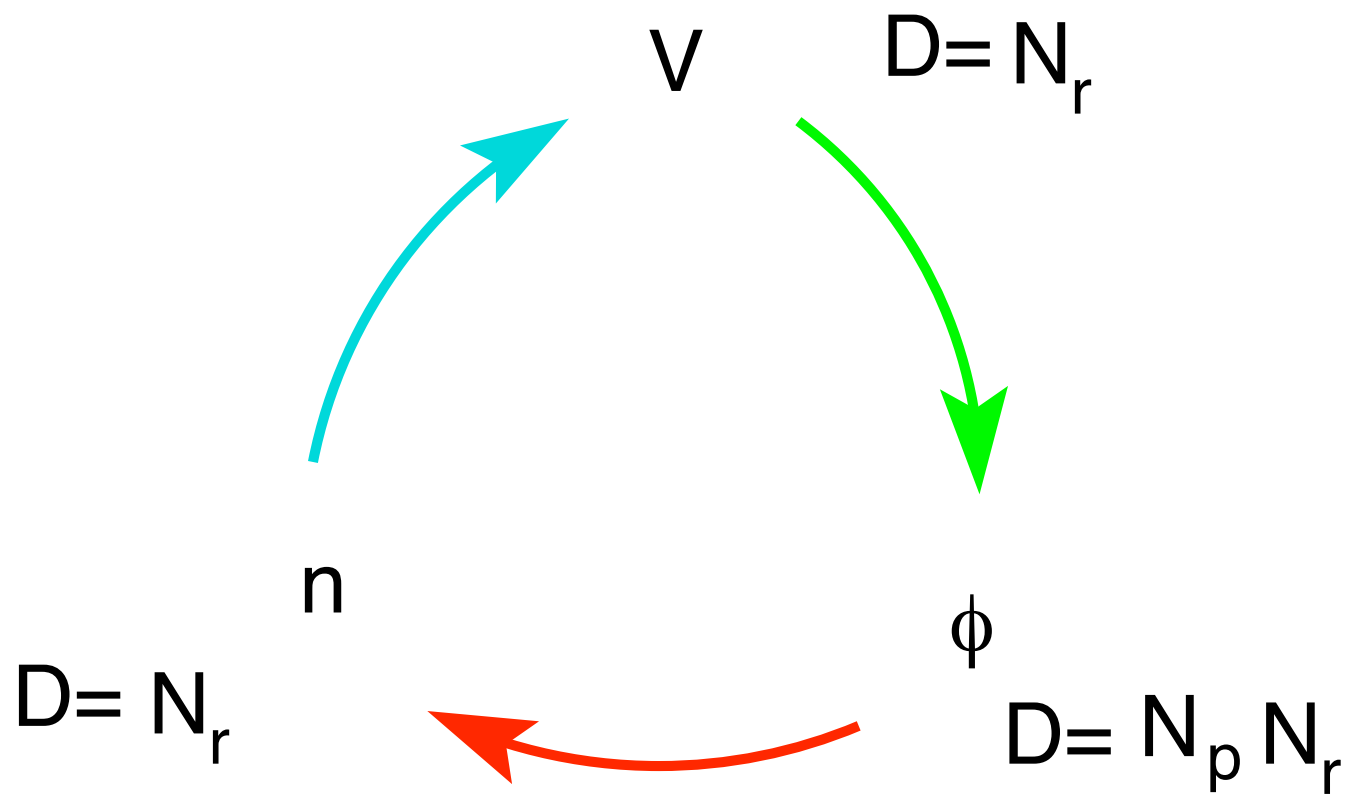


The Self-Consistent Loop



Current Implementation

EV8

```
c      * nxmu                                     *
c      *      damping factor for the mean-field potential (evolve) *
c      *      xmu=nxmu/100.; w(n+1)=xmu*w(n+1)+(1.-xmu)*w(n)      *
c      *      if nxmu is read 0, xmu is set to 0.25                *

xmu = float(nxmu)/t100
ymu = one-xmu
do i=1,2*mv
  rho(i) = xmu* rho(i)+ymu*rvst(i,1)
  vtau(i) = xmu*vtau(i)+ymu*rvst(i,2)
  vdiv(i) = xmu*vdiv(i)+ymu*rvst(i,3)
  rvst(i,1) = rho(i)
  rvst(i,2) = vtau(i)
  rvst(i,3) = vdiv(i)
enddo
call newpot
```

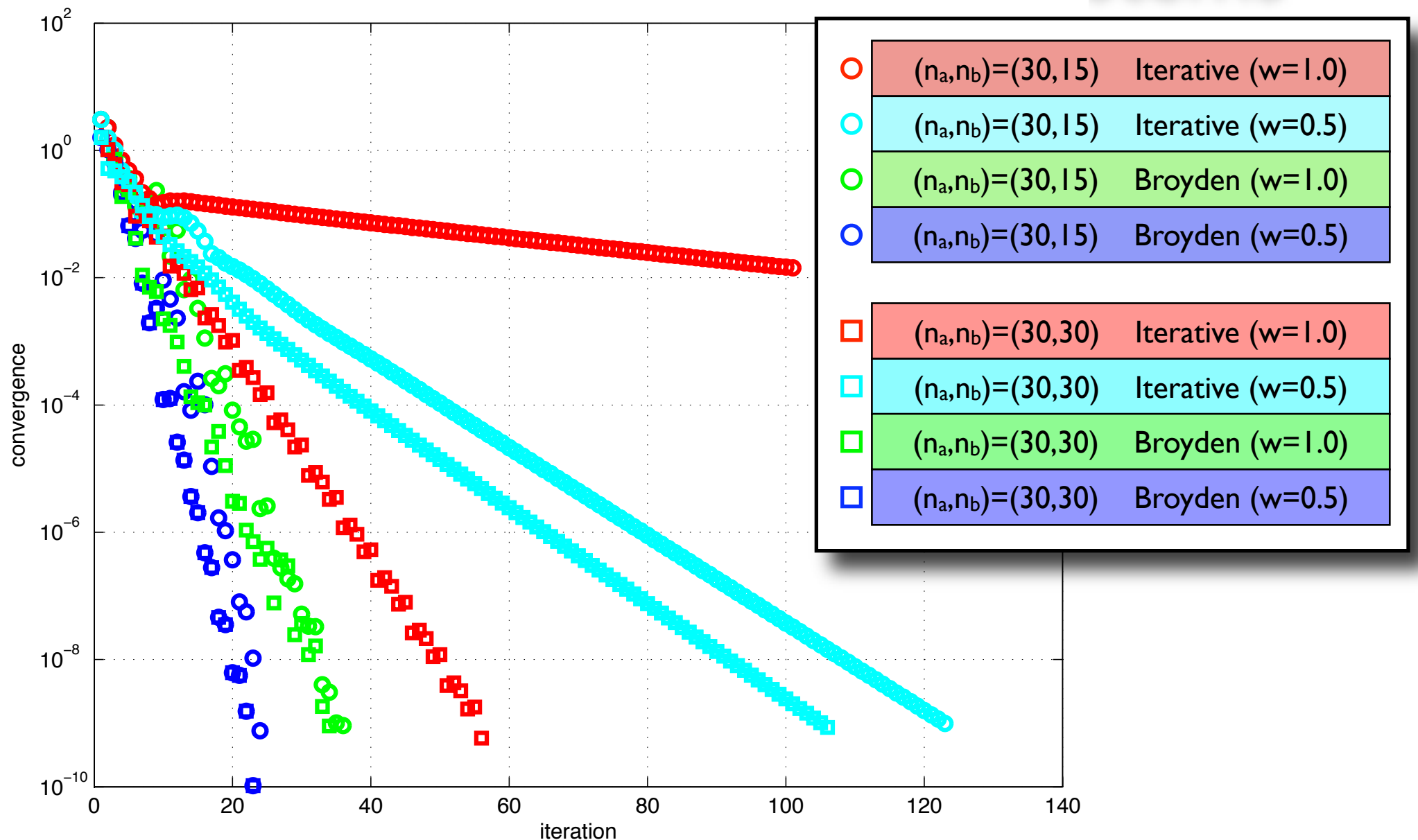
HHODD

```
SLOWEV=0.500
XOLDEV=SLOWEV
XNEWEV=1.00D0-XOLDEV
DO IX=1,NXHERM
  DO IY=1,NYHERM
    DO IZ=1,NZHERM
      VN_MAS(IX,IY,IZ) = VN_MAS(IX,IY,IZ)*XOLDEV+XNEWEV*VNEUTR
    END DO
  END DO
END DO
```

