Microscopic Description of Nuclear Fission:

Induced fission of ²⁴⁰Pu in real time



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Slides (pptx) with movies will be available for download from http://www.faculty.washington.edu/bulgac/Pu240/

Nuclear fission is unquestionably one of the most challenging quantum many-body problems.

Important for fundamental nuclear theory, origin of elements, applications.

Several recent developments have changed radically our prospects of attaining a microscopic description of fission, almost 80 years after it was experimentally discovered.

(In comparison superconductivity needed less than 50 years to attain this goal, from 1911 to 1957.)

• Formulation of a local extension of the Density Functional Theory (DFT), in the spirit of the Local Density Approximation (LDA) formulation of DFT due to Kohn and Sham, to superfluid time-dependent phenomena, the Superfluid Local Density Approximation (SLDA).

- Validation and verification of (TD)SLDA against a large set of theoretical and experimental data.
- Emergence of very powerful computational resources.

• Non-trivial numerical implementation of SLDA and Time-Dependent SLDA (TDSLDA) and deployment of complex codes using the most advanced capabilities of leadership class computers, in particular taking advantage of tens of thousands of GPUs.

SLDA and TDSLDA are problems of extreme computational complexity, requiring the solution of 10,000 ... 1,000,000 coupled complex non-linear time-dependent 3D partial differential equations.

This presentation is a perfect illustration of Dave Barry's suggestion:

Never be afraid to try something new. Remember that amateurs built the Ark and professionals built the Titanic.

I definitely could not call myself a fission or high-performance computing expert at the time when this project started around 2006. At that time nuclear fission looked to me like a good problem to give it a try, being unaware of how complex really is and not having someone around to warn me.

Now I know a bit more.

But then again, as Sydney Brenner (Nobel prize 2002) said:

I'm a strong believer that ignorance is important in science. If you know too much, you start seeing why things won't work. That is why it's important to change your field to collect more ignorance.



How nuclei change their shape at a microscopic level?



• While a nucleus elongates, the Fermi surface becomes oblate. Its sphericity can be restored only by redistributing the nucleons on different energy levels.

• Each single-particle level double is occupied with time-reversed quantum numbers (in the shaded area)

 At each crossing two nucleons change their angular momenta (m,-m) => (m',-m') "Cooper pair" => "Cooper pair"

• <u>Pairing interaction/superfluidity is the most</u> <u>effective mechanism at performing such</u> <u>transitions</u>

From Barranco, Bertsch, Broglia, and Vigezzi Nucl. Phys. A512, 253 (1990)



Distribution derived by G.F. Bertsch

However, in TDHF or TDHF with frozen occupation probabilities $P(l_z)$ is conserved.

Single-particle states with $|l_z| \approx O(k_F r_0 A^{1/3})$, which should not be occupied in the fission fragments, retain their initial occupation probability.

Thus, the initial spherical Fermi momentum distribution acquires an ellipsoidal prolate shape in the final fission fragments.

Bertsch and Bulgac, Phys. Rev. Lett. 79, 3539 (1997)

A different mechanism for nuclear shape evolution was advocated by

J.W. Negele, Nucl. Phys. A 502, 371c-386c (1989) Microscopic theory of fission dynamics





Occupied sp orbitals m-quantum numbers in initial and final configurations

One more problem!

Initial nucleus: 20 positive + 12 negative parity sp orbitals Final nuclei: 16 positive + 16 negative parity sp orbitals

TDHF + BCS with constant pairing gap



FIG. 6. Comparison as a function of time of shapes for 236 U with zero spin-orbit interaction calculated in the TDHF approximation for $\Delta = 2$ MeV and in a macroscopic approach with various types of dissipation. For modified one-body dissipation, we show the result for the preliminary value of $\lambda^2 = 3.2$ fm²; the final value is 3 fm² (Ref. 36). Note that the time scale for the original one-body dissipation is 3 times as long as the time scale for the remaining cases.

