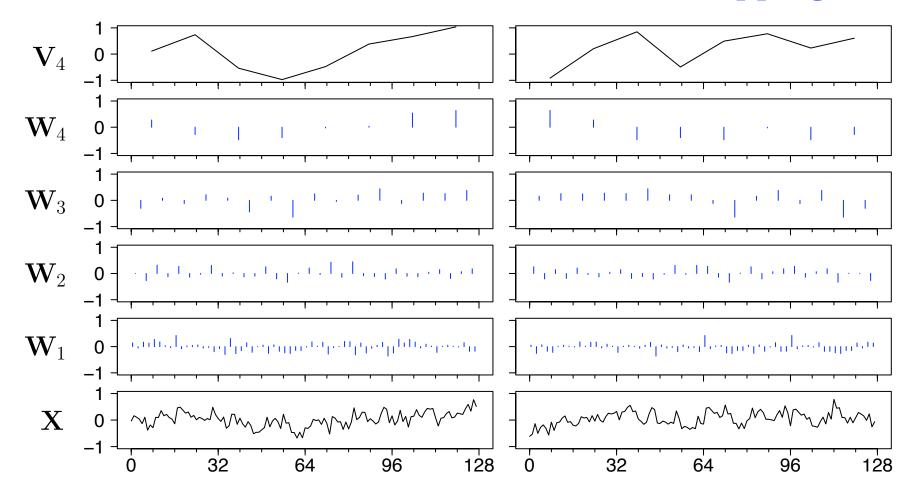




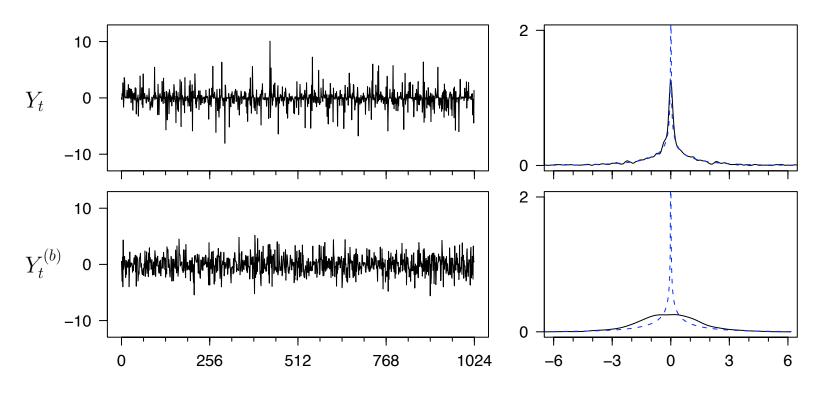




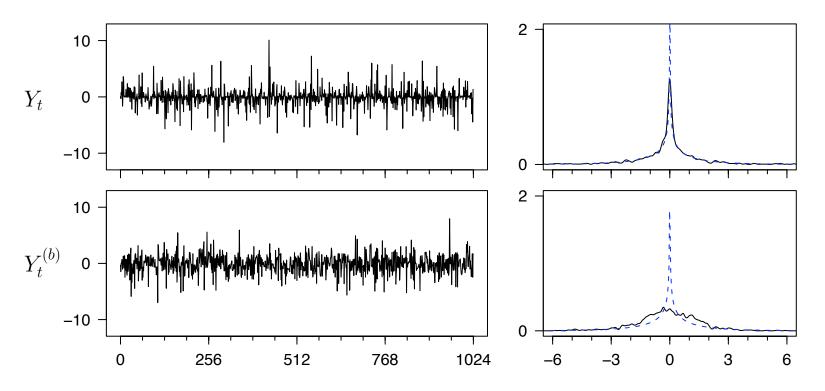




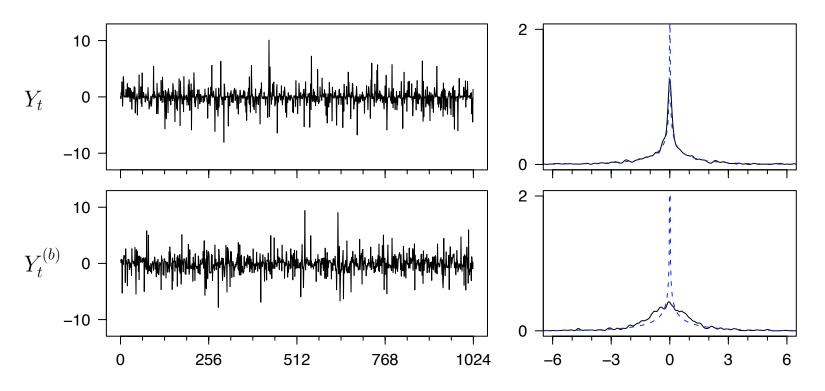
•  $Y_t$  (top row) and j=1 Haar tree-based bootstrap (bottom)