Improving self- consistent calculations of Fermion systems

Michael McNeil Forbes and Aurel Bulgac

Improving self-consistent calculations of Fermion systems



Outline

- Structure of self-consistent calculations
- Current codes
- Broyden method to accelerate convergence
 - Very easy to implement
- DVR Basis to improve representation

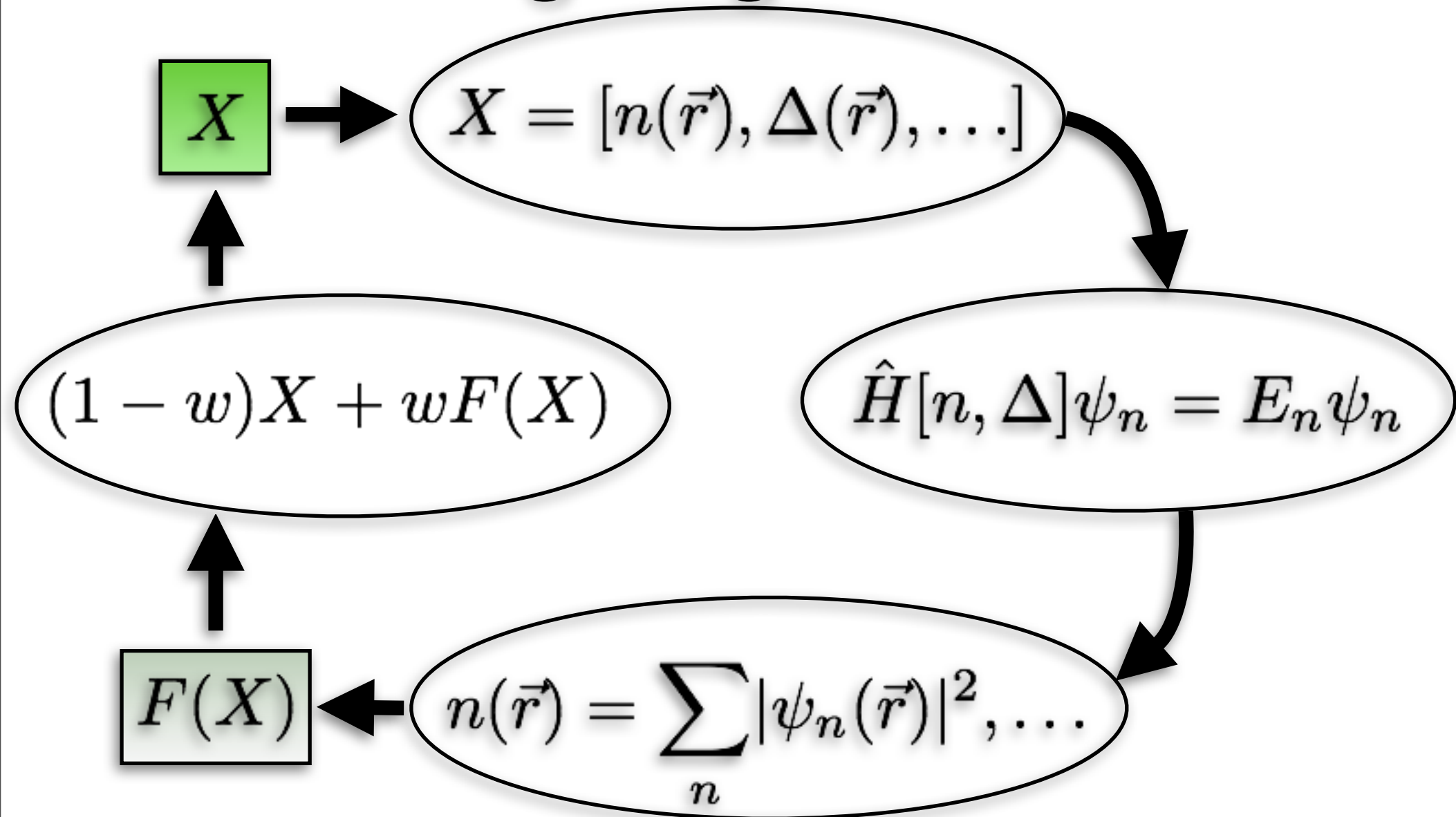
Self-consistent calculations

Find a “fixed-point” in a high dimensional space.