From Negele, Koonin, Möller, Nix, and Sierk Phys. Rev. C 17, 1098 (1978)



FIG. 7. Comparison of prescission and postscission shapes for ²³⁶U with zero spin-orbit interaction calculated in the TDHF approximation for two values of the effective pairing gap Δ . The elapsed time between the two configurations for each Δ is 0.4×10^{-21} s.

TABLE III. Comparison of experimental and calculated most probable fission-fragment kinetic energies for the fission of the compound nucleus ²³⁶U. The initial conditions for each calculation correspond to starting from rest 1 MeV beyond the fission saddle point.

Result	Kinetic energy (MeV)
Experimental ^a	168.0 ± 4.5
Microscopic	
$\Delta = 6 \text{ MeV}$	166
$\Delta = 2 \text{ MeV}$	142
Macroscopic	
Nonviscous	186
Two-body viscosity, $\mu = 0.03$ TP	167
Modified one-body dissipation, $\lambda^2 = 3 \text{ fm}^2$	166
One-body dissipation, Fermi-gas value	177

^a For the fission of ²³²Th induced by 65.0 MeV α particles, averaged over all fission-fragment mass divisions and corrected for the effects of fragment neutron emission (Ref. 64). • Can the adoption of a TDHF + TDBCS approach to fission help restore the sphericity of the Fermi sphere in the fission fragments?

• A little bit.

• In TDHF the nucleus is allowed to acquire in principle any shape, but whether dynamically that is realized is not a foregone conclusion.

• Adding TDBCS to TDHF adds one "complex" collective degree of freedom to the many shape degrees of freedom, a spatially constant throughout the entire space complex time dependent pairing field $\Delta(t)$.

• The phase of $\Delta(t)$ can be eliminated with a trivial gauge transformation, which leads to a small renormalization of the chemical potential, leaving effectively only one additional collective degree of freedom when compared to TDHF, namely $|\Delta(t)|$. Thus TDHF+TDBCS amounts to adding practically only one additional collective degree of freedom.

• Practice shows that nuclei cannot always fission within TDHF + TDBCS. This is likely related to the fact that the initial spherical Fermi surface cannot evolve into two spherical Fermi surfaces in the fission fragments within TDHF + TDBCS.

• Continuity equation is violated in a TDHF + TDBCS approach.

TDHF +TDBCS



FIG. 2. (Color online) Isodensity surfaces at half the saturation density $\rho_0/2 = 0.08 \text{ fm}^{-3}$ as a function of time for the three modes. The time steps between two images Δt are given at the top of the figure.

From Scamps, Simenel, and Lacroix, Phys. Rev. C 92, 011602 (2015)



FIG. 1. (Color online) Potential energy curve of ²⁵⁸Fm nucleus as a function of the quadrupole deformation parameter (in barn units). In this region the Fermi surface is already spherical.



FIG. 2. (Color online) Single-particle energies in ²⁵⁸Fm nucleus along the adiabatic PEC. The green solid curves show the neutron and proton Fermi energies. Positive and negative parity states are

From Tanimura, Lacroix, and Scamps, Phys. Rev. C 92, 034601 (2015)

Main Theoretical Tool

THEOREM: There exist an universal density functional of particle density.



DFT has been developed and used mainly to describe normal (non-superfluid) electron systems – more than <u>50 years old theory</u>:

- DFT Kohn and Hohenberg, 1964 LDA - Kohn and Sham, 1965
- **But not everyone is normal!** Hence, a new local extension of DFT to superfluid systems and time-dependent phenomena was developed.

D Springer

Review: A. Bulgac, *Time-Dependent Density Functional Theory and Real-Time Dynamics* of Fermi Superfluids, Ann. Rev. Nucl. Part. Sci. 63, 97 (2013)