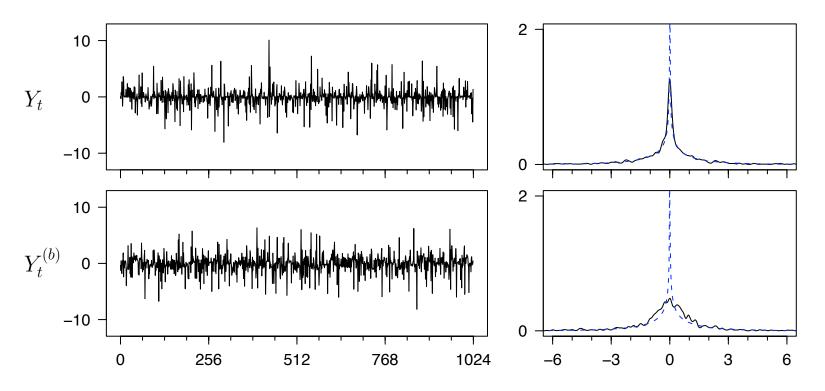
•  $Y_t$  (top row) and j=2 Haar tree-based bootstrap (bottom)



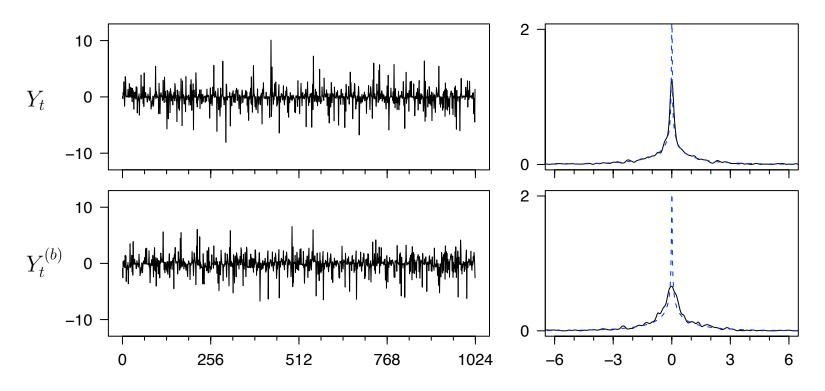
•  $Y_t$  (top row) and j=3 Haar tree-based bootstrap (bottom)



•  $Y_t$  (top row) and j = 4 Haar tree-based bootstrap (bottom)



•  $Y_t$  (top row) and j = 5 Haar tree-based bootstrap (bottom)

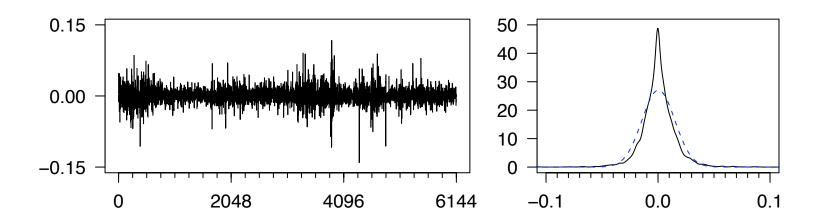


# **Summary of Computer Experiments**

				LA(8)	j=2	j=4	
Statistic	Process	Parm	Block	DWT	Tree	Tree	True
mean	AR	0.86	0.83	0.83	0.84	0.85	0.86
	FD	0.58	0.57	0.54	0.55	0.57	0.59
$\overline{SD}$	AR	0.016	0.021	0.025	0.025	0.024	0.021
	FD	0.025	0.042	0.054	0.051	0.055	0.059

- 50 time series of length N = 1024 for each  $Y_t = \text{sign}\{X_t\} \times X_t^2$
- 100 bootstrap samples from each series, yielding 100 unit lag sample autocorrelations  $\hat{\rho}_1^{(m)}$
- mean and SD of 100 sample autocorrelations recorded
- table reports averages of these two statistics over 50 time series
- true values based on 100,000 generated series for each process

# Application to BMW Stock Prices - I



- right-hand plot: log of daily returns on BMW share prices
- left-hand: nonparametric and Gaussian PDF estimates
- series has small unit lag sample autocorrelation:  $\hat{\rho}_1 \doteq 0.081$ .
- large sample theory appropriate for Gaussian white noise gives standard deviation of  $1/\sqrt{N} \doteq 0.013$

# Application to BMW Stock Prices - II

• bootstrap estimates of standard deviations:

	LA(8) j =				j=4	
	Parm	Block	DWT	Tree	Tree	Gaussian
SD est.	0.012	0.016	0.021	0.019	0.019	0.013

• since  $\hat{\rho}_1 \doteq 0.081$ , bootstrap methods all confirm presence of autocorrelation (small, but presumably exploitable by traders)

# Concluding Remarks

- wavelet-domain & tree-based bootstraps competitive with parametric & block bootstraps for series with short-range dependence and offer improvement in case of long-range dependence
- results to date for tree-based bootstrapping encouraging, but many questions need to be answered, including:
  - are there statistics & non-Gaussian series for which treebased approach offers more than just a marginal improvement over wavelet-domain approach?
  - what are asymptotic properties of tree-based approach?
  - how can the tree-based approach be adjusted to handle stationary processes that are not well decorrelated by the DWT?
- thanks to Maya for the opportunity to speak!

# Shameless Self-Advertizing

- will be teaching EE 524/Stat 530 (Wavelets: Data Analysis, Algorithms and Theory) in Spring Quarter
- meets on MWF from 12:30PM to 1:20PM
- totally cool course offering
  - a look into the fascinating world of wavelets!
  - a chance to become an official waveletician/waveleteer!!
  - homemake pastries to munch on during finals week!!!
  - homework, an exam and a course project!!!!
- be there, or be square . . .

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