$$X \mapsto F(X)$$

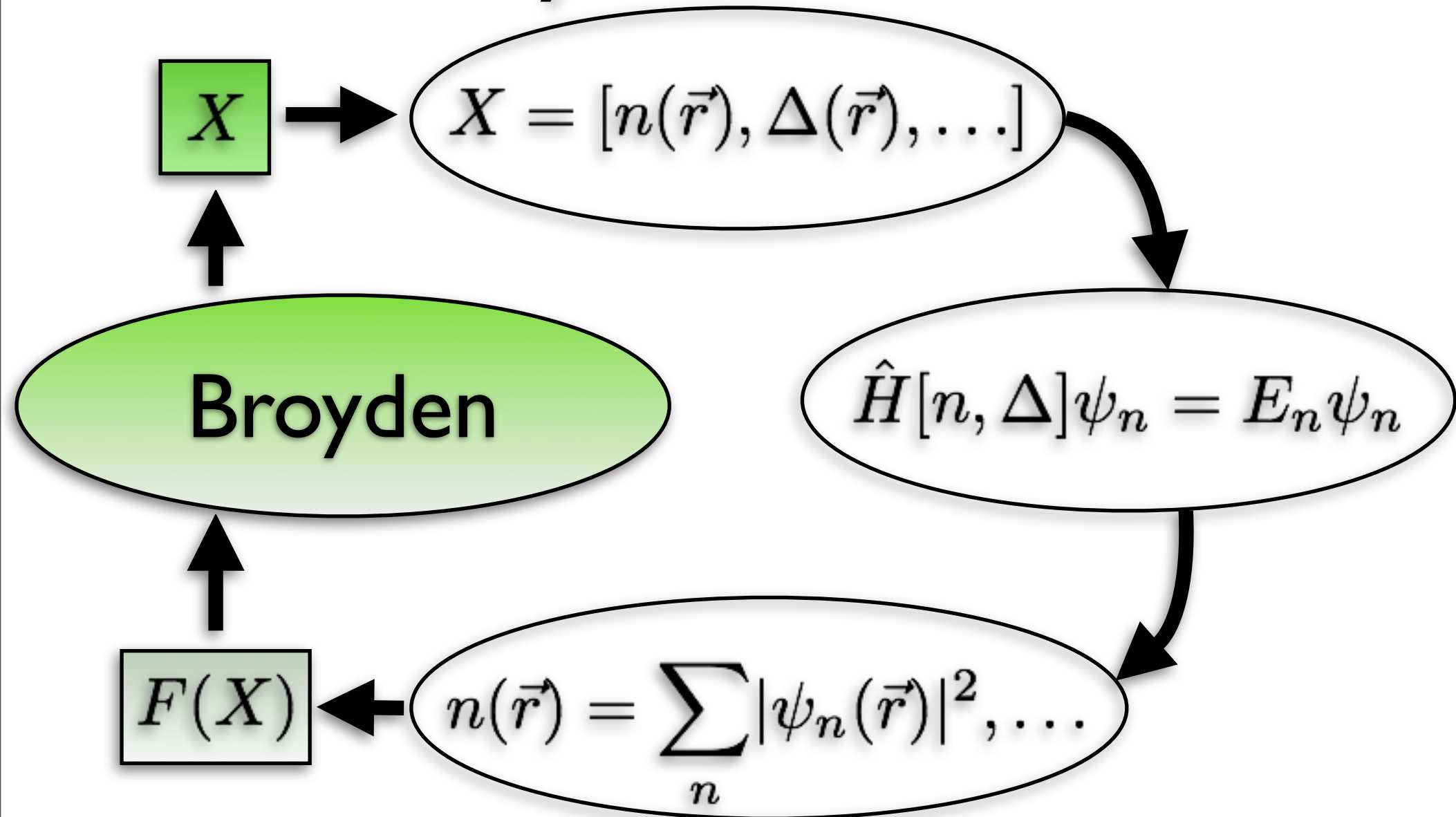
- HFB
- BdG
- DFT (LDA, Kohn)

Self-consistent calculations Weighting Scheme



Self-consistent calculations

Broyden Scheme



Broyden Method

$$G(X) = X - F(X) = 0$$

$$\underline{\underline{(|X_n\rangle, |G_n\rangle, \mathbf{J}_n^{-1})}}$$

$$|dX\rangle = -\mathbf{J}_n^{-1} \cdot |G_n\rangle$$

$$|X_{n+1}\rangle = |X_n\rangle + |dX\rangle$$

$$|G_{n+1}\rangle = G(|X_{n+1}\rangle)$$

$$|dG\rangle = |G_{n+1}\rangle - |G_n\rangle$$

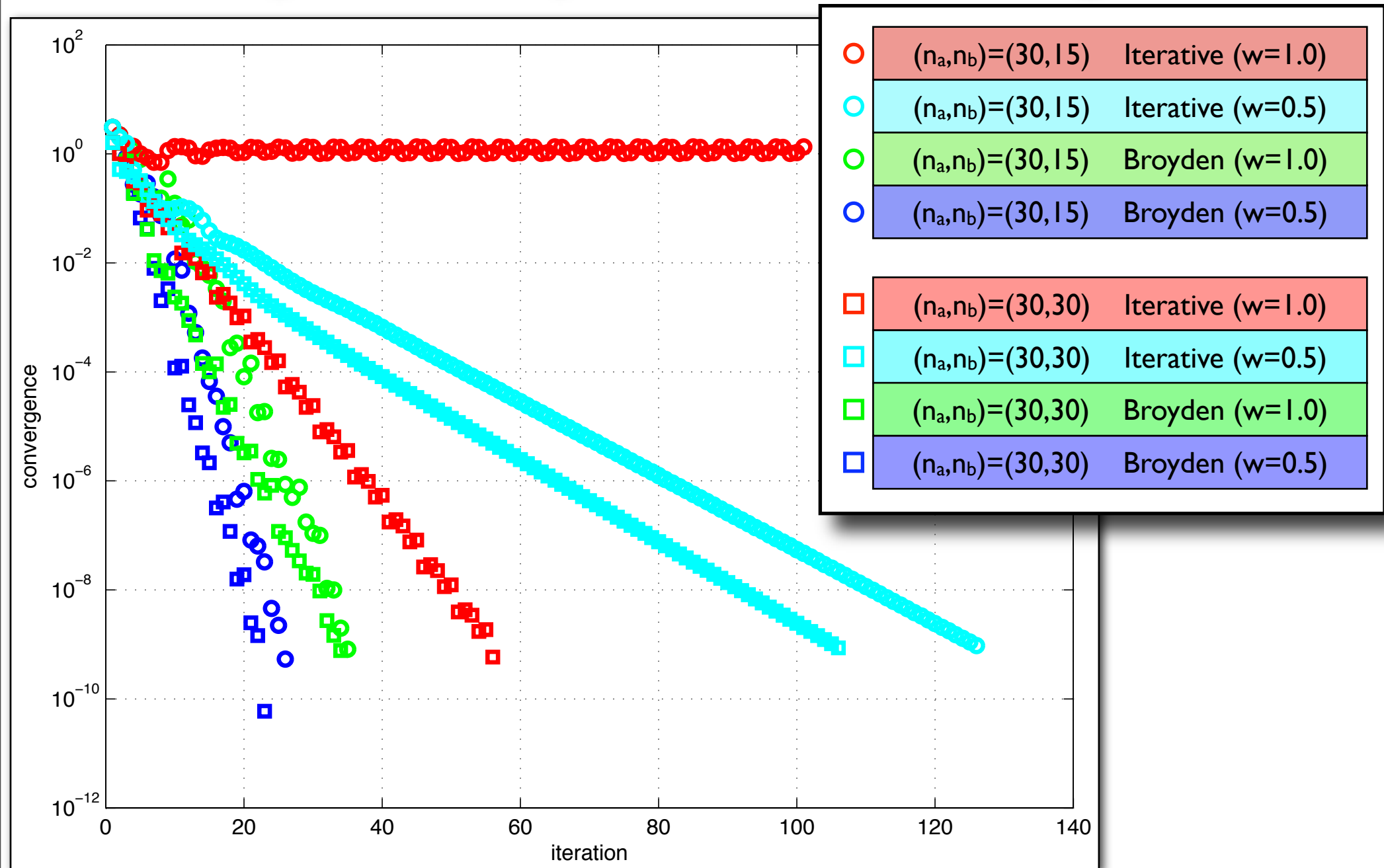
$$\mathbf{J}_{n+1}^{-1} = \mathbf{J}_n^{-1} + \frac{(|dX\rangle - \mathbf{J}_n^{-1}|dG\rangle)\langle dX|\mathbf{J}_n^{-1}}{\langle dX|\mathbf{J}_n^{-1}|dG\rangle}$$

$$\underline{\underline{(|X_{n+1}\rangle, |G_{n+1}\rangle, \mathbf{J}_{n+1}^{-1})}}$$