Kohn-Sham theorem (1965)

$$\begin{split} H &= \sum_{i}^{N} T(i) + \sum_{i < j}^{N} U(ij) + \sum_{i < j < k}^{N} U(ijk) + \dots + \sum_{i}^{N} V_{ext}(i) \\ H \Psi_{0}(1, 2, \dots N) &= E_{0} \Psi_{0}(1, 2, \dots N) \\ n(\vec{r}) &= \left\langle \Psi_{0} \right| \sum_{i}^{N} \delta(\vec{r} - \vec{r}_{i}) \left| \Psi_{0} \right\rangle \\ \Psi_{0}(1, 2, \dots N) &\Leftrightarrow V_{ext}(\vec{r}) \Leftrightarrow n(\vec{r}) \\ E_{0} &= \min_{n(\vec{r})} \int d^{3}r \left\{ \frac{\hbar^{2}}{2m^{*}(\vec{r})} \tau(\vec{r}) + \varepsilon \left[n(\vec{r}) \right] + V_{ext}(\vec{r}) n(\vec{r}) \right\} \\ n(\vec{r}) &= \sum_{i}^{N} \left| \varphi_{i}(\vec{r}) \right|^{2}, \qquad \tau(\vec{r}) = \sum_{i}^{N} \left| \vec{\nabla} \varphi_{i}(\vec{r}) \right|^{2} \end{split}$$

Injective map (one-to-one)!

THEOREM: There exist an universal functional of particle density alone independent of the external potential.

The wave function of ²⁴⁰Pu depends on 720 coordinates!!! It has 1.76x10⁷² spin components!!!

SLDA Extension to Superfluids and Time-Dependent Phenomena, and Verification and Validation

• Since DFT/SLDA is not an approximation, but in principle an exact theoretical framework (unlike HF, HFB, etc.), one has to convincingly prove that its specific realization is equivalent to the Schrödinger equation! (The DFT and the Schrödinger descriptions should be identical.)

- Also, that it correctly describes Nature!
- And also, that the numerical implementation faithfully reproduces the theory.

There exists a real physical system, the Unitary Fermi Gas introduced by G.F. Bertsch, The Many-Body X Challenge, 1999 where many of these aspects can be directly verified: The Unitary Fermi.

The SLDA energy density functional for unitary Fermi gas (infinite scattering length and zero effective range)

<u>Dimensional arguments, renormalizability, Galilean invariance, and symmetries</u> determine fully the functional form of the energy density.

In this respect this system is perhaps unique in Nature. It describes cold atoms and to a large extent dilute neutron matter, making it an ideal testing ground for DFT.

$$\begin{split} & \varepsilon(\vec{r}) = \frac{\hbar^2}{m} \Biggl\{ \Biggl[\alpha \frac{\tau_c(\vec{r})}{2} + \gamma \frac{\left| \mathbf{v}_c(\vec{r}) \right|^2}{n^{1/3}(\vec{r})} \Biggr] + \beta \frac{3(3\pi^2)^{2/3} n^{5/3}(\vec{r})}{5} \Biggr\} - \frac{\hbar^2}{m} (\alpha - 1) \frac{\vec{j}^2(\vec{r})}{2n(\vec{r})} \\ & n(\vec{r}) = 2 \sum_{0 < E_k < E_c} \left| \mathbf{v}_k(\vec{r}) \right|^2, \quad \tau_c(\vec{r}) = 2 \sum_{0 < E_k < E_c} \left| \vec{\nabla} \mathbf{v}_k(\vec{r}) \right|^2, \\ & \mathbf{v}_c(\vec{r}) = \sum_{0 < E < E_c} \mathbf{u}_k(\vec{r}) \mathbf{v}_k^*(\vec{r}) \quad \Leftarrow \text{ divergent without a cutoff, need RG} \end{split}$$

Surprisingly, the gradient corrections are negligible!

• Three dimensionless constants α , β , and γ determining the functional are extracted from Quantum Monte Carlo for homogeneous systems and they determine the total energy, the pairing gap and the effective mass.

Normal S	tate			Superfluid S	state	
$(N_a, N_b) E_{FNDMC}$	E _{ASLDA}	(error)	(N_a, N_b)	E _{FNDMC}	E _{ASLDA}	(error)
(3,1) 6.6±0.01	6.687	1.3%	(1,1)	2.002 ± 0	2.302	15%
$(4,1)$ 8.93 \pm 0.01	8.962	0.36%	(2,2)	5.051 ± 0.009	5.405	7%
$(5,1)$ 12.1 \pm 0.1	12.22	0.97%	(3,3)	8.639 ± 0.03	8.939	3.5%
(5,2) 13.3±0.1	13.54	1.8%	(4,4)	12.573 ± 0.03	12.63	0.48%
(6,1) 15.8±0.1	15.65	0.93%	(5,5)	16.806 ± 0.04	16.19	3.7%
$(7,2)$ 19.9 \pm 0.1	20.11	1.1%	(6,6)	21.278 ± 0.05	21.13	0.69%
$(7,3)$ 20.8 \pm 0.1	21.23	2.1%	(7,7)	25.923 ± 0.05	25.31	2.4%
$(7,4)$ 21.9 \pm 0.1	22.42	2.4%	(8,8)	30.876 ± 0.06	30.49	1.2%
$(8,1)$ 22.5 ± 0.1	22.53	0.14%	(9,9)	35.971 ± 0.07	34.87	3.1%
$(9,1)$ 25.9 ± 0.1	25.97	0.27%	(10,10)	41.302 ± 0.08	40.54	1.8%
(9,2) 26.6±0.1	26.73	0.5%	(11,11)	46.889 ± 0.09	45	4%
$(9,3)$ 27.2 \pm 0.1	27.55	1.3%	(12, 12)	52.624 ± 0.2	51.23	2.7%
$(9,5)$ 30 \pm 0.1	30.77	2.6%	(13, 13)	58.545±0.18	56.25	3.9%
$(10,1)$ 29.4 \pm 0.1	29.41	0.034%	(14, 14)	64.388 ± 0.31	62.52	2.9%
$(10,2)$ 29.9 \pm 0.1	30.05	0.52%	(15, 15)	70.927 ± 0.3	68.72	3.1%
$(10, 6)$ 35 \pm 0.1	35.93	2.7%	(1,0)	1.5 ± 0.0	1.5	0%
(20,1) 73.78±0.01	73.83	0.061%	(2,1)	4.281 ± 0.004	4.417	3.2%
(20,4) 73.79±0.01	74.01	0.3%	(3,2)	7.61 ± 0.01	7.602	0.1%
$(20, 10)$ 81.7 \pm 0.1	82.57	1.1%	(4,3)	11.362 ± 0.02	11.31	0.49%
(20,20) 109.7±0.1	113.8	3.7%	(7,6)	24.787±0.09	24.04	3%
(35,4) 154±0.1	154.1	0.078%	(11,10)	45.474 ± 0.15	43.98	3.3%
(35,10) 158.2±0.1	158.6	0.27%	(15,14)	69.126 ± 0.31	62.55	9.5%
(35,20) 178.6±0.1	180.4	1%				

Bulgac, Forbes, and Magierski, Ch.9 in Lecture Notes in Physics, vol. 836 (2012)

Formalism for Time-Dependent Phenomena

"The time-dependent density functional theory is viewed in general as a reformulation of the exact quantum mechanical time evolution of a many-body system when only one-body properties are considered."

A.K. Rajagopal and J. Callaway, Phys. Rev. B <u>7</u>, 1912 (1973) V. Peuckert, J. Phys. C <u>11</u>, 4945 (1978) E. Runge and E.K.U. Gross, Phys. Rev. Lett. <u>52</u>, 997 (1984)

http://www.tddft.org

 $\begin{aligned} \mathbf{Time-Dependent Superfluid Local Density Approximation (TDSLDA)} \\ E(t) &= \int d^3r \left[\mathcal{E}(n(\vec{r},t),\tau(\vec{r},t),\nu(\vec{r},t),\vec{j}(\vec{r},t)) + V_{ext}(\vec{r},t)n(\vec{r},t) + ... \right] \\ &\left\{ \begin{array}{l} i\hbar \frac{\partial \mathbf{u}_{i}(\vec{r},t)}{\partial t} &= [h(\vec{r},t) + V_{ext}(\vec{r},t) - \mu]\mathbf{u}_{i}(\vec{r},t) + [\Delta(\vec{r},t) + \Delta_{ext}(\vec{r},t)]\mathbf{v}_{i}(\vec{r},t) \\ &i\hbar \frac{\partial \mathbf{v}_{i}(\vec{r},t)}{\partial t} = [\Delta^{*}(\vec{r},t) + \Delta^{*}_{ext}(\vec{r},t)]\mathbf{u}_{i}(\vec{r},t) - [h(\vec{r},t) + V_{ext}(\vec{r},t) - \mu]\mathbf{v}_{i}(\vec{r},t) \end{aligned} \right. \end{aligned}$

Galilean invariance determines the functional dependence on currents.