- Multidimensional Secant method
- Start with $\mathbf{J}_0^{-1} = w$:
 - $X_1 = (1-w)X_0 + wF(X_0)$
- May keep track of dyadics if space is large
- Hold $\mathbf{J}_n^{-1} = w$ for old method

Described in *Numerical Recipes in **, Press, Teukolsky, Vetterling, Flannery (1992)

Broyden Improves Convergence



Current Implementation

EV8

```
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    END DO
  END DO
END DO
```

Simple Code Modifications

MATLAB Code

```
if iter == 1      % usual step for first iteration or if using usual procedure
    G0    =    x0 - [V_0;D_0;V_1;D_1; mu_a*N_a/N0_a;mu_b*N_b/N0_b];
    Jinv0 =    w      % use weight on initial step or if using usual procedure
    dx    = - Jinv0*G0;
    x0    =    x0 + dx;
elseif iter > 1  % broyden step from second iteration
    G1    =    x0 - [V_0;D_0;V_1;D_1; mu_a*N_a/N0_a;mu_b*N_b/N0_b];
    dG    =    G1 - G0;
    ket    =    dx - Jinv0*dG;
    bra    =    dx'*Jinv0;
    inorm  =    1.0/(bra*dG);
    Jinv0 =    Jinv0 + ket*bra*inorm;      % update inverse jacobian here
    dx    = - Jinv0*G1;
    x0    =    x0 + dx;
    G0    =    G1;
end
```

Broyden Method

$$G(X) = X - F(X) = 0$$

$$\underline{\underline{(|X_n\rangle, |G_n\rangle, \mathbf{J}_n^{-1})}}$$

$$|dX\rangle = -\mathbf{J}_n^{-1} \cdot |G_n\rangle$$

$$|X_{n+1}\rangle = |X_n\rangle + |dX\rangle$$

$$|G_{n+1}\rangle = G(|X_{n+1}\rangle)$$

$$|dG\rangle = |G_{n+1}\rangle - |G_n\rangle$$

$$\mathbf{J}_{n+1}^{-1} = \mathbf{J}_n^{-1} + \frac{(|dX\rangle - \mathbf{J}_n^{-1}|dG\rangle)\langle dX|\mathbf{J}_n^{-1}}{\langle dX|\mathbf{J}_n^{-1}|dG\rangle}$$

$$\underline{\underline{(|X_{n+1}\rangle, |G_{n+1}\rangle, \mathbf{J}_{n+1}^{-1})}}$$

- Multidimensional Secant method
- Start with $\mathbf{J}_0^{-1} = w$:
 - $X_1 = (1-w)X_0 + wF(X_0)$
- May keep track of dyadics if space is large
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Described in *Numerical Recipes in **, Press, Teukolsky, Vetterling, Flannery (1992)

Broyden Costs

- Simple: (Maintain and update Jacobian inverse)
 - $O(N^2) \times N_{\text{iter}}$
- Dyadic Representation:
 - $O(N \times N_{\text{iter}}) \times N_{\text{iter}}$

$$\mathbf{J}_{m+1}^{-1} = w\mathbf{1} + \sum_{n=1}^m |a_n\rangle \langle b_n|$$

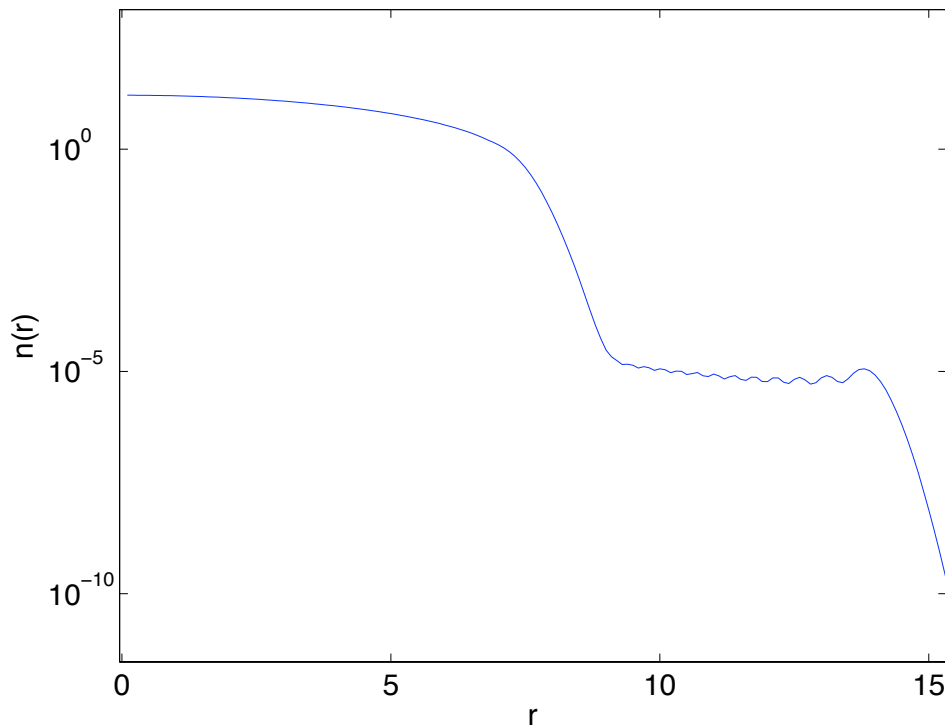
$$|a_n\rangle = |dX_n\rangle - \mathbf{J}_n^{-1} |dG_n\rangle$$

$$\langle b_n| = \frac{\langle dX_n | \mathbf{J}_n^{-1}}{\langle dX_n | \mathbf{J}_n^{-1} | dG_n \rangle}$$

Difficulties with HO Basis

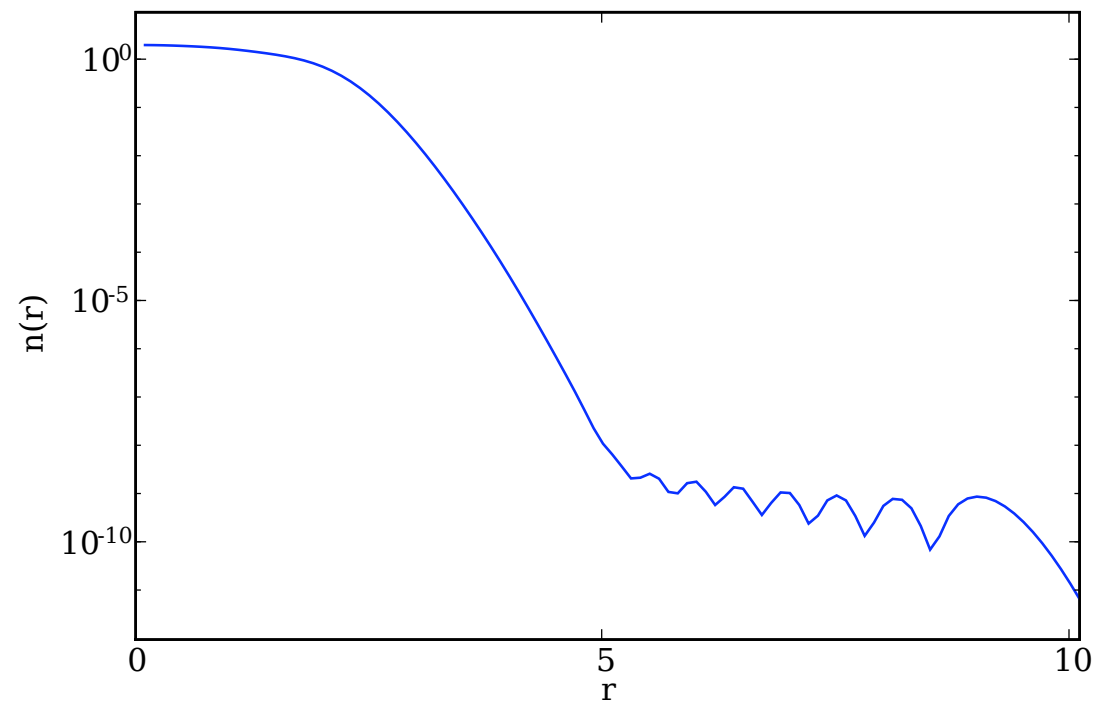
- Large radius behaviour of HO Basis introduces artifacts
- Need large number of states to correct
 - (Requires HO Basis wavefunctions to high precision)

Grasso and Urban, BCS Code

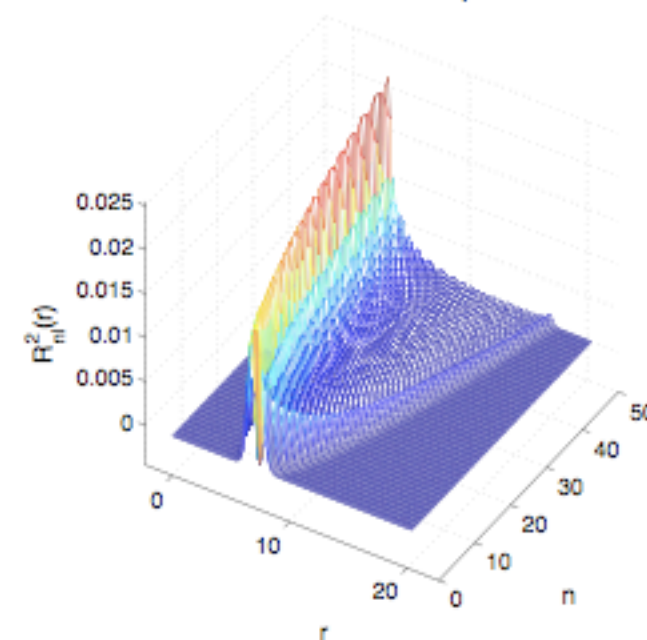
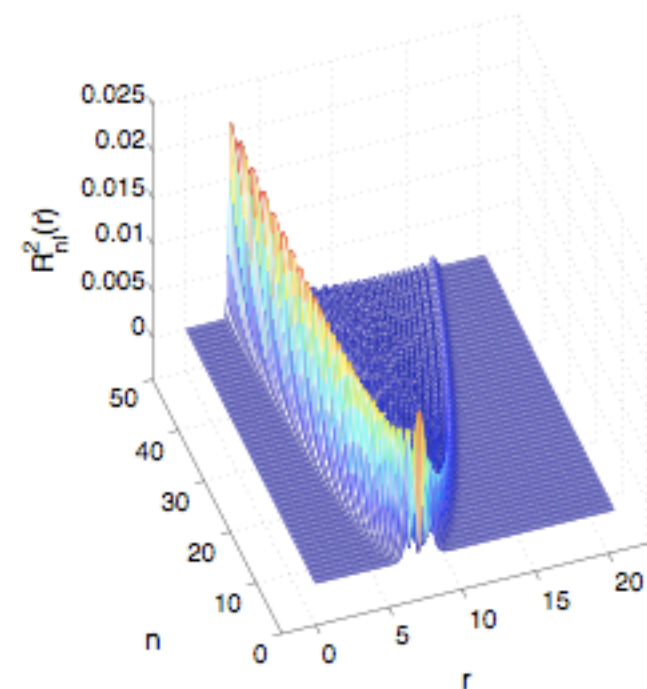
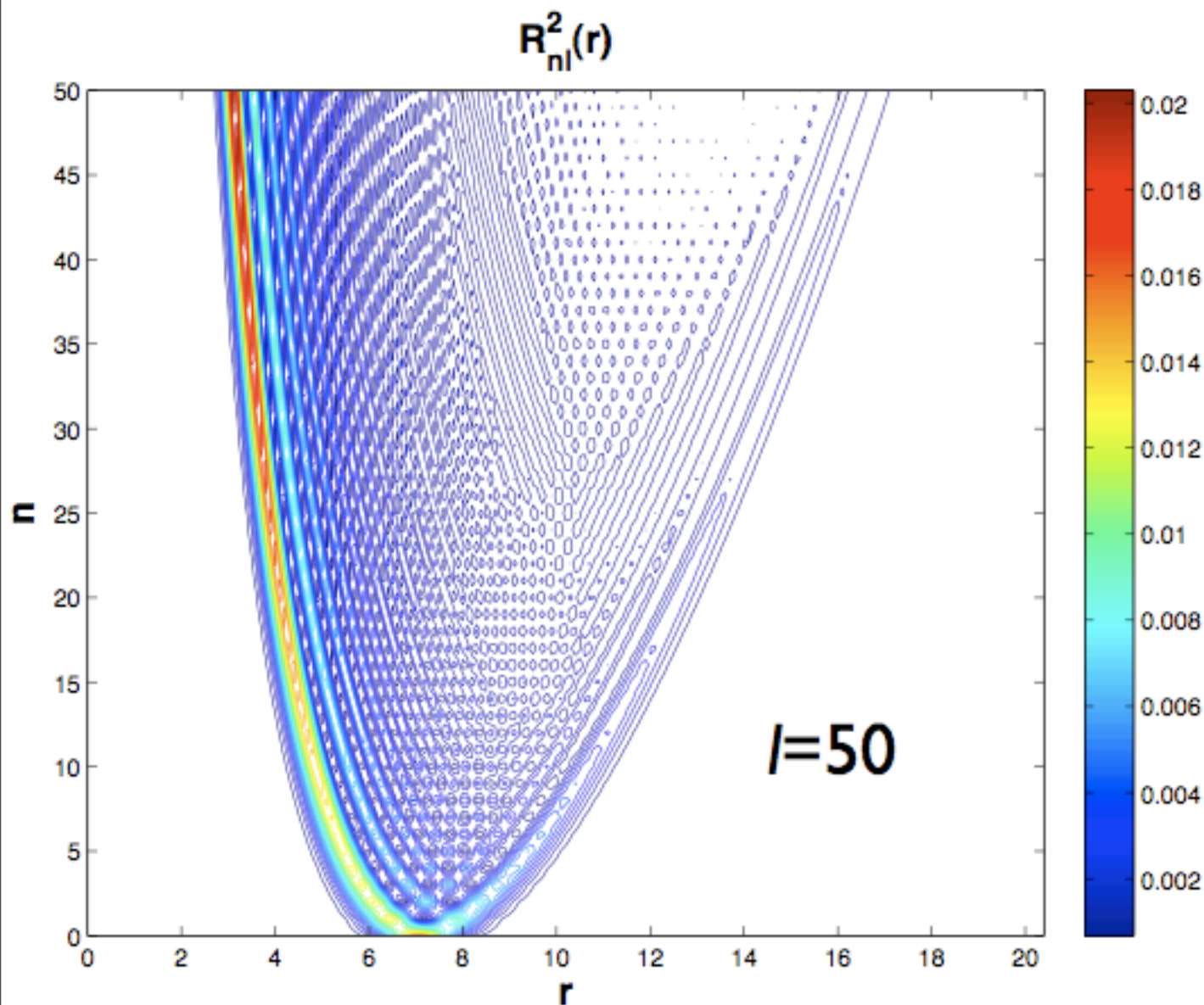