A great example on how TDSLDA help clarify a great puzzle and give a correct interpretation to an experimental result. <u>The "heavy soliton" proved to be a vortex ring.</u>



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Observation of shock waves in a strongly interacting Fermi gas J. Joseph, J.E. Thomas, M. Kulkarni, and A.G. Abanov Phys. Rev. <u>Lett. 106, 150401 (2011)</u>



Dark solitons/domain walls and shock waves in the collision of two UFG clouds of about 1,400 fermions, simulating a real experiment.

Bulgac, Luo, and Roche, Phys. Rev. Lett. 108, 150401 (2012)

The first ab initio simulation of quantum turbulence in a fermionic superfluid.

Pairing field profiles (in units of eF)



Aproximately 1270 fermions on a 48x48x128 spatial lattice, ≈ 260,000 complex PDEs, ≈ 309,000 time-steps, 2048 GPUs on Titan, 27.25 hours of wall time (initial code).

Wlazłowski et al, Phys. Rev. Lett. 112, 025301 (2014), Phys. Rev. A 91, 031602(R) (2015)



Stetcu, et al., Phys. Rev. C <u>84</u>, 051309(R) (2011)

Giant Dipole Resonance deformed and superfluid Nuclei.

Osmium is triaxial, and both protons and neutrons are superfluid.

Main computational tool



Cray XK7, ranked #2, at peak ≈ 27 Petaflops (Peta – 10¹⁵)

On Titan there are 18,688 GPUs, which provide 24.48 Petaflops !!! and 299,008 CPUs which provide only 2.94 Petaflops

A single GPU on Titan performs the same amount of FLOPs as approximately 134 CPUs.

Bright future for GPU computing

US to Build Two Flagship Supercomputers



Partnership for Science 100-300 PFLOPS Peak Performance 10x in Scientific Applications IBM POWER9 CPU + NVIDIA Volta GPU NVLink High Speed Interconnect 40 TFLOPS per Node, >3,400 Nodes 2017

Major Step Forward on the Path to Exascale

	Summit	Titan	Sierra	Sequoia							
CPU Architecture	IBM POWER9	AMD Opteron (Bulldozer)	IBM POWER9	IBM BlueGene/Q							
GPU Architecture	NVIDIA Volta	NVIDIA Kepler	NVIDIA Volta	N/A							
Performance (RPEAK)	150 - 300 PFLOPS	27 PFLOPS	100+ PFLOPS	20 PFLOPS							
Power Consumption	~10MW	~9MW	N/A	~8MW							
Nodes	3,400	18,688	N/A	N/A							
Laboratory	Oak Ridge	Oak Ridge	Lawrence Livermore	Lawrence Livermore							
Mandan	1014	0	1514	1014							

IBM

IBM

IIS Department of Energy Supercompute

Tesla Products	Tesla K40	Tesla M40	Tesla P100		
GPU	GK110 (Kepler)	GM200 (Maxwell)	GP100 (Pascal)		
SMs	15	24	56		
TPCs	15	24	28		
FP32 CUDA Cores / SM	192	128	64		
FP32 CUDA Cores / GPU	2880	3072	3584		
FP64 CUDA Cores / SM	64	4	32		
FP64 CUDA Cores / GPU	960	96	1792		
Base Clock	745 MHz	948 MHz	1328 MHz		
GPU Boost Clock	810/875 MHz	1114 MHz	1480 MHz		
Peak FP32 GFLOPs ¹	5040	6840	10600		
Peak FP64 GFLOPs ¹	1680	210	5300		
Texture Units	240	192	224		
Memory Interface	384-bit GDDR5	384-bit GDDR5	4096-bit HBM2		
Memory Size	Up to 12 GB	Up to 24 GB	16 GB		
L2 Cache Size	1536 KB	3072 KB	4096 KB		

Numerical Implementation and Deployment of TDSLDA on leadership class computers

TDSLDA equations



• The system is placed on a large 3D spatial lattice (adequate representation of continuum)

- Derivatives are computed with FFTW (this insures machine accuracy) and is very fast
- Fully self-consistent treatment with fundamental symmetries respected (isospin, gauge, Galilean, rotation, translation, parity)
- Adams-Bashforth-Milne fifth order predictor-corrector-modifier integrator Effectively a sixth order method
- No symmetry restrictions for the solutions
- Number of PDEs is of the order of the number of spatial lattice points – from 10,000s to 1-2,000,000



- SLDA/TDSLDA (DFT) is formally by construction like meanfield HFB/BdG
- The code was implemented on Jaguar, Titan, Franklin, Hopper, Edison, Hyak, Athena
- Initially Fortran 90, 95, 2003 ..., presently C, CUDA, and obviously MPI, threads, etc.
- Extremely efficient I/O for Check-Point Restart
- For more details about the method see INT talk on October 7, 2013: <u>http://faculty.washington.edu/bulgac/talks.html#most_recent</u>



Over 1 million time-dependent 3D nonlinear complex coupled PDEs

SLy4

Pairing coupling:

EDF:

$$g_{\rm eff}(\vec{r}) = g\left(1 - \eta \frac{\rho(\vec{r})}{\rho_0}\right)$$

Simulation box: 40×22.5^2 fm³

 $40 \times 22.5^2 \text{ fm}^3$ $\hbar \pi$

Momentum cutoff:

$$p_c = \frac{\hbar\pi}{\Delta x} = 500 \text{ fm/c}$$

Efficient use of FFT to calculate exactly derivatives

Adams-Bashforth-Milne $O(\Delta t^6)$ time integration method

with only two evaluations of the rhs of the equations per time-step

Time-step:= 0.119 fm/cNumber of time steps: $\approx 120,000$ Number of PDEs: $\approx 56,000$ Number of GPUs: $\approx 1,750$ Wall time: $\approx 550 \text{ minutes}$

OLCF Titan - Cray XK7

Induced Fission of ²⁴⁰Pu

• No need to introduce and to guess the number and character of collective variables. The number of excited shape degrees of freedom is large and it increases during the evolution. This makes treatments like GCM, based on a fix number of collective coordinates quite doubtful.

• No need to evaluate the rather ill-defined potential energy surface. Not clear how to choose the collective coordinates, how to choose the constraints, how to choose their number, and whether to require the nucleus to be cold or not.

• No need to determine the rather ill-defined inertia tensor. *Several prescriptions are used in literature*.

• There is no need to invoke (or not) adiabaticity, since as a matter of fact the dynamical evolution is not close to equilibrium, at either zero or at a finite temperature. The evolution is truly a non-equilibrium one.

• One-body dissipation, the window and wall dissipation mechanisms are automatically incorporated into the theoretical framework.

• No modeling (except for the energy density functional, which so far is tested in completely unrelated conditions).

• All shapes are allowed and the nucleus chooses dynamically the path in the shape space, the forces acting on nucleons are determined by the nucleon distributions and velocities, and the nuclear system naturally and smoothly evolves into separated fission fragments.

• There is no need to introduce such concepts as "rupture," which is an un-natural concept in quantum mechanics, where everything is smooth, and no need to worry about how to define the scission configuration.

• One can extract difficult to gain otherwise information: angular momentum distribution and excitation energies of the fission fragments.