Grasso and Urban, PRA, 68, 033610 (2003)

Our Unitary HO Basis Code



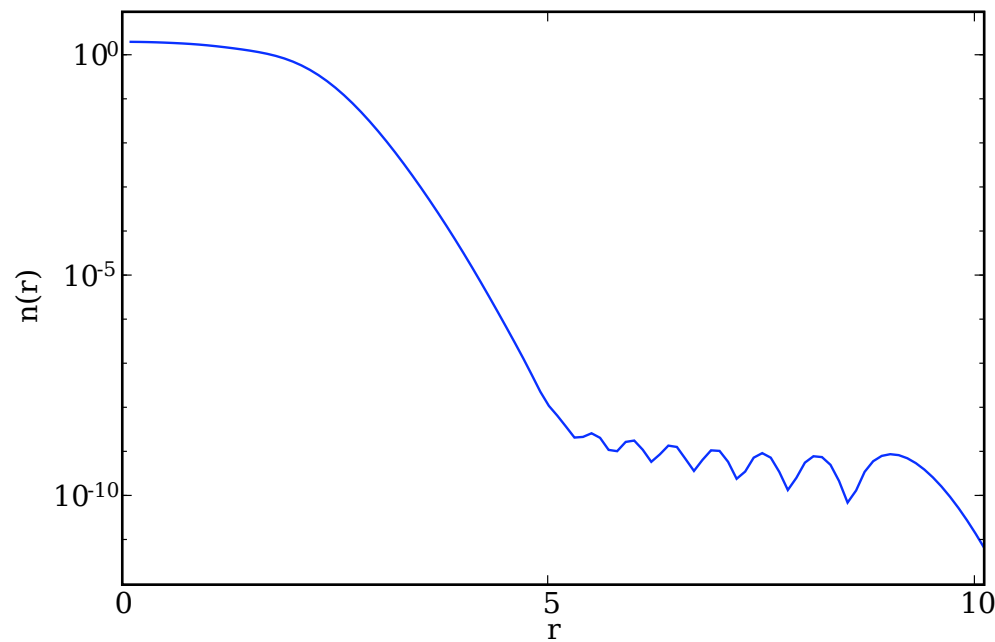
Problem with HO Basis



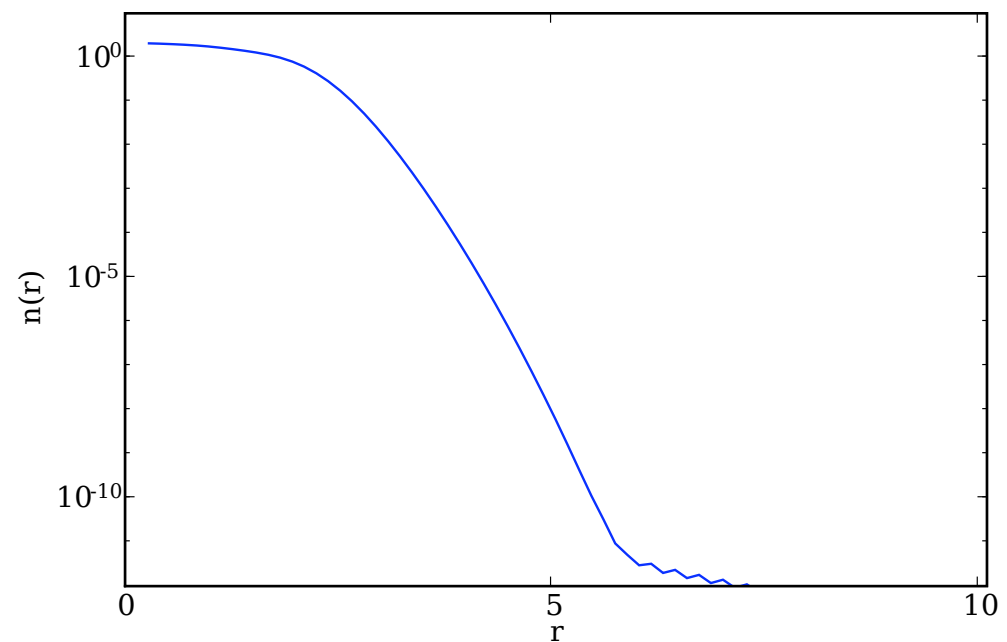
- Tails spoil large r behaviour

DVR solves the problem

Our code in HO Basis



Our code in DVR basis



DVR Basis in one-dimension

(Higher dimensional generalization is straightforward)

$P^2 = P$ (Projection onto restricted Hilbert space)

$$\langle x|P|y\rangle = \int_{-\pi/l}^{\pi/l} \frac{dk}{2\pi} e^{ik(x-y)} = \frac{\sin\left(\frac{\pi}{l}(x-y)\right)}{\pi(x-y)},$$

$$\Delta_\alpha = P[\delta(x - x_\alpha)],$$

$$\langle \Delta_\alpha | \Delta_\beta \rangle = \Delta_\alpha(x_\beta) = \Delta_\beta(x_\alpha) = K_\alpha \delta_{\alpha\beta},$$

$$\psi(x) = \sum_{\alpha=1}^N c_\alpha \Delta_\alpha + O(e^{-cN}) \approx \sum_n \psi(nl) \frac{\sin\left[\frac{\pi}{l}(x - nl)\right]}{\frac{\pi}{l}(x - nl)}$$