Induced fission of ²⁴⁰Pu



Neutron/proton densities (left and top/bottom) Neutron/proton pairing gaps (right and top/bottom)

Bulgac, Magierski, Roche, and Stetcu, Phys. Rev. Lett. 116, 122504 (2016)

TABLE I. The simulation number, the pairing parameter η , the excitation energy (E^*) of ${}^{240}_{94}$ Pu₁₄₆ and of the fission fragments $[E^*_{H,L} = E_{H,L}(t_{SS}) - E_{gs}(N_{H,L}, Z_{H,L})]$, the equivalent neutron incident energy (E_n) , the scaled initial mass moments $q_{20}(0)$ and $q_{30}(0)$, the "saddle-to-scission" time t_{SS} , TKE evaluated as in Ref. [71], TKE, atomic (A_L^{syst}) , neutron (N_L^{syst}) , and proton (Z_L^{syst}) extracted from data [72] using Wahl's charge systematics [73] and the corresponding numbers obtained in simulations, and the number of postscission neutrons for the heavy and light fragments $(\nu_{H,L})$, estimated using a Hauser-Feshbach approach and experimental neutron separation energies [8,74,75]. Units are in MeV, fm², fm³, fm/c as appropriate.

S no.	η	E^*	E_n	q_{zz}	q_{zzz}	t _{SS}	TKE ^{syst}	TKE	$A_L^{\rm syst}$	A_L	$N_L^{\rm syst}$	N_L	$Z_L^{\rm syst}$	Z_L	E_H^*	E_L^*	ν_H	ν_L
<i>S</i> 1	0.75	8.05	1.52	1.78	-0.742	14419	177.27	182	100.55	104.0	61.10	62.8	39.45	41.2	5.26	17.78	0	1.9
<i>S</i> 2	0.5	7.91	1.38	1.78	-0.737	4360	177.32	183	100.56	106.3	60.78	64.0	39.78	42.3	9.94	11.57	1	1
<i>S</i> 3	0	8.08	1.55	1.78	-0.737	14010	177.26	180	100.55	105.5	60.69	63.6	39.81	41.9	3.35	29.73	0	2.9
<i>S</i> 4	0	6.17	-0.36	2.05	-0.956	12751	177.92	181		103.9		62.6		41.3	7.85	9.59	1	1



Fission of ²⁴⁰Pu at excitation energy $E_x = 8.08$ MeV



Time= 0.000000 fm/c

Nuclear density (fm^-3)



Neutron current (c fm^-3)





Time=0 (fm/c)

Fission of ²⁴⁰Pu at excitation energy $E_x = 8.05$; 7.91; 8.08 MeV



Time= 0.000000 fm/c

Fission of ²⁴⁰Pu at excitation energy $E_x = 8.05$; 7.91; 8.08 MeV



Time= 0.000000 fm/c

The most surprising finding was that the saddle-to-scission time was significantly longer than expected from any previous treatments.

Why?

The likeliest cause is the presence in TDSLDA of all possible collective degrees of freedom and that alone, even in the absence of dissipative effects results in longer saddle-to-scission times.

The fluctuating pairing filed, especially for protons, might also cause this behavior.

2D classical analog model of the Drude model for electron conduction in metals.



On the left side there is no "ion lattice" present, only electrons in an "uniform electric field."

On the right side the electrons, again in the presence of an "uniform electric field," collide elastically with the "ions."

Note that kinetic energy is not dissipated and in both cases and the "electrons" arrive at the bottom with the same speed but at different times!

Summary

- TDSLDA will offer insights into nuclear processes and quantities which are either not easy or impossible to obtain in the laboratory:
 fission fragments excitation energies and angular momenta distributions, element formation in astrophysical environments.
 other nuclear reactions ...
- TDSLDA offers an unprecedented opportunity to test the nuclear energy density functional for large amplitude collective motion, non-equilibrium phenomena, and in new regions of the collective degrees of freedom.
- The quality of the agreement with experimental observations is surprisingly good, especially taking into account the fact that we made no effort to reproduce any measured data.
- TDSLDA predicts long saddle-to-scission time scales and the systems behaves superficially as a very viscous one, while at the same time the collective motion is not overdamped. There is no thermalization and the "temperatures" of the fission fragments are not equal.
- It is straightforward to implement the Balian and Vénéroni recipe to compute two-body observables: fission fragments mass, charge, angular momenta, excitation energy widths, ...



Papers we have published so far on SLDA and TDSLDA

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