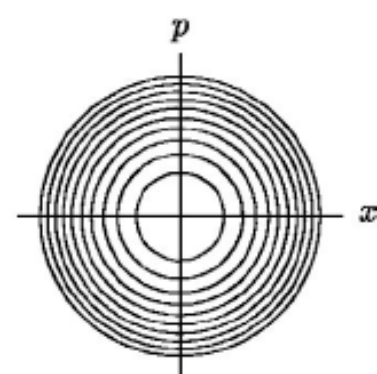
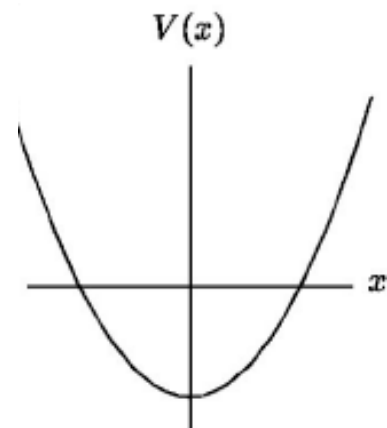
$$c_\alpha = \int dx \frac{1}{K_\alpha} \Delta_\alpha(x) \psi(x) = \frac{1}{K_\alpha} \psi(x_\alpha), \quad x_\alpha = nl$$

Littlejohn et al. J. Chem. Phys. **116**, 8691 (2002)

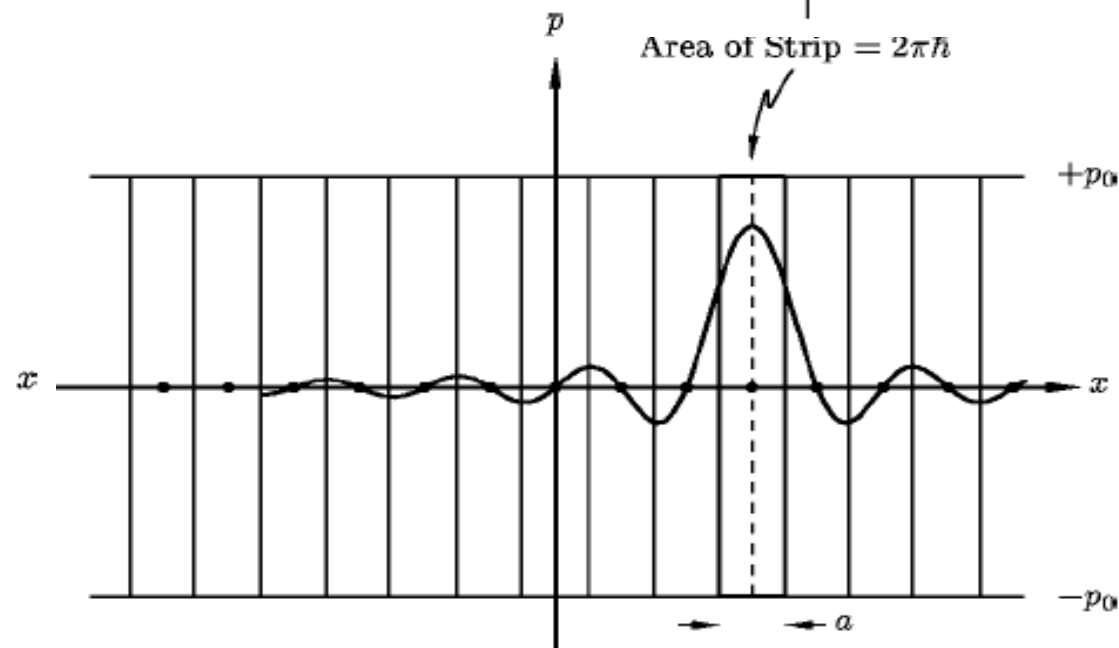
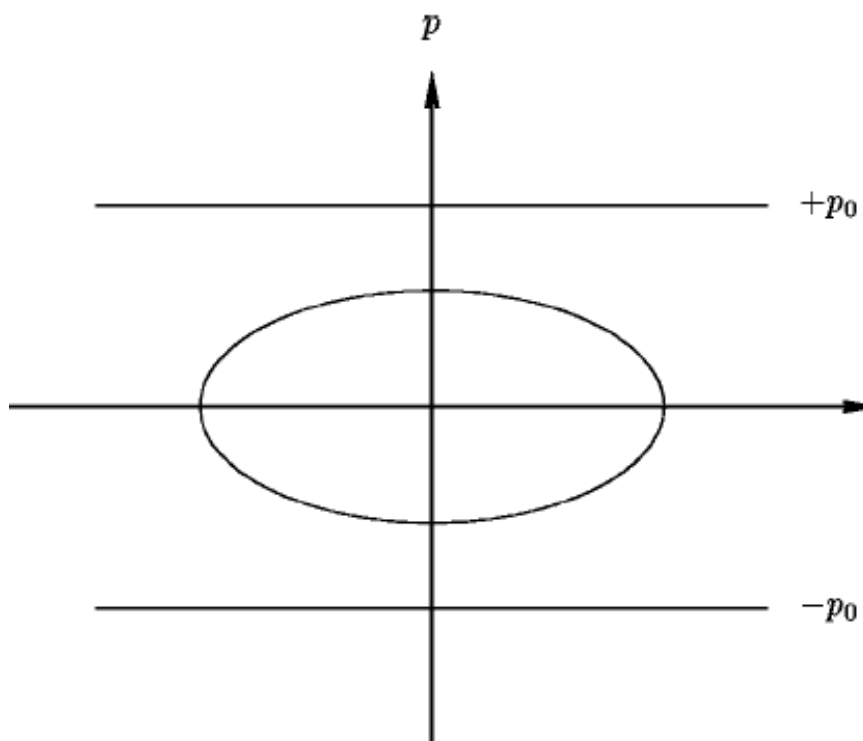
$$\psi(x) = \sum_{\alpha=1}^N d_{\alpha} F_{\alpha}(x) + O(e^{-cN}),$$

$$F_{\alpha} = \frac{1}{\sqrt{K_{\alpha}}} \Delta_{\alpha}(x), \quad x_{\alpha} = nl, \quad \langle F_{\alpha} | F_{\beta} \rangle = \delta_{\alpha, \beta},$$

$$\sum_{\beta} \left[\langle F_{\alpha} | \hat{\mathbf{T}} | F_{\beta} \rangle + V(x_{\alpha}) \delta_{\alpha\beta} \right] d_{\beta} = E d_{\alpha}$$



Area of Strip = $2\pi\hbar$



DVR for Radial Equation: Bessel DVR Basis

Littlejohn *et al.* J. Chem. Phys. **117**, 27 (2002)

$$F_{\nu n}(r) = (-1)^{n+1} \frac{K z_{\nu n} \sqrt{2r}}{K^2 r^2 - z_{\nu n}^2} J_{\nu}(Kr)$$

$$P(r, r') = \int_0^K dk \langle kr | J_{\nu} \rangle \langle J_{\nu} | kr' \rangle$$

$$\langle F_{\nu n} | k_r^2 + \frac{\nu^2 - \frac{1}{4}}{r^2} | F_{\nu n'} \rangle = \begin{cases} \frac{K^2}{3} \left[1 + \frac{2(\nu^2 - 1)}{z_{\nu n}^2} \right], & n = n', \\ (-1)^{n-n'} 8K^2 \frac{z_{\nu n} z_{\nu n'}}{(z_{\nu n}^2 - z_{\nu n'}^2)^2}, & n \neq n', \end{cases}$$

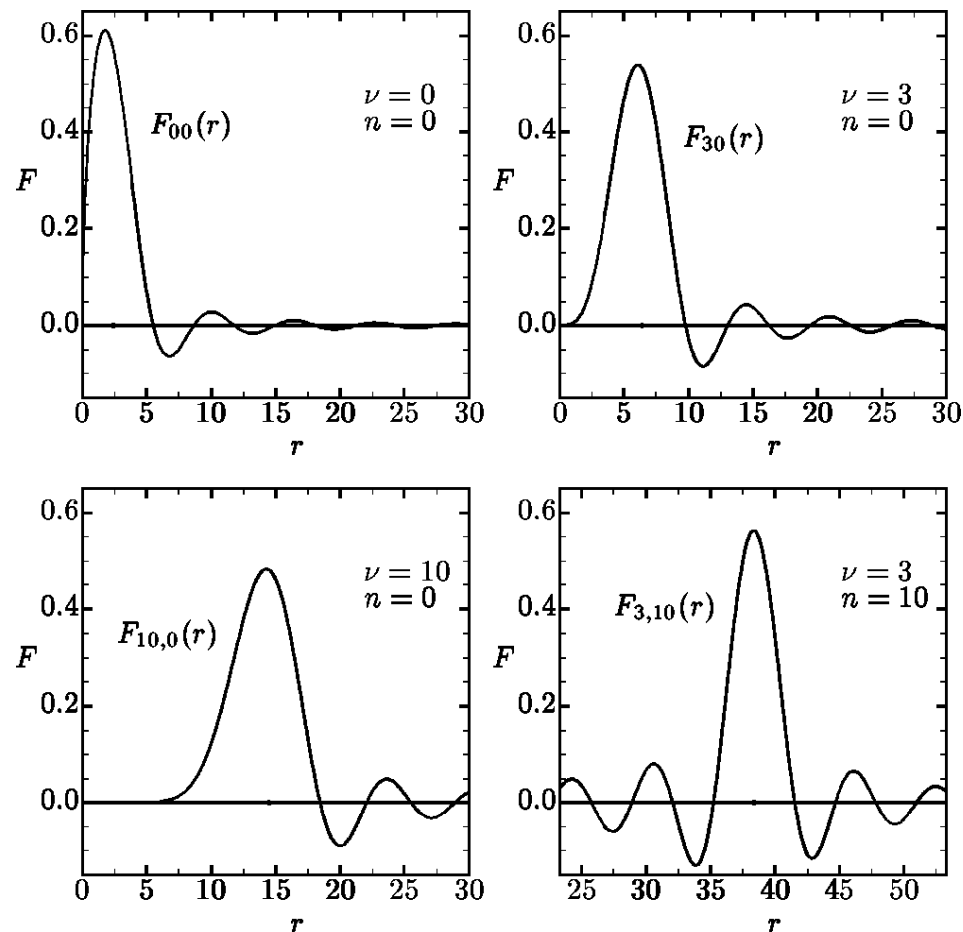
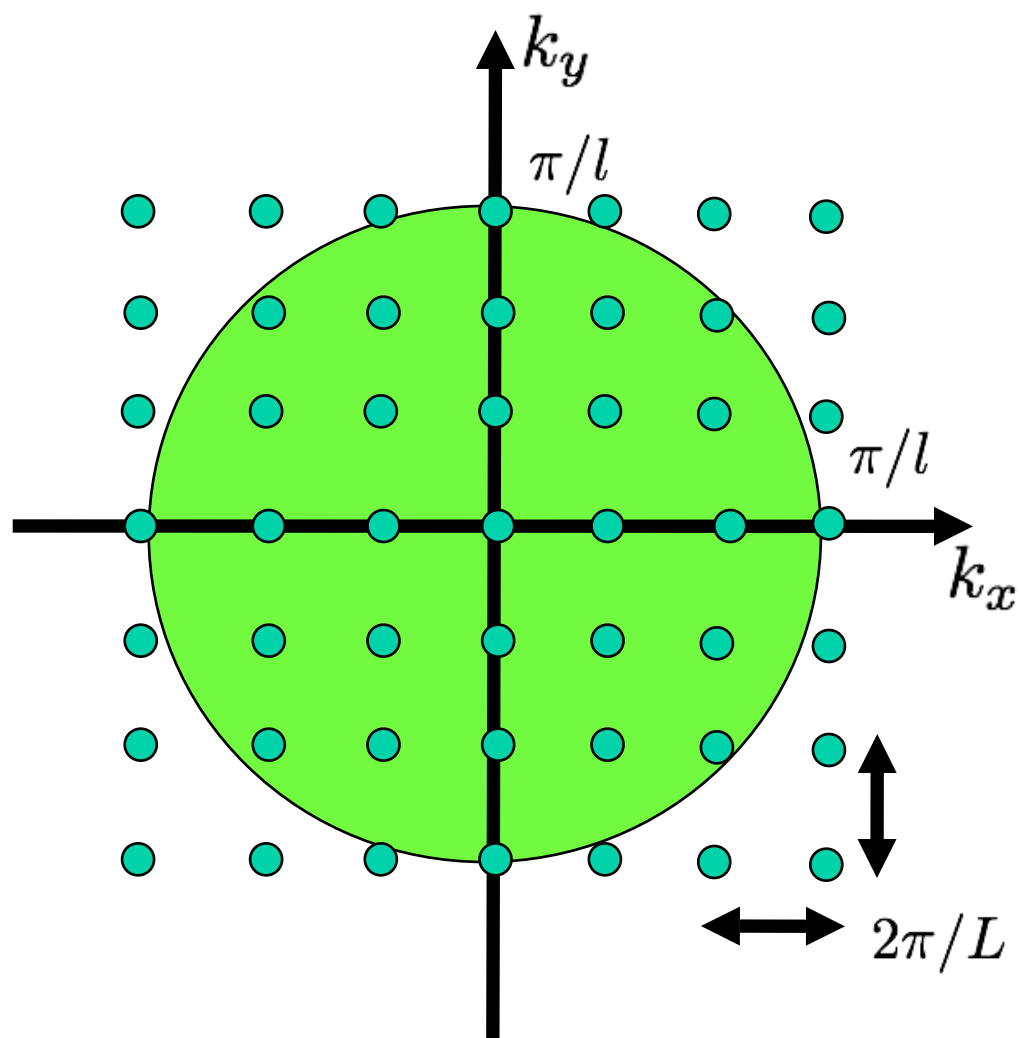


FIG. 2. Plots of the Bessel DVR functions $F_{\nu n}(r)$ for $K=1$ and for selected values of ν and n .



Momentum Space

$$\varepsilon_F, \Delta, T \ll \frac{\hbar^2 \pi^2}{2ml^2},$$

$$\delta\varepsilon > \frac{2\hbar^2 \pi^2}{mL^2},$$

$$\varepsilon_F, \Delta T \gg \frac{2\hbar^2 \pi^2}{mL^2},$$

$$\xi \ll L = N_s l,$$

$$\delta p > \frac{2\pi\hbar}{L}.$$

Summary

- Broyden Improves Convergence
 - Extremely easy to implement
 - Can be made inexpensive
- HO Basis has problems with large r tails
- DVR Basis solves these problems
 - Near optimal phase-space coverage